Mid 1 RC Part 3: Static Electric Fields

1 Conductors and dielectrics in static electric field

- conductors:
 - electrons migrate easily.
 - charges reach the surface and conductor redistribute the charges in a way that the field vanishes.
 - static state conditions:
 - * inside the conductor:

$$\rho = 0, E = 0$$

where $\rho = 0$ represents no charge in the interior

* on the conductor surface (boundary conditions)

$$E_t = 0, E_n = \frac{\rho_s}{\epsilon_0}$$

It is an equal-potential body.

- semiconductors:
 - relatively small number of freely movable charges.
- insulators(dielectrics):
 - electrons are confined to their orbits.
 - external electric field polarizes a dielectric material and create electric dipoles.
 The induced electric dipoles will modify the electric field both inside and outside the dielectric material, as shown in Fig 1.

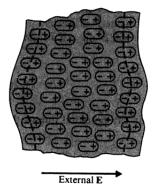


Figure 1: A cross section of a polarized dielectric medium

- polarization charge densities/ bound-charge densities:
 - * polarization vector, *P*:

$$oldsymbol{P} = \lim_{\Delta v o 0} rac{\sum_{k=1}^{n \Delta v} oldsymbol{p_k}}{\Delta v}$$

where the numerator represents the vector sum of the induced dipole moment contained in a very small volume Δv .

* charge distribution on surface density:

$$\rho_{ps} = \boldsymbol{P} \cdot \boldsymbol{a_n}$$

* volume charge distribution density:

$$\rho_p = -\nabla \cdot \boldsymbol{P}$$

 $\mathbf{Ex.1}$ Determine the electric field intensity at the center of a small spherical cavity cut out of a large block of dielectric in which a polarization \mathbf{P} exists.

2 Electric Flux Density and Dielectric Constant

• electric flux density/electric displacement, D:

$$\boldsymbol{D} = \epsilon_0 \boldsymbol{E} + \boldsymbol{P} \quad (C/m^2)$$

•

$$\nabla \cdot \boldsymbol{D} = \rho \quad (C/m^3)$$

where ρ is the volume density of free charges.

• Another form of Gauss's law:

$$\oint_{S} \boldsymbol{D} \cdot d\boldsymbol{s} = Q_{free} \quad (\boldsymbol{C})$$

the total outward flux of the electric displacement (the total outward electric flux) over any closed surface is equal to the total free charge enclosed in the surface.

• If the dielectric of the medium is linear and isotropic,

$$P = \epsilon_0 \chi_e E$$

$$\mathbf{D} = \epsilon_0 (1 + \chi_e) \mathbf{E} = \epsilon_0 \epsilon_r \mathbf{E} = \epsilon \mathbf{E}$$

where χ_e is a dimensionless quantity called electric susceptibility,

 ϵ_r is a dimensionless quantity called as relative permittivity/ electric constant of the medium,

 ϵ is the absolute permittivity/permittivity of the medium (F/m).

• For anisotropic,

$$\begin{bmatrix} D_x \\ D_y \\ D_z \end{bmatrix} = \begin{bmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{21} & \epsilon_{22} & \epsilon_{23} \\ \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{bmatrix} \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix}$$

For bi-axial,

$$\begin{bmatrix} D_x \\ D_y \\ D_z \end{bmatrix} = \begin{bmatrix} \epsilon_1 & 0 & 0 \\ 0 & \epsilon_2 & 0 \\ 0 & 0 & \epsilon_3 \end{bmatrix} \begin{bmatrix} E_x \\ E_y \\ E_z \end{bmatrix}$$

For uni-axial, $\epsilon_1 = \epsilon_2$, For isotropic, $\epsilon_1 = \epsilon_2 = \epsilon_3$ (the only kind of media we deal with in this course).

• dielectric breakdown: electric field is very strong, causes permanent dislocations and damage in the material.

dielectric strength: the maximum electric field intensity that a dielectric material can withstand without breakdown.

3 Boundary Conditions for Electrostatic Fields

ullet the tangential component of an $m{E}$ field is continuous across an interface.

$$E_{1t} = E_{2t} \quad (V/m)$$

or

$$\frac{D_{1t}}{\epsilon_1} = \frac{D_{2t}}{\epsilon_2}$$

 \bullet The normal component of D field is discontinuous across an interface where a surface charge exists - the amount of discontinuity being equal to the surface charge density.

$$\boldsymbol{a_{n2}} \cdot (\boldsymbol{D_1} - \boldsymbol{D_2}) = \rho_s$$

or

$$D_{1n} - D_{2n} = \rho_s \quad (C/m^2)$$

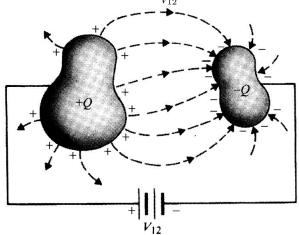
4 Capacitance and Capacitors

4.1 Capacitance

- Definition: The capacitance of isolated conducting body is the electric charge that must be added to the body per unit increase in its electric potential.
- $C = \frac{Q}{V} (F = C/V)$

4.2 Capacitor

• Components: two conductors with arbitrary shapes are separated by free space or dielectric medium. $C = \frac{Q}{V_{12}}$



• Capacitance:

Its Capacitance is independent of V and Q, which means a capacitor has a capacitance even no voltage is applied to it and no free charges exist on its conductors.

- How to calculate its capacitance:
 - 1. Choose a proper coordinate system
 - 2. Assume +Q, -Q on the conductors
 - 3. Find **E** from Q (like, Gauss's law, $D_n = \epsilon E_n = \rho_s$)
 - 4. Find $V_{12} = -\int_{2}^{1} \mathbf{E} \cdot d\mathbf{l}$
 - 5. $C = Q/V_{12}$
- Series Connections of Capacitors:

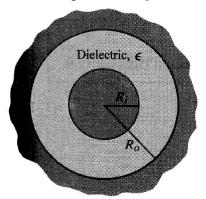
$$\frac{1}{C_{sr}} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n}$$

• Parallel Connections of Capacitors:

$$C_{||} = C_1 + C_2 + \dots + C_n$$

Ex.2 Suppose we have a parallel conductor plane capacitor with capacitance of C, what is the new capacitance C' if we insert a dielectric with relative permittivity of ϵ_r ?

Ex.3 A spherical capacitor consists of an inner conducting sphere of radius R_i and an outer conductor with a sphere inner wall of radius R_o . The space in between is filled with a dielectric of permittivity ϵ . Determine the capacitance.



4.3 Electrostatic Energy and Forces

• Potential difference between P_1 to P_2

$$\frac{W_{12}}{q} = V_{21} = V_2 - V_1 = -\int_{P_1}^{P_2} \mathbf{E} \cdot d\mathbf{l}$$

• Self Energy: Work done to bring a charge Q_2 from infinitely far away to distance R_{12} with Q_1 (initially, Q_1 is in space)

$$W = Q_2 V_2 = Q_2 \frac{Q_1}{4\pi\epsilon_0 R_{12}}$$

• Mutual Energy: Potential energy of a group of N discrete point charges at rest

$$W_e = \frac{1}{2} \sum_{k=1}^{N} Q_k V_k$$

where $V_k = \frac{1}{4\pi\epsilon_0} \sum_{j=1}^N \sum_{kj\neq k}^{Q_j} N_{ote}$ the W_e can be negative, for example, there are 2-point charge systems, and one charge is positive, the other is negative.

- Electrostatic Energy (Volume) density w_e : $W_e = \int_{v'} w_e dv$
- 4.3.1 Electrostatic Energy in terms of Field Quantities
 - v' can be all space.
 - A continuous Charge Distribution of Density ρ

$$W_e = \frac{1}{2} \int_{v} \rho V dv = \frac{1}{2} \int_{v'} (\nabla \cdot \mathbf{D}) V dv$$

Another expression:

$$W_e = \frac{1}{2} \int_{v'} \mathbf{D} \cdot \mathbf{E} dv$$

• If it is a simple dielectric, it should be

$$W_e = \frac{1}{2} \int_{v'} \epsilon E^2 dv = \frac{1}{2} \int_{v'} \frac{D^2}{\epsilon} dv$$

4.3.2 Electrostatic Forces

Here we use **Principle of virtual displacement** to calculate Force in two situations.

- System of bodies with fixed charges
 - 1. Mechanical work is from the reduced stored electrostatic energy

$$F_Q = -\nabla W_e(N)$$

2. Electric torque rotates one of the bodies by $d\phi$ (a virtual rotation) about an axis

$$T_Q = -\frac{\partial W_e}{\partial \phi} (N \cdot m)$$

- System of conducting bodies with Fixed Potentials
 - 1. The fixed potential can be retained by connecting with an external source.
 - 2. $F_v = \nabla W_e$
 - 3. $T_v = \frac{\partial W_e}{\partial \phi}$

Example 3-22 Find the energy required to assemble a uniform sphere of charges of radius b and volume charge ρ .