

1. (a) [10] Perform partial fraction expansion on a system's frequency response

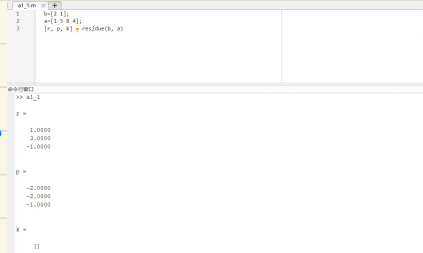
$$H(j\omega) = \frac{2j\omega + 1}{-j\omega^3 - 5\omega^2 + 8j\omega + 4}$$

Then use Matlab `residue` to verify your result. Be careful with the interpretation of Matlab outputs in the case of repeated pole(s).

- (b) [10] Based on (a), find the unit impulse response $h(t)$ of this system and use Matlab to plot your answer as a function of t . Then use Matlab `impz` to generate a same plot and verify your result.

(a) Letting $s = j\omega$, we have

$$H(s) = \frac{2s + 1}{s^3 + 5s^2 + 8s + 4} \Rightarrow \frac{1}{s+2} + \frac{3}{(s+1)^2} - \frac{1}{s+1}$$



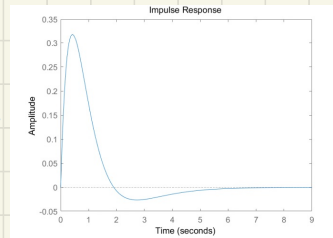
In the case of repeated poles, p is ordered in A_{ik} . Therefore, it's exactly our result.

(b)

$$e^{-at} u(t) \leftrightarrow \frac{1}{j\omega + a}$$

$$te^{-at} u(t) \leftrightarrow \frac{1}{(j\omega + a)^2}$$

$$\Rightarrow h(t) = (3t+1)e^{-t} u(t) - e^{-t} u(t)$$



- (a) [10] Sketch $X_p(\omega)$ for $-9\pi \leq \omega \leq 9\pi$ for the following values of ω_0 .

- $\omega_0 = \pi$
- $\omega_0 = 2\pi$
- $\omega_0 = 3\pi$
- $\omega_0 = 5\pi$

- (b) [4] For which of the preceding values of ω_0 is $x_p(t)$ identical? For which of the preceding values of ω_0 will NOT be able to recover the input sinusoidal signal after lowpass filtering $x_p(t)$?

$$\cos \omega_0 t \rightarrow \text{X} \rightarrow x_p(t)$$

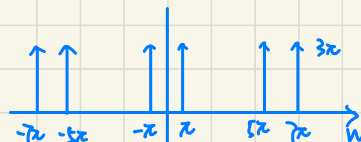
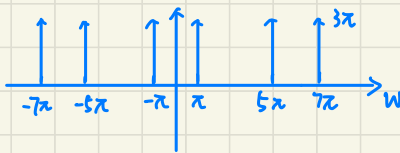
$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT), \quad T = \frac{1}{3}$$

(a) The spectrum of $p(t)$: $P(\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi k}{T}) = 6\pi \sum_{k=-\infty}^{\infty} \delta(\omega - 6\pi k)$

And the spectrum of $\cos(\omega_0 t)$ is $\pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$

Hence, $X_p(\omega) = \frac{1}{2\pi} P(\omega) * [\pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)]$

and the four sketches are given below:

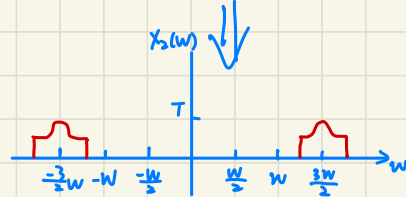
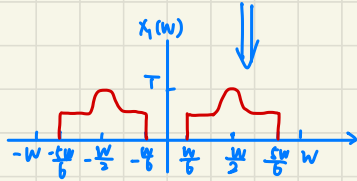
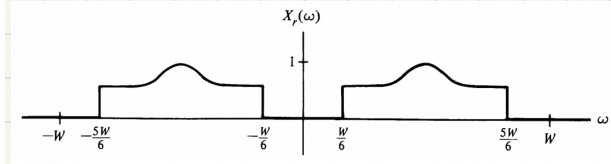
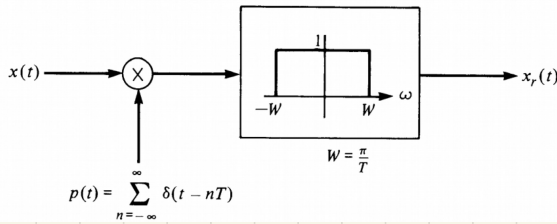


(b)

(i) and (iv) are identical.

We will not be able to reconstruct (iv) from $x_p(t)$

3. [12] Given the system in Figure 0503(a) and the Fourier transform of $x_r(t)$ in Figure 0503(b), sketch the Fourier transform of two different signals $x(t)$ that could have generated $x_r(t)$.



4. [16] Consider the system in Figure 0504.

If $X_1(\omega) = 0$ for $|\omega| > 2W$ and $X_2(\omega) = 0$ for $|\omega| > W$. For the following inputs $x(t)$, find the ranges for the cutoff frequency W_c in terms of T and W and find the maximum values of T and A , such that $x_r(t) = x(t)$.

(a) Time shift doesn't affect bandwidth.

$$X(\omega) = 0 \text{ for } |\omega| > 2W. \text{ Hence } T_{\max} = \frac{\pi}{2W}, A = T.$$

$$2W < W_c < \frac{2\pi}{T} - 2W$$

(a) $x(t) = x_1(t - \pi/2) + x_2(t)$

(b) $x(t) = x_1(t)x_2(t)$

(c) $x(t) = dx_2(t)/dt$

(d) $x(t) = x_2(t) \cos(2Wt)$

(b) $X(\omega) = 0$ for $|\omega| > 3W$. Hence, $T_{\max} = \frac{\pi}{3W}$, $A = T$, $3W < W_c < \frac{2\pi}{T} - 3W$

(c) $X(\omega) = 0$ for $|\omega| > W$. Hence, $T_{\max} = \frac{\pi}{W}$, $A = T$, $W < W_c < \frac{2\pi}{T} - W$

(d) $X(\omega) = \frac{1}{2} (X(\omega - 2W) + X(\omega + 2W))$. $X(\omega) = 0$ for $|\omega| > 3W$.

Hence, $T_{\max} = \frac{\pi}{3W}$. $A = T$, $3W < W_c < \frac{2\pi}{T} - 3W$

5. [20] A signal $x(t)$ with spectrum $X(\omega) = \left(1 - \left|\frac{\omega}{2\pi}\right|\right) \text{rect}\left(\frac{\omega}{4\pi}\right)$ is filtered by a system with frequency response $H(\omega) = \text{rect}\left(\frac{\omega}{2\pi}\right)$. The resulting signal is then multiplied by $\cos(8\pi t)$. Finally, that signal is passed through an integrator system, yielding a signal $y(t)$. Find and sketch $Y(\omega)$.

After filtering, $X_1(\omega) = X(\omega)H(\omega) = \left(1 - \left|\frac{\omega}{2\pi}\right|\right) \text{rect}\left(\frac{\omega}{4\pi}\right) \text{rect}\left(\frac{\omega}{2\pi}\right) = \left(1 - \left|\frac{\omega}{2\pi}\right|\right) \text{rect}\left(\frac{\omega}{2\pi}\right)$

After modulation, $X_2(\omega) = \frac{1}{2} (X_1(\omega + 8\pi) + X_1(\omega - 8\pi))$

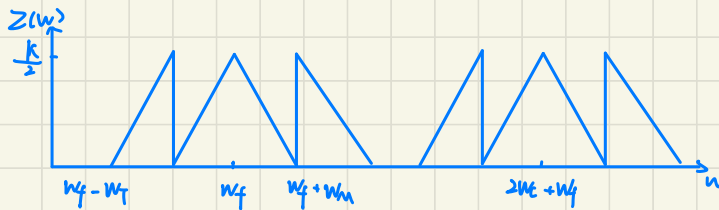
Passing through an integrator,

$$Y(\omega) = X_2(\omega) \cdot \frac{1}{j\omega} + \pi X_2(0) \cdot \delta(\omega) = \frac{1}{j\omega} X_2(\omega) = \frac{1}{2j\omega} (X_1(\omega + 8\pi) + X_1(\omega - 8\pi))$$

6. [18] The accurate demultiplexing-demodulation of radio and television signals is generally performed using a system called the superheterodyne receiver, which is equivalent to a tunable filter. The basic system is shown as Figure 0506.

- (a) [6] The input signal $y(t)$ consists of the superposition of many amplitude-modulated signals that have been multiplexed using frequency-division multiplexing, so that each signal occupies a different frequency channel. Let us consider one such channel that contains the amplitude-modulated signal $y_1(t) = x_1(t) \cos \omega_c t$, with spectrum $Y_1(\omega)$ within $[\omega_c - \omega_M, \omega_c + \omega_M]$ as depicted below. We want to demultiplex and demodulate $y_1(t)$ to recover the modulating signal $x_1(t)$, using the system in the figure. The coarse tunable filter has the spectrum $H_1(\omega)$. Determine the spectrum $Z(\omega)$ of the input signal to the fixed selective filter $H_2(j\omega)$. Sketch and label $Z(\omega)$ for $\omega > 0$.
- (b) [6] The fixed frequency-selective filter is a bandpass type centered around the fixed frequency ω_f . We would like the output of the filter with spectrum $H_2(\omega)$ to be $r(t) = x_1(t) \cos \omega_f t$. In terms of ω_c and ω_M , what constraint must ω_T satisfy to guarantee that an undistorted spectrum of $x_1(t)$ is center around $\omega = \omega_f$?
- (c) [6] What must G , α , and β be in the figure so that $r(t) = x_1(t) \cos \omega_f t$.

(a) The spectrum $Z(\omega)$



(b) From the figure above, we know that to avoid aliasing:

$$\omega_f + \omega_M \leq 2\omega_c + \omega_f - \omega_T \Rightarrow \omega_T \leq 2\omega_c - \omega_M$$

and in case $\omega_f - \omega_T$ is negative, we also have to make sure:

$$-\omega_f + \omega_T \leq \omega_f - \omega_M \Rightarrow \omega_T \leq 2\omega_f - \omega_M$$

(c)

$$G = \frac{2}{K}, \quad \alpha = \omega_f - \omega_M, \quad \beta = \omega_f + \omega_M$$