# **Ve216 Introduction to Signals and Systems: Summary** March 13, 2023, 11:35 Yong Long, UM-SJTU Joint Institute (Based on Lecture Notes by Prof. Jeffrey A. Fessler)

## Signals and Systems: Summary 1

- Circuits:  $v(t)=Ri(t), v(t)=L\frac{\mathrm{d}}{\mathrm{d}t}i(t), i(t)=C\frac{\mathrm{d}}{\mathrm{d}t}v(t)$  Notation:  $x(t)=\left\{ egin{array}{ll} e^{-t}, & t>2, \\ 0, & \mathrm{otherwise} \end{array} \right.=e^{-t}u(t-2)$
- Time transformation:
  - $x(\frac{t-t_0}{w})$ . First scale according to w, then shift according to  $t_0$ . x(at-b). First time-delay by b, then time-scale by a

- Integrator system  $y(t) = \int_{-\infty}^t x(\tau) d\tau = x(t) * u(t)$  Even symmetry: x(-t) = x(t), Odd symmetry: x(-t) = -x(t)• Ev  $\{x(t)\} = \frac{1}{2}(x(t) + x(-t))$ , Od  $\{x(t)\} = \frac{1}{2}(x(t) x(-t))$ ,  $x(t) = \text{Ev }\{x(t)\} + \text{Od }\{x(t)\}$ .
- Average value:  $A \stackrel{\triangle}{=} \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} x(t) dt$
- Energy:  $E \stackrel{\triangle}{=} \int_{-\infty}^{\infty} |x(t)|^2 dt$

- Average power:  $P \stackrel{\triangle}{=} \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} |x(t)|^2 dt$  Energy signal:  $E < \infty, P = 0$ . Power signal:  $E = \infty, 0 < P < \infty$ . Power of periodic signal:  $P = \frac{1}{T_0} \int_0^{T_0} |x(t)|^2 dt$
- Step function: u(t) = 1 for t > 0.
- Rect function: rect(t) = 1 for -1/2 < t < 1/2, rect(t) = u(t+1/2) u(t-1/2) = u(t+1/2)u(1/2-t)
- Impulse functions
  - Sifting property:  $\int_{-\infty}^{\infty} x(t)\delta(t-t_0)\,dt = x(t_0)$  if x(t) is continuous at  $t_0$
  - Sampling property:  $x(t)\delta(t-t_0)=x(t_0)\delta(t-t_0)$  if x(t) is continuous at  $t_0$  unit area property:  $\int_{-\infty}^{\infty}\delta(t-t_0)\,dt=1$  for any  $t_0$  scaling property:  $\delta(at+b)=\frac{1}{|a|}\delta(t+b/a)$  for  $a\neq 0$ .

  - symmetry property:  $\delta(t) = \delta(-t)$
  - support property:  $\delta(t-t_0)=0$  for  $t\neq t_0$
  - $\bullet$  relationships with unit step function:  $\delta(t)=\frac{\mathrm{d}}{\mathrm{d}t}u(t),\,u(t)=\int_{-\infty}^t\delta(\tau)\,d\tau$

## Continuous-time system properties

- Stability (BIBO): all bounded input signals produce bounded output signals
- Invertibility: each output signal is the response to only one input signal
- Causal: output signal value y(t) at any time t depends only on present and past input signal values.
- Static (memoryless): output at any time only depends on input signal at the same time. (otherwise dynamic)
- Time invariant:

- $x(t) \xrightarrow{\mathcal{T}} y(t)$  implies that  $x(t-t_0) \xrightarrow{\mathcal{T}} y(t-t_0)$
- Recipe for showing time-invariance.
  - Determine output signal y(t) due to a generic input signal x(t).
  - Determine the delayed output signal  $y(t-t_0)$ , by replacing t with  $t-t_0$  in y(t) expression.
  - Determine output signal  $y_d(t)$  due to a delayed input signal  $x_d(t) = x(t t_0)$ .
  - If  $y_d(t) = y(t t_0)$ , then system is time-invariant.
- Linear systems:

  - superposition property:  $\mathcal{T}[\sum_k a_k x_k(t)] = \sum_k a_k \mathcal{T}[x_k(t)]$  additivity property:  $\mathcal{T}[x_1(t) + x_2(t)] = \mathcal{T}[x_1(t)] + \mathcal{T}[x_2(t)]$
  - scaling property:  $\mathcal{T}[ax(t)] = a\mathcal{T}[x(t)]$

### LTI systems

input-output relationship described by convolution integral:

$$y(t) = \int_{-\infty}^{\infty} x(t-\tau)h(\tau) d\tau = \int_{-\infty}^{\infty} h(t-\tau)x(\tau) d\tau$$

### Properties:

- Commutative property: x(t) \* h(t) = h(t) \* x(t)
- Associative property:  $[x(t) * h_1(t)] * h_2(t) = x(t) * [h_1(t) * h_2(t)]$
- Distributive property:  $x(t) * [h_1(t) + h_2(t)] = [x(t) * h_1(t)] + [x(t) * h_2(t)]$
- The order of serial connection of LTI systems does not affect the overall impulse response.
- $\bullet \ x(t) * \delta(t) = x(t)$
- Delay property:  $x(t) * \delta(t t_0) = x(t t_0)$
- $\delta(t-t_0) * \delta(t-t_1) = \delta(t-t_0-t_1)$
- Time-invariance: If y(t) = x(t) \* h(t), then  $x(t t_0) * h(t t_1) = y(t t_0 t_1)$

## LTI system properties

- causal: h(t) = 0 for all t < 0

- static:  $h(t) = k\delta(t)$ , otherwise dynamic stable:  $\int_{-\infty}^{\infty} |h(t)| dt < \infty$  invertible:  $h(t) * h_i(t) = \delta(t)$  for some  $h_i(t)$ If h(t) \* x(t) = 0 for some nonzero signal x(t), then not invertible
- $\bullet$  step response:  $h(t) = \frac{\mathrm{d}}{\mathrm{d}t} s(t),$  where  $u(t) \stackrel{\mathrm{LTI}}{\longrightarrow} s(t)$

## Linear, constant coefficient, differential equation systems

- LTI and causal if initially at rest
- dynamic unless N = M = 0
- homogenous solution, natural response:  $y_h(t) = \sum_l C_l e^{s_l t}$ , where  $s_l$ 's are the N roots of the characteristic polynomial  $\sum_{k=0}^N a_k s^k = 0$ .

  • particular solution, forced response:  $y_p(t) = P_0 x(t) + P_1 \frac{\mathrm{d}}{\mathrm{d}t} x(t) + \cdots$

## Topics covered in Chap. 1-2

# Chap. 1

- signal classes
- signal notation
- \* time transformations
- amplitude transformations
- signal operations
- integrator system (running integral operation)
- \* even/odd signals
- \* energy and power signals
- periodicity
- \* unit step / rect signals
- \* unit impulse function
- \* impulse function properties (sifting, sampling)
- CT systems
- block diagrams
- system classes
- \* amplitude properties: linearity, stability, invertibility
- \* time properties: causality, memory, time-invariance

### Chap. 2

- impulse response h(t)
- convolution for CT LTI systems
- \* graphical convolution
- \* properties of convolution and LTI systems
- impulse response vs step response
- \* properties of convolution and impulse response
- LTI system properties characterized by h(t) (causality, memory, stability, invertibility)
- diffeq systems
- solutions of diffeq

The items with a \* are virtually guaranteed to be on the exam.

## Signals and Systems: Summary 2

#### **Fourier Series**

- Analysis equation:  $c_k = \frac{1}{T_0} \int_0^{T_0} x(t) e^{-jk\omega_0 t} dt, \ k = 0, \pm 1, \pm 2, \ldots$
- DC value:  $c_0 = \frac{1}{T_0} \int_0^{T_0} x(t) dt$ .
- Synthesis equation:  $x(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$
- Combined trigonometric form:  $x(t) = c_0 + \sum_{k=1}^{\infty} 2 |c_k| \cos(k\omega_0 t + \angle c_k)$ , if x(t) is real. Trigonometric form:  $x(t) = c_0 + 2 \sum_{k=1}^{\infty} A_k \cos(k\omega_0 t) B_k \sin(k\omega_0 t)$ , where  $A_k = \operatorname{real}\{c_k\}$  and  $B_k = \operatorname{Imag}(c_k)$

# Convergence properties

- Error signal  $e_N(t) = x(t) x_N(t)$  where  $x_N(t) = \sum_{k=-N}^{N} c_k e^{jk\omega_0 t}$  when  $c_k$ 's chosen according to above FS analysis
- Error signal energy  $E_N = \int_{T_0} |e_N(t)|^2 dt \to 0$  as  $N \to \infty$ , provided x(t) square integrable:  $\int_{T_0} |x(t)|^2 dt < \infty$
- ullet  $e_N(t) o 0$  as  $N o \infty$  provided Dirichlet conditions hold
- Near the discontinuity there will usually be overshoot and/or undershoot that persists even as N increases, which is called Gibbs phenomenon.

# **One-signal properties** (Fourier series transformations)

- Amplitude transformation:  $ax(t) + b \leftrightarrow \begin{cases} b + ac_0, & k = 0 \\ ac_k, & k \neq 0. \end{cases}$  Time transformation:  $x(at+b) \leftrightarrow \begin{cases} c_k e^{jk\omega_0 b}, & a > 0 \\ c_{-k} e^{jk\omega_0 b}, & a < 0. \end{cases}$  Time shift:  $x(t-t_0) \leftrightarrow c_0 e^{-jk\omega_0 t_0}$
- Time shift:  $x(t-t_0) \leftrightarrow c_k e^{-jk\omega_0 t_0}$
- Conjugation:  $[x(t)]^* \leftrightarrow c_{-k}^*$
- Complex modulation (frequency shift):  $x(t)e^{j\omega_0tN} \leftrightarrow c_{k-N}$
- Differentiation:  $y(t) = \frac{d}{dt}x(t) \leftrightarrow jk\omega_0 c_k$

## **Properties**

- If x(t) is real, then  $c_{-k} = c_k^*$ .
- Linearity (add coefficients if same period  $T_0$ )
- Multiplication  $c_k = \sum_{l=-\infty}^{\infty} a_l b_{k-l}$ . (discrete convolution) Parseval's theorem:
- Filtering: see below
- Circular convolution: skip
- Total harmonic distortion: THD =  $(1 2|c_1|^2/P) \cdot 100\%$  Magnitude spectrum:  $|c_k|$ . Phase spectrum:  $\angle c_k$
- Power of  $ce^{jk\omega_0t}$  is  $|c|^2$
- Power of  $A\cos(\omega t + \phi)$  is  $A^2/2$

• Power density spectrum: 
$$|c_k|^2 dt = \sum_{k=-\infty}^{\infty} |c_k|^2$$
  
• Power density spectrum:  $|c_k|^2$ 

# **Foundations of Filtering**

- $x(t)=e^{st} \xrightarrow{\mathrm{LTI}} y(t)=H(s)e^{st}$  Laplace transform of h(t), aka system function:  $H(s)=\int_{-\infty}^{\infty} h(t)e^{-st}\,dt$
- $x(t) = e^{j\omega t} \xrightarrow{\text{LTI}} y(t) = H(j\omega)e^{j\omega t} = |H(j\omega)|e^{j(\omega t + \angle H(j\omega))}$
- Fourier transform of h(t), aka frequency response:  $H(j\omega) = \int_{-\infty}^{\infty} h(t)e^{-j\omega t} dt = H(s)|_{s=j\omega} = |H(j\omega)|e^{j\angle H(j\omega)}$
- $x(t) = \sum_k c_k e^{j\omega_k t} \xrightarrow{\mathrm{LTI}} y(t) = \sum_k c_k H(j\omega_k) e^{j\omega_k t}$  If h(t) is real, then  $H^*(s) = H(s^*)$  and  $H(-j\omega) = H^*(j\omega)$ . (Hermitian symmetry)
- If h(t) is real,  $x(t) = \cos(\omega t + \phi) \xrightarrow{\text{LTI}} y(t) = |H(j\omega)| \cos(\omega t + \phi + \angle H(j\omega))$   $x(t) = \sum_k A_k \cos(\omega_k t + \phi_k) \rightarrow \boxed{\text{LTI } h(t)} \rightarrow y(t) = \sum_k A_k |H(j\omega_k)| \cos(\omega_k t + \phi_k + \angle H(j\omega_k))$

### **Fourier Transform**

- Fourier transform (analysis):  $F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-j\omega t} dt$ .
- Inverse Fourier transform (synthesis):  $f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$
- The FT of a signal f(t) exists (converges) if f(t) is absolutely integrable, i.e.,  $\int_{-\infty}^{\infty} |f(t)| dt < \infty$ . (more rigorously, f(t)satisfies the Dirichlet conditions)
- For periodic signals:  $x(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t} \stackrel{\mathcal{F}}{\longleftrightarrow} X(\omega) = \sum_{k=-\infty}^{\infty} c_k 2\pi \delta(\omega k\omega_0).$   $x(t) = \sum_{n=-\infty}^{\infty} g(t-nT_0) \stackrel{\mathcal{F}}{\longleftrightarrow} X(\omega) = \sum_{k=-\infty}^{\infty} \omega_0 G(k\omega_0) \delta(\omega k\omega_0)$  Energy density spectrum:  $|X(\omega)|^2$  Energy over a spectral band.  $E_{--} = \frac{1}{2\pi} \int_{-\infty}^{\infty} dt X(\omega) dt X(\omega)$

$$f(t) = f_R^e(t) + jf_I^e(t) + f_R^o(t) + jf_I^o(t)$$

## Topics covered in Chap. 3-4

### Ch. 3

- eigenfunctions of LTI systems (complex-exponential signals)
- \* Fourier series (3.3)
- Convergence of Fourier series (Gibbs phenomenon)(3.4)
- Properties of Fourier series (3.5)
- trigonometric forms of FS
- system transfer function (Laplace)
- frequency response (Fourier)
- Parseval's Relation for CT Periodic Signals(3.5.7)
- Power density spectrum
- magnitude/phase spectrum
- \* Fourier Series and LTI Systems (3.8)
- differentiation/modulation properties
- Filtering (3.9)
- \* Filters described by diffeqs (3.10)
- Rational transfer functions for diffeq systems

#### Ch. 4

- Defined FT and inverse FT by limits of FS
- Existence of FT
- \* FT of many important signals
- \* FT properties
- FT of periodic signals
- Parseval's relation (Energy density spectrum)
- \* convolution property and LTI systems
- \* Application of FT to RLC and diffeq systems

The items with a \* are virtually guaranteed to be on the exam.

Table of Fourier Series for Common Signals

Name	Waveform	$c_0$	$c_k, k \neq 0$	Comments
	x(t)		16, ,	
Sawtooth	$X_0$	$\frac{X_0}{2}$	$jrac{X_0}{2\pi k}$	
	$\downarrow x(t)$	4	υ 2πκ	
Impulse train	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\frac{X_0}{T_0}$	$rac{X_0}{T_0}$	
	$\bigwedge^{x(t)}$			
Rectangular wave	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\frac{TX_0}{T_0}$	$\frac{TX_0}{T_0}\operatorname{sinc}\left(\frac{Tk\omega_0}{2\pi}\right)$	$\frac{Tk\omega_0}{2\pi} = \frac{Tk}{T_0}$
Square wave	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	0	$-jrac{2X_0}{\pi k}$	$c_k = 0, k$ even
	$\bigwedge x(t)$			
Triangular wave sine	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\frac{X_0}{2}$	$\frac{-2X_0}{(\pi k)^2}$	$c_k = 0, k \text{ even}$

Table of Fourier transform pairs

Table of Fourier transform pairs					
f(t)	$F(\omega)$				
$\delta(t)$	1				
1	$2\pi\delta(\omega) = \delta\!\left(\frac{\omega}{2\pi}\right)$				
u(t)	$\pi  \delta(\omega) + \frac{1}{j\omega}$				
$\operatorname{sgn}(t)$	$rac{2}{j\omega}$				
$e^{i\omega_0 t}$	$2\pi\delta(\omega-\omega_0)$				
$\cos \omega_0 t$	$\pi  \delta(\omega - \omega_0) + \pi  \delta(\omega + \omega_0)$				
$\sin \omega_0 t$	$\frac{\pi}{j}\delta(\omega-\omega_0) - \frac{\pi}{j}\delta(\omega+\omega_0)$				
$e^{-bt^2}$	$\sqrt{\pi/b} \mathrm{e}^{-\omega^2/(4b)}$				
$\sum_{n=-\infty}^{\infty} \delta(t - nT_0)$	$\sum_{k=-\infty}^{\infty} \omega_0  \delta(\omega - k\omega_0)$				

f(t)	$F(\omega)$
$\frac{1}{b^2 + t^2}$	$\frac{\pi}{b} e^{-b \omega }$
$e^{-b t }$	$\frac{2b}{b^2 + \omega^2}$
$\operatorname{rect}\left(\frac{t}{T}\right)$	$T\operatorname{sinc}\left(T\frac{\omega}{2\pi}\right)$
$\mathrm{tri}(t)$	$\operatorname{sinc}^2\left(\frac{\omega}{2\pi}\right)$
$\frac{\omega_0}{2\pi}\operatorname{sinc}\left(\frac{\omega_0}{2\pi}t\right)$	$\operatorname{rect}\left(\frac{\omega}{\omega_0}\right)$
$\operatorname{sinc}^2(t)$	$\operatorname{tri}\!\left(\frac{\omega}{2\pi}\right)$
$e^{-at} u(t)$	$\frac{1}{i\omega + a}$
$\frac{t^{n-1}}{(n-1)!} e^{-at} u(t)$	$\frac{1}{(j\omega+a)^n}$
$\frac{j}{\pi t}$	$\mathrm{sgn}(\omega)$

b is a real positive number throughout. a is a real or complex number throughout, with positive real part.

Properties of the Continuous-Time Fourier Transform

Troportion	Time	Fourier	
Synthesis, Analysis	$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$	$F(\omega) = \int_{-\infty}^{\infty} f(t)e^{-j\omega t} dt$	
Eigenfunction		$H(\omega)2\pi\delta(\omega - \omega_0)$ $= H(\omega_0)2\pi\delta(\omega - \omega_0)$	
Linearity	$a_1 f_1(t) + a_2 f_2(t)$	$a_1 F_1(\omega) + a_2 F_2(\omega)$	
Time transformation	$f(at+b), \ a \neq 0$	$\frac{1}{ a }e^{j\omega b/a}F(\omega/a)$	
Time shift	f(t- au)	$F(\omega)e^{-j\omega\tau}$	
Time reversal	f(-t)	$F(-\omega)$	
Time-scaling	$f(at), a \neq 0$	$\frac{1}{ a }F\left(\frac{\omega}{a}\right)$	
Convolution	$f_1(t) * f_2(t)$	$F_1(\omega) \cdot F_2(\omega)$	
Time-domain Multiplication	$f_1(t) \cdot f_2(t)$	$\frac{1}{2\pi}F_1(\omega)*F_2(\omega)$	
Frequency shift	$f(t)e^{j\omega_0 t}$	$F(\omega - \omega_0)$	
Modulation (cosine)	$f(t)\cos(\omega_0 t)$	$\frac{F(\omega - \omega_0) + F(\omega + \omega_0)}{2}$	
Time. Differentiation	$\frac{d^n}{dt^n}f(t)$	$(j\omega)^n F(\omega)$	
Freq. Differentiation	$(-jt)^n f(t)$	$\frac{d^n}{d\omega^n}F(\omega)$	
Integration	$\int_{-\infty}^{t} f(\tau) d\tau = f(t) * u(t)$	$\frac{1}{j\omega}F(\omega) + \pi F(0)\delta(\omega)$	
Conjugation	$f^*(t)$	$F^*(-\omega)$	
Duality	F(t)	$2\pi f(-\omega)$	
Relation to Laplace	$F(\omega) = F(s) _{s=j\omega}$ , if ROC includes $j\omega$ axis		
Parseval's Theorem	$\int_{-\infty}^{\infty} f_1(t) f_2^*(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} F_1(\omega) F_2^*(\omega) d\omega$		
Parseval/Rayleigh Theorem	$E = \int_{-\infty}^{\infty}  f(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  F(\omega) ^2 d\omega$		
DC Value	$\int_{-\infty}^{\infty} f(t)  dt = F(0)$		

A function that satisfies  $f(t)=f^{*}(-t)$  is said to have **Hermitian symmetry**.

# **Tips for Exam Preparation**

- **Review quizzes.** Some practice problems are selected from previous exams. Make sure that you completely understand the answers to all problems on previous problems.
- **Study lecture slides.** Read through lecture slides and the summary notes carefully. Make sure that you fully understand all the lecture materials.
- Study homework solutions. Review your HW sets and the posted solutions on Canvas.
- Attend exam recitation classes.