

# VE216 Recitation Class 1

## Chapter 1

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May 2023

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1 Signals

2 Singularity Functions

3 System Characteristics

# Definition of Signals & Systems

- Signal is a function of time:  $x(t)$
- System is a function of time AND the input  $x(t)$ :  $F(t, x(t))$

## Examples

Amplifier applied at  $t=1$  on a singer's voice which starts at  $t=0$ .

## CHANGE OF VARIABLES!

- Folding/ Reflection/ Time-reversal  $y(t) = x(-t)$
- Time-scaling  $y(t) = x(at)$
- Time-shifting  $y(t) = x(t - t_0)$

$$y(t) = x(at - b) = x\left(\frac{t-t_0}{w}\right)$$

### Example

$$x(t) = t, t > 0$$

- $y(t) = x(-t)$
- $y(t) = x(2t)$
- $y(t) = x(t-2)$

# Amplitude-Transformation

- Amplitude-reversal  $y(t) = -x(t)$
- Amplitude-scaling  $y(t) = ax(t)$
- Amplitude-shifting  $y(t) = x(t) + b$

# Calculus

- Differentiator  $y = \frac{d}{dt}x(t)$
- Integrator  $y = \int_{-\infty}^t x(\tau) d\tau$

# Two-Signal Operations

- Sum  $y(t)=x_1(t) + x_2(t)$
- Product  $y(t)=x_1(t) \cdot x_2(t)$

# Signal Characteristics

- Period  $T$ :  $x(t+T) = x(t)$ ,  $T > 0$ , for any  $t$ 
  - ▶ Fundamental period  $T_0$ : smallest period
  - ▶ Sum of two periodic signals is periodic  $\Leftrightarrow \frac{T_1}{T_2}$  is rational
- Even/Odd Symmetry:  $x(t)=x(-t)$  /  $x(t)=-x(-t)$
- Average value:  $A = \lim_{x \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) dt$
- Energy:  $E = \int_{-\infty}^{\infty} |x(t)|^2 dt$ 
  - ▶ Energy signal:  $E < \infty$
- Average power:  $P = \lim_{x \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$ 
  - ▶ Power signal:  $E=\infty$  &  $P < \infty$  &  $P \neq 0$

## Examples

- $x(t)=\sin(t)$
- $x(t)=u(t) \cdot e^{-t+1}$



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# Unit Step Function

- $u(t) = \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases}$

Caution

EDGE DOES NOT MATTER

# Rect(angle) Function

- $\text{rect}(t) = \begin{cases} 1, & -\frac{1}{2} < t < \frac{1}{2} \\ 0, & \text{otherwise} \end{cases}$ 
  - ▶  $\text{rect}(t) = u(t + \frac{1}{2}) - u(t - \frac{1}{2})$
  - ▶  $\text{rect}(\frac{t-t_0}{T})$ : centered at  $t_0$  with width  $T$

## Examples

- $\text{rect}(\frac{t-1}{2})$
- $\text{rect}(\frac{t}{4} - \frac{3}{2})$

# Unit Impulse function

- $\delta(t)$ : zero width & infinite height
  - ▶ Sampling:  $x(t) \cdot \delta(t - t_0) = x(t_0) \cdot \delta(t - t_0)$
  - ▶ Convolution:  $x(t) * \delta(t - t_0) = \int_{-\infty}^{\infty} x(t - \tau) \cdot \delta(\tau - t_0) d\tau = x(t - t_0)$
  - ▶ Shifting:  $\int_{-\infty}^{\infty} x(t) \cdot \delta(t - t_0) dt = x(t_0)$
  - ▶  $\delta(t) = \frac{d}{dt} u(t)$ ,  $u(t) = \int_{-\infty}^t \delta(\tau) d\tau$
  - ▶ Unit Area:  $\int_{-\infty}^{\infty} \delta(t - t_0) dt = 1$ , for any  $t_0$
  - ▶ Scaling:  $\delta(at + b) = \frac{1}{|a|} \delta(t + \frac{b}{a})$ , for any  $a \neq 0$
  - ▶ Symmetry:  $\delta(t) = \delta(-t)$
  - ▶ Algebraic:  $t \cdot \delta(t) = 0$

## Examples

Evaluate the following

- $\int_{-\infty}^{\infty} \sin(t) \cdot \delta(t - \pi) dt$
- $\frac{d}{dt} [e^{-3t} \cdot u(t)]|_{t=2}$

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# Linearity

$$T[a_1x_1(t) + a_2x_2(t)] = a_1 T[x_1(t)] + a_2 T[x_2(t)]$$

## Skill

1.  $x_1(t) \rightarrow y_1(t)$  &  $x_2(t) \rightarrow y_2(t)$
2.  $a_1x_1(t) + a_2x_2(t) \rightarrow y(t)$
3.  $y(t)$  vs.  $a_1y_1(t) + a_2y_2(t)$

## Example

$$y(t) = \frac{x(t+1)}{x(t-1)}$$

# Stability

## Skill

1. Assume there exists  $M_x$  s.t.  $|x(t)| \leq M_x < \infty$
2. Substitute in  $y$  to see whether  $y$  is bounded

## Example

$$y(t) = \int_t^{t+T} x(\tau) d\tau$$

# Causality & Memory

- Causal: Depends only on present and past
- Memory: Depends only on present
  - ▶ Memoryless  $\rightarrow$  Causal

## Example

- $y = x(\cos(t + \frac{\pi}{4}))$



# Time-Invariance

## Skill

1. Find  $y(t - t_0)$  by replacing every  $t$  in  $y$  with  $t - t_0$
2. Find the output  $y_d$  when input is  $x_d = x(t - t_0)$
3.  $y(t - t_0)$  vs.  $y_d$

## Examples

- $y(t) = (t-2) \cdot x(t)$
- $y(t) = 2 \cdot x(3t)$
- $y(t) = 5 \cdot x(t-1)$