view\_frames Result Recorded at time: 89.249 world Broadcaster: /link1\_broadcaster Broadcaster: /fake\_wrench Average rate: 10000.000 Hz Average rate: 50.202 Hz Most recent transform: 89.240 ( 0.009 sec old) Most recent transform: 0.000 (89.249 sec old) Buffer length: 0.000 sec Buffer length: 4.940 sec base\_link fake\_force\_pose Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 89.233 (0.016 sec old) Buffer length: 4.940 sec shoulder\_link Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 89.233 (0.016 sec old) Buffer length: 4.940 sec upper\_arm\_link Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 89.233 (0.016 sec old) Buffer length: 4.940 sec forearm\_link Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 89.233 (0.016 sec old) Buffer length: 4.940 sec wrist\_1\_link Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 89.233 (0.016 sec old) Buffer length: 4.940 sec wrist\_2\_link Broadcaster: /robot\_state\_publisher Average rate: 50.202 Hz Most recent transform: 89.233 (0.016 sec old) Buffer length: 4.940 sec wrist\_3\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (89.249 sec old) Buffer length: 0.000 sec ee\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (89.249 sec old) Buffer length: 0.000 sec FT\_link