

Design and Analysis of Algorithms

Lecture 3—Heapsort

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September 22, 2008

Probabilistic Analysis and Randomized Algorithms

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Heapsort

- $O(n \lg n)$ worst case—like merge sort.
- Sorts in place—like insertion sort.
- Combines the best of both algorithms.

To understand heapsort, we'll cover heaps and heap operations, and then we'll take a look at priority queues.

Heap data structure

Heap as a tree:

Heap A (not garbage-collected storage) is a nearly complete binary tree.

- **Height** of node = # of edges on a longest simple path from the node down to a leaf.
- **Height** of heap = height of root = $\Theta(\lg n)$.

Heap as a array: A heap can be stored as an array A .

- Root of tree is $A[1]$.
- Parent of $A[i] = A[i/2]$.
- Left child of $A[i] = A[2i]$.
- Right child of $A[i] = A[2i + 1]$.
- Computing is fast with binary representation implementation.

Heap data structure (cont.)

Heap property:

- For max-heaps (largest element at root), *max-heap property*: for all nodes i , excluding the root, $A[\text{PARENT}(i)] \geq A[i]$.
- For min-heaps (smallest element at root), *min-heap property*: for all nodes i , excluding the root, $A[\text{PARENT}(i)] \leq A[i]$.

By induction and transitivity of \leq , the max-heap property guarantees that the maximum element of a max-heap is **at the root**. Similar argument for min-heaps.

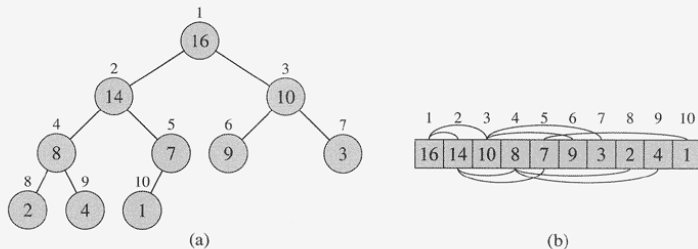


Figure 6.1 A max-heap viewed as (a) a binary tree and (b) an array. The number within the circle at each node in the tree is the value stored at that node. The number above a node is the corresponding index in the array. Above and below the array are lines showing parent-child relationships; parents are always to the left of their children. The tree has height three; the node at index 4 (with value 8) has height one.

Maintaining the heap property

MAX-HEAPIFY is important for manipulating max-heaps—to maintain the max-heap property.

- Before MAX-HEAPIFY, $A[i]$ may be smaller than its children.
- Assume left and right subtrees of i are max-heaps.
- After MAX-HEAPIFY, subtree rooted at i is a max-heap.

MAX-HEAPIFY

```
MAX-HEAPIFY( $A, i$ )
1   $l \leftarrow \text{LEFT}(i)$ 
2   $r \leftarrow \text{RIGHT}(i)$ 
3  if  $l \leq \text{heap-size}[A]$  and  $A[l] > A[i]$ 
4      then  $\text{largest} \leftarrow l$ 
5      else  $\text{largest} \leftarrow i$ 
6  if  $r \leq \text{heap-size}[A]$  and  $A[r] > A[\text{largest}]$ 
7      then  $\text{largest} \leftarrow r$ 
8  if  $\text{largest} \neq i$ 
9      then exchange  $A[i] \leftrightarrow A[\text{largest}]$ 
10     MAX-HEAPIFY( $A, \text{largest}$ )
```

The way MAX-HEAPIFY works

- Compare $A[i]$, $A[\text{LEFT}(i)]$, and $A[\text{RIGHT}(i)]$.
- If necessary, swap $A[i]$ with the larger of the two children to preserve heap property.
- Continue until subtree rooted at i is max-heap.

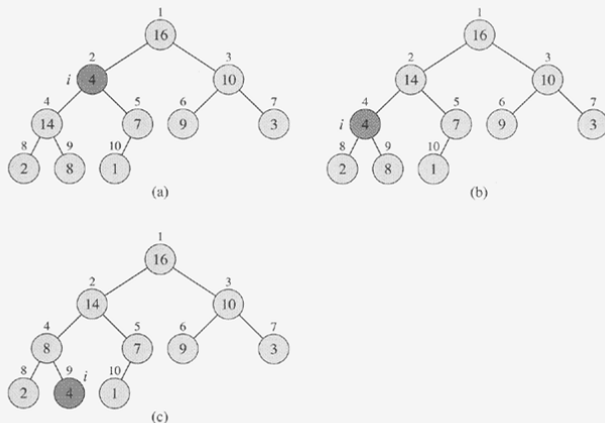


Figure 6.2 The action of MAX-HEAPIFY($A, 2$), where $\text{heap-size}[A] = 10$. (a) The initial configuration, with $A[2]$ at node $i = 2$ violating the max-heap property since it is not larger than both children. The max-heap property is restored for node 2 in (b) by exchanging $A[2]$ with $A[4]$, which destroys the max-heap property for node 4. The recursive call MAX-HEAPIFY($A, 4$) now has $i = 4$. After swapping $A[4]$ with $A[9]$, as shown in (c), node 4 is fixed up, and the recursive call MAX-HEAPIFY($A, 9$) yields no further change to the data structure.

Building a heap

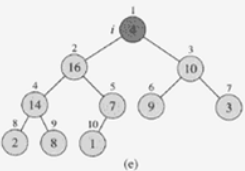
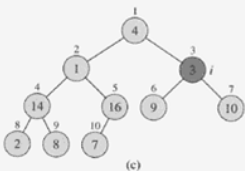
BUILD-MAX-HEAP

BUILD-MAX-HEAP(A)

```
1   $heap-size[A] \leftarrow length[A]$   
2  for  $i \leftarrow \lfloor length[A]/2 \rfloor$  downto 1  
3      do MAX-HEAPIFY( $A, i$ )
```

- **Simple bound:** $O(n)$ calls to MAX-HEAPIFY, each of which takes $O(\lg n)$ time $\Rightarrow O(n \lg n)$.

A [4 1 3 2 16 9 10 14 8 7]



The Heapsort Algorithm

- Builds a max-heap from the array.
- Starting with the root, the algorithm places the maximum element into the correct place in the array by swapping it with the last array element.
- “Discard” this last node by decreasing the heap size, and calling MAX-HEAPIFY on the new (possibly incorrectly-placed) root.
- Repeat this “discarding” process until only one node remains.

```
HEAPSORT(A)
1  BUILD-MAX-HEAP(A)
2  for  $i \leftarrow \text{length}[A]$  downto 2
3      do exchange  $A[1] \leftrightarrow A[i]$ 
4          $\text{heap-size}[A] \leftarrow \text{heap-size}[A] - 1$ 
5         MAX-HEAPIFY( $A, 1$ )
```

Analysis:

- BUILD-MAX-HEAP: $O(n)$
- for loop: $n - 1$ times
- exchange elements: $O(1)$
- MAX-HEAPIFY: $O(\lg n)$

Total time: $O(n \lg n)$.

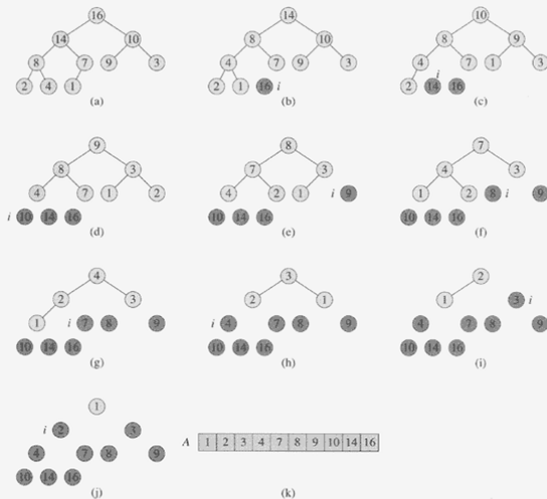


Figure 6.4 The operation of HEAPSORT. (a) The max-heap data structure just after it has been built by BUILD-MAX-HEAP. (b)–(j) The max-heap just after each call of MAX-HEAPIFY in line 5. The value of i at that time is shown. Only lightly shaded nodes remain in the heap. (k) The resulting sorted array A .

Priority queue

- Maintains a dynamic set S of elements.
- Each set element has a key—an associated value.
- Max-priority queue supports dynamic-set operations:
 - $\text{INSERT}(S, x)$: inserts element x into set S .
 - $\text{MAXIMUM}(S)$: returns element of S with largest key.
 - $\text{EXTRACT-MAX}(S)$: removes and returns element of S with largest key.
 - $\text{INCREASE-KEY}(S, x, k)$: increases value of element x 's key to k . Assume $k \geq x$'s current key value.
 - Example max-priority queue application: **schedule jobs on shared computer.**