

# Automated Discovery of Temperature Dependent Structural Change

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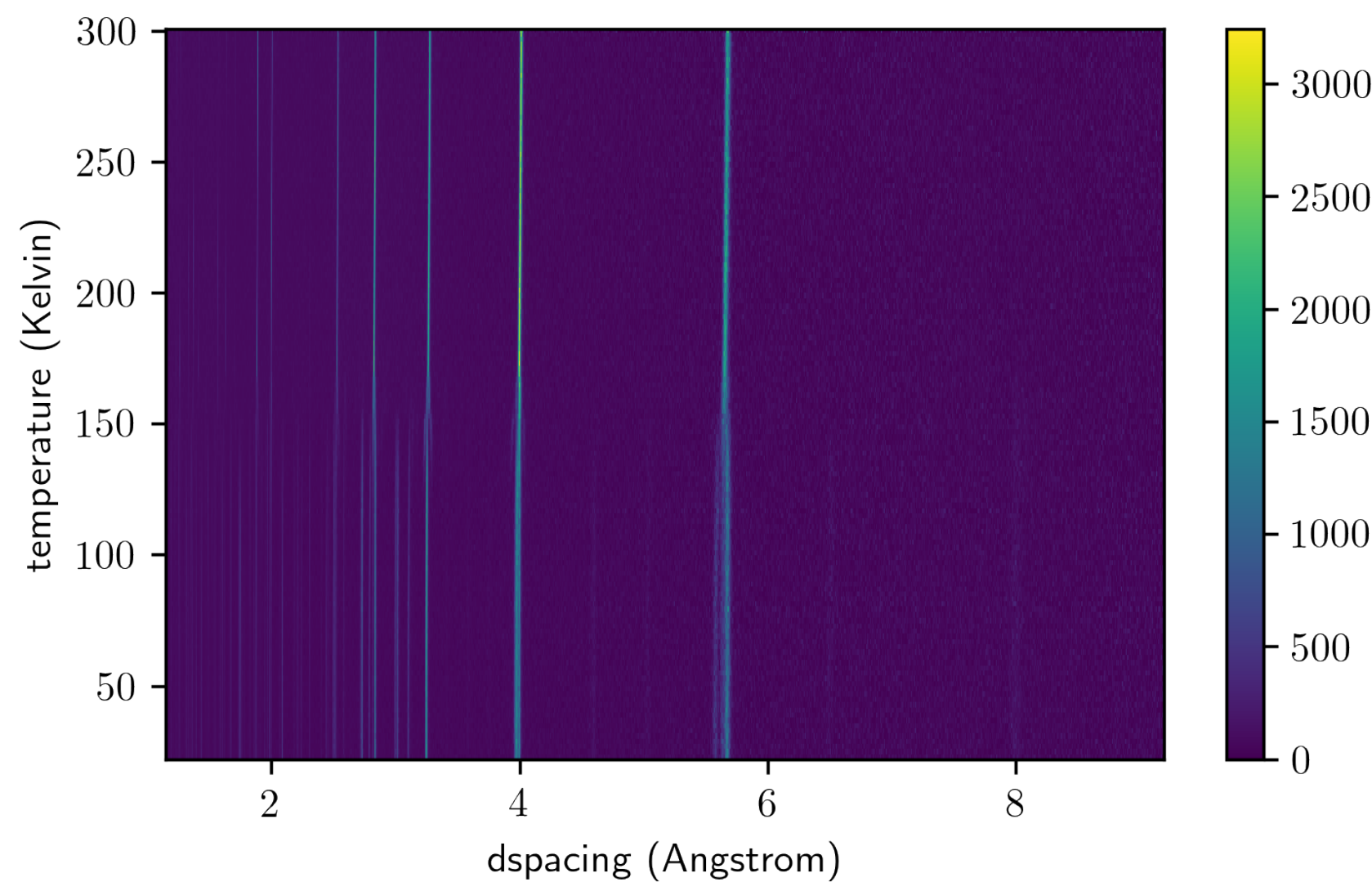
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Jupyter notebook available @ <https://github.com/yaohualiu/NPD>



Image credit:  
David Delano

## Introduction



2D Time-of-Flight neutron powder diffraction data:  $I = I(d, T)$

- Parametric experiments as a function of temperature.
- No error bars.

Four tasks:

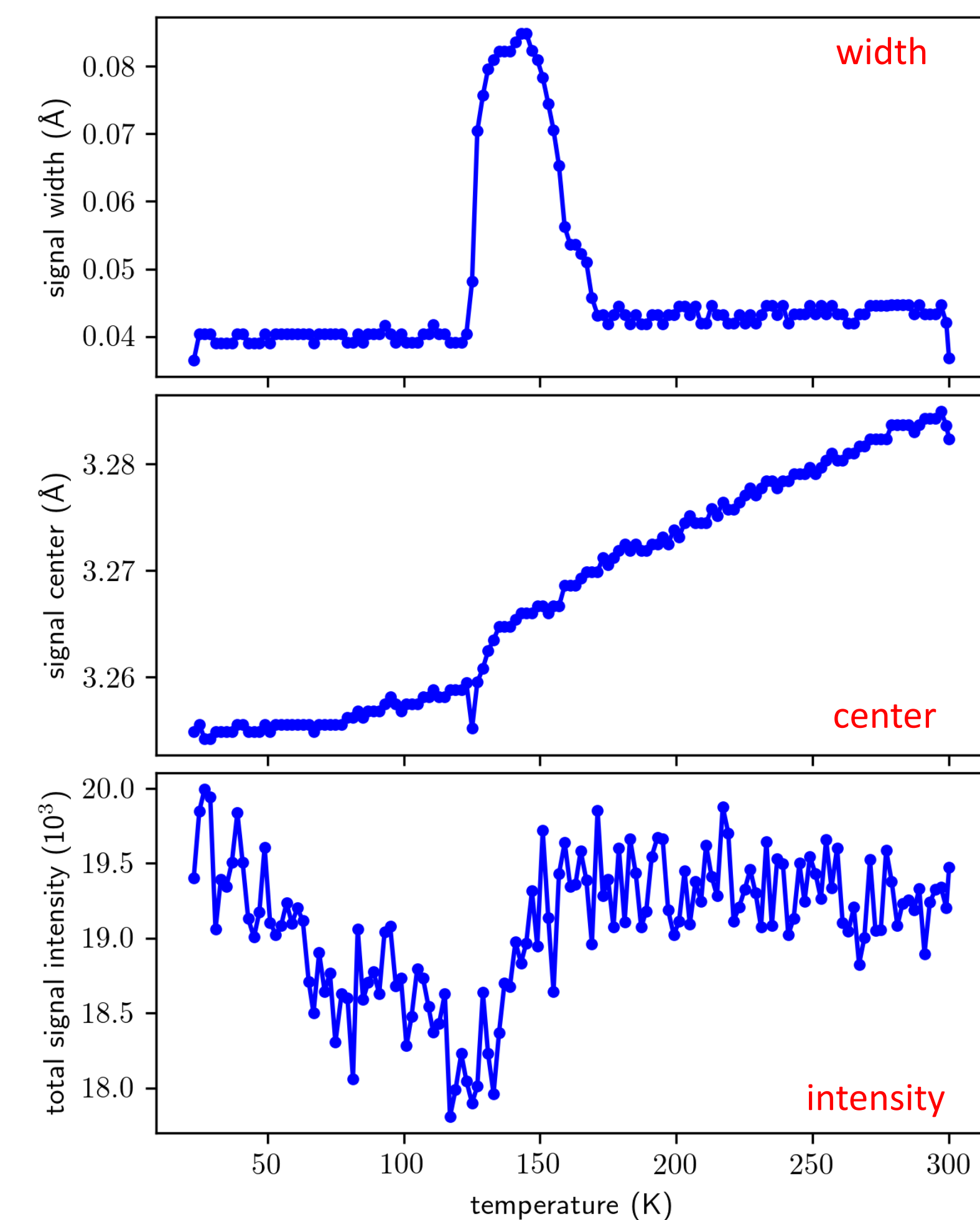
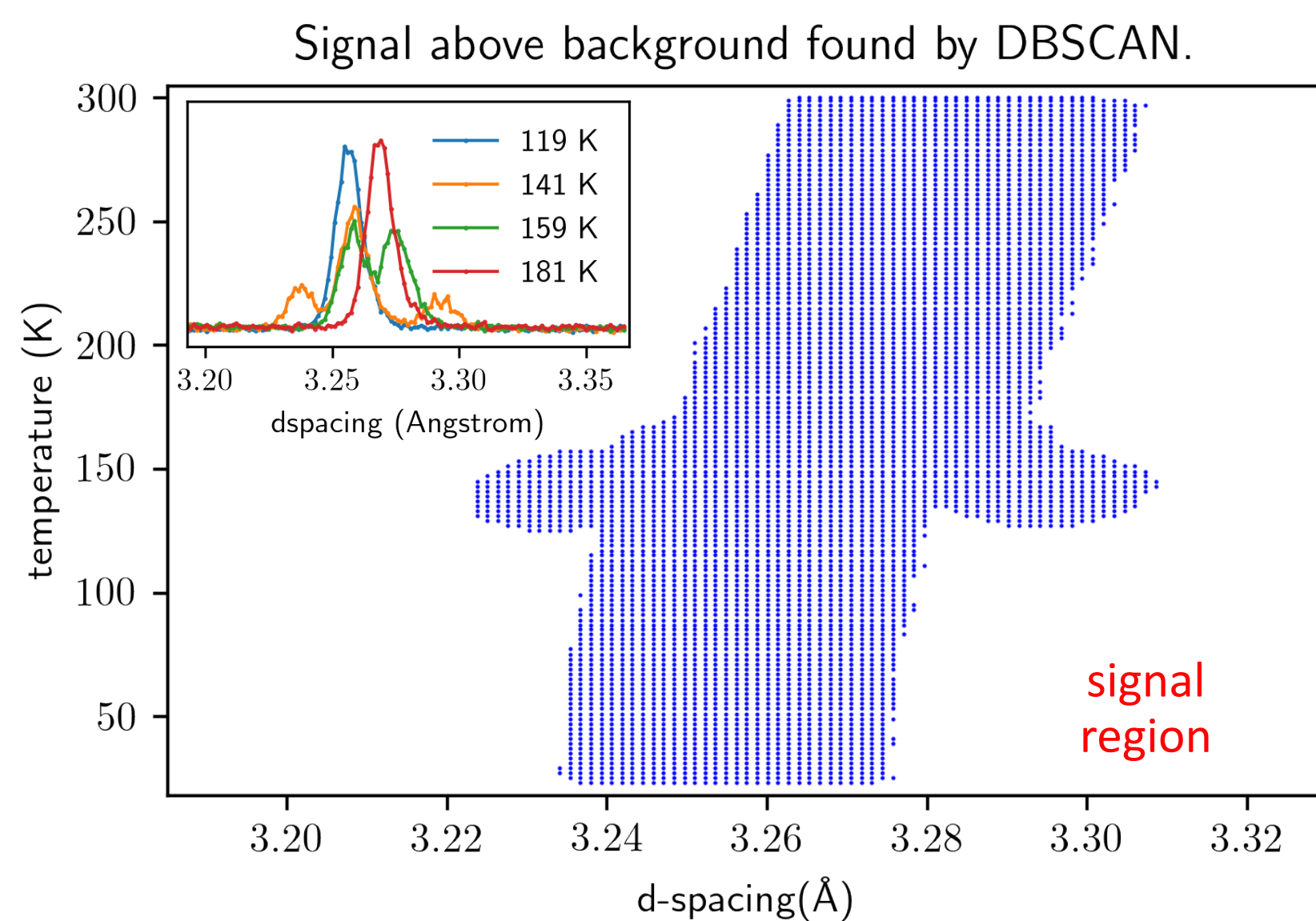
- Find structural transition temperature(s).
- Determine signal characteristics b/w 3.22 and 3.32 Å as a function of T.
- Resolve information for all peaks at a given T.
- Report a phase transition likelihood b/w two adjacent T's. Peak tables for all T's.

**Key philosophy: Emphasizing the global information.**

Key algorithms:

- Density-based spatial clustering of applications with noise (DBSCAN).
- Hierarchical peak finding approach using Wavelet Transformation and Le Bail fitting.

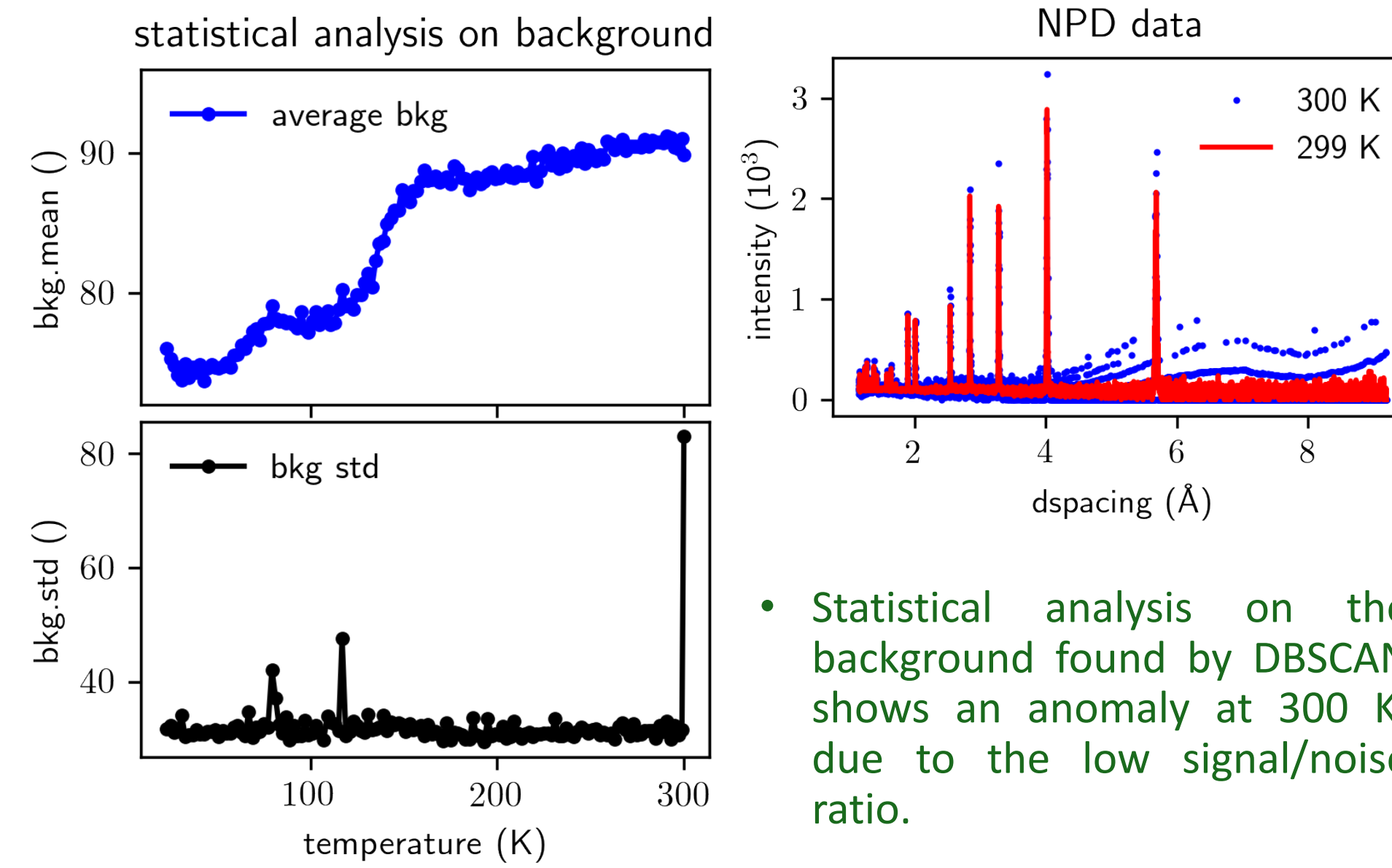
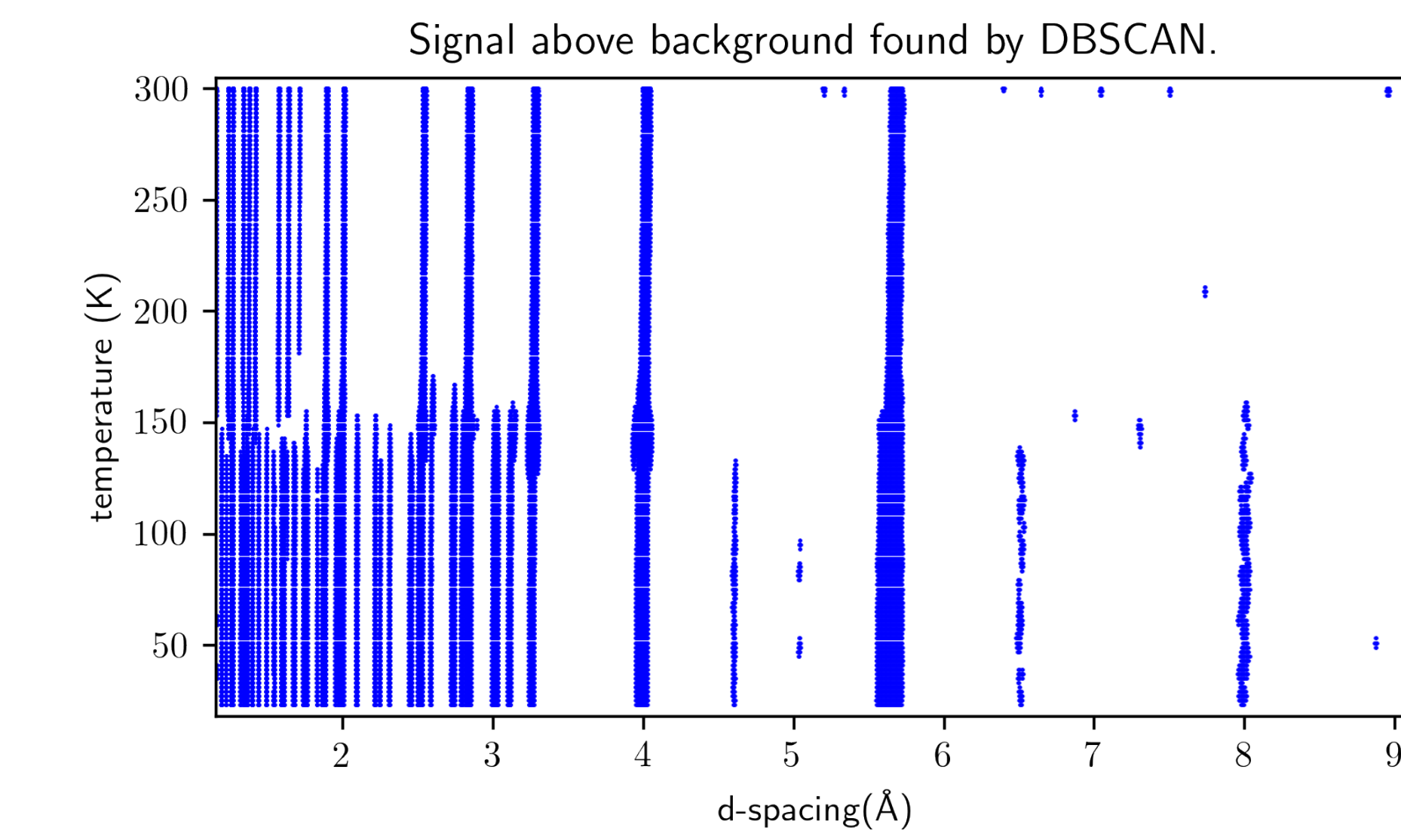
## T2: Signal between 3.22 and 3.32 Å as a function of T



DBSCAN is used for finding the signal region.

- Identify the background region and signal above background region via DBSCAN.
- Determine the signal center and width directly from the signal region.
- Parameterize the background level using a polynomial function of temperature and d-spacing.
- Remove the background from the raw data to calculate the signal intensity.

## T0: Data characteristics

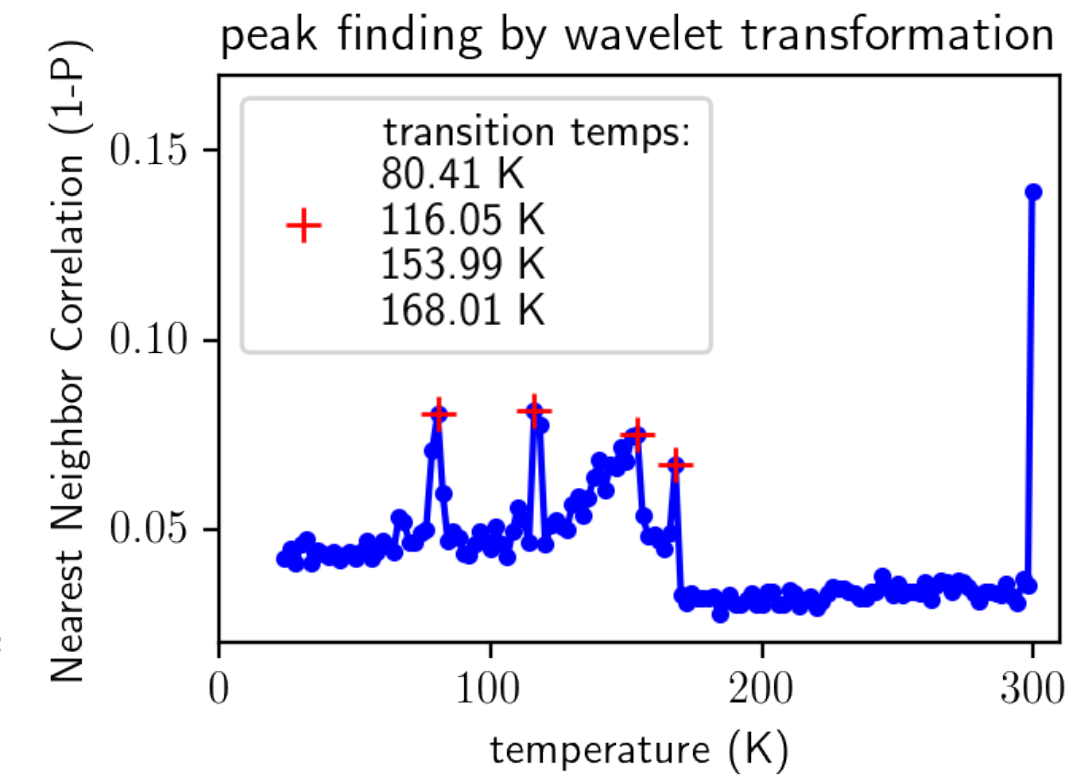


- Statistical analysis on the background found by DBSCAN shows an anomaly at 300 K, due to the low signal/noise ratio.

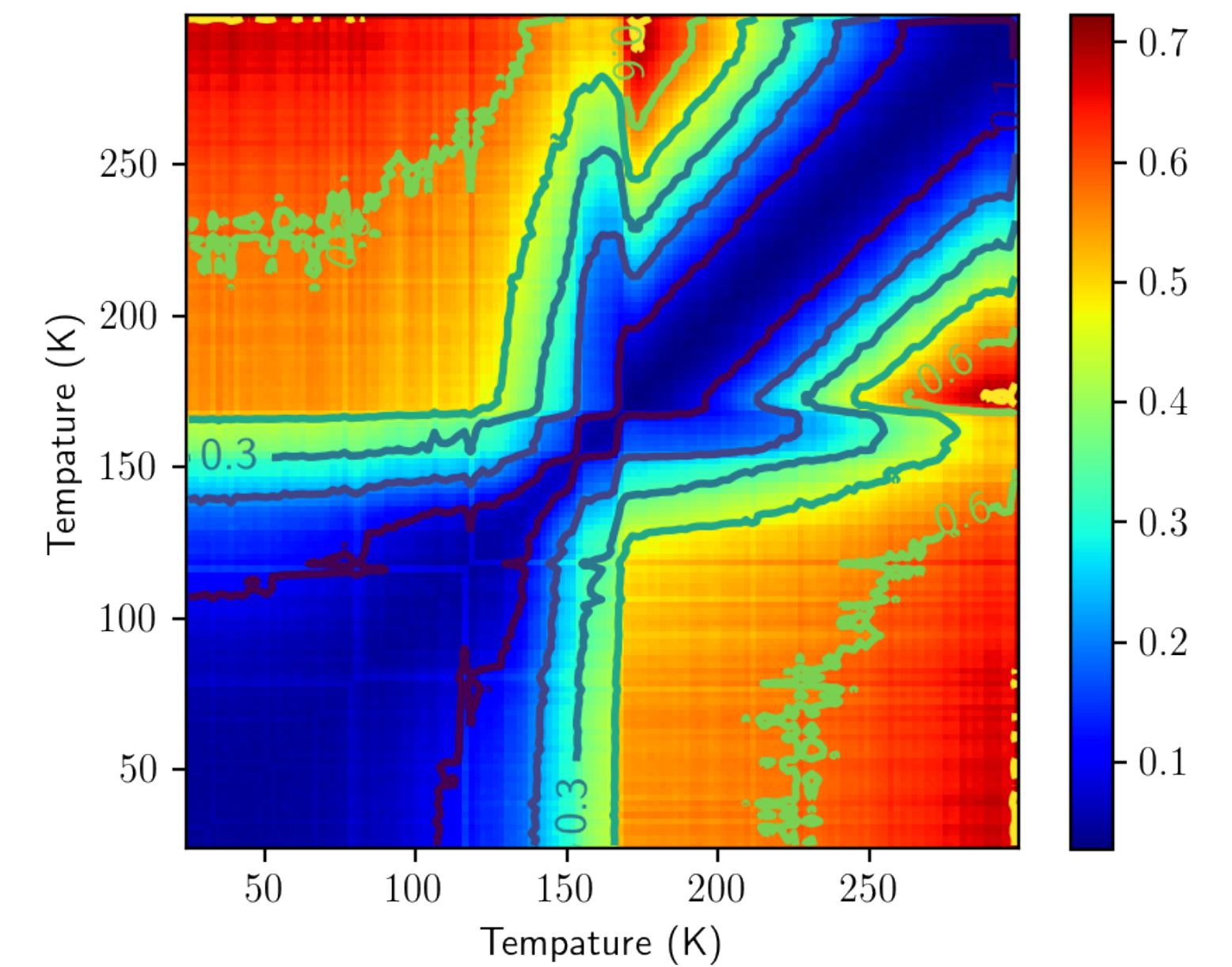
## T1: Structural transition temperature

- Represent NPD data at each temperature is represented as a vector  $x = (x_1, x_2, \dots, x_n)$ .
- Calculate Pearson correlation coefficient b/w two temperatures,

$$\rho = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}$$

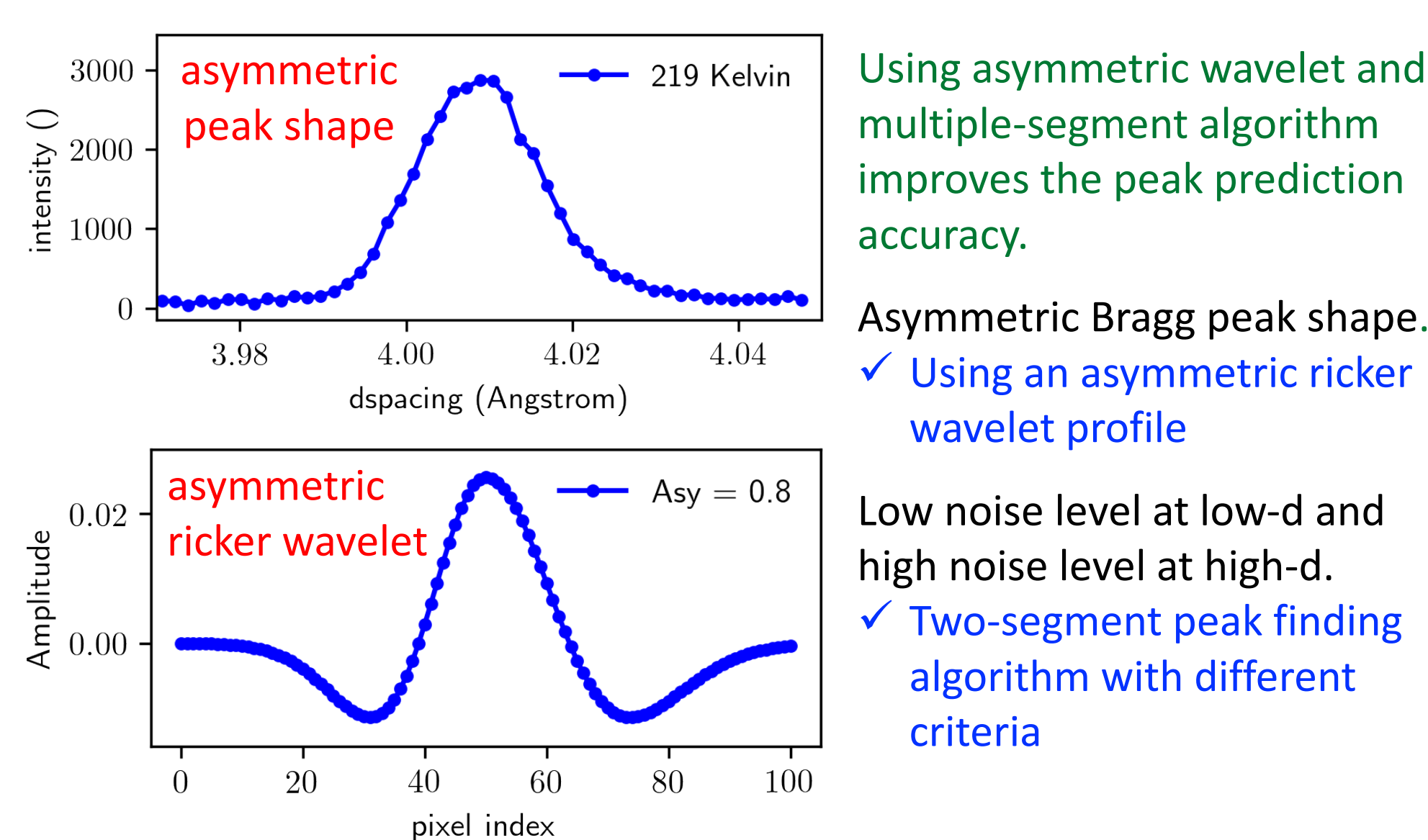


(1 -  $P_{corr}$ ) map



Visualization: abrupt color changes at potential phase transition temperatures.

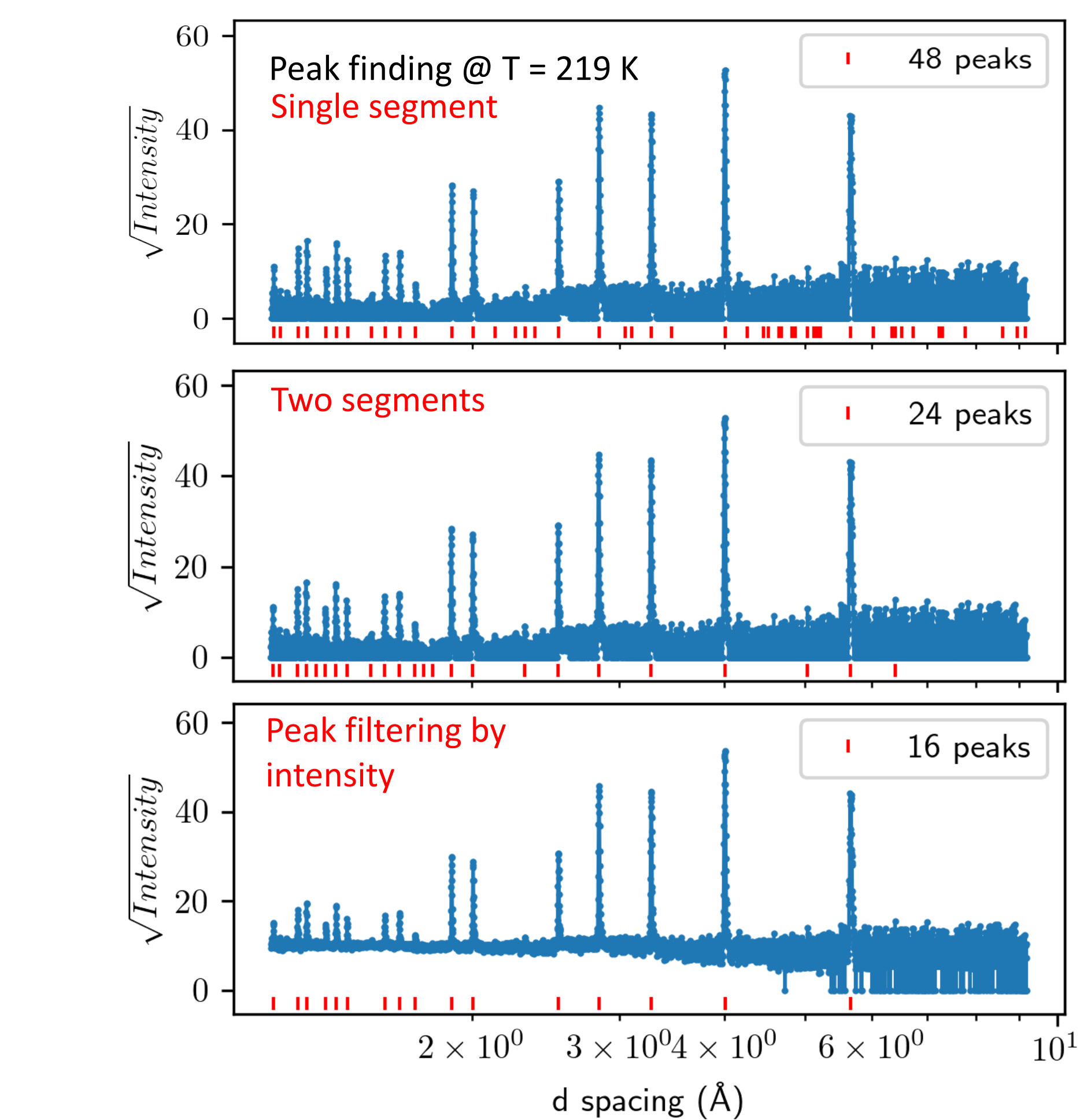
## T3: Intensity, center & width for all peaks at a given T



Using asymmetric wavelet and multiple-segment algorithm improves the peak prediction accuracy.

Asymmetric Bragg peak shape.  
✓ Using an asymmetric ricker wavelet profile

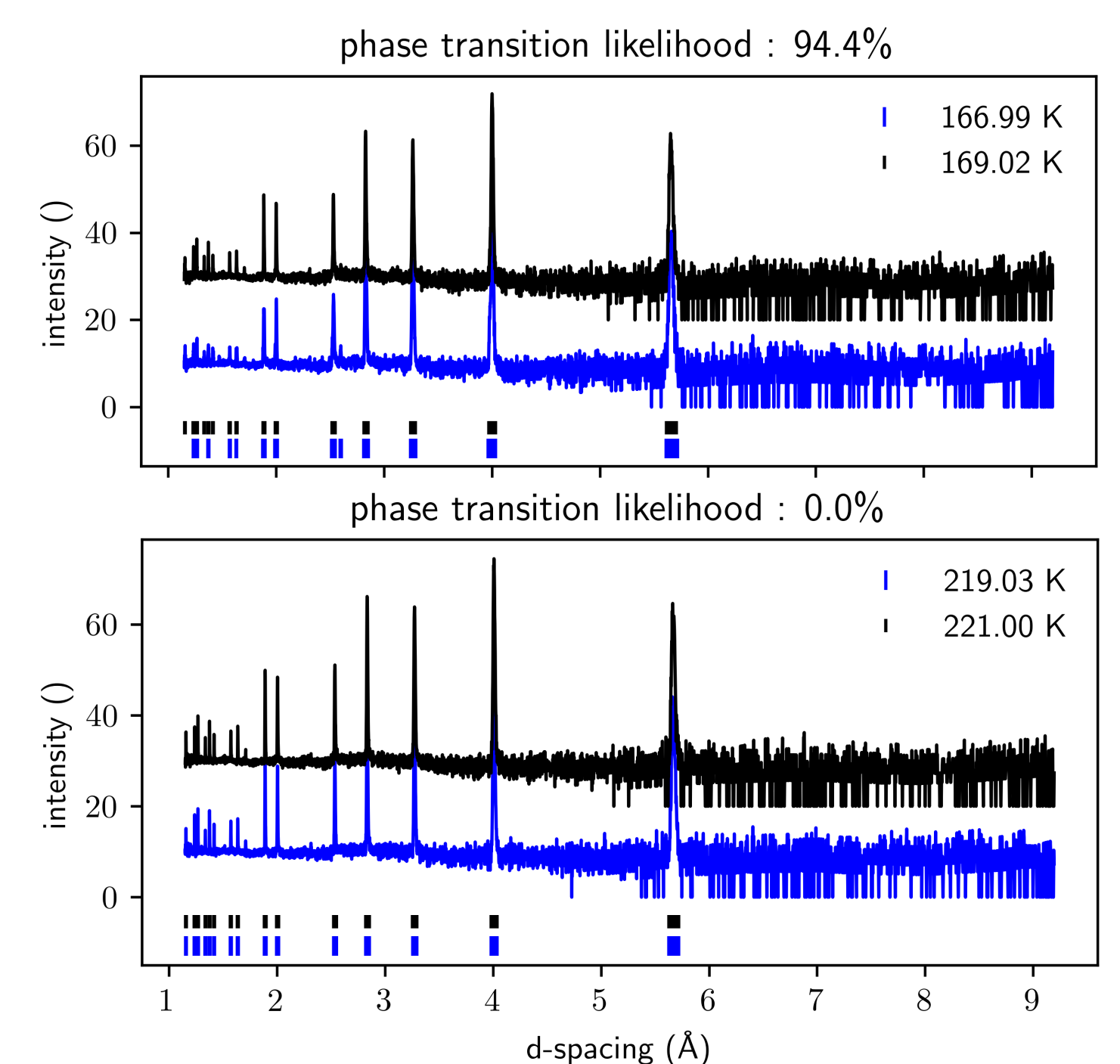
Low noise level at low-d and high noise level at high-d.  
✓ Two-segment peak finding algorithm with different criteria



Le Bail fitting is used to generate the peak table.

- Background is parameterized,  $bkg = bkg(d, T)$ , and then removed.
- Peak width is parameterized as a polynomial function of d-spacing.
- Peak positions from the wavelet transformation are tightly constrained.
- Peak amplitudes are loosely constrained.
- Low intensity peaks ( $< 1.5 * bkg.std(T)$ ) are removed from the initial peak list.

## T4 (a): Phase transition likelihood b/w two adjacent T's



If limited information was available, e.g. only two datasets:

- Find regions of signal above background via DBSCAN.
- Calculate shared and unshared signal bins b/w two temperatures.
  - More shared signal bin  $\rightarrow$  lower likelihood
  - More unshared signal bin  $\rightarrow$  higher likelihood

## T4 (b): Peak tables for all T's

