Memory Management

Memory Addressing

```
* main()
```

```
{ static int a, b, c;
  a = 5; b = 3; c = a + b;
  printf ("addresses: %d, %d, %d\n", &a, &b, &c);
}
```

Question: Run two instances of the same program, will the addresses of a be the same?

System Operations

- Compiler uses offset for addressing
 - ➤ Need to do this because program may reside in different memory locations even during execution
- Linker combines all object files into an executable unifies the address offset
- ❖ Loader loads executable into memory, the base address is determined after loading

Memory Allocation

- ❖ Important elements in memory allocation
- Allocation Policy
 - ➤ Where in the memory to allocate a program
- Relocation
 - ➤ Allow the program being swapped out and swapped back in at a different memory location
- Addressing
 - ➤ Has to be offset, otherwise, the instructions has to be changed continuously
 - ➤ How to compute physical addresses from offsets
 - Computation needs to be very efficient

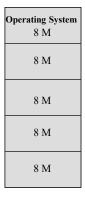
Memory Allocation

- ❖ Important elements in memory allocation
- Protection
 - ➤ A process should only access its designated memory locations
- Performance Metrics of memory allocation algorithms
 - > Fragmentation
 - External fragmentation
 - Internal fragmentation
 - ➤ Allocation time
 - Time for executing the allocation algorithm

Allocation Policies

- Fixed Partitioning
- Dynamic Partitioning
- Simple Paging
- ❖ Simple Segmentation
- ❖ Virtual Memory and Demand Paging
- ❖ Virtual Memory and Demand Segmentation

Fixed Partitioning



Equal-sized partitioning

Operating System 8 M	
2 M	
4 M	
6 M	
8 M	Common sizes: 2^x
8 M	
12 M	

Unequal-sized partitioning

Fixed Partitioning

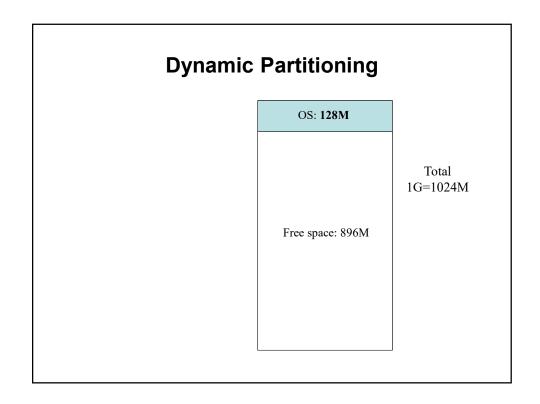
- ❖ Partitions are set up at system initialization time
 - > Programs are still allocated dynamically
 - ➤ A program can only be in one partition
- **❖** Advantages
 - **>** Simple
- Disadvantages
 - ➤ Internal fragmentation
 - ➤ Cannot handle processes larger than the biggest partition but smaller than the entire memory

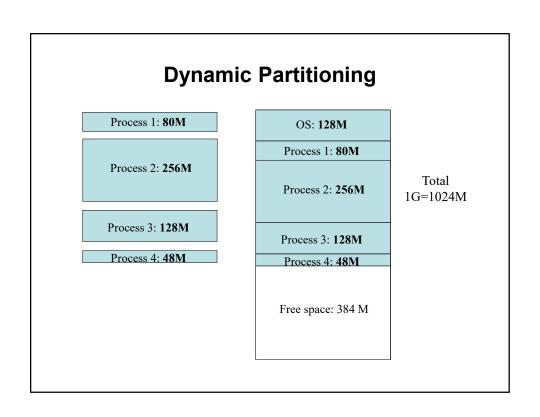
Fixed Partitioning

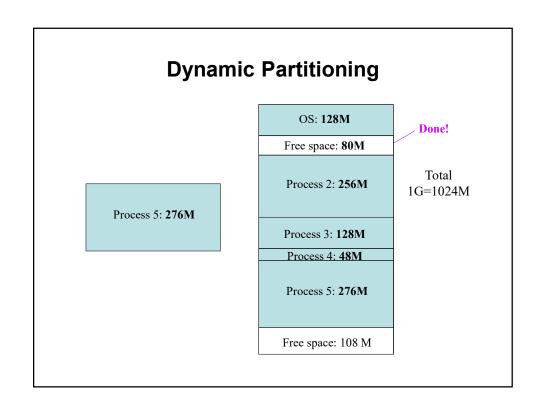
- Allocation policy
 - ➤ For equal-sized partitioning → just allocate any available partition
 - Very simple
 - Small process ⇒ big fragmentation, Big process ⇒ No slot can fit
 - ➤ For unequal-sized partitioning →
 - A job goes to the best-fitted partition that is currently available
 - Possible that the best-fit partition is in use
 - Internal fragmentation
 - Each job wait for the best-fitted partition
 - Less fragmentation
 - If many jobs fit one particular partition, these jobs have to wait even though there are many other available partitions

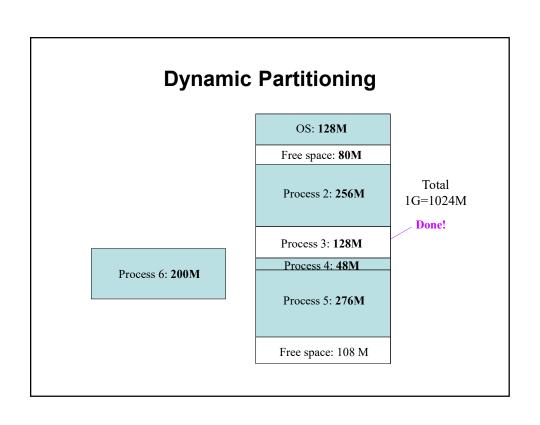
Dynamic Partitioning

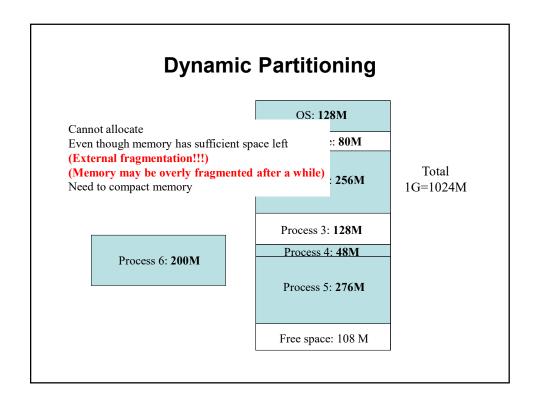
- ❖ Fixed partitioning is not good
 - ➤ Internal fragmentation
 - ➤ Cannot handle large processes
- Dynamic partitioning
 - ➤ Memory is not partitioned in the beginning
 - ➤ One whole partition at initialization time
- Allocation policy
 - ➤ Allocation size = Process size
 - ➤ No internal fragmentation





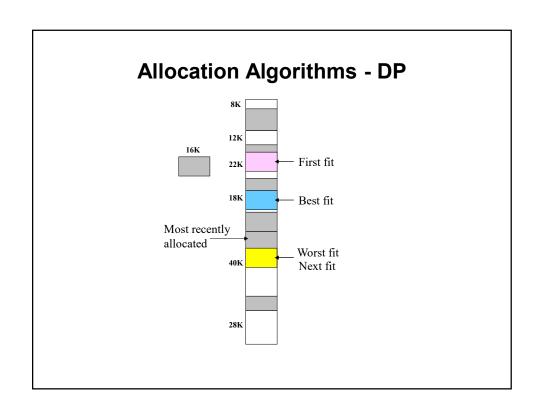


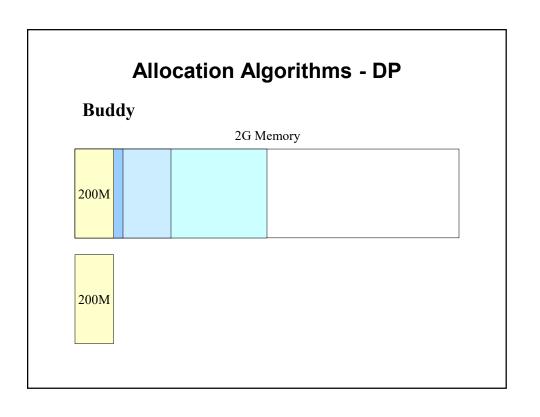


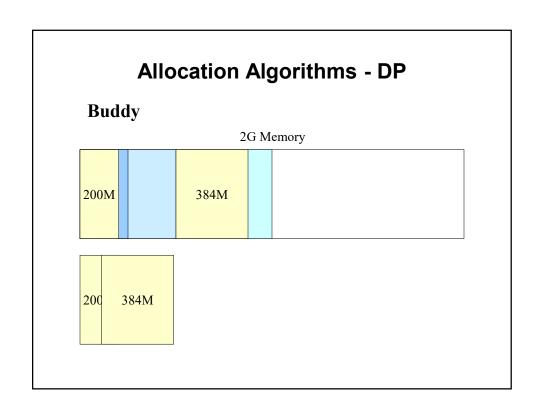


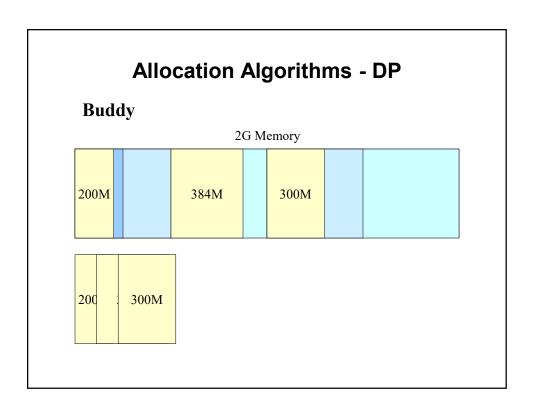
Dynamic Partitioning

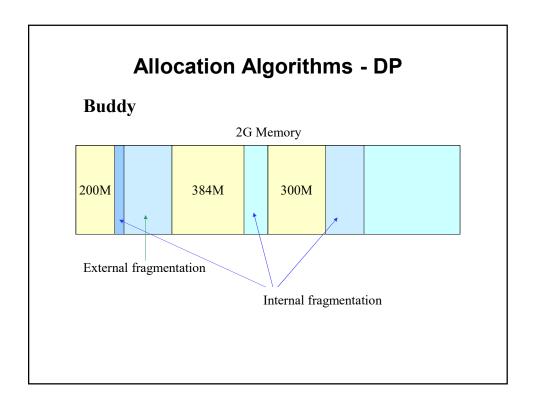
- **❖** Allocation Algorithms
 - Where should a new process be allocated?
 - > First fit
 - Find first slot which is large enough for the new process
 - > Best fit
 - Select the slot with size closest to the requested size
 - > Worst fit
 - Select the slot with the largest size
 - Next fit
 - Start to search from the most recently allocated slot
 - Find the first fitting slot
 - ➤ Buddy Scheme
 - Split a partition into sizes of 2^x and allocate
 - Merge partitions (if possible) after a process leaves









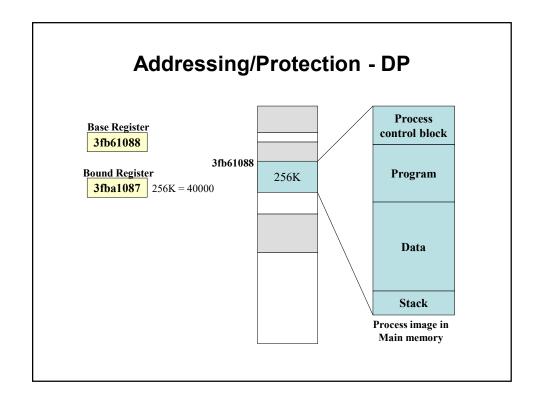


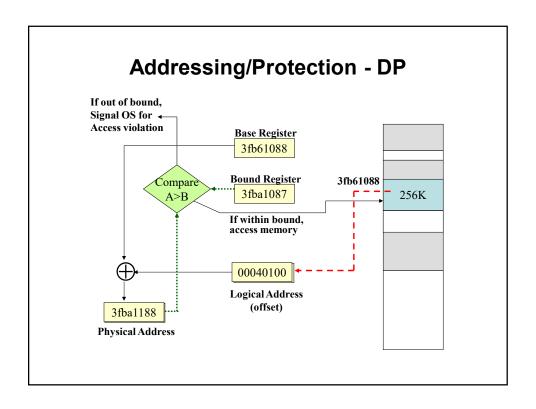
Allocation Algorithms - DP

- Buddy scheme
 - ➤ Has both internal and external fragmentation problems
 - Easy table look up (maintain a tree)
- First, best, worst, next fit
 - ➤ All has external fragmentation problem
 - > Performance studies show they perform similarly
 - ➤ Need to keep a free list
 - Best fit and worst fit: list sorted in the order of free partition size
 - First fit and next fit: list sorted in the order of starting address
 - \triangleright When a job leaves \rightarrow return to free list \rightarrow merge free slots
 - Memory manager checks the neighboring slots
 - Found a pair of free neighboring partitions ⇒ Merge them
 - If free list is sorted by size ⇒ Hard to locate neighbors

Addressing/Protection - DP

- **❖** Addressing
 - > physical address = base address + relative address
 - (relative address, offset, logical address) are the same
 - > (physical address, absolute address) are the same
 - > Use a base address register to store the base address
- Protection
 - > physical address limit = base address + program size
 - > Use a bound register to protect against access violations





Simple Paging

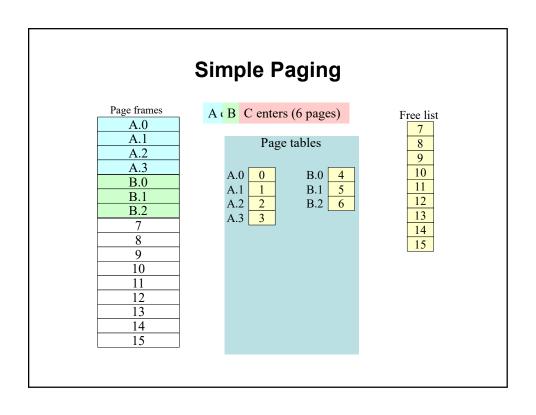
- ❖ Dynamic partitioning
 - ➤ Major fragmentation problem
 - Have sufficient space but do not have sufficient consecutive space
 - ➤ Better solution
 - Let a program to occupy non-consecutive regions
 - Use a table to keep track of the regions used for a program
 - But table may be too long
 - Use page as a unit → reduce number of table entries
- ⇒ Paging scheme
 - ➤ Memory is divided into fixed-size blocks
 - \triangleright Physical memory block \rightarrow page frames
 - ➤ Process address space block → pages

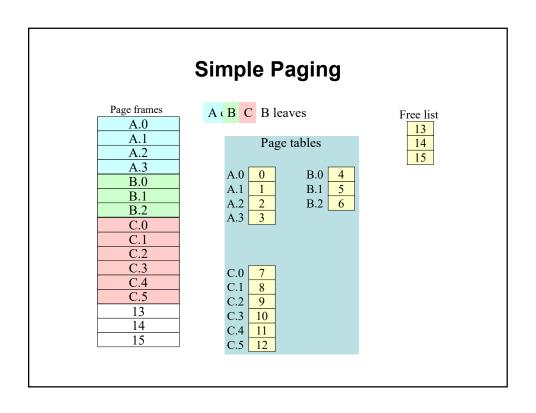
Simple Paging

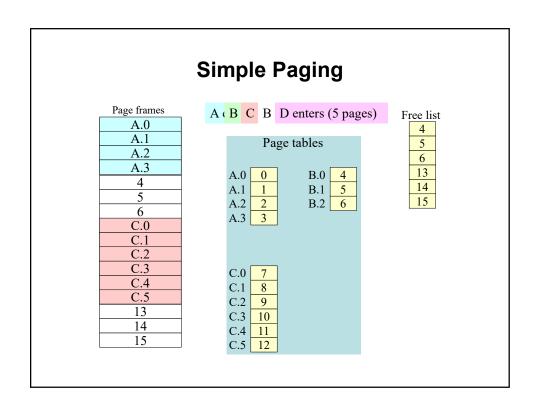
- ❖ OS maintains a list of free frames
- ❖ Each process maintains a page table in PCB
- Process does not need to have contiguous frames
- ❖ Page size
 - > Typically, 1KB to 8KB
 - ➤ Too big → internal fragmentation
 - \triangleright Too small \rightarrow large page table
- Performance
 - ➤ little internal fragmentation (in the last page)
 - > Table space and table maintenance overhead

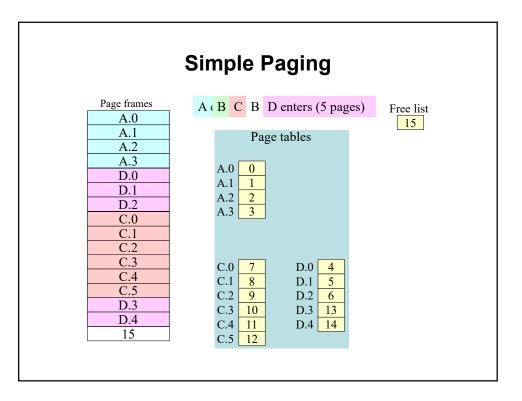
Simple Paging				
Page frames 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	A enters (4 pages) Page tables	Free list 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15		

	ple Paging	Oiii	
Free lis 4 5 6 7 8 9 10 11 12 13 14	Page tables 0 0 1 1 2 2 3 3		A.0 A.1 A.2 A.3 4 5 6 7 8 9 10 11 12 13 14 15



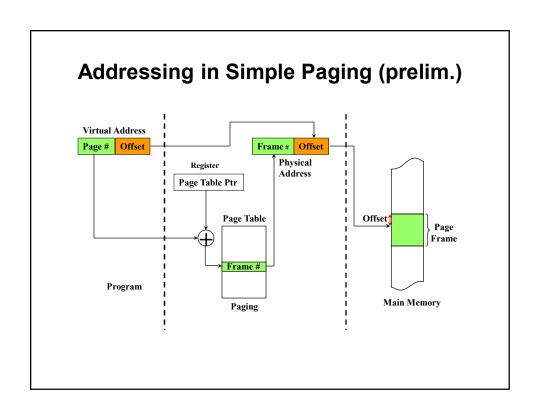






- ❖ Address computation?
 - \triangleright Logical address x
 - \triangleright Page #: p = x div PS
 - PS: page size
 - \triangleright Page offset: $t = x \mod PS$
 - > Frame # in physical memory: f
 - Need a mapping table, maps p to f
 - \triangleright Memory address = f * PS + t
 - $(x \operatorname{div} PS) * PS + (x \operatorname{mod} PS)$
 - ightharpoonup If $PS = 2^n$?
 - *n* bits for offset and beyond *n* bits for page number

- ❖ How many bits are required to address the memory
 - ≥ 1KB memory = 2^{10} Bytes \rightarrow 10 bits
 - ≥ 1GB memory = 2^{30} Bytes \rightarrow 30 bits
 - \triangleright 32 bits → can address 2^{32} Bytes = 4GB
- ❖ Page size and number of pages
 - ➤ 1GB memory, 8KB per page ⇒ 128 K pages
- ❖ Address (offset) within a page
 - \triangleright 8KB per page \Rightarrow 13 bits to address the offset
- Address for pages
 - $ightharpoonup 128 \text{ K page} \Rightarrow 17 \text{ bits}$



- **❖** Addressing
 - ➤ 1GB memory, 8KB per page ⇒ 128K pages



- > 000000000000001010000000101011
 - Logical address in hexdecimal: 0x0001402b
 - Page number = 1010 = 10
 - Page offset = 101011 = 43
- > 00<mark>000000000000101010000000101011</mark>
 - Physical address in hexdecimal: 0x0002a02b
 - Frame number = 21 = 10101

P.0 7 P.1 40 P.2 1

- ...
- P.9 15 P.10 21

Addressing in Simple Paging (prelim.)

- Addressing
 - ➤ 64MB memory, 1KB per page ⇒ 64K pages



- > 000000<mark>000000000000001010111010111</mark>
 - Logical address in hexdecimal: 0x00000aeb
 - Page number = 10 = 2
 - Page offset = 1011101011
- > 000000<mark>0000000000000011011101011</mark>
 - Physical address in hexdecimal: 0x000006eb
 - Frame number = 1

P.0	7
P.1	40
P.2	1

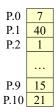
...

P.9 15 P.10 21

- **❖** Addressing
 - ightharpoonup 256MB memory, 4KB per page \Rightarrow 64K pages



- > 0000<mark>0000000000010010<mark>101011101011</mark></mark>
 - Logical address in hexdecimal: 0x00012aeb
 - Page number = 10010 = 18
 - Exceed page table → access violation



Readings

❖ Section 7.1-7.3