

Review

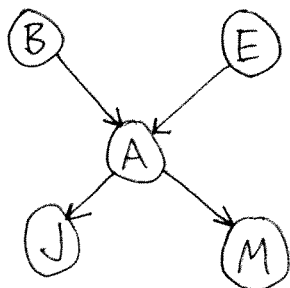
B = burglar

E = earthquake

A = alarm

J = John Calls

M = Mary Calls



* Belief Network (BN)
= DAG + CPTs

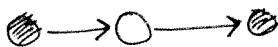
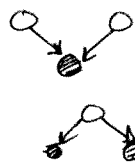
* Conditional Independence

$$\begin{aligned}
 P(X_1, X_2, \dots, X_n) &= P(X_1) P(X_2 | X_1) \dots P(X_n | X_1, \dots, X_{n-1}) \quad \text{product rule} \\
 &= \prod_{i=1}^n P(X_i | X_1, X_2, \dots, X_{i-1}) = \prod_{i=1}^n P(X_i | \text{pa}(X_i))
 \end{aligned}$$

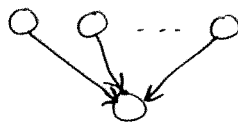
↑ parents of X_i

* Types of Reasoning

- 1) competing explanations of observed event
- 2) multiple events with common explanation
- 3) intervening events

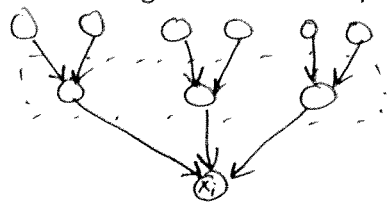
* Representing CPTs $P(X_i | \text{pa}(X_i))$

- lookup table
- logical AND, OR operations
- noisy OR



Conditional Independence

- A node is conditionally independent of its non-parent ancestors given its parents.



$$P(x_i | pa(x_i)) = P(x_i | x_1, x_2, \dots, x_{i-1})$$

- * More generally:

Let X, Y, E refer to sets of nodes.

When is X conditionally independent of Y given evidence E ?

When is $P(X|E, Y) = P(X|E)$?

$$P(X, Y|E) = P(X|E) P(Y|E)?$$

Above is a special case: $X = \{x_i\}$, $E = \{pa(x_i)\}$,
 $Y = \{x_1, x_2, \dots, x_{i-1}\} - pa(x_i)$

- * d-separation

"direction-dependent" separation

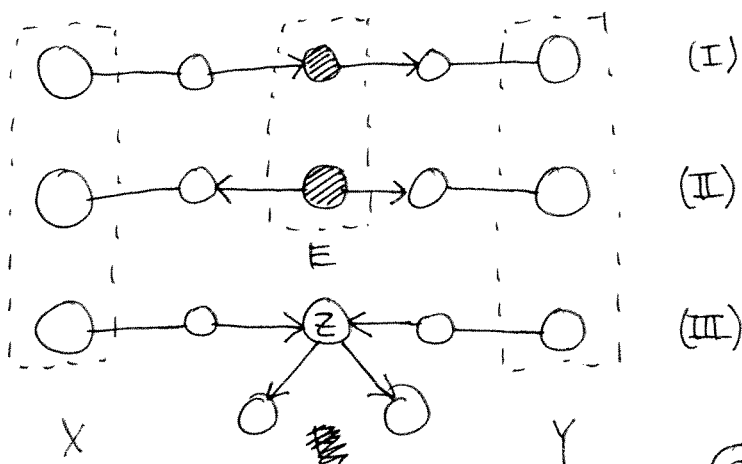
Relates conditional independence to graph theoretic properties.


- * $P(X, Y|E) = P(X|E) P(Y|E)$ if and only if every undirected path from a node in X to a node in Y is "d-separated" by E .

- * Definition: a path π is d-separated if there exists a node $z \in \pi$ for which one of 3 conditions hold:

(I) $z \in E$ with $\rightarrow z \rightarrow$
 is an "intervening" event

(II) $z \in E$ with $\leftarrow z \rightarrow$
 is a common explanation

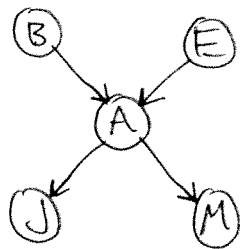


(III) $z \notin E, \text{desc}(z) \notin E$, with 
no observed common effects

* Proof that d-separation \Leftrightarrow conditional independence is difficult, beyond course.

* Efficient algorithms exist for tests of d-separation

* Alarm BN Example



1) $P(B|A, M) \stackrel{?}{=} P(B|A)$ true

alarm is an intervening event

2) $P(J, M|A) \stackrel{?}{=} P(J|A)P(M|A)$ true

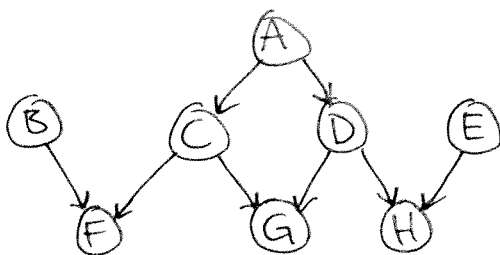
alarm is common explanation of J, M

3) $P(B, E) \stackrel{?}{=} P(B)P(E)$ true, condition III

$P(B, E|J) \stackrel{?}{=} P(B|J)P(E|J)$ false

"explaining away"

* Loopy BN Example



statement

true or false?

$P(D|H) = P(D|E, H)$

false (case III)

$P(F, H|A) = P(F|A)P(H|A)$

true

top path ok by (II)

$P(F, G, H|A) = P(F|A)P(G|A)P(H|A)$

false

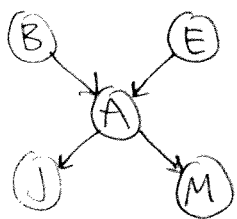
zigzag path ok by (III)

$P(G|A) \neq P(G|A, F, H)$

$\hookrightarrow = P(F|A)P(H|A, F)P(G|A, F, H)$

by product rule

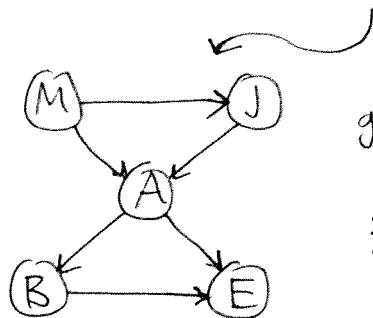
Ex: node ordering



* What is BN with node ordering $\{M, J, A, B, E\}$?

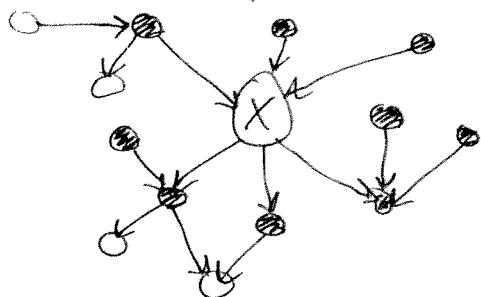
$$P(M, J, A, B, E) = P(M) P(J|M) P(A|J, M) P(B|J, M, A) \\ \times P(E|M, J, A, B) \quad \text{product rule}$$

$$= P(M) P(J|M) P(A|J, M) P(B|A) P(E|A, B)$$



graph based on
node ordering
 $\{M, J, A, B, E\}$

Def: Markov Blanket B_X of individual node X consists of parents of X , children of X , and parents of children of X (not including X).



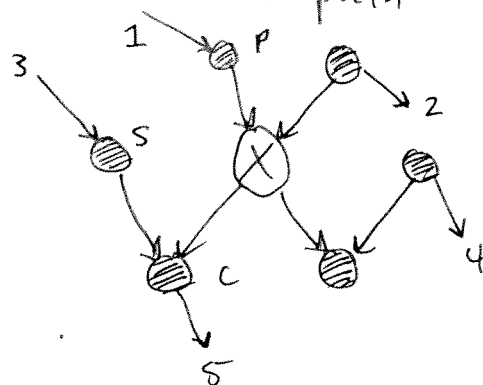
Thm: A node X is conditionally independent of all nodes outside B_X given nodes inside B_X :

$$P(X|B_X, Y) = P(X|B_X) \text{ where } Y \notin \{B_X, X\}$$

Proof: For any node $Y \notin \{X, B_X\}$, the undirected path from Y to X must pass through B_X .

There are five cases to consider:

- 1) from parent of parent of X
(satisfies case I)
- 2) from child of parent P of node X
(satisfies case II)
- 3) from parent of spouse S of node X
(satisfies case I)



4) from child of spouse S of node X
(satisfies case II)

5) from child of child C of node X
(satisfies case I)

All paths are "d-separated" from Y to X ,
hence $P(X|B_X, Y) = P(X|B_X)$