

# Advanced Data Structures and Algorithm Analysis

丁尧相  
浙江大学

Fall & Winter 2025  
Lecture 5

# Divide and Conquer

- Introduction
- Closest pair of points
- Solving recurrent equations
- Multiplication problems
- Take-home messages

# Divide and Conquer

- **Introduction**
- Closest pair of points
- Solving recurrent equations
- Multiplication problems
- Take-home messages

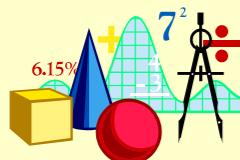
**Recursively:**

**Divide** the problem into a number of sub-problems

**Conquer** the sub-problems by solving them recursively

**Combine** the solutions to the sub-problems into the solution for the original problem

General recurrence:  $T(N) = aT(N/b) + f(N)$



Cases solved by divide and conquer

- ❖ The maximum subsequence sum – the  $O(N \log N)$  solution
- ❖ Tree traversals –  $O(N)$
- ❖ Mergesort and quicksort –  $O(N \log N)$

# Maximum Sequence of Sum

【Example】 Given (possibly negative) integers  $A_1, A_2, \dots, A_N$ , find the maximum value of  $\sum_{k=i}^j A_k$ .

## Algorithm 1

```
int MaxSubsequenceSum ( const int A[ ], int N )
{
    int ThisSum, MaxSum, i, j, k;
    /* 1*/ MaxSum = 0; /* initialize the maximum sum */
    /* 2*/ for( i = 0; i < N; i++ ) /* start from A[ i ] */
    /* 3*/     for( j = i; j < N; j++ ) { /* end at A[ j ] */
        /* 4*/         ThisSum = 0;
        /* 5*/         for( k = i; k <= j; k++ )
            /* 6*/             ThisSum += A[ k ]; /* sum from A[ i ] to A[ j ] */
        /* 7*/         if ( ThisSum > MaxSum )
            /* 8*/             MaxSum = ThisSum; /* update max sum */
    } /* end for-j and for-i */
    /* 9*/ return MaxSum;
}
```

$$T(N) = O(N^3)$$

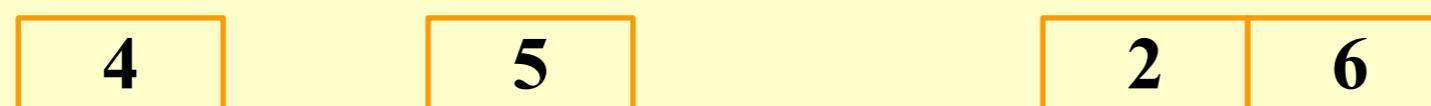
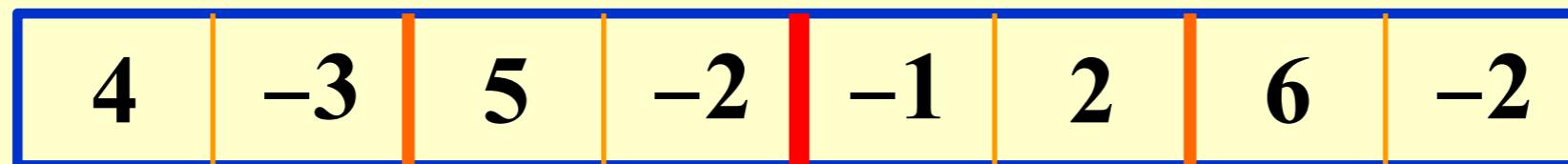
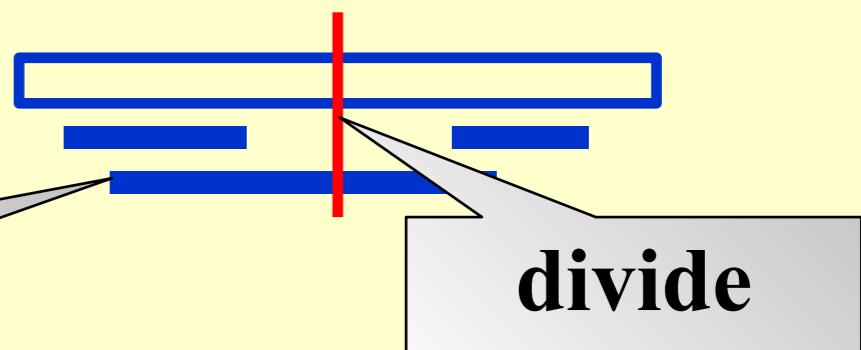
## Algorithm 2

```

int MaxSubsequenceSum ( const int A[ ], int N )
{
    int ThisSum, MaxSum, i, j;
/* 1*/    MaxSum = 0; /* initialize the maximum sum */
/* 2*/    for( i = 0; i < N; i++ ) { /* start from A[ i ] */
/* 3*/        ThisSum = 0;
/* 4*/        for( j = i; j < N; j++ ) { /* end at A[ j ] */
/* 5*/            ThisSum += A[ j ]; /* sum from A[ i ] to A[ j ] */
/* 6*/            if ( ThisSum > MaxSum )
/* 7*/                MaxSum = ThisSum; /* update max sum */
            } /* end for-j */
    } /* end for-i */
/* 8*/    return MaxSum;
}

```

$$T(N) = O(N^2)$$

**Algorithm 3****Divide and Conquer**

11

$T(N/2)$

$O(N)$

$T(N/2)$

$$T(N) = 2 T(N/2) + c N, \quad T(1) = O(1)$$

$$= 2 [2 T(N/2^2) + c N/2] + c N$$

$$= 2^k O(1) + c k N \quad \text{where } N/2^k = 1$$

$$= O(N \log N)$$

Also true for  
 $N \neq 2^k$

# Divide-and-conquer paradigm

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## Divide-and-conquer.

- Divide up problem into several subproblems (of the same kind).
- Solve (conquer) each subproblem recursively.
- Combine solutions to subproblems into overall solution.

## Most common usage.

- Divide problem of size  $n$  into two subproblems of size  $n/2$ .  $\leftarrow O(n)$  time
- Solve (conquer) two subproblems recursively.
- Combine two solutions into overall solution.  $\leftarrow O(n)$  time

## Consequence.

- Brute force:  $\Theta(n^2)$ .
- Divide-and-conquer:  $O(n \log n)$ .

Common situation.  
Not always the case.



attributed to Julius Caesar

# Divide and Conquer

- Introduction
- **Closest pair of points**
- Solving recurrent equations
- Multiplication problems
- Take-home messages

# Closest pair of points

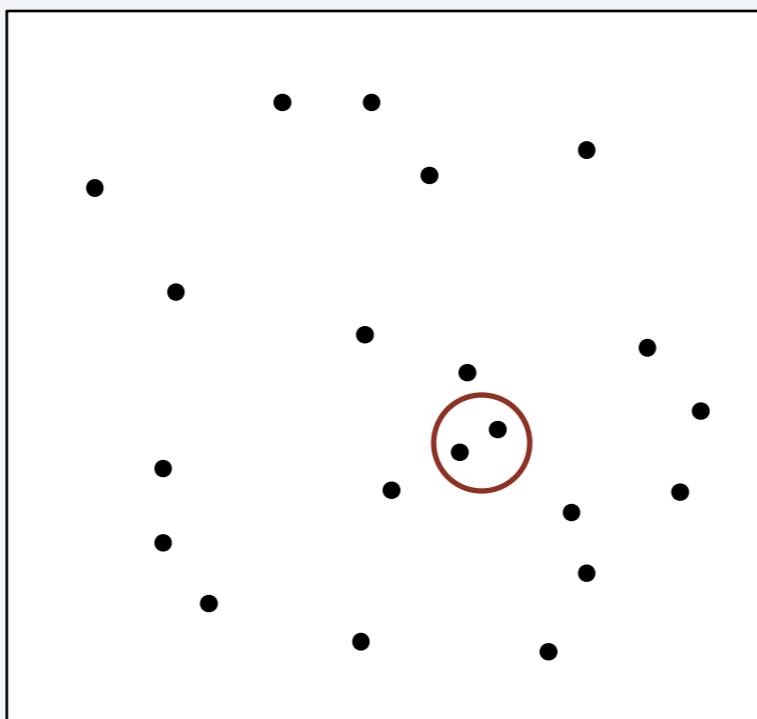
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**Closest pair problem.** Given  $n$  points in the plane, find a pair of points with the smallest Euclidean distance between them.

Fundamental geometric primitive.

- Graphics, computer vision, geographic information systems, molecular modeling, air traffic control.
- Special case of nearest neighbor, Euclidean MST, Voronoi.

fast closest pair inspired fast algorithms for these problems



# Closest pair of points

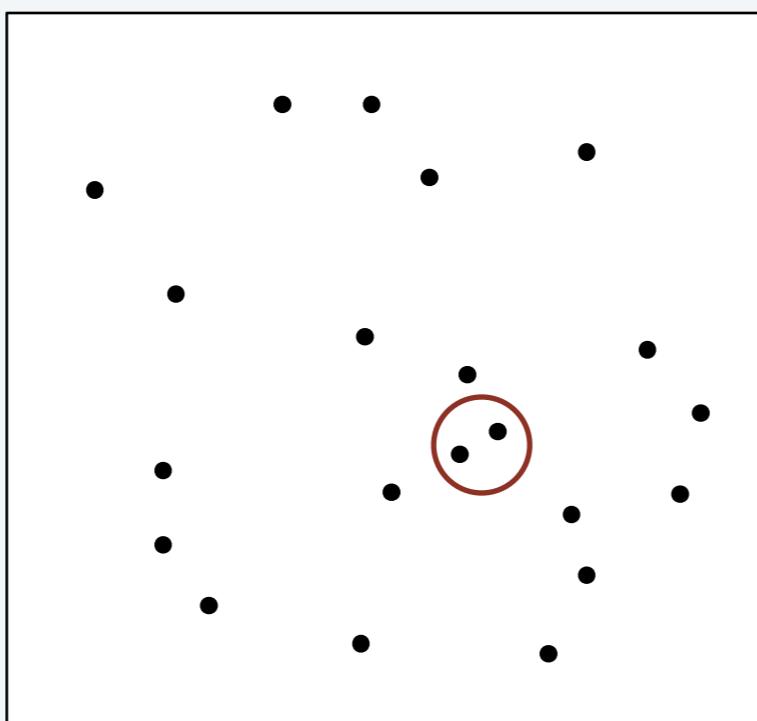
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**Closest pair problem.** Given  $n$  points in the plane, find a pair of points with the smallest Euclidean distance between them.

**Brute force.** Check all pairs with  $\Theta(n^2)$  distance calculations.

**1D version.** Easy  $O(n \log n)$  algorithm if points are on a line.

**Non-degeneracy assumption.** No two points have the same  $x$ -coordinate.

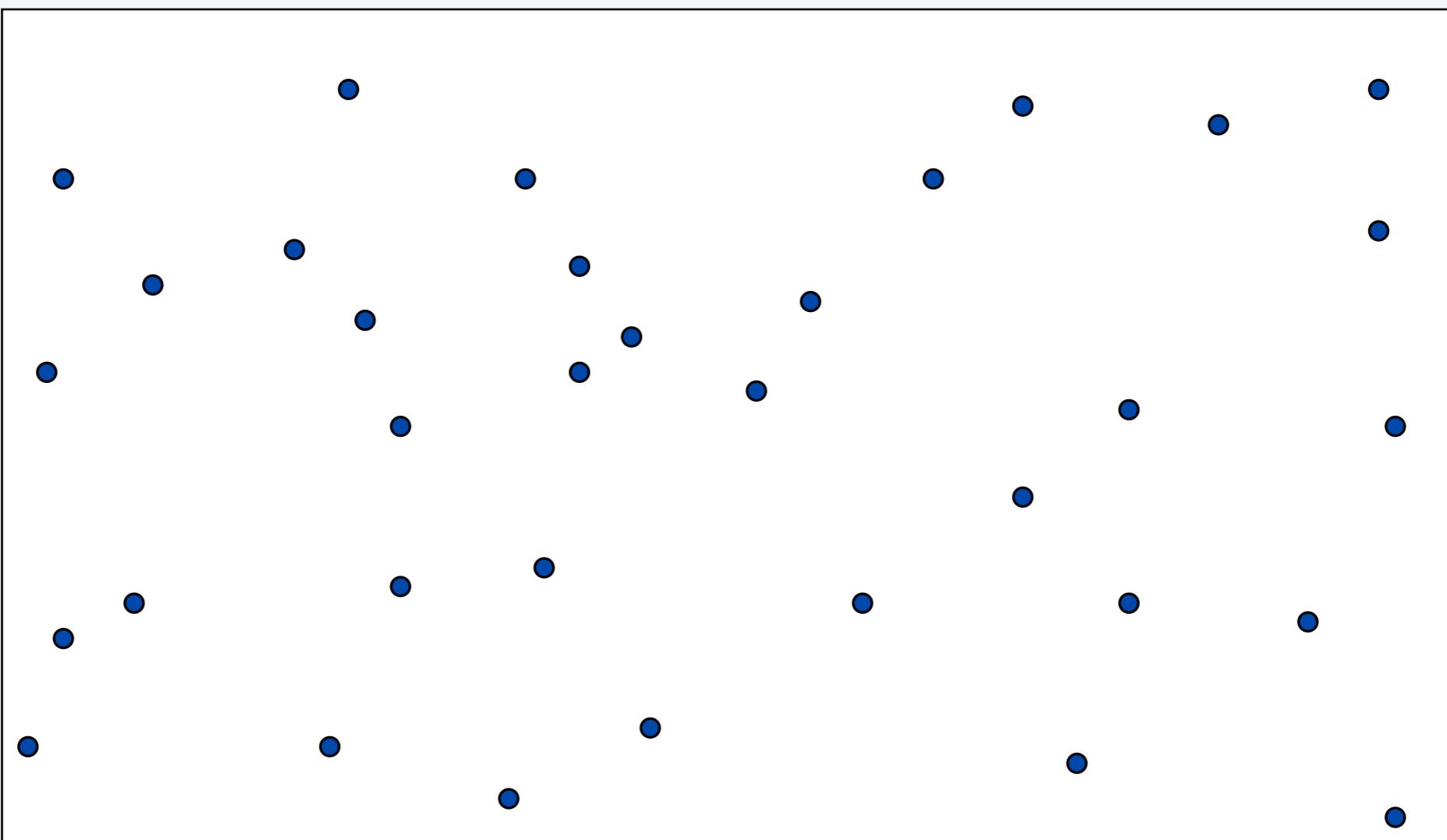


## Closest pair of points: first attempt

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Sorting solution.

- Sort by  $x$ -coordinate and consider nearby points.
- Sort by  $y$ -coordinate and consider nearby points.

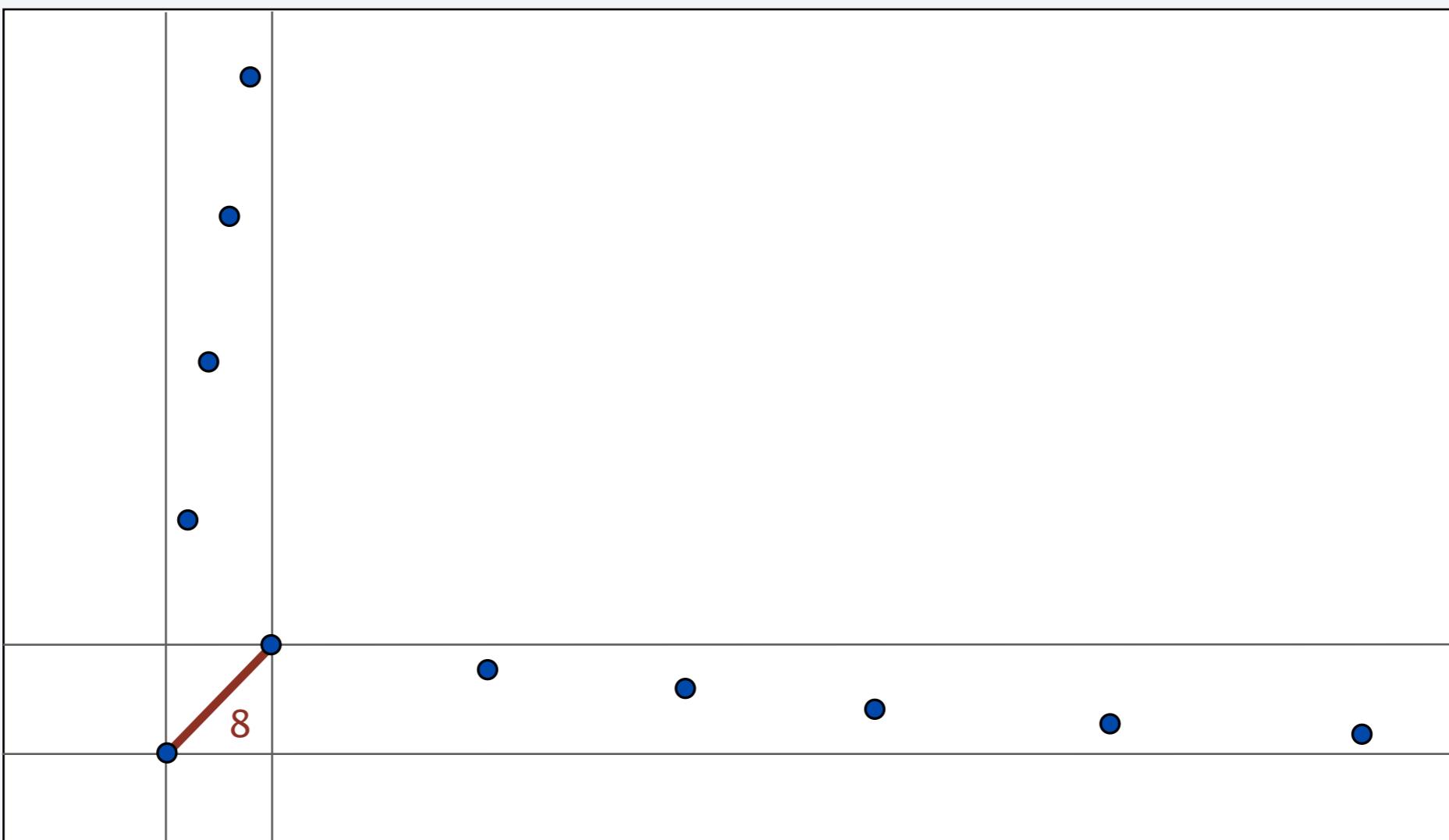


# Closest pair of points: first attempt

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Sorting solution.

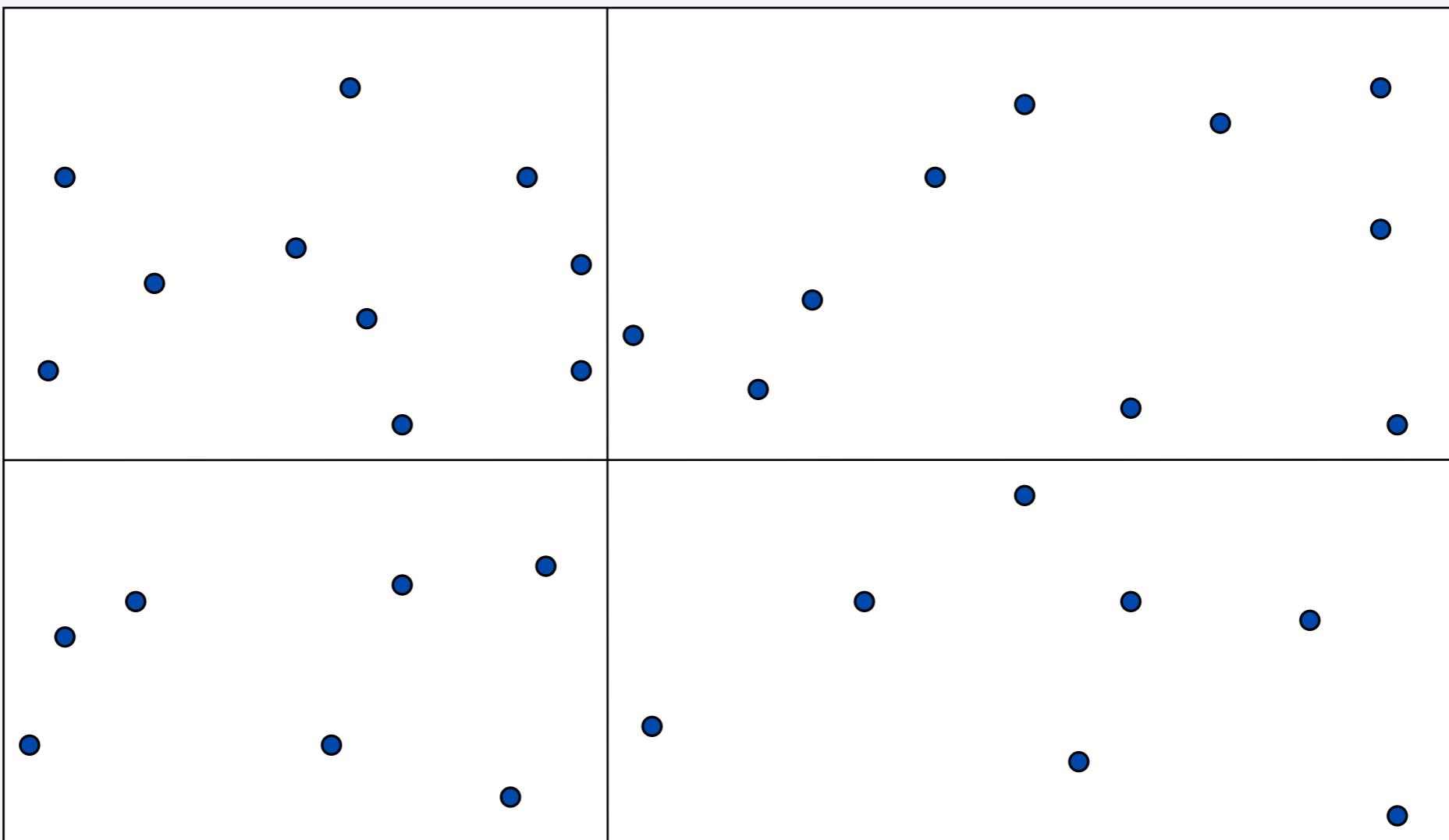
- Sort by  $x$ -coordinate and consider nearby points.
- Sort by  $y$ -coordinate and consider nearby points.



## Closest pair of points: second attempt

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Divide. Subdivide region into 4 quadrants.

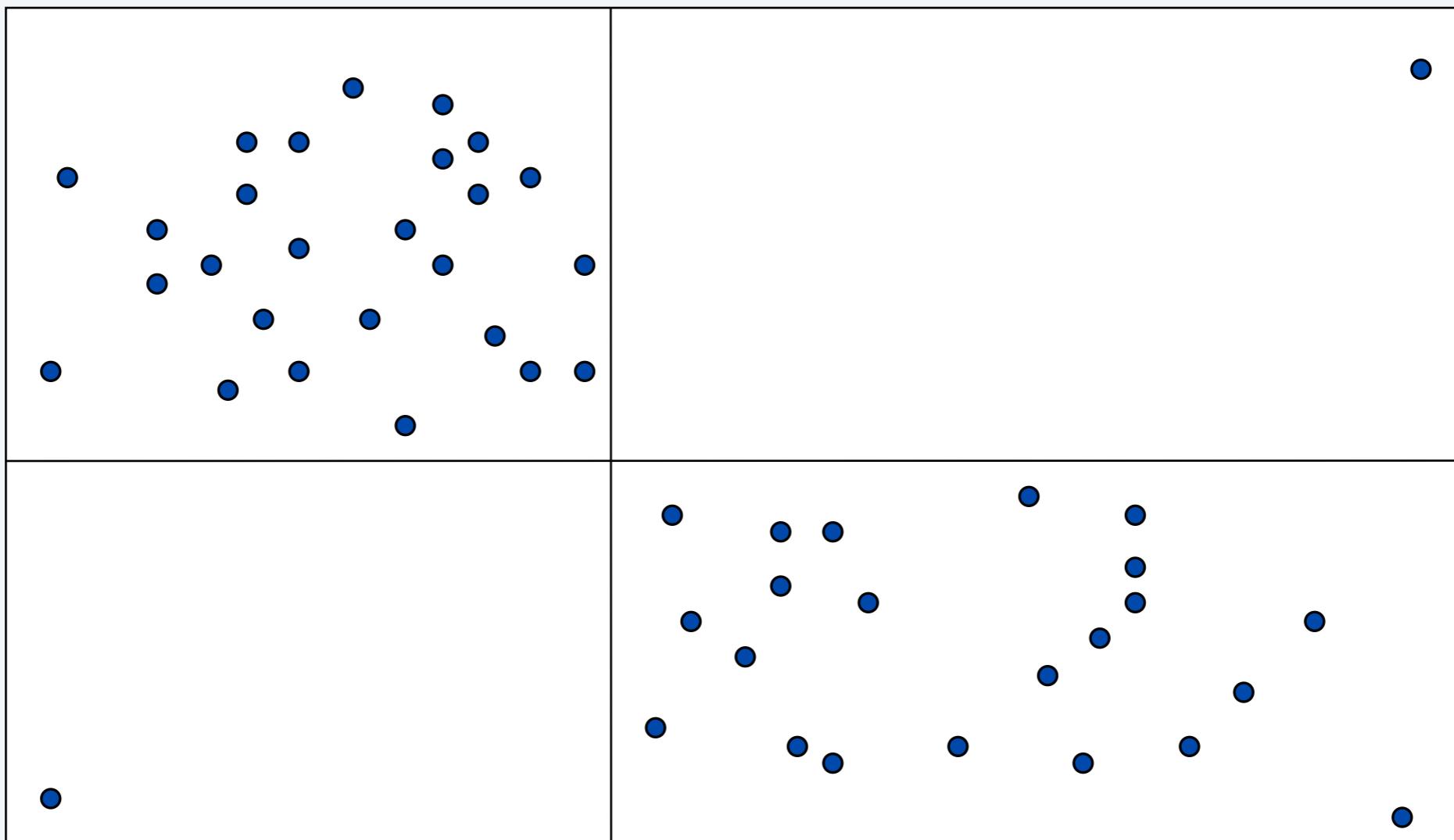


## Closest pair of points: second attempt

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**Divide.** Subdivide region into 4 quadrants.

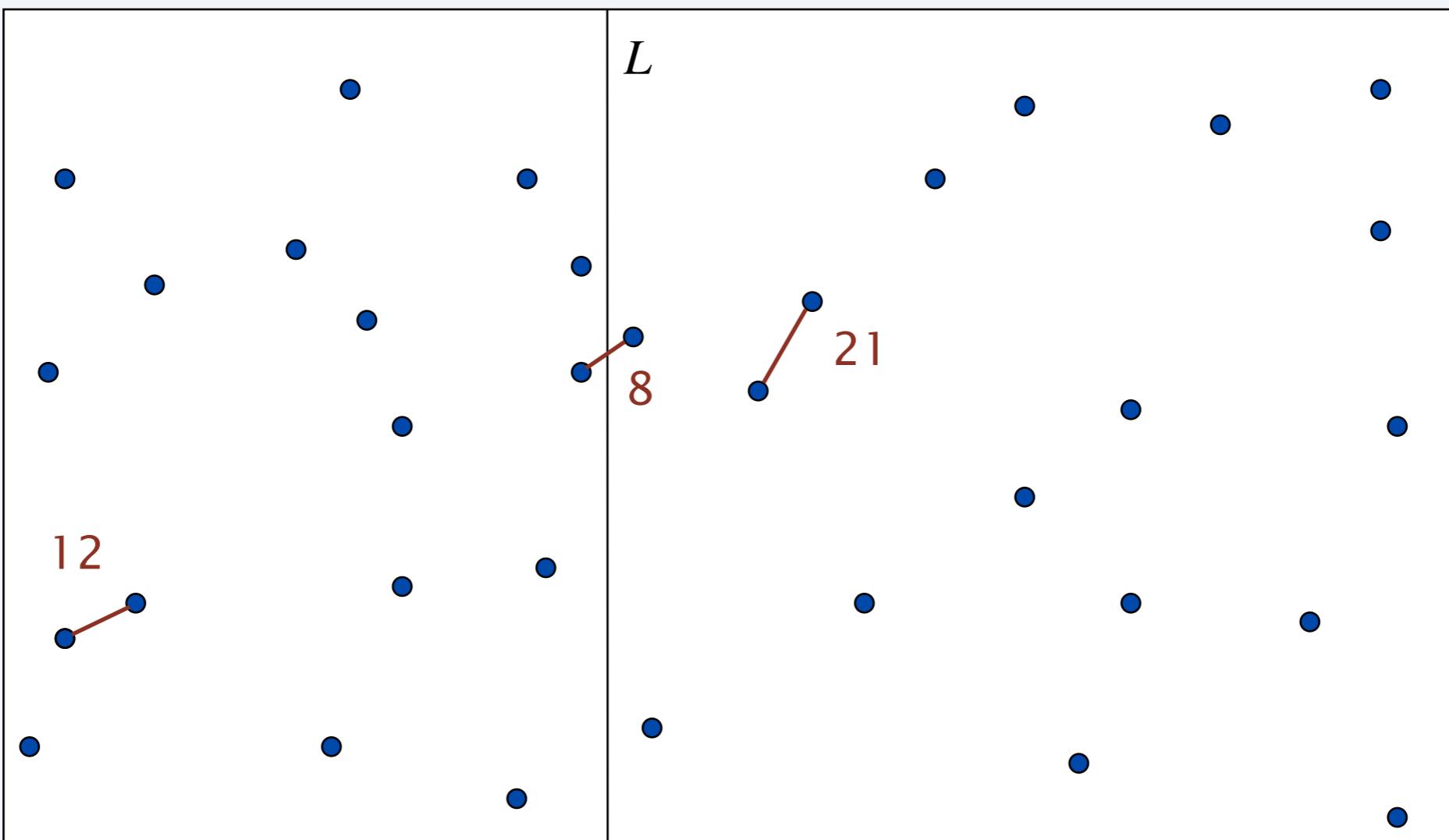
**Obstacle.** Impossible to ensure  $n/4$  points in each piece.



# Closest pair of points: divide-and-conquer algorithm

- Divide: draw vertical line  $L$  so that  $n/2$  points on each side.
- Conquer: find closest pair in each side recursively.
- Combine: find closest pair with one point in each side.
- Return best of 3 solutions.

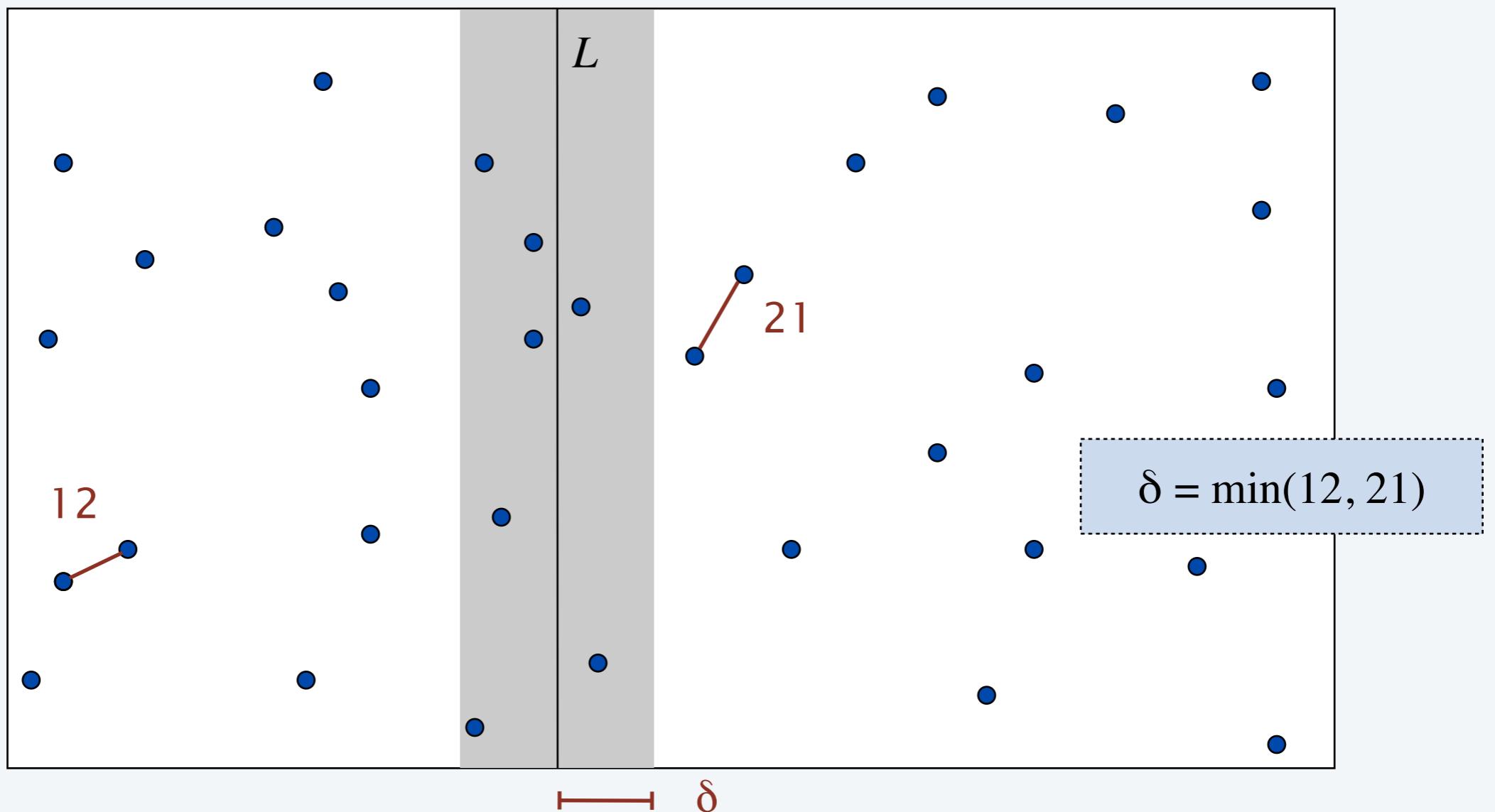
seems like  $\Theta(n^2)$



# How to find closest pair with one point in each side?

Find closest pair with one point in each side, assuming that distance  $< \delta$ .

- Observation: suffices to consider only those points within  $\delta$  of line  $L$ .

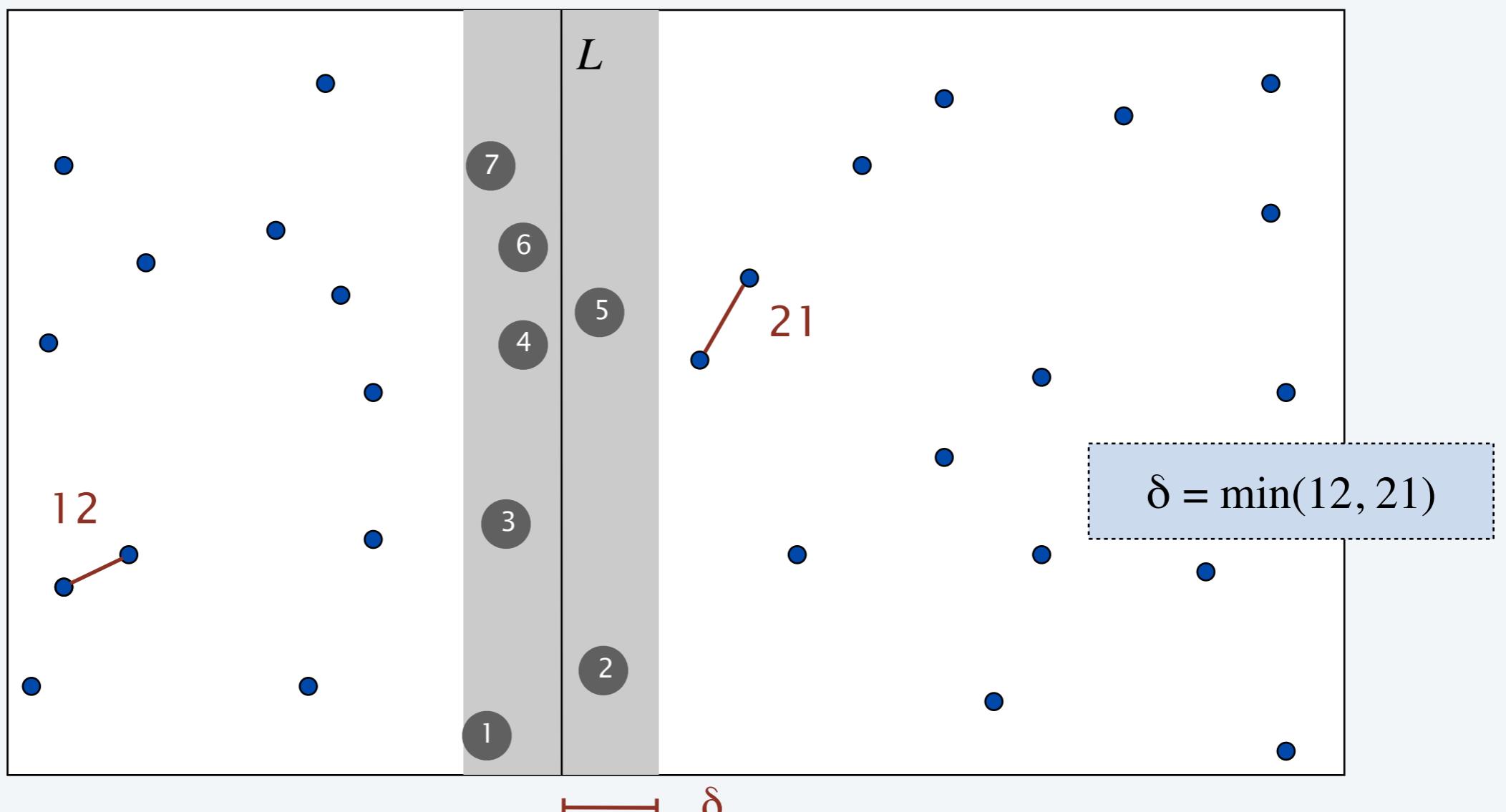


# How to find closest pair with one point in each side?

Find closest pair with one point in each side, assuming that distance  $< \delta$ .

- Observation: suffices to consider only those points within  $\delta$  of line  $L$ .
- Sort points in  $2\delta$ -strip by their  $y$ -coordinate.
- Check distances of only those points within 7 positions in sorted list!

why?



# How to find closest pair with one point in each side?

**Def.** Let  $s_i$  be the point in the  $2\delta$ -strip, with the  $i^{th}$  smallest  $y$ -coordinate.

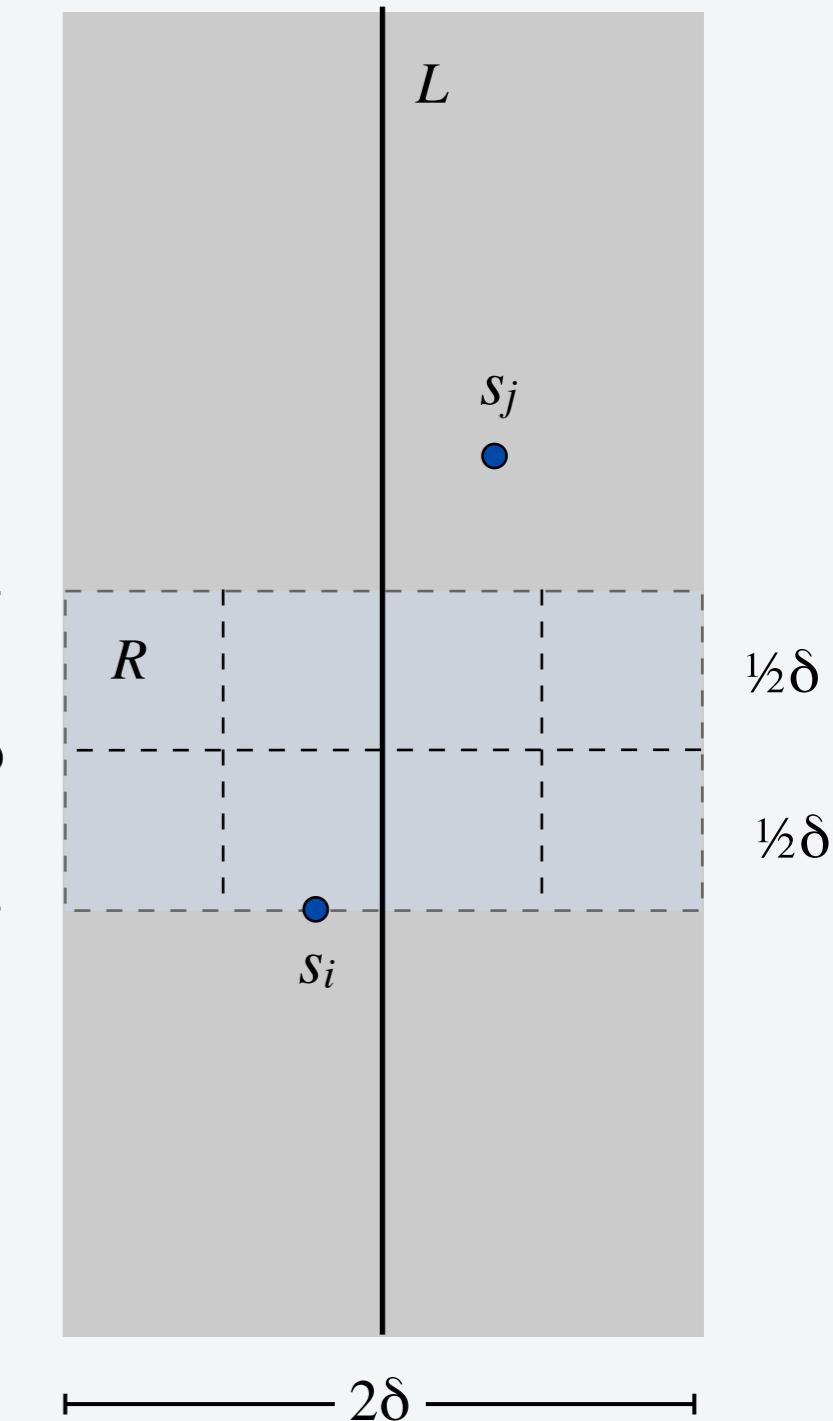
**Claim.** If  $|j - i| > 7$ , then the distance between  $s_i$  and  $s_j$  is at least  $\delta$ .

**Pf.**

- Consider the  $2\delta$ -by- $\delta$  rectangle  $R$  in strip whose min  $y$ -coordinate is  $y$ -coordinate of  $s_i$ .
- Distance between  $s_i$  and any point  $s_j$  above  $R$  is  $\geq \delta$ .
- Subdivide  $R$  into 8 squares.
- At most 1 point per square.
- At most 7 other points can be in  $R$ . ■

diameter is  
 $\delta / \sqrt{2} < \delta$

constant can be improved with more refined geometric packing argument



# Closest pair of points: divide-and-conquer algorithm

**CLOSEST-PAIR**( $p_1, p_2, \dots, p_n$ )

Compute vertical line  $L$  such that half the points  
are on each side of the line.

$\delta_1 \leftarrow \text{CLOSEST-PAIR}(\text{points in left half}).$

←  $O(n)$

$\delta_2 \leftarrow \text{CLOSEST-PAIR}(\text{points in right half}).$

←  $T(n / 2)$

$\delta \leftarrow \min \{ \delta_1, \delta_2 \}.$

←  $T(n / 2)$

Delete all points further than  $\delta$  from line  $L$ .

←  $O(n)$

Sort remaining points by  $y$ -coordinate.

←  $O(n \log n)$

Scan points in  $y$ -order and compare distance between  
each point and next 7 neighbors. If any of these  
distances is less than  $\delta$ , update  $\delta$ .

←  $O(n)$

**RETURN**  $\delta$ .



What is the solution to the following recurrence?

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + \Theta(n \log n) & \text{if } n > 1 \end{cases}$$

- A.  $T(n) = \Theta(n).$
- B.  $T(n) = \Theta(n \log n).$
- C.  $T(n) = \Theta(n \log^2 n).$
- D.  $T(n) = \Theta(n^2).$

# Refined version of closest-pair algorithm

Q. How to improve to  $O(n \log n)$ ?

A. Don't sort points in strip from scratch each time.

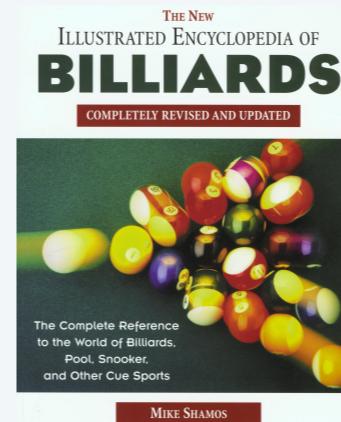
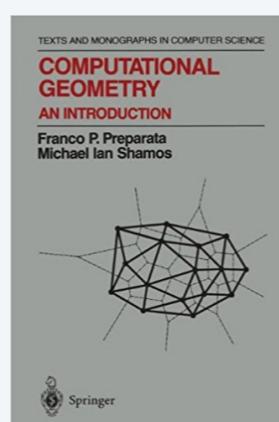
- Each recursive call returns two lists: all points sorted by  $x$ -coordinate, and all points sorted by  $y$ -coordinate.
- Sort by **merging** two pre-sorted lists.

Either pre-sort beforehand  
Or do merge sort along with recurrence  
Check our exercise

**Theorem.** [Shamos 1975] The divide-and-conquer algorithm for finding a closest pair of points in the plane can be implemented in  $O(n \log n)$  time.

Pf.

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + \Theta(n) & \text{if } n > 1 \end{cases}$$



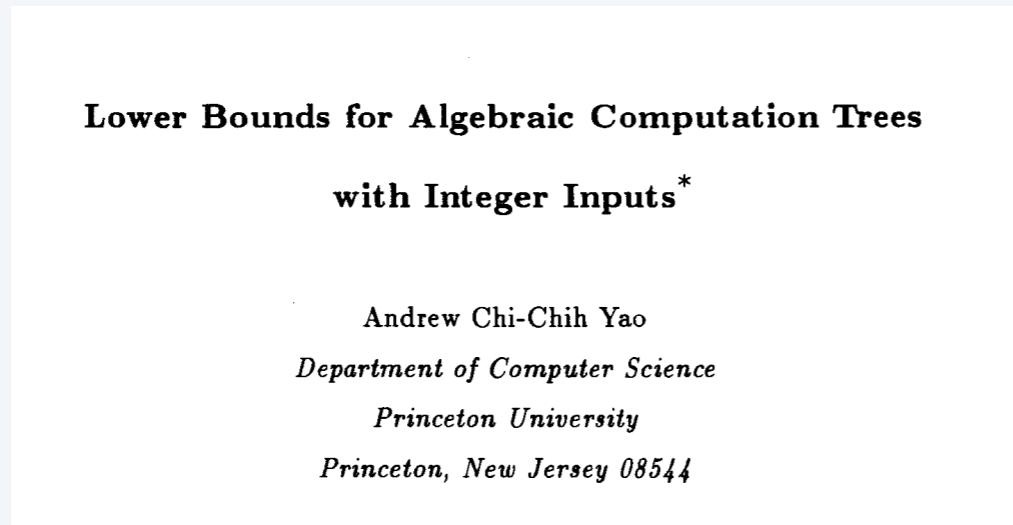


**What is the complexity of the 2D closest pair problem?**

- A.  $\Theta(n)$ .
- B.  $\Theta(n \log^* n)$ .
- C.  $\Theta(n \log \log n)$ .
- D.  $\Theta(n \log n)$ .
- E. Not even Tarjan knows.

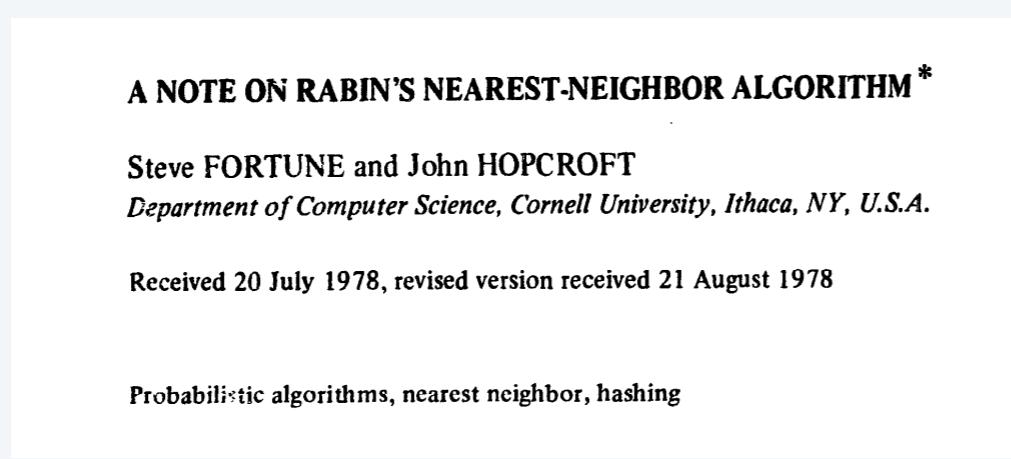
# Computational complexity of closest-pair problem

**Theorem.** [Ben-Or 1983, Yao 1989] In quadratic decision tree model, any algorithm for closest pair (even in 1D) requires  $\Omega(n \log n)$  quadratic tests.



$$(x_1 - x_2)^2 + (y_1 - y_2)^2$$

**Theorem.** [Rabin 1976] There exists an algorithm to find the closest pair of points in the plane whose expected running time is  $O(n)$ .



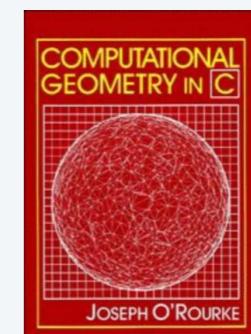
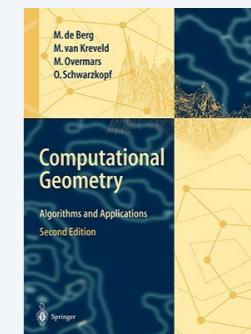
not subject to  $\Omega(n \log n)$  lower bound  
because it uses the floor function

# Digression: computational geometry

Ingenious divide-and-conquer algorithms for core geometric problems.

problem	brute	clever
<b>closest pair</b>	$O(n^2)$	$O(n \log n)$
<b>farthest pair</b>	$O(n^2)$	$O(n \log n)$
<b>convex hull</b>	$O(n^2)$	$O(n \log n)$
<b>Delaunay/Voronoi</b>	$O(n^4)$	$O(n \log n)$
<b>Euclidean MST</b>	$O(n^2)$	$O(n \log n)$

running time to solve a 2D problem with  $n$  points

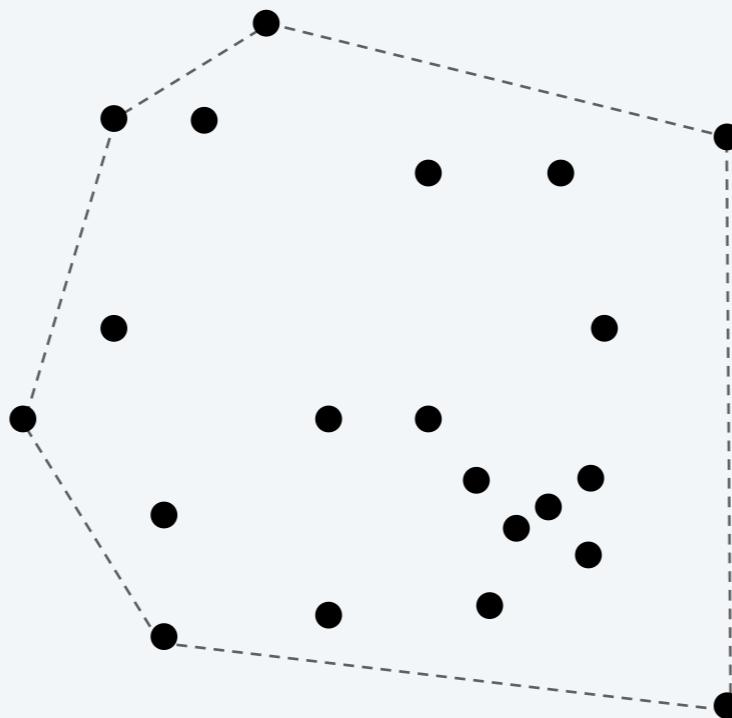


Note. 3D and higher dimensions test limits of our ingenuity.

# Convex hull

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The **convex hull** of a set of  $n$  points is the smallest perimeter fence enclosing the points.



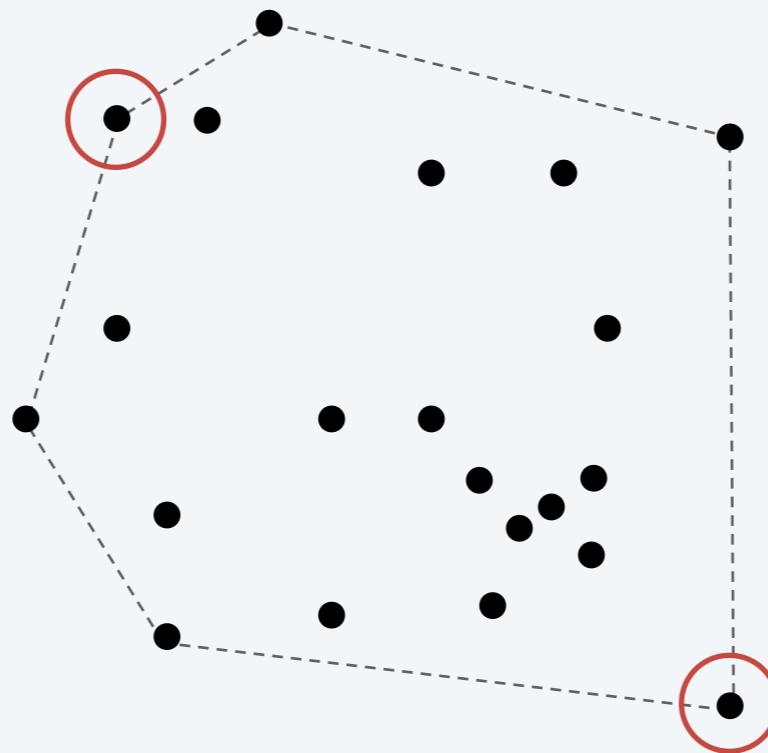
## Equivalent definitions.

- Smallest area convex polygon enclosing the points.
- Intersection of all convex set containing all the points.

## Farthest pair

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Given  $n$  points in the plane, find a pair of points with the largest Euclidean distance between them.

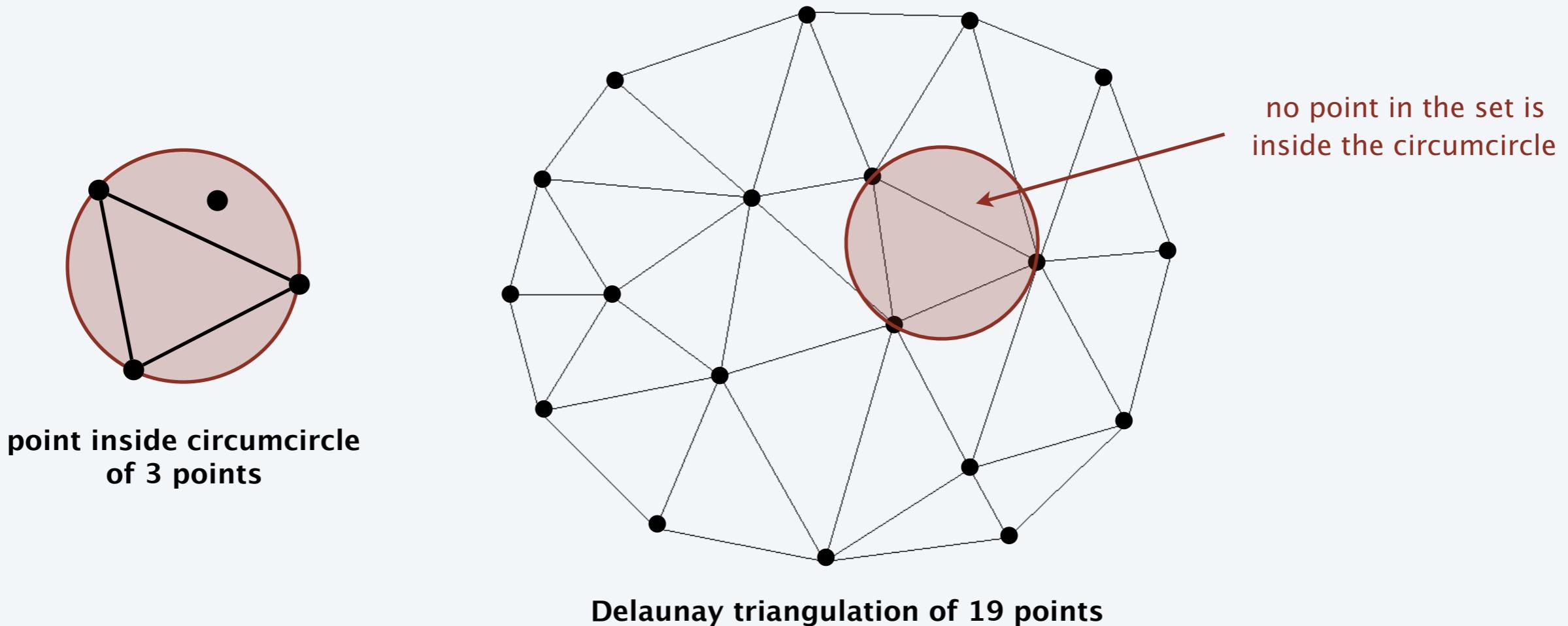


Fact. Points in farthest pair are extreme points on convex hull.

# Delaunay triangulation

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The **Delaunay triangulation** is a triangulation of  $n$  points in the plane such that no point is inside the circumcircle of any triangle.



Some useful properties.

- No edges cross.
- Among all triangulations, it maximizes the minimum angle.
- Contains an edge between each point and its nearest neighbor.

# Euclidean MST

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Given  $n$  points in the plane, find MST connecting them.

[distances between point pairs are Euclidean distances]



**Fact.** Euclidean MST is subgraph of Delaunay triangulation.

**Implication.** Can compute Euclidean MST in  $O(n \log n)$  time.

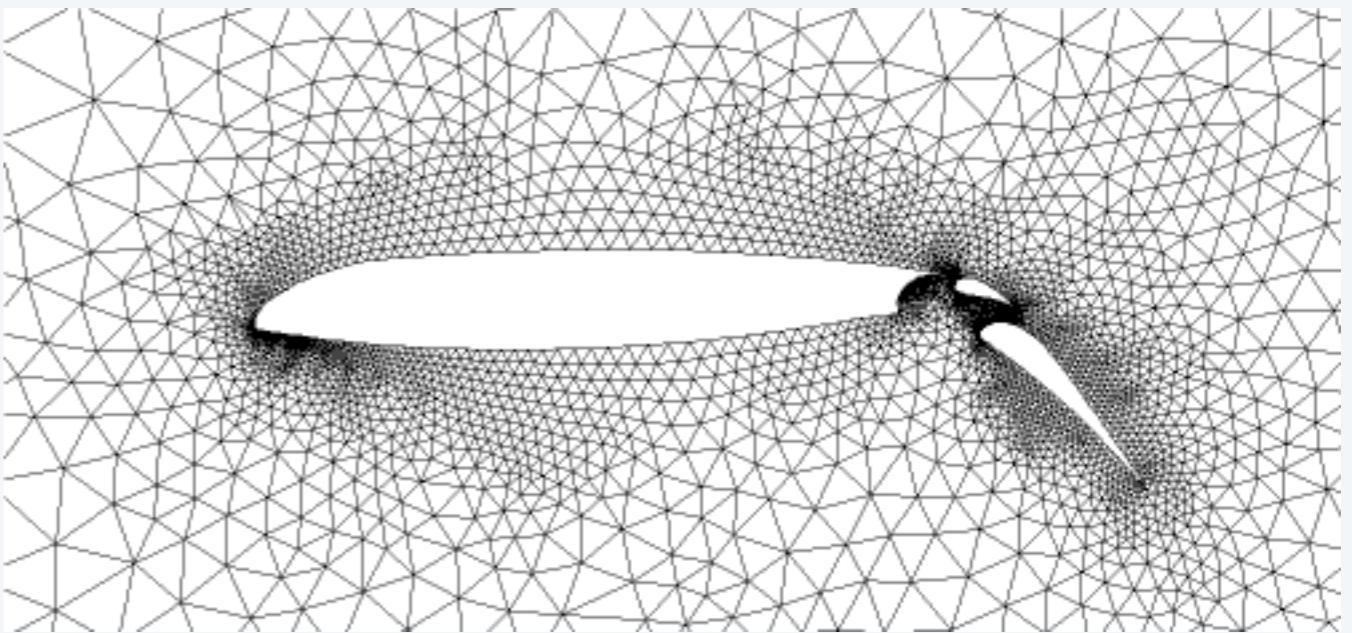
- Compute Delaunay triangulation.
- Compute MST of Delaunay triangulation. ← it's planar  
( $\leq 3n$  edges)

# Computational geometry applications

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## Applications.

- Robotics.
- VLSI design.
- Data mining.
- Medical imaging.
- Computer vision.
- Scientific computing.
- Finite-element meshing.
- Astronomical simulation.
- Models of physical world.
- Geographic information systems.
- Computer graphics (movies, games, virtual reality).



airflow around an aircraft wing

<http://www.ics.uci.edu/~eppstein/geom.html>

# Divide and Conquer

- Introduction
- Closest pair of points
- **Solving recurrent equations**
- Multiplication problems
- Take-home messages

# Three methods for solving recurrences:

$$T(N) = a T(N/b) + f(N)$$

👉 Substitution method

👉 Recursion-tree method

👉 Master method

✖ Details to be ignored:

👉 if  $(N/b)$  is an integer or not

👉 always assume  $T(n) = \Theta(1)$  for small  $n$

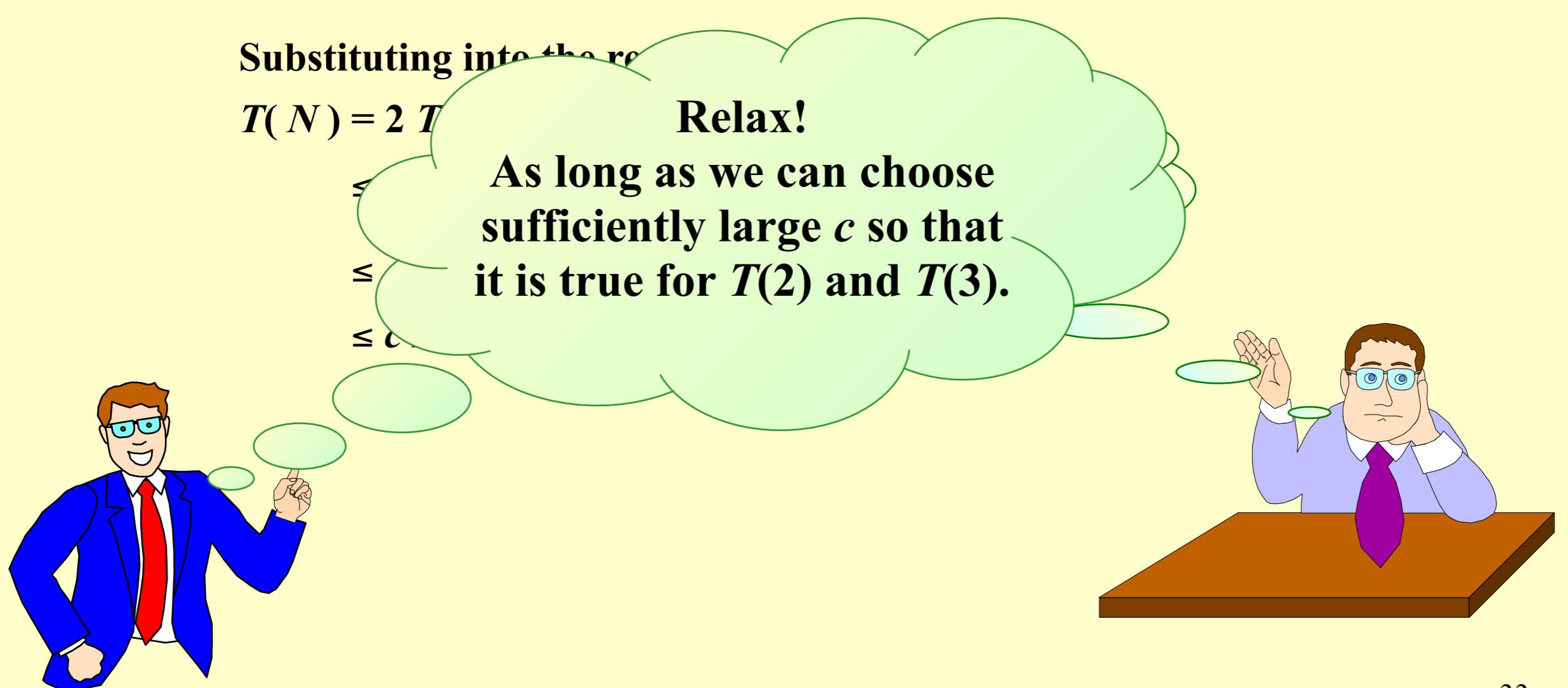
☞ Substitution method — guess, then prove by induction

【Example】  $T(N) = 2 T(\lfloor N/2 \rfloor) + N$

Guess:  $T(N) = O(N \log N)$

**Proof:** Assume it is true for all  $m < N$ , in particular for  $m = \lfloor N/2 \rfloor$ .

Then there exists a constant  $c > 0$  so that  $T(\lfloor N/2 \rfloor) \leq c \lfloor N/2 \rfloor \log \lfloor N/2 \rfloor$



【Example】  $T(N) = 2 T(\lfloor N/2 \rfloor) + N$

Wrong guess:  $T(N) = O(N)$

**Proof:** Assume it is true for all  $m < N$ , in particular for  $m = \lfloor N/2 \rfloor$ .

$$T(\lfloor N/2 \rfloor) \leq c \lfloor N/2 \rfloor$$

Substituting into the recurrence:

$$\begin{aligned} T(N) &= 2 T(\lfloor N/2 \rfloor) + N \\ &\leq 2 c \lfloor N/2 \rfloor + N \\ &\leq cN + N = O(N) \end{aligned}$$

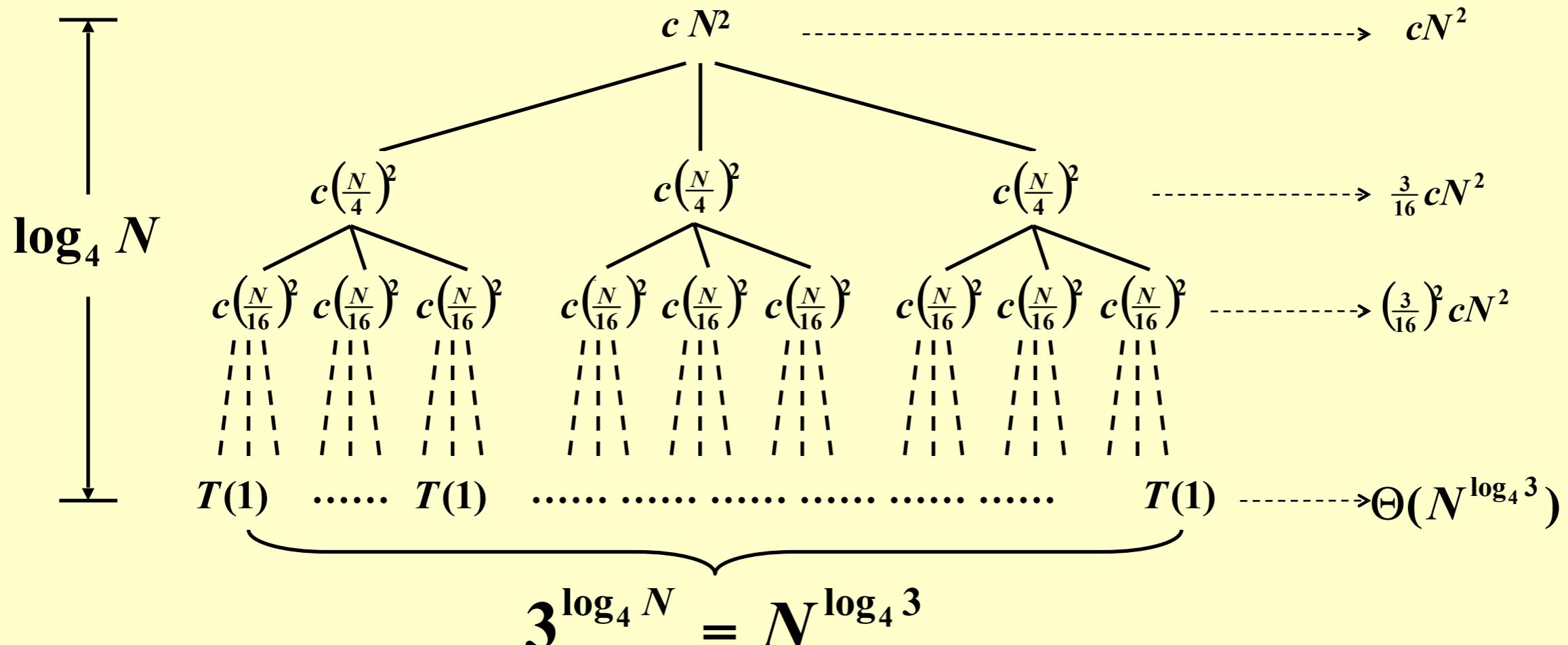
If we use  $O(N)$  here, then we cannot guarantee that there is a fixed constant  $c$  holds for all  $N$

Must prove the *exact form*

How to make a good guess?

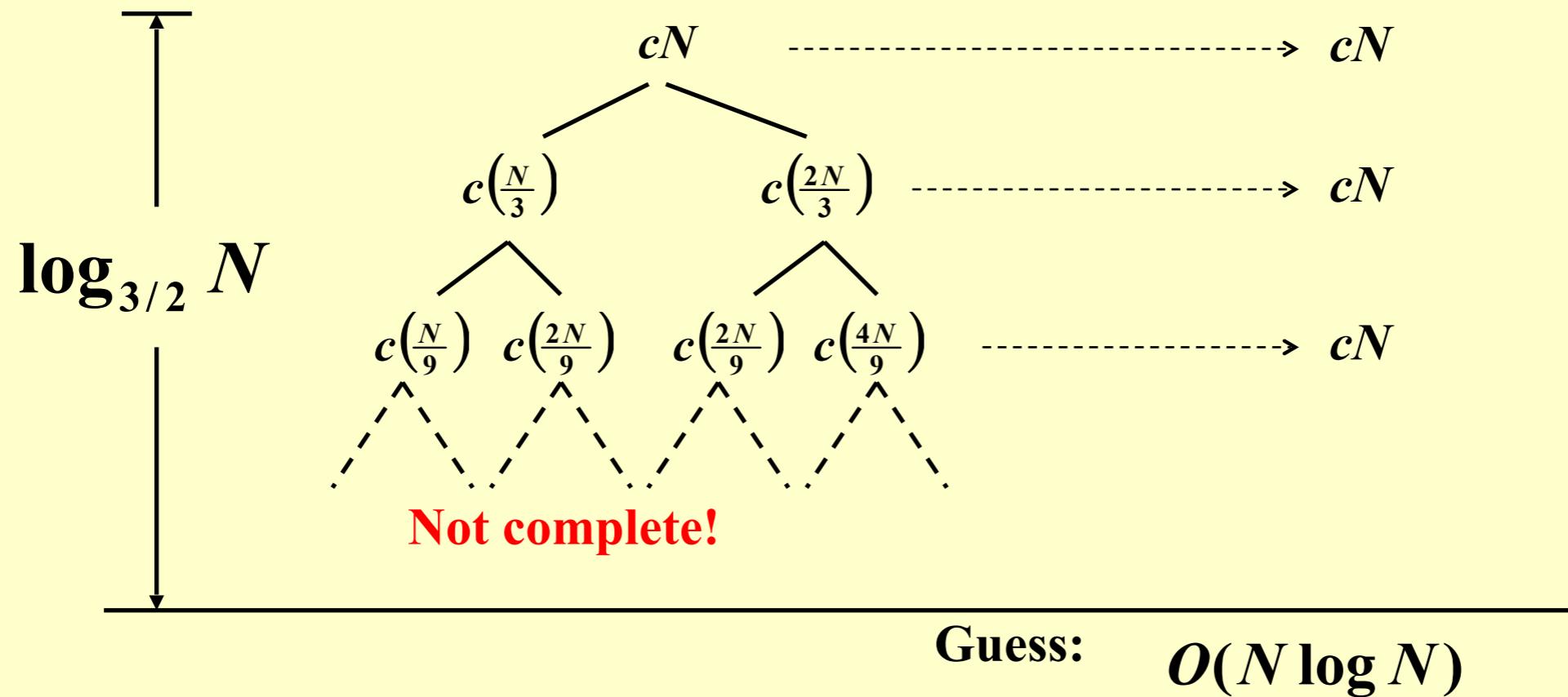
 **Recursion-tree method**

〔Example〕  $T(N) = 3 T(N/4) + \Theta(N^2)$



$$T(N) = \sum_{i=0}^{\log_4 N - 1} \left(\frac{3}{16}\right)^i cN^2 + \Theta(N^{\log_4 3})$$

〔Example〕  $T(N) = T(N/3) + T(2N/3) + cN$



**Proof by substitution:**

$$\begin{aligned}
 T(N) &= T(N/3) + T(2N/3) + cN \leq d(N/3)\log(N/3) + d(2N/3)\log(2N/3) + cN \\
 &= dN \log N - dN(\log_2 3 - \frac{2}{3}) + cN \leq dN \log N \\
 &\quad \text{for } d \geq c / (\log_2 3 - \frac{2}{3})
 \end{aligned}$$

# Divide-and-conquer recurrences

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Goal. Recipe for solving common divide-and-conquer recurrences:

$$T(n) = a T\left(\frac{n}{b}\right) + f(n)$$

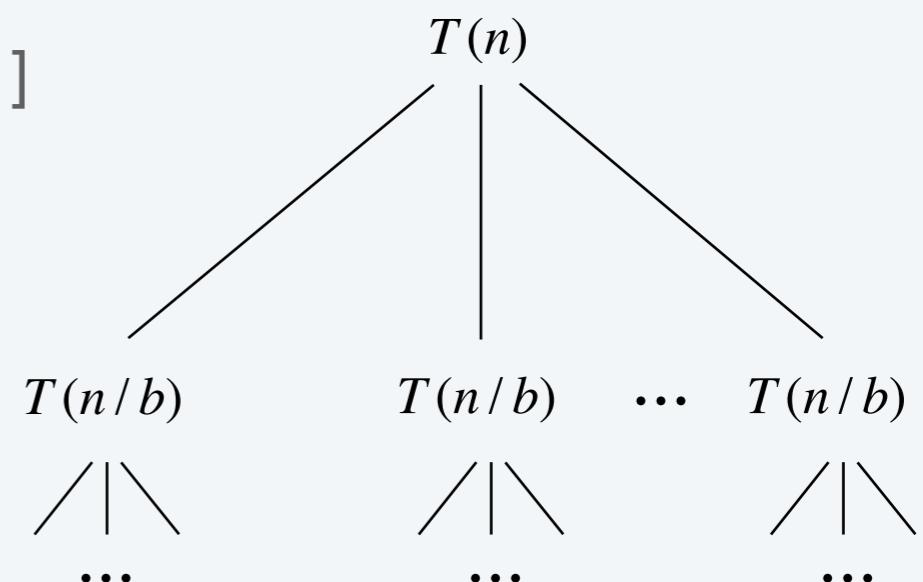
with  $T(0) = 0$  and  $T(1) = \Theta(1)$ .

## Terms.

- $a \geq 1$  is the number of subproblems.
- $b \geq 2$  is the factor by which the subproblem size decreases.
- $f(n) \geq 0$  is the work to divide and combine subproblems.

Recursion tree. [ assuming  $n$  is a power of  $b$  ]

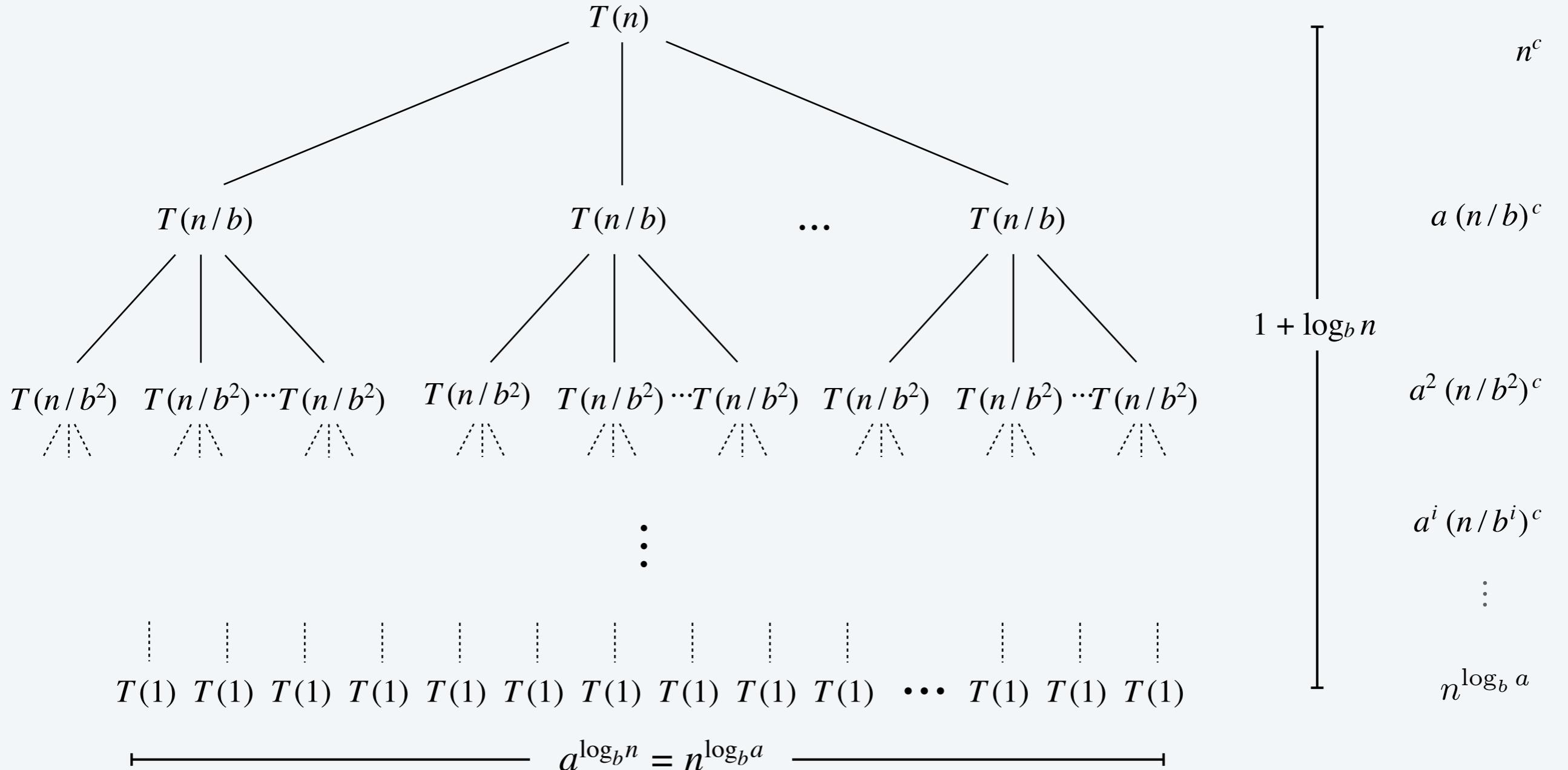
- $a$  = branching factor.
- $a^i$  = number of subproblems at level  $i$ .
- $1 + \log_b n$  levels.
- $n / b^i$  = size of subproblem at level  $i$ .



# Divide-and-conquer recurrences: recursion tree

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Suppose  $T(n)$  satisfies  $T(n) = a T(n / b) + n^c$  with  $T(1) = 1$ , for  $n$  a power of  $b$ .



$$r = a / b^c \quad T(n) = n^c \sum_{i=0}^{\log_b n} r^i$$

# Divide-and-conquer recurrences: recursion tree analysis

Suppose  $T(n)$  satisfies  $T(n) = a T(n / b) + n^c$  with  $T(1) = 1$ , for  $n$  a power of  $b$ .

Let  $r = a / b^c$ . Note that  $r < 1$  iff  $c > \log_b a$ .

$$T(n) = n^c \sum_{i=0}^{\log_b n} r^i = \begin{cases} \Theta(n^c) & \text{if } r < 1 \\ \Theta(n^c \log n) & \text{if } r = 1 \\ \Theta(n^{\log_b a}) & \text{if } r > 1 \end{cases}$$

← cost dominated by cost of root  
← cost evenly distributed in tree  
← cost dominated by cost of leaves

## Geometric series.

- If  $0 < r < 1$ , then  $1 + r + r^2 + r^3 + \dots + r^k \leq 1 / (1 - r)$ .
- If  $r = 1$ , then  $1 + r + r^2 + r^3 + \dots + r^k = k + 1$ .
- If  $r > 1$ , then  $1 + r + r^2 + r^3 + \dots + r^k = (r^{k+1} - 1) / (r - 1)$ .

## Divide-and-conquer recurrences: master theorem

**Master theorem.** Let  $a \geq 1$ ,  $b \geq 2$ , and  $c \geq 0$  and suppose that  $T(n)$  is a function on the non-negative integers that satisfies the recurrence

$$T(n) = a T\left(\frac{n}{b}\right) + \Theta(n^c)$$

with  $T(0) = 0$  and  $T(1) = \Theta(1)$ , where  $n/b$  means either  $\lfloor n/b \rfloor$  or  $\lceil n/b \rceil$ . Then,

**Case 1.** If  $c > \log_b a$ , then  $T(n) = \Theta(n^c)$ .

**Case 2.** If  $c = \log_b a$ , then  $T(n) = \Theta(n^c \log n)$ .

**Case 3.** If  $c < \log_b a$ , then  $T(n) = \Theta(n^{\log_b a})$ .



**D. Blostein Jon Bentley**

**James B. Saxe**

Pf sketch.

- Prove when  $b$  is an integer and  $n$  is an exact power of  $b$ .
- Extend domain of recurrences to reals (or rationals).
- Deal with floors and ceilings. ← at most 2 extra levels in recursion tree

$$\begin{aligned} \lceil \lceil \lceil n/b \rceil / b \rceil / b \rceil &< n/b^3 + (1/b^2 + 1/b + 1) \\ &\leq n/b^3 + 2 \end{aligned}$$

## Divide-and-conquer recurrences: master theorem

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**Master theorem.** Let  $a \geq 1$ ,  $b \geq 2$ , and  $c \geq 0$  and suppose that  $T(n)$  is a function on the non-negative integers that satisfies the recurrence

$$T(n) = a T\left(\frac{n}{b}\right) + \Theta(n^c)$$

with  $T(0) = 0$  and  $T(1) = \Theta(1)$ , where  $n/b$  means either  $\lfloor n/b \rfloor$  or  $\lceil n/b \rceil$ . Then,

**Case 1.** If  $c > \log_b a$ , then  $T(n) = \Theta(n^c)$ .

**Case 2.** If  $c = \log_b a$ , then  $T(n) = \Theta(n^c \log n)$ .

**Case 3.** If  $c < \log_b a$ , then  $T(n) = \Theta(n^{\log_b a})$ .



### Extensions.

- Can replace  $\Theta$  with  $O$  everywhere.
- Can replace  $\Theta$  with  $\Omega$  everywhere.
- Can replace initial conditions with  $T(n) = \Theta(1)$  for all  $n \leq n_0$  and require recurrence to hold only for all  $n > n_0$ .

## Divide-and-conquer recurrences: master theorem

---

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**Case 3.** If  $c < \log_b a$ , then  $T(n) = \Theta(n^{\log_b a})$ .



**Ex.** [Case 1]  $T(n) = 3 T(\lfloor n/2 \rfloor) + 5n$ .

- $a = 3$ ,  $b = 2$ ,  $c = 1 < \log_b a = 1.5849\dots$
- $T(n) = \Theta(n^{\log_2 3}) = O(n^{1.58})$ .

## Divide-and-conquer recurrences: master theorem

**Master theorem.** Let  $a \geq 1$ ,  $b \geq 2$ , and  $c \geq 0$  and suppose that  $T(n)$  is a function on the non-negative integers that satisfies the recurrence

$$T(n) = a T\left(\frac{n}{b}\right) + \Theta(n^c)$$

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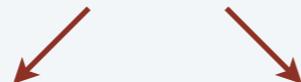
**Case 1.** If  $c > \log_b a$ , then  $T(n) = \Theta(n^c)$ .

**Case 2.** If  $c = \log_b a$ , then  $T(n) = \Theta(n^c \log n)$ .

**Case 3.** If  $c < \log_b a$ , then  $T(n) = \Theta(n^{\log_b a})$ .



ok to intermix floor and ceiling



**Ex.** [Case 2]  $T(n) = T(\lfloor n/2 \rfloor) + T(\lceil n/2 \rceil) + 17n$ .

- $a = 2$ ,  $b = 2$ ,  $c = 1 = \log_b a$ .
- $T(n) = \Theta(n \log n)$ .

## Divide-and-conquer recurrences: master theorem

**Master theorem.** Let  $a \geq 1$ ,  $b \geq 2$ , and  $c \geq 0$  and suppose that  $T(n)$  is a function on the non-negative integers that satisfies the recurrence

$$T(n) = a T\left(\frac{n}{b}\right) + \Theta(n^c)$$

with  $T(0) = 0$  and  $T(1) = \Theta(1)$ , where  $n/b$  means either  $\lfloor n/b \rfloor$  or  $\lceil n/b \rceil$ . Then,

**Case 1.** If  $c > \log_b a$ , then  $T(n) = \Theta(n^c)$ .

**Case 2.** If  $c = \log_b a$ , then  $T(n) = \Theta(n^c \log n)$ .

**Case 3.** If  $c < \log_b a$ , then  $T(n) = \Theta(n^{\log_b a})$ .



**Ex.** [Case 3]  $T(n) = 48 T(\lfloor n/4 \rfloor) + n^3$ .

- $a = 48$ ,  $b = 4$ ,  $c = 3 > \log_b a = 2.7924\dots$
- $T(n) = \Theta(n^3)$ .

# Master theorem need not apply

---

Gaps in master theorem.

- Number of subproblems is not a constant.

$$T(n) = \textcircled{n} T(n/2) + n^2$$

- Number of subproblems is less than 1.

$$T(n) = \textcircled{\frac{1}{2}} T(n/2) + n^2$$

- Work to divide and combine subproblems is not  $\Theta(n^c)$ .

$$T(n) = 2 T(n/2) + \textcircled{n \log n}$$

Note: This is actually not limited.  
The master theorem has a more general version to handle logarithm in  $f(n)$ .

**Theorem 4.1 (Master theorem)**

Let  $a > 0$  and  $b > 1$  be constants, and let  $f(n)$  be a driving function that is defined and nonnegative on all sufficiently large reals. Define the recurrence  $T(n)$  on  $n \in \mathbb{N}$  by

$$T(n) = aT(n/b) + f(n), \quad (4.17)$$

where  $aT(n/b)$  actually means  $a'T(\lfloor n/b \rfloor) + a''T(\lceil n/b \rceil)$  for some constants  $a' \geq 0$  and  $a'' \geq 0$  satisfying  $a = a' + a''$ . Then the asymptotic behavior of  $T(n)$  can be characterized as follows:

1. If there exists a constant  $\epsilon > 0$  such that  $f(n) = O(n^{\log_b a - \epsilon})$ , then  $T(n) = \Theta(n^{\log_b a})$ .
2. If there exists a constant  $k \geq 0$  such that  $f(n) = \Theta(n^{\log_b a} \lg^k n)$ , then  $T(n) = \Theta(n^{\log_b a} \lg^{k+1} n)$ .
3. If there exists a constant  $\epsilon > 0$  such that  $f(n) = \Omega(n^{\log_b a + \epsilon})$ , and if  $f(n)$  additionally satisfies the **regularity condition**  $af(n/b) \leq cf(n)$  for some constant  $c < 1$  and all sufficiently large  $n$ , then  $T(n) = \Theta(f(n))$ . ■

From CLRS 4th edition. Sec. 4.5.

The last theorem in our official slides is actual similar, easier to use, but less rigorous (For our course, may be better to use it).

# Akra–Bazzi theorem

Examples of functions that satisfy the polynomial-growth condition include any function of the form  $f(n) = \Theta(n^\alpha \lg^\beta n \lg \lg^\gamma n)$ , where  $\alpha, \beta$ , and  $\gamma$  are constants.

CLRS Sec. 4.7

**Theorem.** [Akra–Bazzi 1998] Given constants  $a_i > 0$  and  $0 < b_i < 1$ , functions  $|h_i(n)| = O(n / \log^2 n)$  and  $g(n) = O(n^c)$ . If  $T(n)$  satisfies the recurrence:

$$T(n) = \sum_{i=1}^k a_i T(b_i n + h_i(n)) + g(n)$$

**Also not limited to this form**

$\nwarrow$        $\uparrow$        $\nearrow$

$a_i$  subproblems  
of size  $b_i n$       small perturbation to handle  
floors and ceilings



then,  $T(n) = \Theta\left(n^p \left(1 + \int_1^n \frac{g(u)}{u^{p+1}} du\right)\right)$ , where  $p$  satisfies  $\sum_{i=1}^k a_i b_i^p = 1$ .

**Ex.**  $T(n) = T(\lfloor n/5 \rfloor) + T(n - 3\lfloor n/10 \rfloor) + 11/5 n$ , with  $T(0) = 0$  and  $T(1) = 0$ .

- $a_1 = 1, b_1 = 1/5, a_2 = 1, b_2 = 7/10 \Rightarrow p = 0.83978\dots < 1$ .
- $h_1(n) = \lfloor n/5 \rfloor - n/5, h_2(n) = 3/10 n - 3\lfloor n/10 \rfloor$ .
- $g(n) = 11/5 n \Rightarrow T(n) = \Theta(n)$ .

 **Master method**

**[ Master Theorem ]** Let  $a \geq 1$  and  $b > 1$  be constants, let  $f(N)$  be a function, and let  $T(N)$  be defined on the nonnegative integers by the recurrence  $T(N) = aT(N/b) + f(N)$ . Then:

1. If  $f(N) = O(N^{\underline{\log_b a - \varepsilon}})$  for some constant  $\varepsilon > 0$ , then  $T(N) = \Theta(N^{\underline{\log_b a}})$
2. If  $f(N) = \Theta(N^{\log_b a})$ , then  $T(N) = \Theta(N^{\log_b a} \log N)$  regularity condition
3. If  $f(N) = \Omega(N^{\log_b a + \varepsilon})$  for some constant  $\varepsilon > 0$ , and if  $af(N/b) < cf(N)$  for some constant  $c < 1$  and all sufficiently large  $N$ , then  $T(N) = \Theta(f(N))$

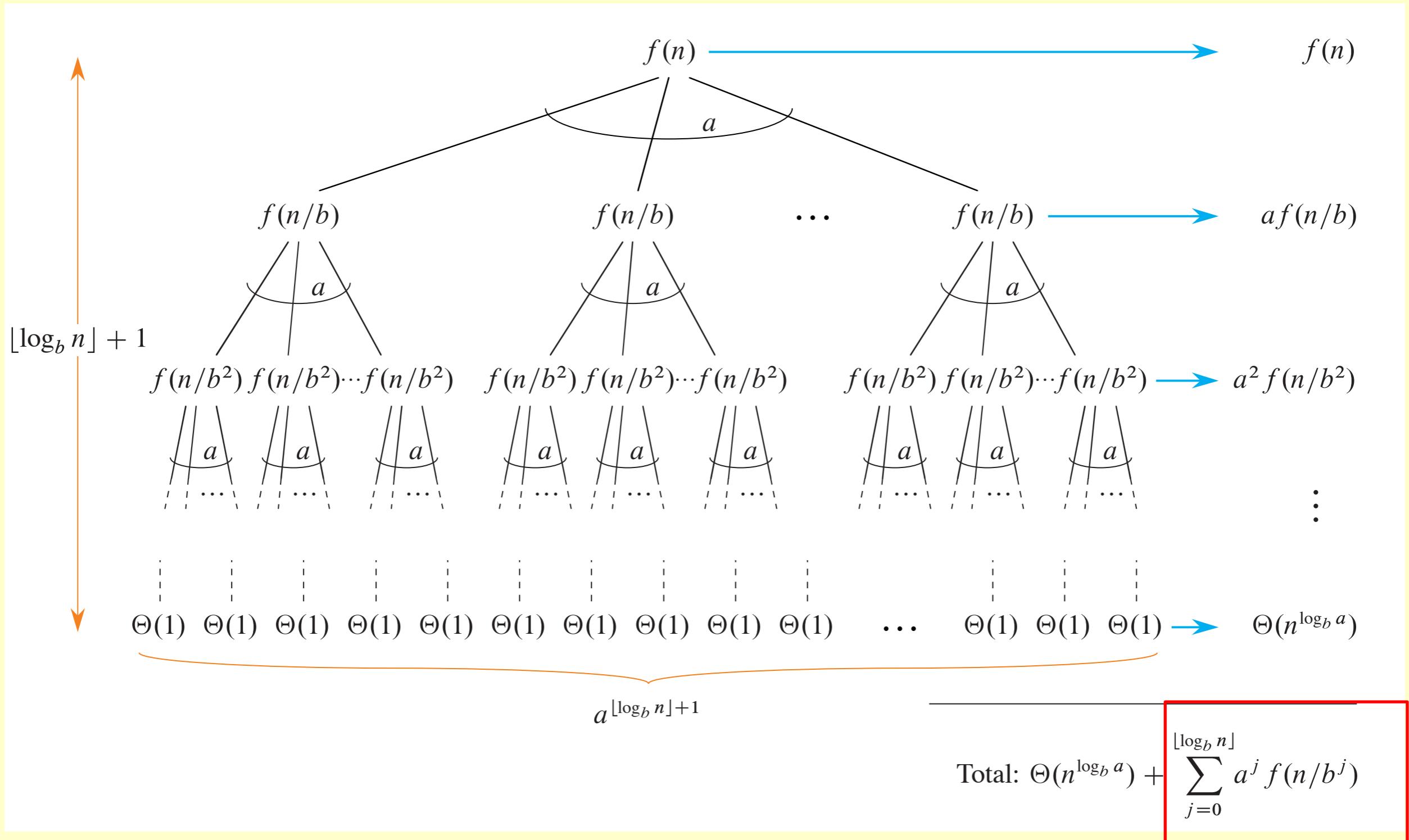
**【Example】 Mergesort has  $a = b = 2$ , and case 2**

$$\rightarrow T = O(N \log N)$$

**【Example】  $a = b = 2$ ,  $f(N) = N \log N$  ?**

$$\rightarrow T = O(N \cancel{\log} N)$$

Proof by recursion tree: for  $n = b^k$  for some integer  $k$



For case 1 where

$$f(N) = O(N^{\log_b a - \varepsilon})$$

$$\sum_{j=0}^{\log_b N - 1} a^j f(N/b^j) =$$

$$\begin{aligned} &= O(N^{\log_b a - \varepsilon} \sum_{j=0}^{\log_b N - 1} (b^\varepsilon)^j) = O(N^{\log_b a - \varepsilon} \frac{b^{\varepsilon \log_b N} - 1}{b^\varepsilon - 1}) \\ &= O(N^{\log_b a - \varepsilon} N^\varepsilon) = O(N^{\log_b a}) \end{aligned}$$

$$T(N) = \Theta(N^{\log_b a}) + O(N^{\log_b a}) = \Theta(N^{\log_b a})$$

### Discussion 9:

Please prove case 2.

Read Ch.4 of “Introduction to Algorithms” for the rest of the proof.

 **Master method – another form**

**[ Master Theorem ]** The recurrence  $T(N) = aT(N/b) + f(N)$  can be solved as follows:

1. If  $af(N/b) = \kappa f(N)$  for some constant  $\kappa < 1$ , then  $T(N) = \Theta(f(N))$
2. If  $af(N/b) = Kf(N)$  for some constant  $K > 1$ , then  $T(N) = \Theta(N^{\log_b a})$
3. If  $af(N/b) = f(N)$ , then  $T(N) = \Theta(f(N) \log_b N)$

**【Example】**  $a = 4, b = 2, f(N) = N \log N$

$$af(N/b) = 4(N/2) \log(N/2) = 2N \log N - 2N \quad ?$$

$$f(N) = N \log N \quad O(N^{\log_b a - \varepsilon}) = O(N^{2-\varepsilon})$$

$$\rightarrow T = O(N^2)$$

**[Theorem]** The solution to the equation

$$T(N) = a T(N/b) + \Theta(N^k \log^p N),$$

where  $a \geq 1$ ,  $b > 1$ , and  $p \geq 0$  is

$$T(N) = \begin{cases} O(N^{\log_b a}) & \text{if } a > b^k \\ O(N^k \log^{p+1} N) & \text{if } a = b^k \\ O(N^k \log^p N) & \text{if } a < b^k \end{cases}$$

**[Example]** Mergesort has  $a = b = 2$ ,  $p = 0$  and  $k = 1$ .

$$\rightarrow T = O(N \log N)$$

**[Example]** Divide with  $a = 3$ , and  $b = 2$  for each recursion;  
Conquer with  $O(N)$  – that is,  $k = 1$  and  $p = 0$  .

$$\rightarrow T = O(N^{1.59})$$

If conquer takes  $O(N^2)$  then  $T = O(N^2)$  .

**[Example]**  $a = b = 2$ ,  $f(N) = N \log N$   $\rightarrow T = O(N \log^2 N)$

# Divide and Conquer

- Introduction
- Closest pair of points
- Solving recurrent equations
- **Multiplication problems**
  - Integer multiplication
  - Matrix multiplication
  - Polynomial multiplication with FFT
- Take-home messages

# Integer addition and subtraction

---

Addition. Given two  $n$ -bit integers  $a$  and  $b$ , compute  $a + b$ .

Subtraction. Given two  $n$ -bit integers  $a$  and  $b$ , compute  $a - b$ .

Grade-school algorithm.  $\Theta(n)$  bit operations. ← “bit complexity”  
(instead of word RAM)

1	1	1	1	1	1	0	1
	1	1	0	1	0	1	0
+	0	1	1	1	1	1	0
	1	0	1	0	1	0	0
	1	0	1	0	1	0	0

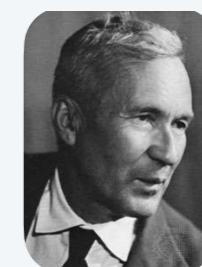
Remark. Grade-school addition and subtraction algorithms are optimal.

# Integer multiplication

Multiplication. Given two  $n$ -bit integers  $a$  and  $b$ , compute  $a \times b$ .

Grade-school algorithm (long multiplication).  $\Theta(n^2)$  bit operations.

	1	1	0	1	0	1	0	1
$\times$	0	1	1	1	1	1	0	1
	1	1	0	1	0	1	0	1
	0	0	0	0	0	0	0	0
	1	1	0	1	0	1	0	1
	1	1	0	1	0	1	0	1
	1	1	0	1	0	1	0	1
	1	1	0	1	0	1	0	1
	0	0	0	0	0	0	0	0
	0	1	1	0	1	0	0	0



Conjecture. [Kolmogorov 1956] Grade-school algorithm is optimal.

Theorem. [Karatsuba 1960] Conjecture is false.

# Divide-and-conquer multiplication

To multiply two  $n$ -bit integers  $x$  and  $y$ :

- Divide  $x$  and  $y$  into low- and high-order bits.
- Multiply **four**  $\frac{1}{2}n$ -bit integers, recursively.
- Add and shift to obtain result.

$$m = \lceil n / 2 \rceil$$

$$\begin{array}{ll} a = \lfloor x / 2^m \rfloor & b = x \bmod 2^m \\ c = \lfloor y / 2^m \rfloor & d = y \bmod 2^m \end{array}$$

← use bit shifting  
to compute 4 terms

$$x y = (2^m a + b) (2^m c + d) = 2^{2m} ac + 2^m (bc + ad) + bd$$

1                  2                  3                  4

Ex.  $x = 1\ 0\ 0\ 0\ 1\ 1\ 0\ 1$      $y = 1\ 1\ 1\ 0\ 0\ 0\ 0\ 1$

$\underbrace{\phantom{000}}_a$      $\underbrace{\phantom{00}}_b$      $\underbrace{\phantom{000}}_c$      $\underbrace{\phantom{00}}_d$

# Divide-and-conquer multiplication

**MULTIPLY**( $x, y, n$ )

**IF** ( $n = 1$ )

**RETURN**  $x \times y$ .

**ELSE**

$m \leftarrow \lceil n / 2 \rceil$ .

$a \leftarrow \lfloor x / 2^m \rfloor; b \leftarrow x \bmod 2^m$ .

$c \leftarrow \lfloor y / 2^m \rfloor; d \leftarrow y \bmod 2^m$ .

$e \leftarrow \text{MULTIPLY}(a, c, m)$ .

$f \leftarrow \text{MULTIPLY}(b, d, m)$ .

$g \leftarrow \text{MULTIPLY}(b, c, m)$ .

$h \leftarrow \text{MULTIPLY}(a, d, m)$ .

**RETURN**  $2^{2m} e + 2^m (g + h) + f$ .  $\Theta(n)$

$\Theta(n)$

$4 T(\lceil n / 2 \rceil)$

$\Theta(n)$



**How many bit operations to multiply two  $n$ -bit integers using the divide-and-conquer multiplication algorithm?**

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 4T(\lceil n/2 \rceil) + \Theta(n) & \text{if } n > 1 \end{cases}$$

- A.**  $T(n) = \Theta(n^{1/2})$ .
- B.**  $T(n) = \Theta(n \log n)$ .
- C.**  $T(n) = \Theta(n^{\log_2 3}) = O(n^{1.585})$ .
- D.**  $T(n) = \Theta(n^2)$ .

The mathematician Carl Friedrich Gauss (1777–1855) once noticed that although the product of two complex numbers

$$(a + bi)(c + di) = ac - bd + (bc + ad)i$$

seems to involve *four* real-number multiplications, it can in fact be done with just *three*:  $ac$ ,  $bd$ , and  $(a + b)(c + d)$ , since

$$bc + ad = (a + b)(c + d) - ac - bd.$$



# Karatsuba trick

To multiply two  $n$ -bit integers  $x$  and  $y$ :

- Divide  $x$  and  $y$  into low- and high-order bits.
- To compute middle term  $bc + ad$ , use identity:

$$bc + ad = ac + bd - (a - b)(c - d)$$

- Multiply only three  $\frac{1}{2}n$ -bit integers, recursively.

$$m = \lceil n / 2 \rceil$$

$$a = \lfloor x / 2^m \rfloor \quad b = x \bmod 2^m$$

$$c = \lfloor y / 2^m \rfloor \quad d = y \bmod 2^m$$

$$x y = (2^m a + b) (2^m c + d) = 2^{2m} ac + 2^m (bc + ad) + bd$$

$$= 2^{2m} ac + 2^m (ac + bd - (a - b)(c - d)) + bd$$

1

1

3

2

3

$$x = 1 \overbrace{000}^a \overbrace{1101}^b 1$$

$$y = 1 \overbrace{110}^c \overbrace{0001}^d 1$$

# Karatsuba multiplication

**KARATSUBA-MULTIPLY( $x, y, n$ )**

IF ( $n = 1$ )

RETURN  $x \times y$ .

ELSE

$m \leftarrow \lceil n / 2 \rceil$ .

$a \leftarrow \lfloor x / 2^m \rfloor; b \leftarrow x \bmod 2^m$ .

$c \leftarrow \lfloor y / 2^m \rfloor; d \leftarrow y \bmod 2^m$ .

$e \leftarrow \text{KARATSUBA-MULTIPLY}(a, c, m)$ .

$f \leftarrow \text{KARATSUBA-MULTIPLY}(b, d, m)$ .

$g \leftarrow \text{KARATSUBA-MULTIPLY}(|a - b|, |c - d|, m)$ .

Flip sign of  $g$  if needed.

RETURN  $2^{2m} e + 2^m (e + f - g) + f$ . —————  $\Theta(n)$

—————  $\Theta(n)$

—————  $3 T(\lceil n / 2 \rceil)$

## Karatsuba analysis

---

**Proposition.** Karatsuba's algorithm requires  $O(n^{1.585})$  bit operations to multiply two  $n$ -bit integers.

**Pf.** Apply Case 3 of the master theorem to the recurrence:

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 3T(\lceil n/2 \rceil) + \Theta(n) & \text{if } n > 1 \end{cases}$$

$$\implies T(n) = \Theta(n^{\log_2 3}) = O(n^{1.585})$$

**Practice.**

- Use base 32 or 64 (instead of base 2).
- Faster than grade-school algorithm for about 320–640 bits.

# Integer arithmetic reductions

Integer multiplication. Given two  $n$ -bit integers, compute their product.

arithmetic problem	formula	bit complexity
integer multiplication	$a \times b$	$M(n)$
integer square	$a^2$	$\Theta(M(n))$
integer division	$\lfloor a / b \rfloor, a \bmod b$	$\Theta(M(n))$
integer square root	$\lfloor \sqrt{a} \rfloor$	$\Theta(M(n))$

integer arithmetic problems with the same bit complexity  $M(n)$  as integer multiplication

$$ab = \frac{(a+b)^2 - a^2 - b^2}{2}$$



# History of asymptotic complexity of integer multiplication

year	algorithm	bit operations
12xx	grade school	$O(n^2)$
1962	Karatsuba-Ofman	$O(n^{1.585})$
1963	Toom-3, Toom-4	$O(n^{1.465}), O(n^{1.404})$
1966	Toom-Cook	$O(n^{1+\varepsilon})$
1971	Schönhage-Strassen	$O(n \log n \cdot \log \log n)$
2007	Fürer	$n \log n 2^{O(\log^* n)}$
2019	Harvey-van der Hoeven	$O(n \log n)$
	???	$O(n)$

number of bit operations to multiply two  $n$ -bit integers

Remark. GNU Multiple Precision library uses one of first five algorithms depending on  $n$ .



used in Maple, Mathematica, gcc, cryptography, ...

**GMP**  
«Arithmetic without limitations»

# Divide and Conquer

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## Dot product

---

Dot product. Given two length- $n$  vectors  $a$  and  $b$ , compute  $c = a \cdot b$ .

Grade-school.  $\Theta(n)$  arithmetic operations.

$$a \cdot b = \sum_{i=1}^n a_i b_i$$

$$a = [ .70 \quad .20 \quad .10 ]$$

$$b = [ .30 \quad .40 \quad .30 ]$$

$$a \cdot b = (.70 \times .30) + (.20 \times .40) + (.10 \times .30) = .32$$

Remark. “Grade-school” dot product algorithm is asymptotically optimal.

# Matrix multiplication

---

**Matrix multiplication.** Given two  $n$ -by- $n$  matrices  $A$  and  $B$ , compute  $C = AB$ .

**Grade-school.**  $\Theta(n^3)$  arithmetic operations.

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$\begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1n} \\ c_{21} & c_{22} & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \cdots & c_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{nn} \end{bmatrix}$$

$$\begin{bmatrix} .59 & .32 & .41 \\ .31 & .36 & .25 \\ .45 & .31 & .42 \end{bmatrix} = \begin{bmatrix} .70 & .20 & .10 \\ .30 & .60 & .10 \\ .50 & .10 & .40 \end{bmatrix} \times \begin{bmatrix} .80 & .30 & .50 \\ .10 & .40 & .10 \\ .10 & .30 & .40 \end{bmatrix}$$

**Q.** Is “grade-school” matrix multiplication algorithm asymptotically optimal?

# Block matrix multiplication

$$\begin{matrix}
 & C_{11} \\
 & \searrow \\
 \left[ \begin{array}{cccc}
 152 & 158 & 164 & 170 \\
 504 & 526 & 548 & 570 \\
 856 & 894 & 932 & 970 \\
 1208 & 1262 & 1316 & 1370
 \end{array} \right] & = & \left[ \begin{array}{cc|cc}
 0 & 1 & 2 & 3 \\
 4 & 5 & 6 & 7 \\
 \hline
 8 & 9 & 10 & 11 \\
 12 & 13 & 14 & 15
 \end{array} \right] & \times & \left[ \begin{array}{cccc}
 16 & 17 & 18 & 19 \\
 20 & 21 & 22 & 23 \\
 24 & 25 & 26 & 27 \\
 28 & 29 & 30 & 31
 \end{array} \right]
 \end{matrix}$$

$A_{11}$        $A_{12}$        $B_{11}$   
 $B_{21}$

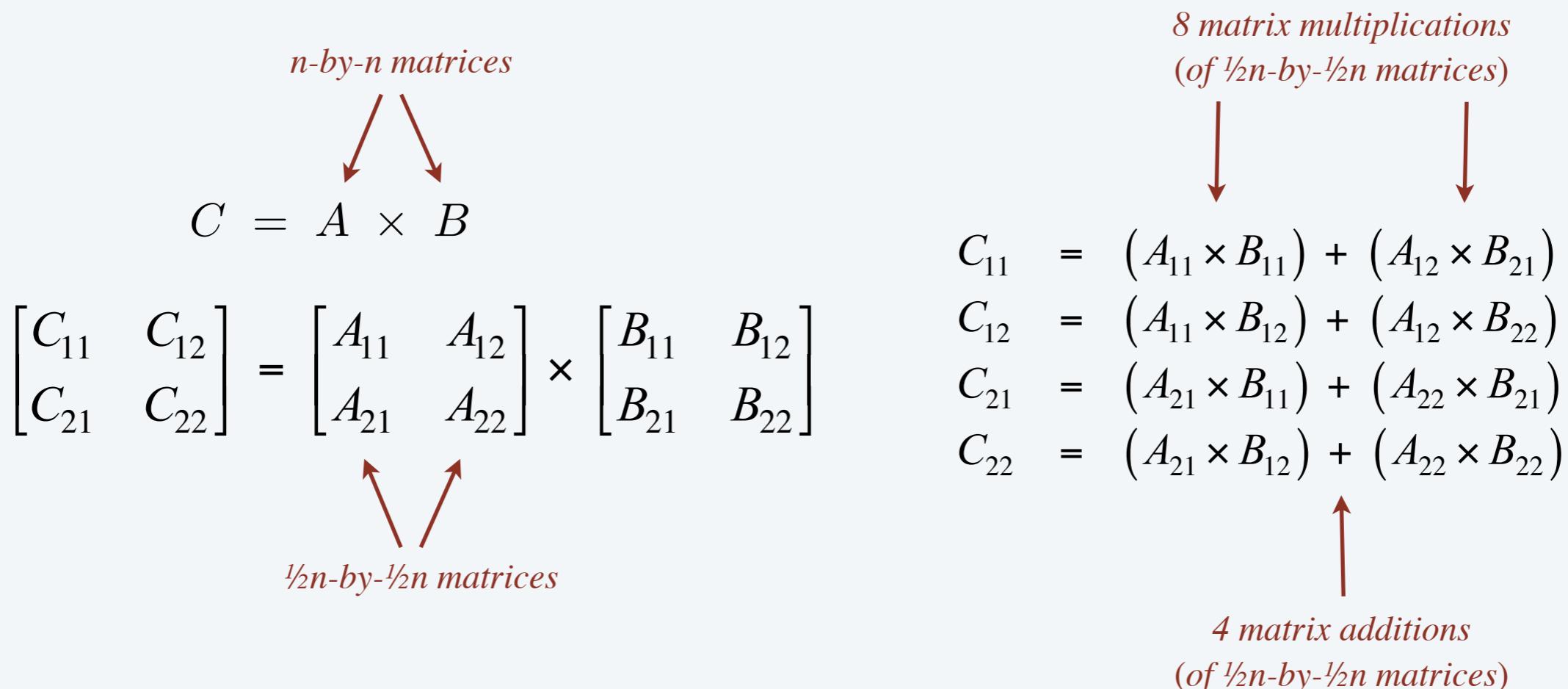
$$C_{11} = A_{11} \times B_{11} + A_{12} \times B_{21} = \begin{bmatrix} 0 & 1 \\ 4 & 5 \end{bmatrix} \times \begin{bmatrix} 16 & 17 \\ 20 & 21 \end{bmatrix} + \begin{bmatrix} 2 & 3 \\ 6 & 7 \end{bmatrix} \times \begin{bmatrix} 24 & 25 \\ 28 & 29 \end{bmatrix} = \begin{bmatrix} 152 & 158 \\ 504 & 526 \end{bmatrix}$$

# Block matrix multiplication: warmup

---

To multiply two  $n$ -by- $n$  matrices  $A$  and  $B$ :

- Divide: partition  $A$  and  $B$  into  $\frac{1}{2}n$ -by- $\frac{1}{2}n$  blocks.
- Conquer: multiply 8 pairs of  $\frac{1}{2}n$ -by- $\frac{1}{2}n$  matrices, recursively.
- Combine: add appropriate products using 4 matrix additions.



**Running time.** Apply Case 3 of the master theorem.

$$T(n) = \underbrace{8T(n/2)}_{\text{recursive calls}} + \underbrace{\Theta(n^2)}_{\text{add, form submatrices}} \Rightarrow T(n) = \Theta(n^3)$$

## Strassen's trick

**Key idea.** Can multiply two 2-by-2 matrices via 7 scalar multiplications (plus 11 additions and 7 subtractions).

$$\begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}$$

*scalars*



$$C_{11} = P_5 + P_4 - P_2 + P_6$$

$$C_{12} = P_1 + P_2$$

$$C_{21} = P_3 + P_4$$

$$C_{22} = P_1 + P_5 - P_3 - P_7$$

$$P_1 \leftarrow A_{11} \times (B_{12} - B_{22})$$

$$P_2 \leftarrow (A_{11} + A_{12}) \times B_{22}$$

$$P_3 \leftarrow (A_{21} + A_{22}) \times B_{11}$$

$$P_4 \leftarrow A_{22} \times (B_{21} - B_{11})$$

$$P_5 \leftarrow (A_{11} + A_{22}) \times (B_{11} + B_{22})$$

$$P_6 \leftarrow (A_{12} - A_{22}) \times (B_{21} + B_{22})$$

$$P_7 \leftarrow (A_{11} - A_{21}) \times (B_{11} + B_{12})$$



*7 scalar multiplications*

Pf.  $C_{12} = P_1 + P_2$

$$= A_{11} \times (B_{12} - B_{22}) + (A_{11} + A_{12}) \times B_{22}$$

$$= A_{11} \times B_{12} + A_{12} \times B_{22}. \quad \checkmark$$

# Strassen's trick

*n*-by-*n*       $\frac{1}{2}n$ -by- $\frac{1}{2}n$  matrix  
**Key idea.** Can multiply two ~~2-by-2~~ matrices via 7 ~~scalar~~ multiplications  
 (plus 11 additions and 7 subtractions).

$\frac{1}{2}n$ -by- $\frac{1}{2}n$  matrices

$$\begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}$$


$$C_{11} = P_5 + P_4 - P_2 + P_6$$

$$C_{12} = P_1 + P_2$$

$$C_{21} = P_3 + P_4$$

$$C_{22} = P_1 + P_5 - P_3 - P_7$$

$$P_1 \leftarrow A_{11} \times (B_{12} - B_{22})$$

$$P_2 \leftarrow (A_{11} + A_{12}) \times B_{22}$$

$$P_3 \leftarrow (A_{21} + A_{22}) \times B_{11}$$

$$P_4 \leftarrow A_{22} \times (B_{21} - B_{11})$$

$$P_5 \leftarrow (A_{11} + A_{22}) \times (B_{11} + B_{22})$$

$$P_6 \leftarrow (A_{12} - A_{22}) \times (B_{21} + B_{22})$$

$$P_7 \leftarrow (A_{11} - A_{21}) \times (B_{11} + B_{12})$$



*7 matrix multiplications  
 (of  $\frac{1}{2}n$ -by- $\frac{1}{2}n$  matrices)*

**Pf.**  $C_{12} = P_1 + P_2$   
 $= A_{11} \times (B_{12} - B_{22}) + (A_{11} + A_{12}) \times B_{22}$   
 $= A_{11} \times B_{12} + A_{12} \times B_{22}. \quad \checkmark$

# Strassen's algorithm

assume  $n$  is a power of 2  
STRASSEN( $n, A, B$ )

IF ( $n = 1$ ) RETURN  $A \times B$ .

Partition  $A$  and  $B$  into  $\frac{1}{2}n$ -by- $\frac{1}{2}n$  blocks.

$P_1 \leftarrow \text{STRASSEN}(n / 2, A_{11}, (B_{12} - B_{22}))$ .

$P_2 \leftarrow \text{STRASSEN}(n / 2, (A_{11} + A_{12}), B_{22})$ .

$P_3 \leftarrow \text{STRASSEN}(n / 2, (A_{21} + A_{22}), B_{11})$ .

$P_4 \leftarrow \text{STRASSEN}(n / 2, A_{22}, (B_{21} - B_{11}))$ .

$P_5 \leftarrow \text{STRASSEN}(n / 2, (A_{11} + A_{22}), (B_{11} + B_{22}))$ .

$P_6 \leftarrow \text{STRASSEN}(n / 2, (A_{12} - A_{22}), (B_{21} + B_{22}))$ .

$P_7 \leftarrow \text{STRASSEN}(n / 2, (A_{11} - A_{21}), (B_{11} + B_{12}))$ .

$C_{11} = P_5 + P_4 - P_2 + P_6$ .

$C_{12} = P_1 + P_2$ .

$C_{21} = P_3 + P_4$ .

$C_{22} = P_1 + P_5 - P_3 - P_7$ .

RETURN  $C$ .

$\leftarrow 7 T(n / 2) + \Theta(n^2)$

$\leftarrow \Theta(n^2)$

$$\begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}$$

# Analysis of Strassen's algorithm

**Theorem.** Strassen's algorithm requires  $O(n^{2.81})$  arithmetic operations to multiply two  $n$ -by- $n$  matrices.

## Gaussian Elimination is not Optimal

VOLKER STRASSEN\*

Received December 12, 1968

1. Below we will give an algorithm which computes the coefficients of the product of two square matrices  $A$  and  $B$  of order  $n$  from the coefficients of  $A$  and  $B$  with less than  $4.7 \cdot n^{\log 7}$  arithmetical operations (all logarithms in this paper are for base 2, thus  $\log 7 \approx 2.8$ ; the usual method requires approximately  $2n^3$  arithmetical operations). The algorithm induces algorithms for inverting a matrix of order  $n$ , solving a system of  $n$  linear equations in  $n$  unknowns, computing a determinant of order  $n$  etc. all requiring less than  $\text{const } n^{\log 7}$  arithmetical operations.



# Analysis of Strassen's algorithm

---

**Theorem.** Strassen's algorithm requires  $O(n^{2.81})$  arithmetic operations to multiply two  $n$ -by- $n$  matrices.

Pf.

- When  $n$  is a power of 2, apply Case 1 of the master theorem:

$$T(n) = \underbrace{7T(n/2)}_{\text{recursive calls}} + \underbrace{\Theta(n^2)}_{\text{add, subtract}} \Rightarrow T(n) = \Theta(n^{\log_2 7}) = O(n^{2.81})$$

- When  $n$  is not a power of 2, pad matrices with zeros to be  $n'$ -by- $n'$ , where  $n \leq n' < 2n$  and  $n'$  is a power of 2.

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 7 & 8 & 9 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 10 & 11 & 12 & 0 \\ 13 & 14 & 15 & 0 \\ 16 & 17 & 18 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 84 & 90 & 96 & 0 \\ 201 & 216 & 231 & 0 \\ 318 & 342 & 366 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

# Strassen's algorithm: practice

---

## Implementation issues.

- Sparsity.
- Caching.
- $n$  not a power of 2.
- Numerical stability.
- Non-square matrices.
- Storage for intermediate submatrices.
- Crossover to classical algorithm when  $n$  is “small.”
- Parallelism for multi-core and many-core architectures.

**Common misconception.** “*Strassen’s algorithm is only a theoretical curiosity.*”

- Apple reports 8x speedup when  $n \approx 2,048$ .
- Range of instances where it’s useful is a subject of controversy.

### Strassen’s Algorithm Reloaded

Jianyu Huang\*, Tyler M. Smith\*†, Greg M. Henry‡, Robert A. van de Geijn\*†

\*Department of Computer Science and †Institute for Computational Engineering and Sciences,

The University of Texas at Austin, Austin, TX 78712

Email: jianyu,tms,rvdg@cs.utexas.edu

‡Intel Corporation, Hillsboro, OR 97124

Email: greg.henry@intel.com



Suppose that you could multiply two 3-by-3 matrices with 21 scalar multiplications. How fast could you multiply two n-by-n matrices?

- A.  $\Theta(n^{\log_3 21})$
- B.  $\Theta(n^{\log_2 21})$
- C.  $\Theta(n^{\log_9 21})$
- D.  $\Theta(n^2)$



**Is it possible to multiply two 3-by-3 matrices using only 21 scalar multiplications?**

- A.** Yes.
- B.** No.
- C.** Unknown.

## Fast matrix multiplication: theory

---

Q. Multiply two 2-by-2 matrices with 7 scalar multiplications?

A. Yes! [Strassen 1969]  $\Theta(n^{\log_2 7}) = O(n^{2.81})$

Q. Multiply two 2-by-2 matrices with 6 scalar multiplications?

A. Impossible. [Hopcroft–Kerr, Winograd 1971]  $\Theta(n^{\log_2 6}) = O(n^{2.59})$

Begun, the decimal wars have. [Pan 1978, Bini et al., Schönhage, ...]

- Two 70-by-70 matrices with 143,640 scalar multiplications.  $O(n^{2.7962})$
- Two 48-by-48 matrices with 47,217 scalar multiplications.  $O(n^{2.7801})$
- A year later.  $O(n^{2.7799})$
- December 1979.  $O(n^{2.521813})$
- January 1980.  $O(n^{2.521801})$

# History of arithmetic complexity of matrix multiplication

year	algorithm	arithmetic operations
1858	“grade school”	$O(n^3)$
1969	Strassen	$O(n^{2.808})$
1978	Pan	$O(n^{2.796})$
1979	Bini	$O(n^{2.780})$
1981	Schönhage	$O(n^{2.522})$
1982	Romani	$O(n^{2.517})$
1982	Coppersmith-Winograd	$O(n^{2.496})$
1986	Strassen	$O(n^{2.479})$
1989	Coppersmith-Winograd	$O(n^{2.3755})$
2010	Strother	$O(n^{2.3737})$
2011	Williams	$O(n^{2.372873})$
2014	Le Gall	$O(n^{2.372864})$
	???	$O(n^{2+\varepsilon})$

galactic algorithms

number of arithmetic operations to multiply two n-by-n matrices

# Numeric linear algebra reductions

---

**Matrix multiplication.** Given two  $n$ -by- $n$  matrices, compute their product.

linear algebra problem	expression	arithmetic complexity
<b>matrix multiplication</b>	$A \times B$	$MM(n)$
<b>matrix squaring</b>	$A^2$	$\Theta(MM(n))$
<b>matrix inversion</b>	$A^{-1}$	$\Theta(MM(n))$
<b>determinant</b>	$ A $	$\Theta(MM(n))$
<b>rank</b>	$rank(A)$	$\Theta(MM(n))$
<b>system of linear equations</b>	$Ax = b$	$\Theta(MM(n))$
<b>LU decomposition</b>	$A = L U$	$\Theta(MM(n))$
<b>least squares</b>	$\min \ Ax - b\ _2$	$\Theta(MM(n))$

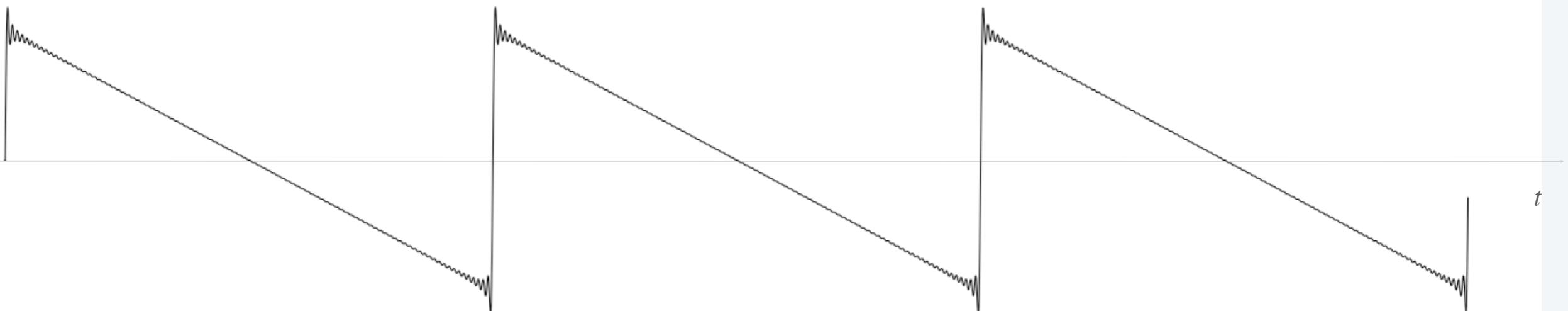
numerical linear algebra problems with the same  
arithmetic complexity  $MM(n)$  as matrix multiplication

# Divide and Conquer

- Introduction
- Closest pair of points
- Solving recurrent equations
- **Multiplication problems**
  - Integer multiplication
  - Matrix multiplication
  - **Polynomial multiplication with FFT**
- Take-home messages

# Fourier analysis

**Fourier theorem.** [Fourier, Dirichlet, Riemann] Any (sufficiently smooth) periodic function can be expressed as the sum of a series of sinusoids.



$$y(t) = \frac{2}{\pi} \sum_{k=1}^n \frac{\sin kt}{k} \quad n = 100$$

## Euler's identity

---

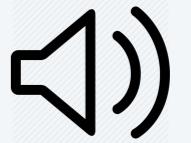
Euler's identity.  $e^{ix} = \cos x + i \sin x.$

Sinusoids. Sum of sine and cosines = sum of complex exponentials.

# Time domain vs. frequency domain

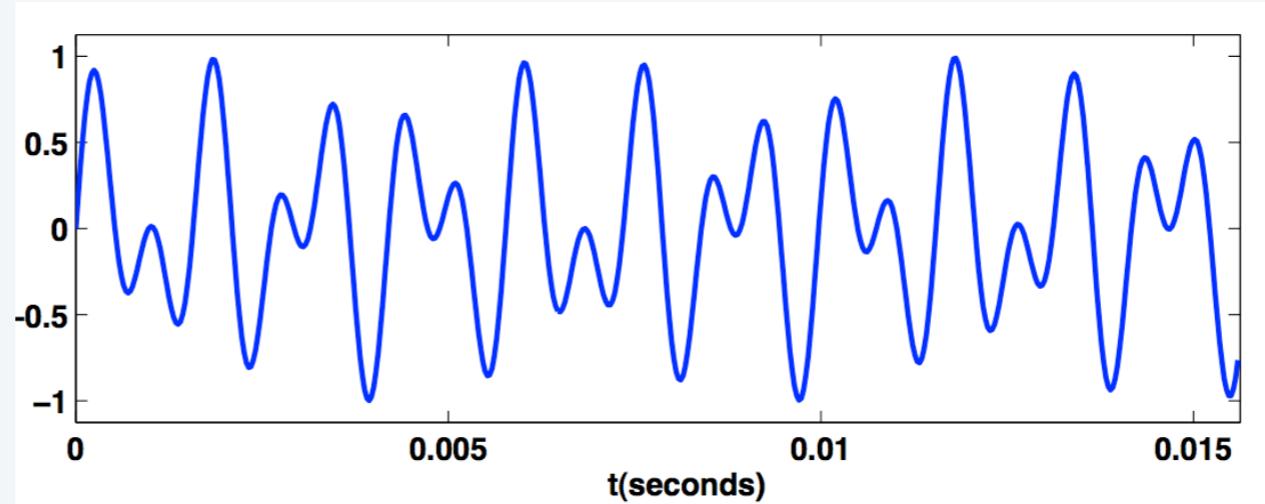
Signal. [touch tone button 1]

$$y(t) = \frac{1}{2} \sin(2\pi \cdot 697 t) + \frac{1}{2} \sin(2\pi \cdot 1209 t)$$



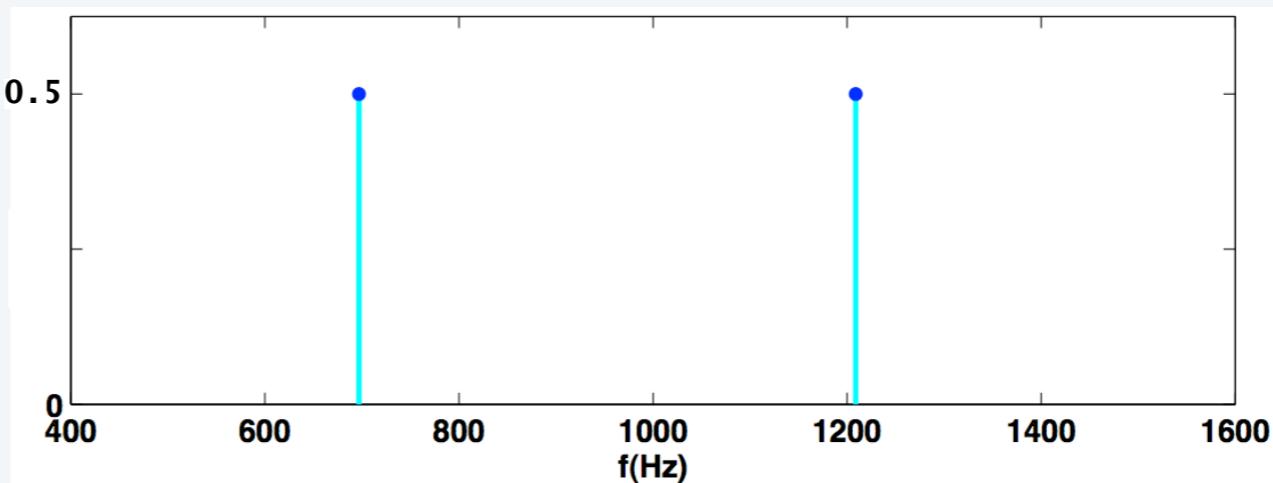
Time domain.

sound  
pressure



Frequency domain.

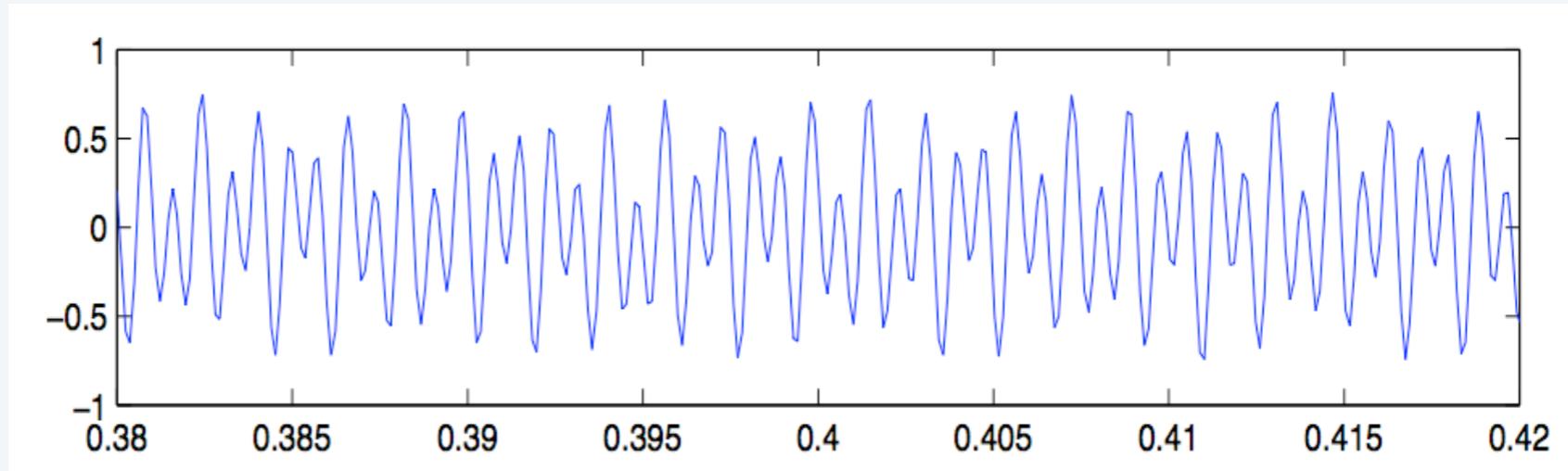
amplitude



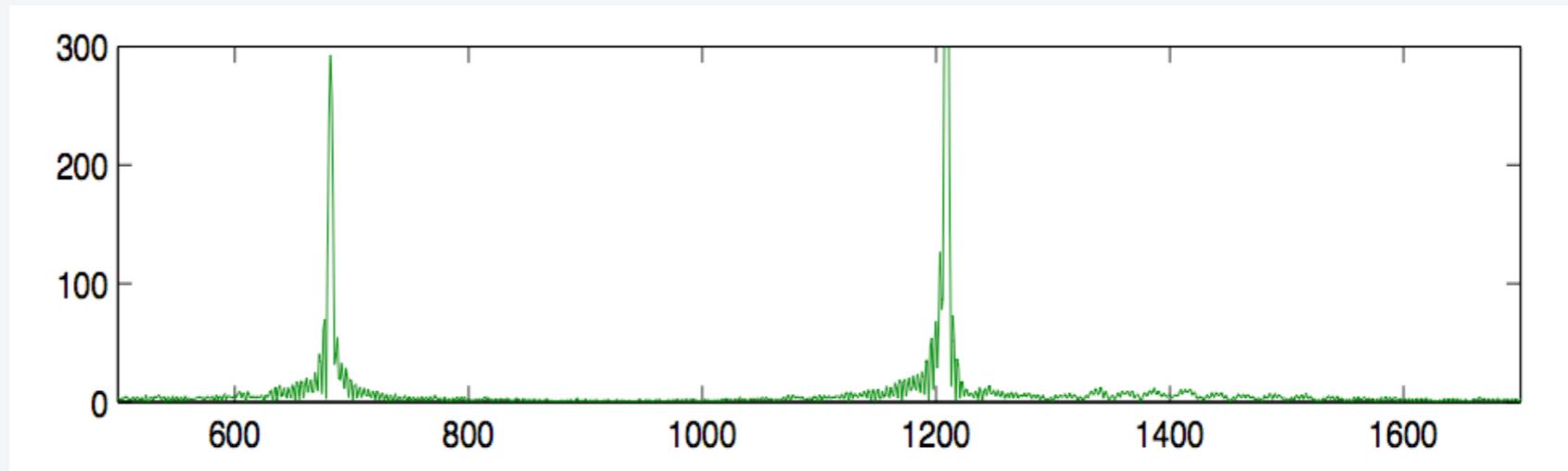
# Time domain vs. frequency domain

---

Signal. [recording, 8192 samples per second]



Magnitude of discrete Fourier transform.



# Fast Fourier transform

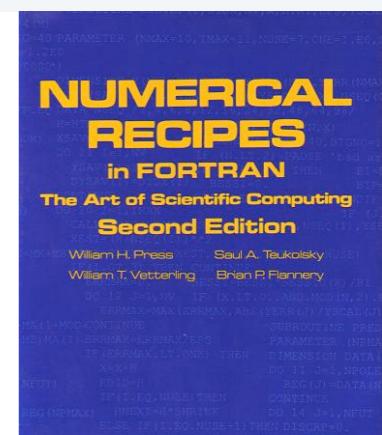
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FFT. Fast way to convert between time domain and frequency domain.

Alternate viewpoint. Fast way to multiply and evaluate polynomials.

we take this approach

*“If you speed up any nontrivial algorithm by a factor of a million or so the world will beat a path towards finding useful applications for it.” — Numerical Recipes*



# Fast Fourier transform: applications

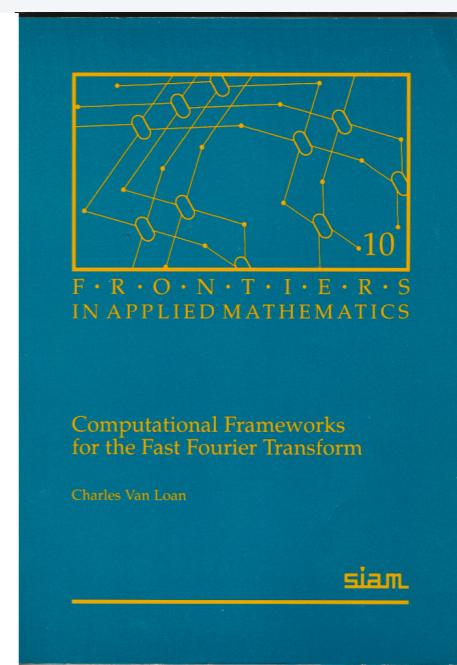
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## Applications.

- Optics, acoustics, quantum physics, telecommunications, radar, control systems, signal processing, speech recognition, data compression, image processing, seismology, mass spectrometry, ...
- Digital media. [DVD, JPEG, MP3, H.264]
- Medical diagnostics. [MRI, CT, PET scans, ultrasound]
- Numerical solutions to Poisson's equation.
- Integer and polynomial multiplication.
- Shor's quantum factoring algorithm.
- ...

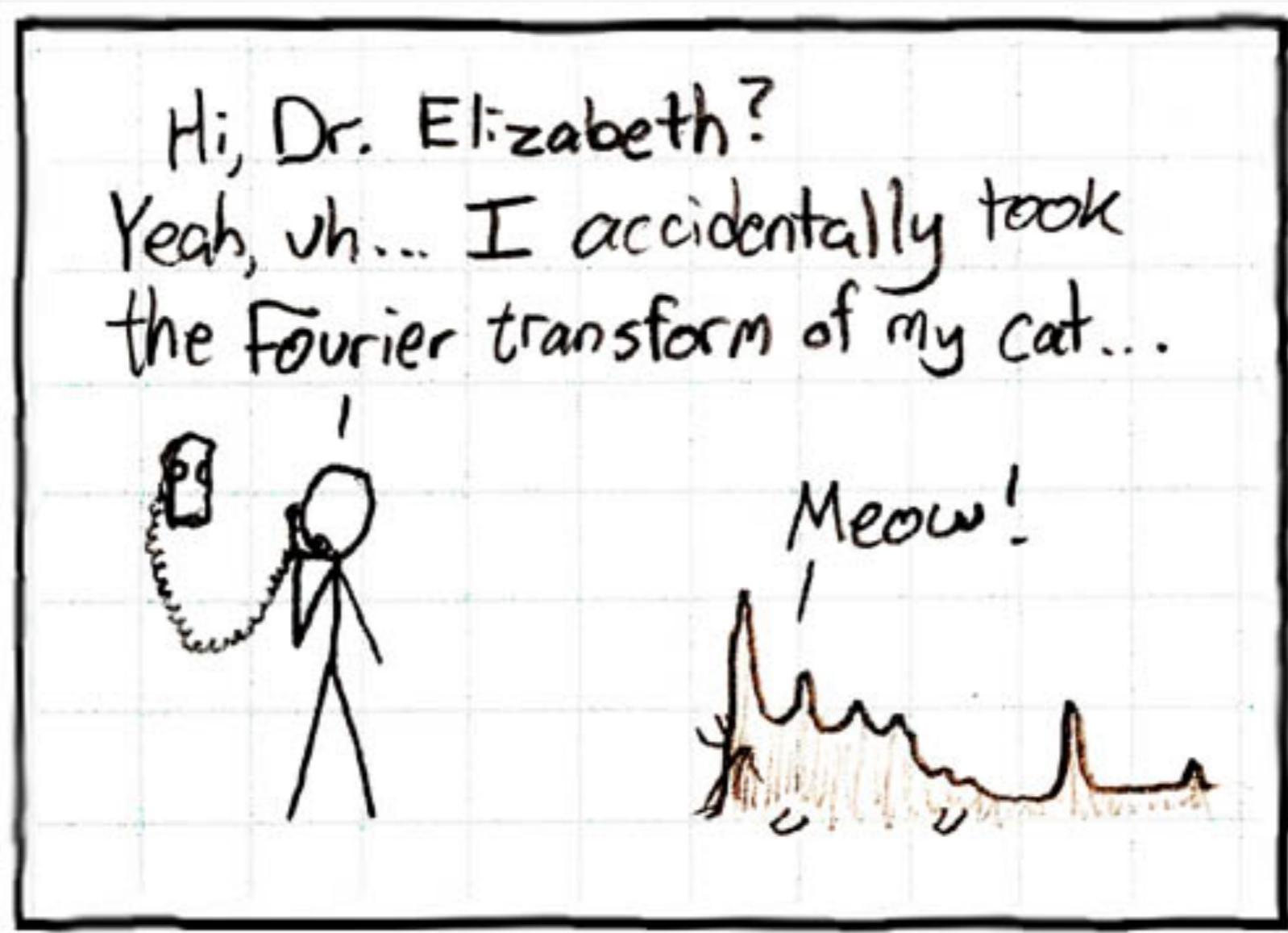
*“The FFT is one of the truly great computational developments of [the 20th] century. It has changed the face of science and engineering so much that it is not an exaggeration to say that life as we know it would be very different without the FFT.”*

— Charles van Loan



## Fast Fourier transform: applications

---



<https://xkcd.com/26>

# Fast Fourier transform: brief history

---

Gauss (1805, 1866). Analyzed periodic motion of asteroid Ceres.

Runge–König (1924). Laid theoretical groundwork.

Danielson–Lanczos (1942). Efficient algorithm, x-ray crystallography.

Cooley–Tukey (1965). Detect nuclear tests in Soviet Union and track submarines. Rediscovered and popularized FFT.



## An Algorithm for the Machine Calculation of Complex Fourier Series

By James W. Cooley and John W. Tukey

An efficient method for the calculation of the interactions of a  $2^m$  factorial experiment was introduced by Yates and is widely known by his name. The generalization to  $3^m$  was given by Box et al. [1]. Good [2] generalized these methods and gave elegant algorithms for which one class of applications is the calculation of Fourier series. In their full generality, Good's methods are applicable to certain problems in which one must multiply an  $N$ -vector by an  $N \times N$  matrix which can be factored into  $m$  sparse matrices, where  $m$  is proportional to  $\log N$ . This results in a procedure requiring a number of operations proportional to  $N \log N$  rather than  $N^2$ .



Importance not fully realized until emergence of digital computers.



**What was the subject of Gauss' Ph.D thesis?**

- A. Gaussian elimination.
- B. Fast Fourier transform.
- C. Prime number theorem.
- D. Cauchy integral theorem.
- E. Fundamental theorem of algebra.
- F. Angle-preserving maps.
- G. Method of least squares.
- H. Non-Euclidean geometry.
- I. Constructing a regular heptadecagon with straightedge and compass.

# A modest Ph.D. dissertation title

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DEMONSTRATIO NOVA  
THEOREMATIC  
OMNEM FVNCTIONEM ALGEBRAICAM  
RATIONALEM INTEGRAM  
VNIVS VARIABILIS  
IN FACTORES REALES PRIMI VEL SECUNDI GRADVS  
RESOLVI POSSE

AVCTORE  
CAROLO FRIDERICO GAVSS  
HELMSTADII  
APVD C. G. FLECKEISEN. 1799

1.

Quaelibet aequatio algebraica determinata reduci potest ad formam  $x^m + Ax^{m-1} + Bx^{m-2} + \dots + M = 0$ , ita vt  $m$  sit numerus integer positivus. Si partem primam huius aequationis per  $X$  denotamus, aequationique  $X=0$  per plures valores inaequales ipsius  $x$  satisfieri supponimus, puta ponendo  $x=\alpha, x=\beta, x=\gamma$  etc. functio  $X$  per productum e factoribus  $x-\alpha, x-\beta, x-\gamma$  etc. diuisibilis erit. Vice versa, si productum e pluribus factoribus simplicibus  $x-\alpha, x-\beta, x-\gamma$  etc. functionem  $X$  metitur: aequationi  $X=0$  satisfiet, aquando ipsam  $x$  cuicunque quantitatum  $\alpha, \beta, \gamma$  etc. Denique si  $X$  producto ex  $m$  factoribus talibus simplicibus aequalis est (siue omnes diuersi sint, siue quidam ex ipsis identici): alii factores simplices praeter hos functionem  $X$  metiri non poterunt. Quamobrem aequatio  $m^{ti}$  gradus plures quam  $m$  radices habere nequit; simul vero patet, aequationem  $m^{ti}$  gradus pauciores radices habere posse, etsi  $X$  in  $m$  factores simplices resolubilis sit:

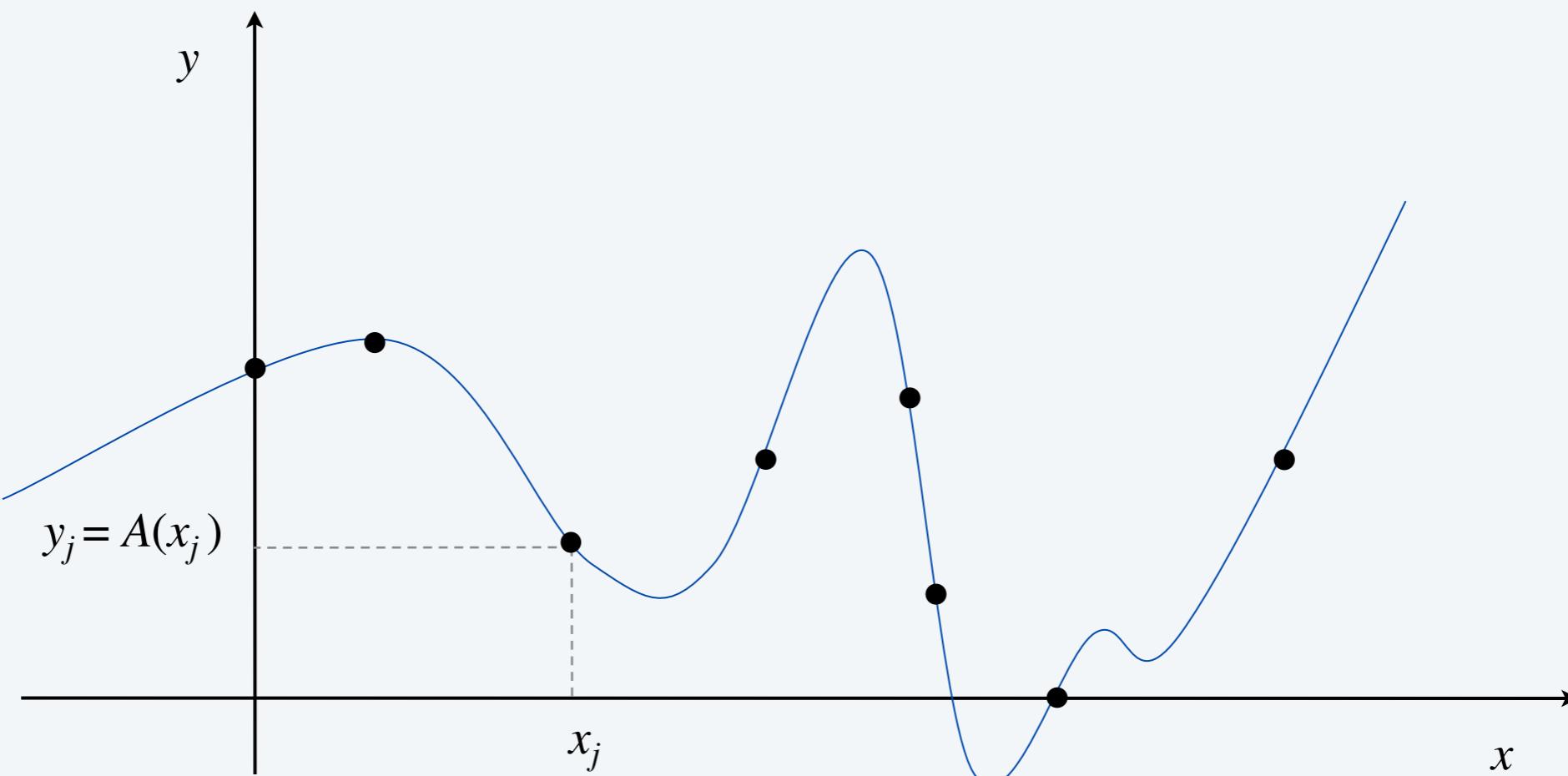
**“ New proof of the theorem that every algebraic rational integral function in one variable can be resolved into real factors of the first or the second degree. ”**

## Polynomials: point-value representation

---

Fundamental theorem of algebra. A degree  $n$  univariate polynomial with complex coefficients has exactly  $n$  complex roots.

Corollary. A degree  $n - 1$  univariate polynomial  $A(x)$  is uniquely specified by its evaluation at  $n$  distinct values of  $x$ .



# Polynomials: point-value representation

---

Univariate polynomial. [ point-value representation ]

$A(x)$ :  $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$

$B(x)$ :  $(x_0, z_0), \dots, (x_{n-1}, z_{n-1})$

Addition.  $O(n)$  arithmetic operations.

$A(x) + B(x)$ :  $(x_0, y_0 + z_0), \dots, (x_{n-1}, y_{n-1} + z_{n-1})$

Multiplication.  $O(n)$ , but represent  $A(x)$  and  $B(x)$  using  $2n$  points.

$A(x) \times B(x)$ :  $(x_0, y_0 \times z_0), \dots, (x_{2n-1}, y_{2n-1} \times z_{2n-1})$

Evaluation.  $O(n^2)$  using Lagrange's formula.

$$A(x) = \sum_{k=0}^{n-1} y_k \frac{\prod_{j \neq k} (x - x_j)}{\prod_{j \neq k} (x_k - x_j)}$$

← not used

# Converting between two representations

Tradeoff. Either fast evaluation or fast multiplication. We want both!

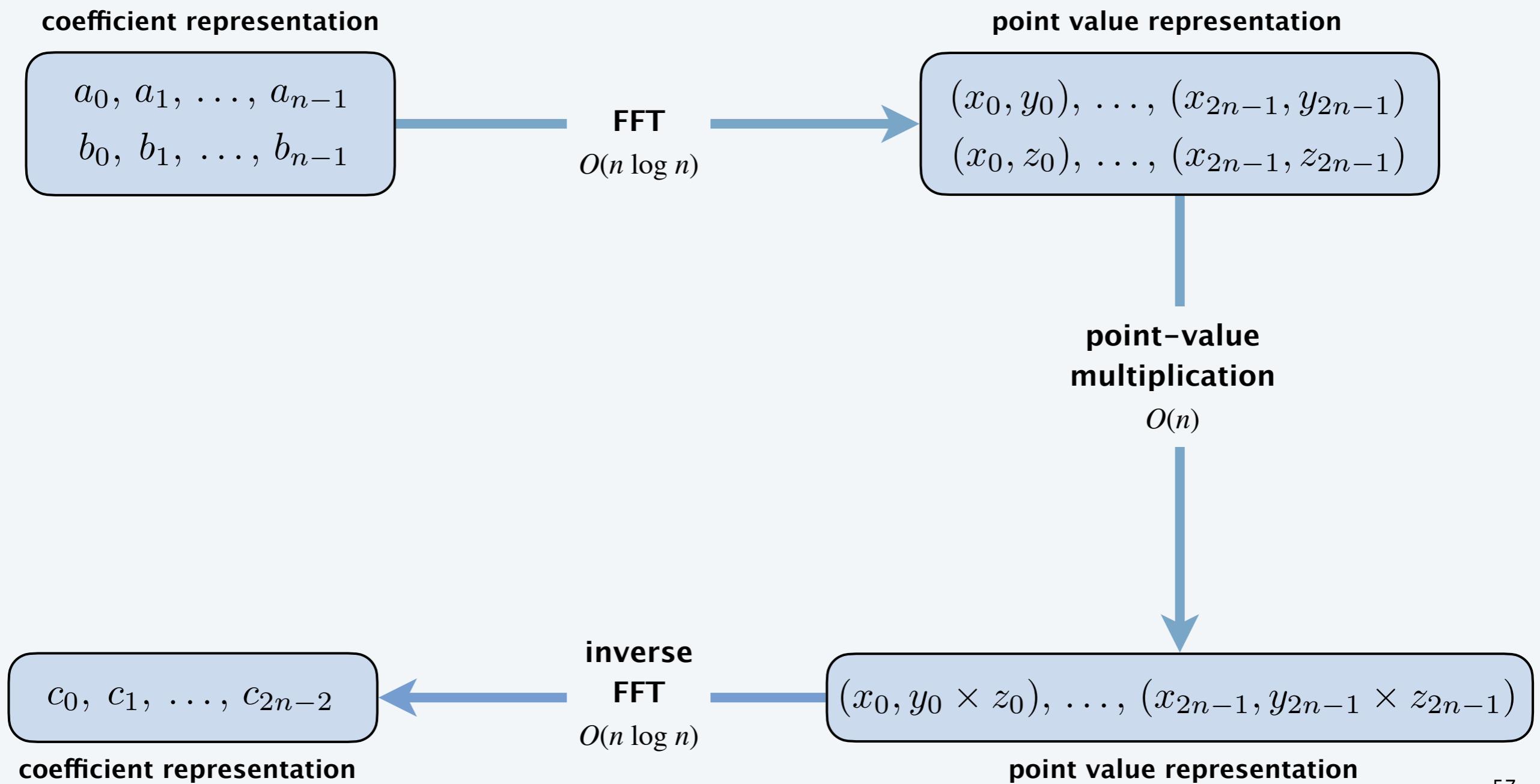
representation	multiply	evaluate
coefficient	$O(n^2)$	$O(n)$
point-value	$O(n)$	$O(n^2)$

Goal. Efficient conversion between two representations  $\Rightarrow$  all ops fast.



# Converting between two representations

Application. Polynomial multiplication (coefficient representation).



## Converting between two representations: brute force

---

Coefficient  $\Rightarrow$  point-value. Given a polynomial  $A(x) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$ , evaluate it at  $n$  distinct points  $x_0, \dots, x_{n-1}$ .

$$\begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & x_{n-1}^2 & \cdots & x_{n-1}^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

Running time.  $O(n^2)$  via matrix–vector multiply (or  $n$  Horner’s).

## Converting between two representations: brute force

---

**Point-value  $\Rightarrow$  coefficient.** Given  $n$  distinct points  $x_0, \dots, x_{n-1}$  and values  $y_0, \dots, y_{n-1}$ , find unique polynomial  $A(x) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$ , that has given values at given points.

$$\begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ \vdots \\ y_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & x_0 & x_0^2 & \cdots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \cdots & x_1^{n-1} \\ 1 & x_2 & x_2^2 & \cdots & x_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & x_{n-1}^2 & \cdots & x_{n-1}^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{bmatrix}$$



Vandermonde matrix is invertible iff  $x_i$  distinct

**Running time.**  $O(n^3)$  via Gaussian elimination.



or  $O(n^{2.38})$  via fast matrix multiplication



## Which divide-and-conquer approach to use to multiply polynomials?

$$A(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4 + a_5 x^5 + a_6 x^6 + a_7 x^7.$$

- A. Divide polynomial into low- and high-degree terms.

$$A_{low}(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3.$$

$$A_{high}(x) = a_4 + a_5 x + a_6 x^2 + a_7 x^3.$$

- B. Divide polynomial into even- and odd-degree terms.

$$A_{even}(x) = a_0 + a_2 x + a_4 x^2 + a_6 x^3.$$

$$A_{odd}(x) = a_1 + a_3 x + a_5 x^2 + a_7 x^3.$$

- C. Either A or B.

- D. Neither A nor B.

## Divide-and-conquer

---

Decimation in time. Divide into even- and odd- degree terms.

- $A(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4 + a_5 x^5 + a_6 x^6 + a_7 x^7.$
- $A_{even}(x) = a_0 + a_2 x + a_4 x^2 + a_6 x^3.$
- $A_{odd}(x) = a_1 + a_3 x + a_5 x^2 + a_7 x^3.$
- $A(x) = A_{even}(x^2) + x A_{odd}(x^2).$

Cooley-Tukey radix 2 FFT

Decimation in frequency. Divide into low- and high-degree terms.

- $A(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4 + a_5 x^5 + a_6 x^6 + a_7 x^7.$
- $A_{low}(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3.$
- $A_{high}(x) = a_4 + a_5 x + a_6 x^2 + a_7 x^3.$
- $A(x) = A_{low}(x) + x^4 A_{high}(x).$

Sande-Tukey radix 2 FFT

## Coefficient to point-value representation: intuition

---

**Coefficient  $\Rightarrow$  point-value.** Given a polynomial  $A(x) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$ , evaluate it at  $n$  distinct points  $x_0, \dots, x_{n-1}$ . ← we get to choose which ones!

**Divide.** Break up polynomial into even- and odd-degree terms.

- $A(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4 + a_5 x^5 + a_6 x^6 + a_7 x^7.$
- $A_{even}(x) = a_0 + a_2 x + a_4 x^2 + a_6 x^3.$
- $A_{odd}(x) = a_1 + a_3 x + a_5 x^2 + a_7 x^3.$
- $A(x) = A_{even}(x^2) + x A_{odd}(x^2).$
- $A(-x) = A_{even}(x^2) - x A_{odd}(x^2).$

**Intuition.** Choose two points to be  $\pm 1$ .

- $A(1) = A_{even}(1) + 1 A_{odd}(1).$
  - $A(-1) = A_{even}(1) - 1 A_{odd}(1).$
- ← Can evaluate polynomial of degree  $n-1$  at 2 points by evaluating two polynomials of degree  $\frac{1}{2}n - 1$  at only 1 point.

## Coefficient to point-value representation: intuition

---

**Coefficient  $\Rightarrow$  point-value.** Given a polynomial  $A(x) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$ , evaluate it at  $n$  distinct points  $x_0, \dots, x_{n-1}$ . ← we get to choose which ones!

**Divide.** Break up polynomial into even- and odd-degree terms.

- $A(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + a_4 x^4 + a_5 x^5 + a_6 x^6 + a_7 x^7.$
- $A_{even}(x) = a_0 + a_2 x + a_4 x^2 + a_6 x^3.$
- $A_{odd}(x) = a_1 + a_3 x + a_5 x^2 + a_7 x^3.$
- $A(x) = A_{even}(x^2) + x A_{odd}(x^2).$
- $A(-x) = A_{even}(x^2) - x A_{odd}(x^2).$

**Intuition.** Choose four **complex** points to be  $\pm 1, \pm i$ .

- $A(1) = A_{even}(1) + 1 A_{odd}(1).$
- $A(-1) = A_{even}(1) - 1 A_{odd}(1).$
- $A(i) = A_{even}(-1) + i A_{odd}(-1).$
- $A(-i) = A_{even}(-1) - i A_{odd}(-1).$

← Can evaluate polynomial of degree  $n-1$  at 4 points by evaluating two polynomials of degree  $\frac{1}{2}n - 1$  at only 2 points.

# Discrete Fourier transform

Coefficient  $\Rightarrow$  point-value. Given a polynomial  $A(x) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$ , evaluate it at  $n$  distinct points  $x_0, \dots, x_{n-1}$ .  $\leftarrow$  we get to choose which ones!

Key idea. Choose  $x_k = \omega^k$  where  $\omega$  is principal  $n^{\text{th}}$  root of unity.

$$y_k = A(\omega^k) \rightarrow \begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega^1 & \omega^2 & \omega^3 & \cdots & \omega^{n-1} \\ 1 & \omega^2 & \omega^4 & \omega^6 & \cdots & \omega^{2(n-1)} \\ 1 & \omega^3 & \omega^6 & \omega^9 & \cdots & \omega^{3(n-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \omega^{3(n-1)} & \cdots & \omega^{(n-1)(n-1)} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

$\uparrow$                                    $\uparrow$   
DFT                                  Fourier matrix  $F_n$

# Roots of unity

---

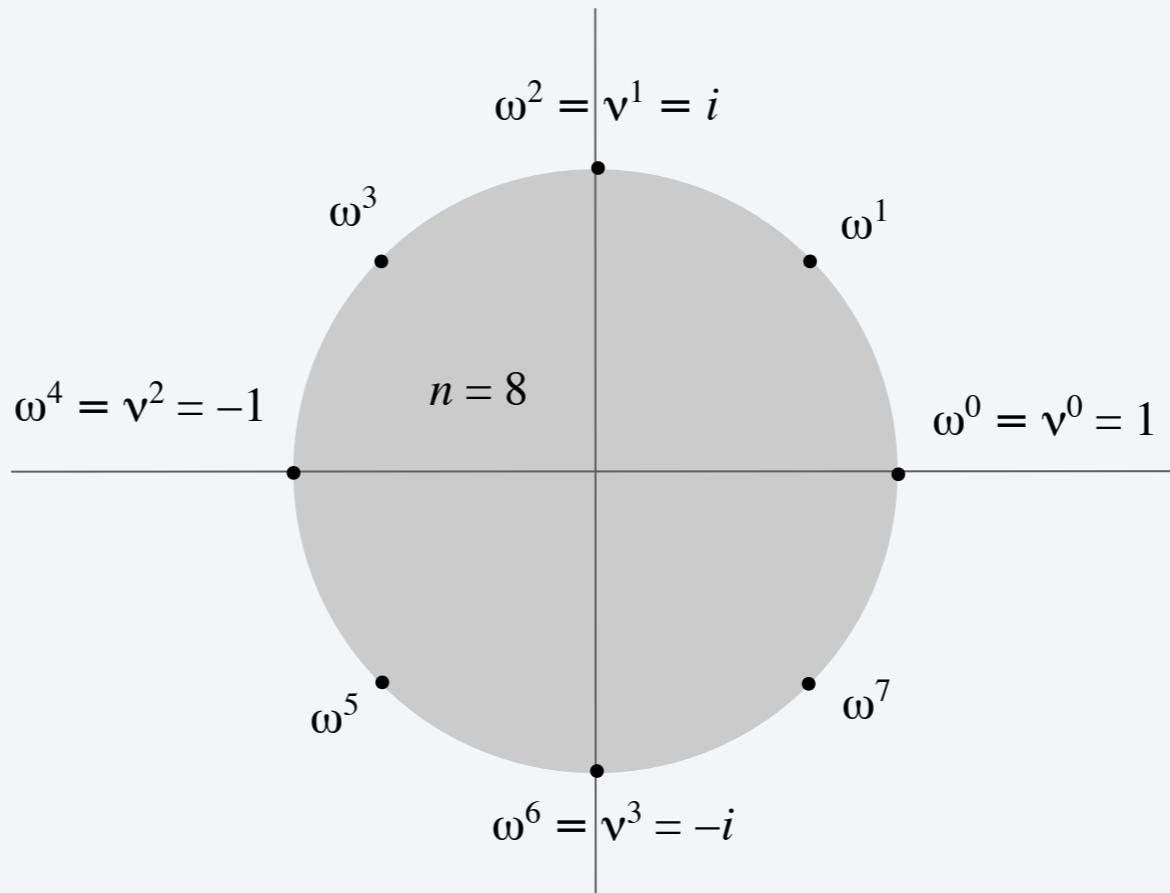
**Def.** An  $n^{\text{th}}$  root of unity is a complex number  $x$  such that  $x^n = 1$ .

**Fact.** The  $n^{\text{th}}$  roots of unity are:  $\omega^0, \omega^1, \dots, \omega^{n-1}$  where  $\omega = e^{2\pi i / n}$ .

**Pf.**  $(\omega^k)^n = (e^{2\pi i k / n})^n = (e^{\pi i})^{2k} = (-1)^{2k} = 1$ .

common alternative:  $\omega = e^{-2\pi i / n}$

**Fact.** The  $\frac{1}{2}n^{\text{th}}$  roots of unity are:  $v^0, v^1, \dots, v^{n/2-1}$  where  $v = \omega^2 = e^{4\pi i / n}$ .



# Fast Fourier transform

---

**Goal.** Evaluate a degree  $n - 1$  polynomial  $A(x) = a_0 + \dots + a_{n-1} x^{n-1}$  at its  $n^{\text{th}}$  roots of unity:  $\omega^0, \omega^1, \dots, \omega^{n-1}$ .

**Divide.** Break up polynomial into even- and odd-degree terms.

- $A_{\text{even}}(x) = a_0 + a_2 x + a_4 x^2 + \dots + a_{n-2} x^{n/2-1}$ .
- $A_{\text{odd}}(x) = a_1 + a_3 x + a_5 x^2 + \dots + a_{n-1} x^{n/2-1}$ .
- $A(x) = A_{\text{even}}(x^2) + x A_{\text{odd}}(x^2)$ .
- $A(-x) = A_{\text{even}}(x^2) - x A_{\text{odd}}(x^2)$ .

**Conquer.** Evaluate  $A_{\text{even}}(x)$  and  $A_{\text{odd}}(x)$  at the  $\frac{1}{2}n^{\text{th}}$  roots of unity:  $\nu^0, \nu^1, \dots, \nu^{n/2-1}$ .

**Combine.**

- $$\nu^k = (\omega^k)^2$$
- 
- $y_k = A(\omega^k) = A_{\text{even}}(\nu^k) + \omega^k A_{\text{odd}}(\nu^k), \quad 0 \leq k < n/2$ .
  - $y_{k+\frac{1}{2}n} = A(\omega^{k+\frac{1}{2}n}) = A_{\text{even}}(\nu^k) - \omega^k A_{\text{odd}}(\nu^k), \quad 0 \leq k < n/2$ .

$$\begin{array}{c} \uparrow \\ A(-\omega^k) \end{array}$$

# FFT: implementation

**Goal.** Evaluate a degree  $n - 1$  polynomial  $A(x) = a_0 + \dots + a_{n-1} x^{n-1}$  at its  $n^{\text{th}}$  roots of unity:  $\omega^0, \omega^1, \dots, \omega^{n-1}$ .

- $y_k = A(\omega^k) = A_{\text{even}}(\mathbf{v}^k) + \omega^k A_{\text{odd}}(\mathbf{v}^k), \quad 0 \leq k < n/2.$
- $y_{k+\frac{n}{2}} = A(\omega^{k+\frac{n}{2}}) = A_{\text{even}}(\mathbf{v}^k) - \omega^k A_{\text{odd}}(\mathbf{v}^k), \quad 0 \leq k < n/2.$

**FFT**( $n, a_0, a_1, a_2, \dots, a_{n-1}$ )

**IF** ( $n = 1$ ) **RETURN**  $a_0$ .

$(e_0, e_1, \dots, e_{n/2-1}) \leftarrow \text{FFT}(n / 2, a_0, a_2, a_4, \dots, a_{n-2}).$

$(d_0, d_1, \dots, d_{n/2-1}) \leftarrow \text{FFT}(n / 2, a_1, a_3, a_5, \dots, a_{n-1}).$

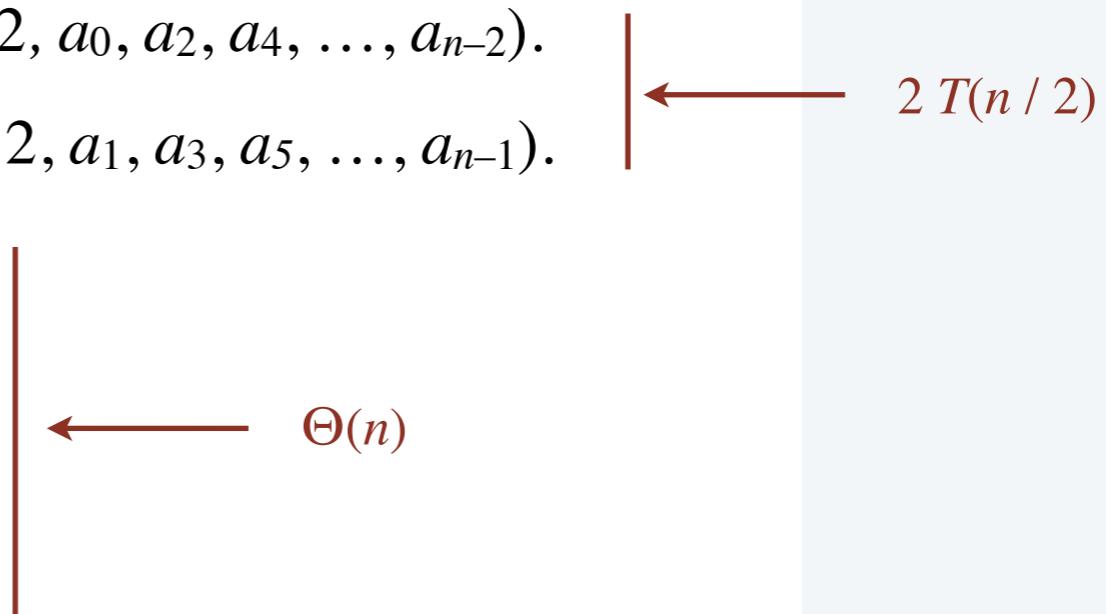
**FOR**  $k = 0$  **TO**  $n / 2 - 1$ .

$$\omega^k \leftarrow e^{2\pi i k/n}.$$

$$y_k \leftarrow e_k + \omega^k d_k.$$

$$y_{k+n/2} \leftarrow e_k - \omega^k d_k.$$

**RETURN**  $(y_0, y_1, y_2, \dots, y_{n-1})$ .



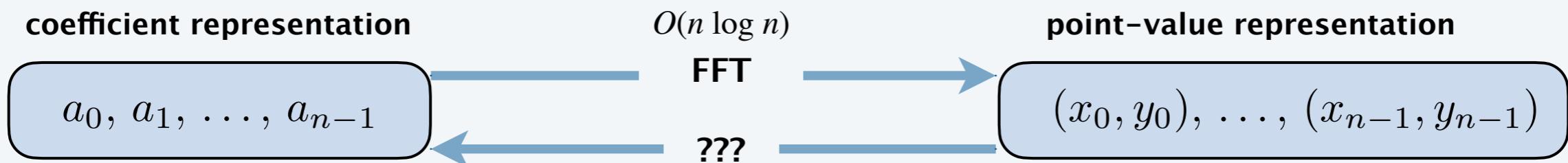
## FFT: summary

**Theorem.** The FFT algorithm evaluates a degree  $n - 1$  polynomial at each of the  $n^{\text{th}}$  roots of unity in  $O(n \log n)$  arithmetic operations and  $O(n)$  extra space.

Pf.

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 2T(n/2) + \Theta(n) & \text{if } n > 1 \end{cases}$$

assumes  $n$  is a power of 2



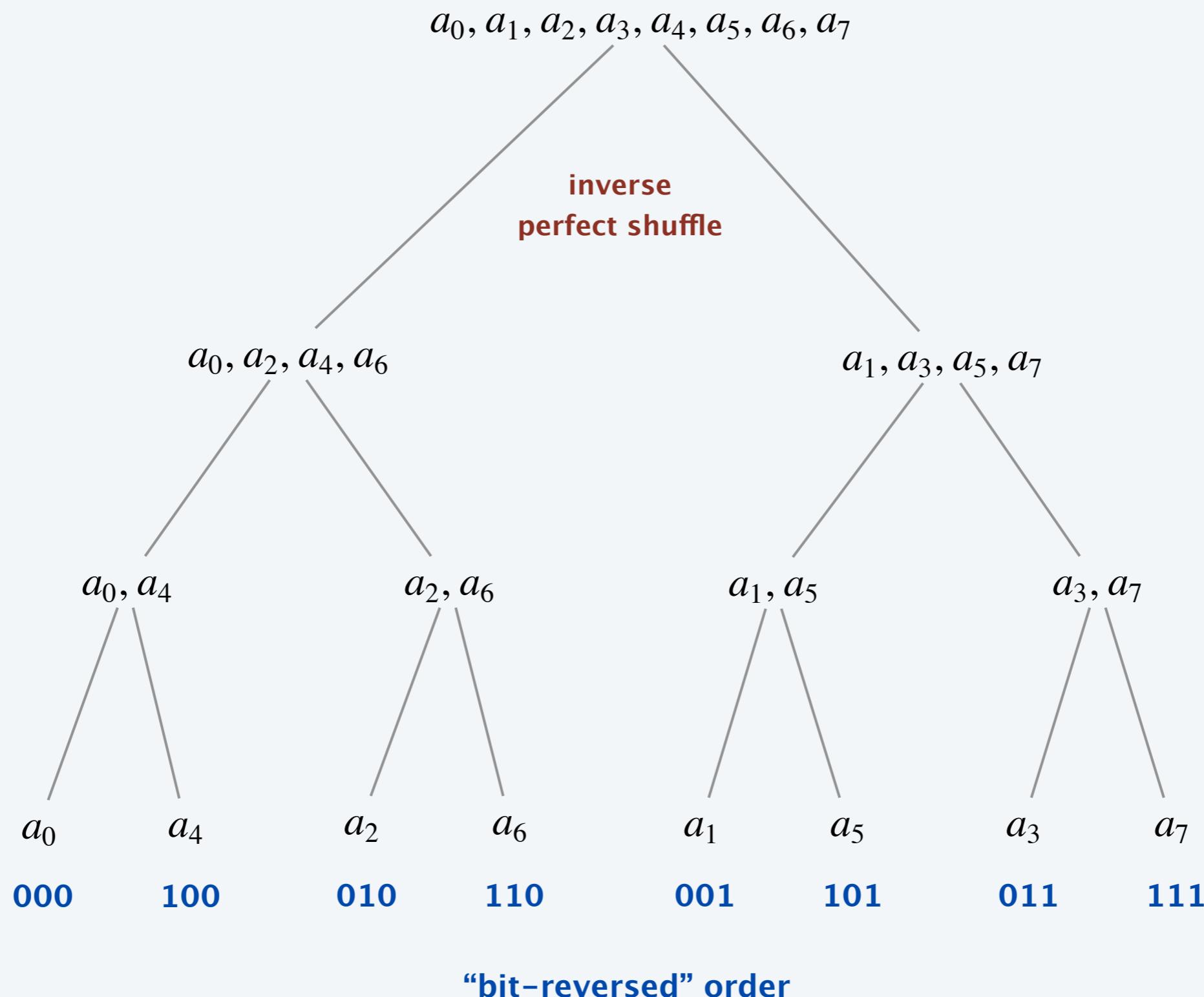


**When computing the FFT of  $(a_0, a_1, a_2, \dots, a_7)$ , which are the first two coefficients involved in an arithmetic operation?**

- A.  $a_0$  and  $a_1$ .
- B.  $a_0$  and  $a_2$ .
- C.  $a_0$  and  $a_4$ .
- D.  $a_0$  and  $a_7$ .
- E. None of the above.

## FFT: recursion tree

---



# FFT: Fourier matrix decomposition

Alternative viewpoint. FFT is a recursive decomposition of Fourier matrix.

$$F_n = \begin{bmatrix} 1 & 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega^1 & \omega^2 & \omega^3 & \cdots & \omega^{n-1} \\ 1 & \omega^2 & \omega^4 & \omega^6 & \cdots & \omega^{2(n-1)} \\ 1 & \omega^3 & \omega^6 & \omega^9 & \cdots & \omega^{3(n-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \omega^{3(n-1)} & \cdots & \omega^{(n-1)(n-1)} \end{bmatrix} \quad a = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{bmatrix}$$

Fourier matrix

$$I_n = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} \quad D_n = \begin{bmatrix} \omega^0 & 0 & 0 & \cdots & 0 \\ 0 & \omega^1 & 0 & \cdots & 0 \\ 0 & 0 & \omega^2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \omega^{n-1} \end{bmatrix}$$

DFT

$$y = F_n a = \begin{bmatrix} I_{n/2} & D_{n/2} \\ I_{n/2} & -D_{n/2} \end{bmatrix} \begin{bmatrix} F_{n/2} a_{even} \\ F_{n/2} a_{odd} \end{bmatrix}$$

# Inverse discrete Fourier transform

**Point-value  $\Rightarrow$  coefficient.** Given  $n$  distinct points  $x_0, \dots, x_{n-1}$  and values  $y_0, \dots, y_{n-1}$ , find unique polynomial  $a_0 + a_1x + \dots + a_{n-1}x^{n-1}$ , that has given values at given points.

$$\begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega^1 & \omega^2 & \omega^3 & \cdots & \omega^{n-1} \\ 1 & \omega^2 & \omega^4 & \omega^6 & \cdots & \omega^{2(n-1)} \\ 1 & \omega^3 & \omega^6 & \omega^9 & \cdots & \omega^{3(n-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \omega^{3(n-1)} & \cdots & \omega^{(n-1)(n-1)} \end{bmatrix}^{-1} \begin{bmatrix} y_0 \\ y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_{n-1} \end{bmatrix}$$

## Inverse discrete Fourier transform

---

**Claim.** Inverse of Fourier matrix  $F_n$  is given by following formula:

$$G_n = \frac{1}{n} \begin{bmatrix} 1 & 1 & 1 & 1 & \cdots & 1 \\ 1 & \omega^{-1} & \omega^{-2} & \omega^{-3} & \cdots & \omega^{-(n-1)} \\ 1 & \omega^{-2} & \omega^{-4} & \omega^{-6} & \cdots & \omega^{-2(n-1)} \\ 1 & \omega^{-3} & \omega^{-6} & \omega^{-9} & \cdots & \omega^{-3(n-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{-(n-1)} & \omega^{-2(n-1)} & \omega^{-3(n-1)} & \cdots & \omega^{-(n-1)(n-1)} \end{bmatrix}$$

$F_n / \sqrt{n}$  is a unitary matrix

**Consequence.** To compute the inverse FFT, apply the same algorithm but use  $\omega^{-1} = e^{-2\pi i / n}$  as principal  $n^{\text{th}}$  root of unity (and divide the result by  $n$ ).

## Inverse FFT: proof of correctness

---

**Claim.**  $F_n$  and  $G_n$  are inverses.

Pf.

$$(F_n G_n)_{kk'} = \frac{1}{n} \sum_{j=0}^{n-1} \omega^{kj} \omega^{-jk'} = \frac{1}{n} \sum_{j=0}^{n-1} \omega^{(k-k')j} = \begin{cases} 1 & \text{if } k = k' \\ 0 & \text{otherwise} \end{cases}$$

summation lemma (below)

**Summation lemma.** Let  $\omega$  be a principal  $n^{\text{th}}$  root of unity. Then

$$\sum_{j=0}^{n-1} \omega^{kj} = \begin{cases} n & \text{if } k \equiv 0 \pmod{n} \\ 0 & \text{otherwise} \end{cases}$$

Pf.

- If  $k$  is a multiple of  $n$ , then  $\omega^k = 1 \Rightarrow$  series sums to  $n$ .
- Each  $n^{\text{th}}$  root of unity  $\omega^k$  is a root of  $x^n - 1 = (x - 1)(1 + x + x^2 + \dots + x^{n-1})$ .
- if  $\omega^k \neq 1$ , then  $1 + \omega^k + \omega^{k(2)} + \dots + \omega^{k(n-1)} = 0 \Rightarrow$  series sums to 0. ▀

# Inverse FFT: implementation

Note. Need to divide result by  $n$ .

**INVERSE-FFT**( $n, y_0, y_1, y_2, \dots, y_{n-1}$ )

**IF** ( $n = 1$ ) **RETURN**  $y_0$ .

$(e_0, e_1, \dots, e_{n/2-1}) \leftarrow \text{INVERSE-FFT}(n / 2, y_0, y_2, y_4, \dots, y_{n-2})$ .

$(d_0, d_1, \dots, d_{n/2-1}) \leftarrow \text{INVERSE-FFT}(n / 2, y_1, y_3, y_5, \dots, y_{n-1})$ .

**FOR**  $k = 0$  **TO**  $n / 2 - 1$ .

$$\omega^k \leftarrow e^{-2\pi i k / n}.$$

$$a_k \leftarrow e_k + \omega^k d_k.$$

$$a_{k+n/2} \leftarrow e_k - \omega^k d_k.$$

**RETURN**  $(a_0, a_1, a_2, \dots, a_{n-1})$ .

switch roles of  $a_i$  and  $y_i$

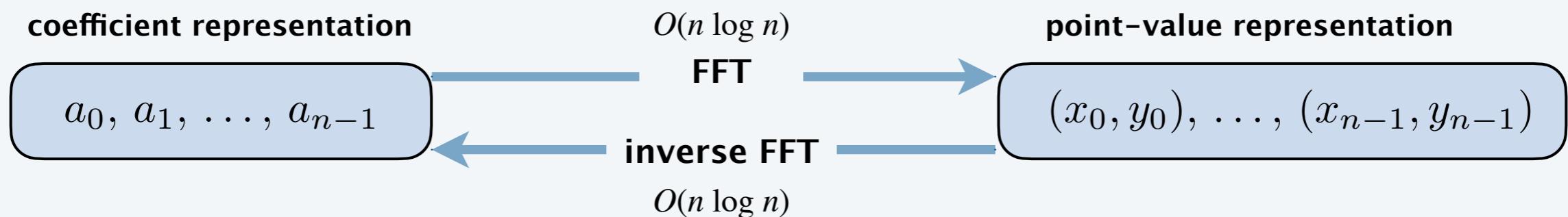
## Inverse FFT: summary

---

**Theorem.** The inverse FFT algorithm interpolates a degree  $n - 1$  polynomial at each of the  $n^{\text{th}}$  roots of unity in  $O(n \log n)$  arithmetic operations.

assumes  $n$  is a power of 2

**Corollary.** Can convert between coefficient and point-value representations in  $O(n \log n)$  arithmetic operations.

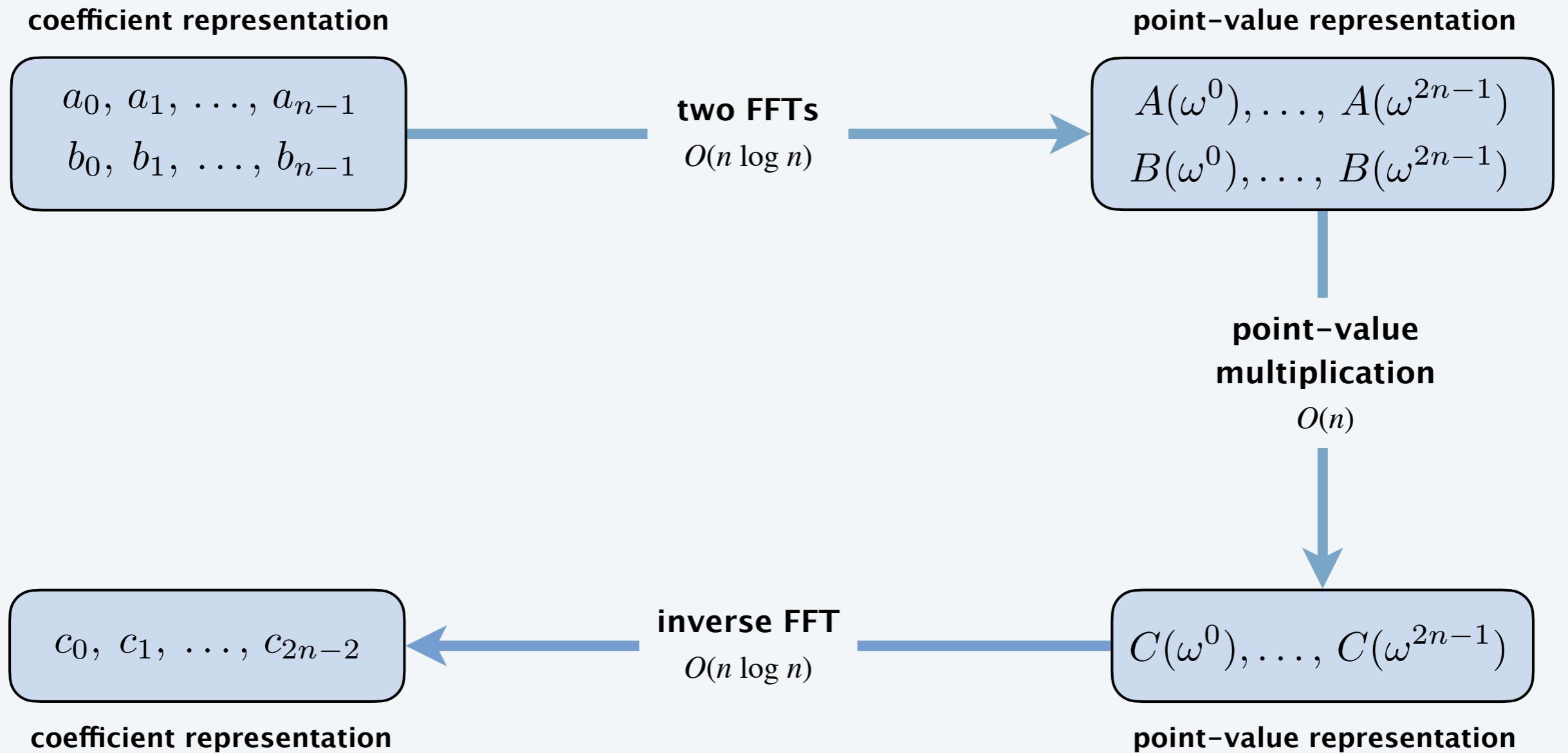


# Polynomial multiplication

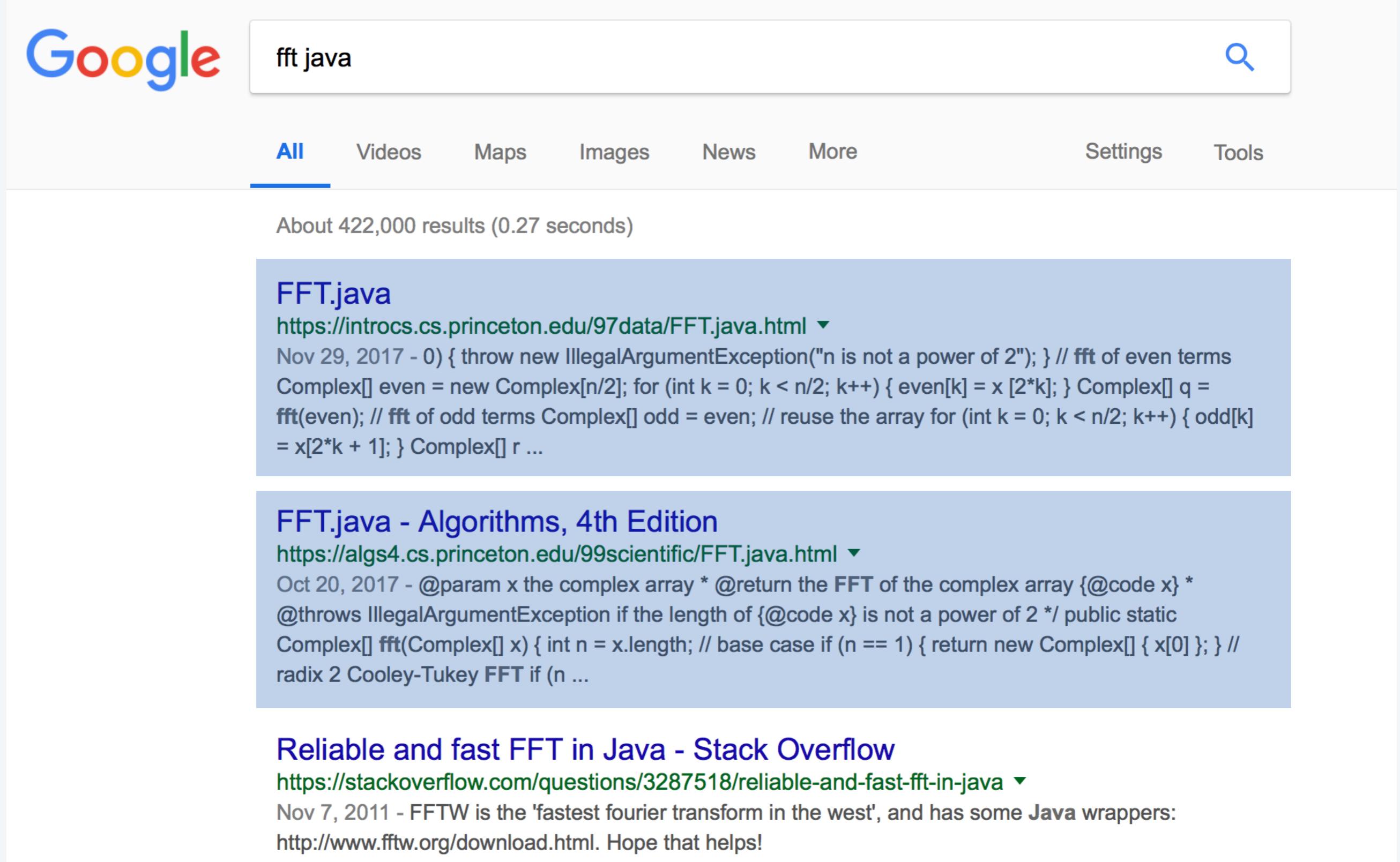
**Theorem.** Given two polynomials  $A(x) = a_0 + a_1 x + \dots + a_{n-1} x^{n-1}$  and  $B(x) = b_0 + b_1 x + \dots + b_{n-1} x^{n-1}$  of degree  $n - 1$ , can multiply them in  $O(n \log n)$  arithmetic operations.

pad with 0s to make  
 $n$  a power of 2

Pf.



# FFT in practice ?



A screenshot of a Google search results page. The search query "fft java" is entered in the search bar. The "All" tab is selected, showing approximately 422,000 results found in 0.27 seconds. The first result is a snippet from "FFT.java" located at <https://introcs.cs.princeton.edu/97data/FFT.java.html>. It shows Java code for performing an FFT on a complex array. The second result is a snippet from "FFT.java - Algorithms, 4th Edition" located at <https://algs4.cs.princeton.edu/99scientific/FFT.java.html>. It shows Java code for the Cooley-Tukey FFT algorithm. The third result is a snippet from "Reliable and fast FFT in Java - Stack Overflow" located at <https://stackoverflow.com/questions/3287518/reliable-and-fast-fft-in-java>. It discusses FFTW and provides a link to its Java wrappers.

Google search results for "fft java":

About 422,000 results (0.27 seconds)

**FFT.java**  
<https://introcs.cs.princeton.edu/97data/FFT.java.html> ▾

Nov 29, 2017 - 0) { throw new IllegalArgumentException("n is not a power of 2"); } // fft of even terms  
Complex[] even = new Complex[n/2]; for (int k = 0; k < n/2; k++) { even[k] = x[2\*k]; } Complex[] q =  
fft(even); // fft of odd terms Complex[] odd = even; // reuse the array for (int k = 0; k < n/2; k++) { odd[k]  
= x[2\*k + 1]; } Complex[] r ...

**FFT.java - Algorithms, 4th Edition**  
<https://algs4.cs.princeton.edu/99scientific/FFT.java.html> ▾

Oct 20, 2017 - @param x the complex array \* @return the FFT of the complex array {@code x} \*  
@throws IllegalArgumentException if the length of {@code x} is not a power of 2 \*/ public static  
Complex[] fft(Complex[] x) { int n = x.length; // base case if (n == 1) { return new Complex[] { x[0] }; } //  
radix 2 Cooley-Tukey FFT if (n ...

**Reliable and fast FFT in Java - Stack Overflow**  
<https://stackoverflow.com/questions/3287518/reliable-and-fast-fft-in-java> ▾

Nov 7, 2011 - FFTW is the 'fastest fourier transform in the west', and has some Java wrappers:  
<http://www.fftw.org/download.html>. Hope that helps!

# FFT in practice

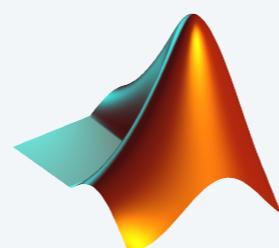
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Fastest Fourier transform in the West. [Frigo–Johnson]

- Optimized C library.
- Features: DFT, DCT, real, complex, any size, any dimension.
- Won 1999 Wilkinson Prize for Numerical Software.
- Portable, competitive with vendor-tuned code.

Implementation details.

- Core algorithm is an in-place, nonrecursive version of Cooley–Tukey.
- Instead of executing a fixed algorithm, it evaluates the hardware and uses a special-purpose compiler to generate an optimized algorithm catered to “shape” of the problem.
- Runs in  $O(n \log n)$  time, even when  $n$  is prime.
- Multidimensional FFTs.
- Parallelism.



<http://www.fftw.org>

# Top 10 algorithms of the 20th century

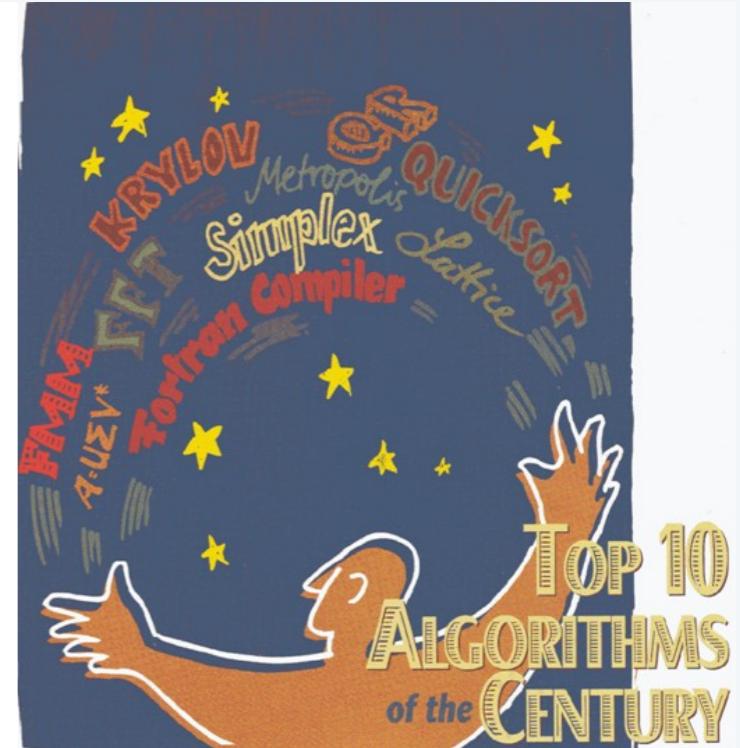
FROM THE  
EDITORS

## THE JOY OF ALGORITHMS

*Francis Sullivan, Associate Editor-in-Chief*



THE THEME OF THIS FIRST-OF-THE-CENTURY ISSUE OF *COMPUTING IN SCIENCE & ENGINEERING* IS ALGORITHMS. IN FACT, WE WERE BOLD ENOUGH—AND PERHAPS FOOLISH ENOUGH—TO CALL THE 10 EXAMPLES WE'VE SELECTED “THE TOP 10 ALGORITHMS OF THE CENTURY.”



Daniel Rockmore describes the FFT as an algorithm “the whole family can use.” The FFT is perhaps the most ubiquitous algorithm in use today to analyze and manipulate digital or discrete data. The FFT takes the operation count for discrete Fourier transform from  $O(N^2)$  to  $O(N \log N)$ .

# Integer multiplication, redux

---

**Integer multiplication.** Given two  $n$ -bit integers  $a = a_{n-1} \dots a_1 a_0$  and  $b = b_{n-1} \dots b_1 b_0$ , compute their product  $a \cdot b$ .

## Convolution algorithm.

- Form two polynomials.
  - Note:  $a = A(2)$ ,  $b = B(2)$ .
  - Compute  $C(x) = A(x) \cdot B(x)$ .
  - Evaluate  $C(2) = a \cdot b$ .
  - Running time:  $O(n \log n)$  floating-point operations.
- $$A(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_{n-1} x^{n-1}$$
- $$B(x) = b_0 + b_1 x + b_2 x^2 + \dots + b_{n-1} x^{n-1}$$

## Theory. [Schönhage–Strassen 1971]

- $O(n \log^2 n)$  bit operations.  $\leftarrow$  FFT over complex numbers; need  $O(\log n)$  bits of precision
- $O(n \log n \cdot \log \log n)$  bit operations.  $\leftarrow$  FFT over ring of integers (modulo a Fermat number)

## Practice. [GNU Multiple Precision Arithmetic Library]

Switches to FFT-based algorithm when  $n$  is large ( $\geq 5\text{--}10K$ ).

# 3-SUM (REVISITED)



**3-SUM.** Given three sets  $X$ ,  $Y$ , and  $Z$  of  $n$  integers each, determine whether there is a triple  $i \in X, j \in Y, k \in Z$  such that  $i + j = k$ .

**Assumption.** All integers are between 0 and  $m$ .

**Goal.**  $O(m \log m + n \log n)$  time.

$$m = 19, n = 3$$

$$X = \{ 4, 7, 10 \}$$

$$Y = \{ 5, 8, 15 \}$$

$$Z = \{ 4, 13, 19 \}$$

a yes instance

$$(4 + 15 = 19)$$

# 3-SUM (REVISITED)



An  $O(m \log m + n)$  solution.

- Form polynomial  $A(x) = a_0 + a_1 x + \dots + a_m x^m$  with  $a_i = 1$  iff  $i \in X$ .
- Form polynomial  $B(x) = b_0 + b_1 x + \dots + b_m x^m$  with  $b_j = 1$  iff  $j \in Y$ .
- Compute product/convolution  $C(x) = A(x) \times B(x)$ .
- The coefficient  $c_k =$  number of ways to choose an integer  $i \in X$  and an integer  $j \in Y$  that sum to exactly  $k$ .
- For each  $k \in Z$ : check whether  $c_k > 0$ .

$$m = 19, n = 3$$

$$X = \{ 4, 7, 10 \}$$

$$Y = \{ 5, 8, 15 \}$$

$$Z = \{ 4, 13, 19 \}$$

a yes instance

$$(4 + 15 = 19)$$

$$A(x) = x^4 + x^7 + x^{10}$$

$$B(x) = x^5 + x^8 + x^{15}$$

$$C(x) = x^9 + 2x^{12} + 2x^{15} + x^{18} + x^{19} + x^{22} + x^{25}$$

# Divide and Conquer

- Introduction
- Closest pair of points
- Solving recurrent equations
- Multiplication problems
  - Integer multiplication
  - Matrix multiplication
  - Polynomial multiplication with FFT
- Take-home messages

# Divide-and-conquer paradigm

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## Divide-and-conquer.

- Divide up problem into several subproblems (of the same kind).
- Solve (conquer) each subproblem recursively.
- Combine solutions to subproblems into overall solution.

## Most common usage.

- Divide problem of size  $n$  into two subproblems of size  $n/2$ .  $\leftarrow O(n)$  time
- Solve (conquer) two subproblems recursively.
- Combine two solutions into overall solution.  $\leftarrow O(n)$  time

## Consequence.

- Brute force:  $\Theta(n^2)$ .
- Divide-and-conquer:  $O(n \log n)$ .

Common situation.  
Not always the case.



attributed to Julius Caesar

Thanks for your attention!  
Discussions?

# Reference

<https://www.cs.princeton.edu/~wayne/kleinberg-tardos/pdf/05DivideAndConquerI.pdf>

<https://www.cs.princeton.edu/~wayne/kleinberg-tardos/pdf/05DivideAndConquerII.pdf>

Algorithms by Sanjoy Dasgupta, Christos Papadimitriou, Umesh Vazirani: Chap. 2.

Algorithm design: Chap. 5.

Introduction to algorithms (4th edition): Chap. 4.