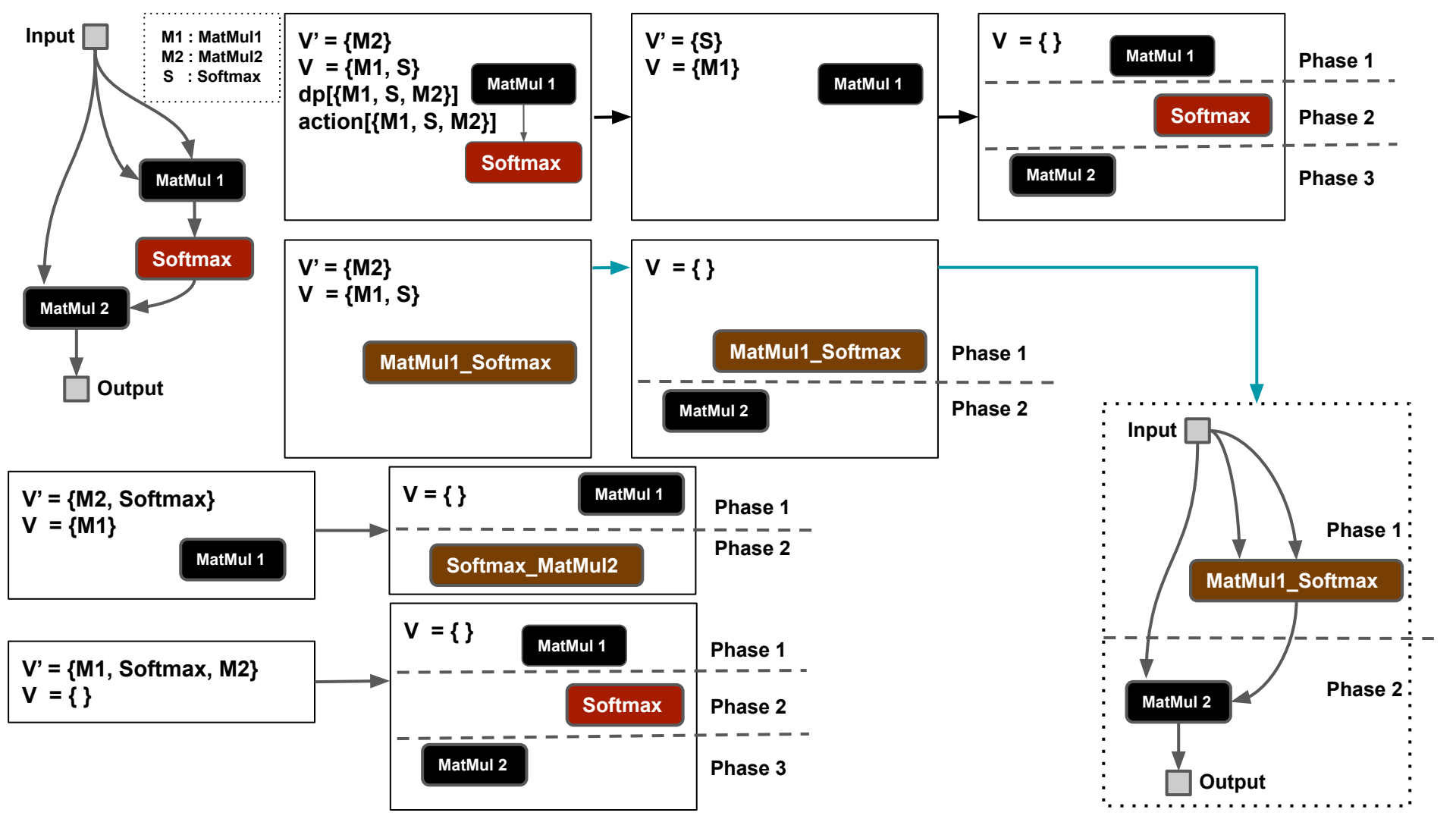
Input
M1 : MatMul1
M2 : MatMul2
S : Softmax
MatMul 1
Softmax
MatMul 2
Output
V' = {M2}
V = {M1, S}
dp[{M1, S, M2}]
action[{M1, S, M2}]
MatMul 1
Softmax
V' = {S}
V = {M1}
MatMul 1
V = { }
MatMul 1
Softmax
MatMul 2
Phase 1
Phase 2
Phase 3
V' = {M2}
V = {M1, S}
MatMul1_Softmax
V = { }
MatMul1_Softmax
MatMul 2
Phase 1
Phase 2
V' = {M2, Softmax}
V = {M1}
MatMul 1
V = { }
MatMul 1
Softmax_MatMul2
Phase 1
Phase 2
V' = {M1, Softmax, M2}
V = { }
V = { }
MatMul 1
Softmax
MatMul 2
Phase 1
Phase 2
Phase 3
Input
MatMul1_Softmax
MatMul 2
Output
Phase 1
Phase 2