Answers/Solutions of Exercise 5 (Version: November 9, 2018)

1. (a)
$$||\boldsymbol{u}|| = \sqrt{13}$$
, $||\boldsymbol{v}|| = \sqrt{2}$, $d(\boldsymbol{u}, \boldsymbol{v}) = \sqrt{5}$, $\boldsymbol{u} \cdot \boldsymbol{v} = 5$, $\theta = \cos^{-1}(\frac{5}{\sqrt{26}}) \approx 11.3^{\circ}$.

(b)
$$||\boldsymbol{u}|| = \sqrt{2}$$
, $||\boldsymbol{v}|| = \sqrt{10}$, $d(\boldsymbol{u}, \boldsymbol{v}) = \sqrt{20}$, $\boldsymbol{u} \cdot \boldsymbol{v} = -4$, $\theta = \cos^{-1}(\frac{-4}{\sqrt{20}}) \approx 153.4^{\circ}$.

(c)
$$||\boldsymbol{u}|| = \sqrt{14}$$
, $||\boldsymbol{v}|| = \sqrt{13}$, $d(\boldsymbol{u}, \boldsymbol{v}) = \sqrt{27}$, $\boldsymbol{u} \cdot \boldsymbol{v} = 0$, $\theta = 90^{\circ}$.

(d)
$$||\boldsymbol{u}|| = 2$$
, $||\boldsymbol{v}|| = \sqrt{10}$, $d(\boldsymbol{u}, \boldsymbol{v}) = \sqrt{14}$, $\boldsymbol{u} \cdot \boldsymbol{v} = 0$, $\theta = 90^{\circ}$.

- 2. (a) (1,1,0,0) (1,-1,0,0) = (0,2,0,0) so $|AB| = \sqrt{(0^2 + 2^2 + 0^2 + 0^2)} = 2$. Likewise $|BC| = \sqrt{3}$ and $|AC| = \sqrt{3}$.
 - (b) $\mathbf{u} = AB = (1, -1, 0, 0) (1, 1, 0, 0) = (0, -2, 0, 0), \ \mathbf{v} = AC = (2, 0, 0, 1) (1, 1, 0, 0) = (1, -1, 0, 1).$ So the angle between AB and AC is $\cos^{-1}(\frac{\mathbf{u} \cdot \mathbf{v}}{|AB||AC|}) = \cos^{-1}(\frac{1}{\sqrt{3}}) \approx 54.7^{\circ}$.
 - (c) Easily verified that $2(2)(\sqrt{3})(\frac{1}{\sqrt{3}}) = 4 + 3 3$.
- 3. Let $\mathbf{u} = (u_1, u_2, \dots, u_n)$, $\mathbf{v} = (v_1, v_2, \dots, v_n)$ and $\mathbf{w} = (w_1, w_2, \dots, w_n)$.
 - (a) $\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n = v_1 u_1 + v_2 u_2 + \dots + v_n u_n = \mathbf{v} \cdot \mathbf{u}$.

(b)
$$(\boldsymbol{u} + \boldsymbol{v}) \cdot \boldsymbol{w} = (u_1 + v_1, u_2 + v_2, \dots, u_n + v_n) \cdot \boldsymbol{w}$$

$$= (u_1 + v_1)w_1 + (u_2 + v_2)w_2 + \dots + (u_n + v_n)w_n$$

$$= (u_1w_1 + v_1w_1) + (u_2w_2 + v_2w_2) + \dots + (u_nw_n + v_nw_n)$$

$$= (u_1w_1 + u_2w_2 + \dots + u_nw_n) + (v_1w_1 + v_2w_2 + \dots + v_nw_n)$$

$$= \boldsymbol{u} \cdot \boldsymbol{w} + \boldsymbol{v} \cdot \boldsymbol{w}.$$

(c)
$$(c\mathbf{u}) \cdot \mathbf{v} = (cu_1, cu_2, \dots, cu_n) \cdot \mathbf{v}$$

= $cu_1v_1 + cu_2v_2 + \dots + cu_nv_n = c(u_1v_1 + u_2v_2 + \dots + u_nv_n) = c(\mathbf{u} \cdot \mathbf{v}).$

The proof for $\mathbf{u} \cdot (c\mathbf{v}) = c(\mathbf{u} \cdot \mathbf{v})$ is similar.

(d)
$$||c\mathbf{u}|| = \sqrt{(c\mathbf{u}) \cdot (c\mathbf{u})} = \sqrt{c^2(\mathbf{u} \cdot \mathbf{u})}$$
 (by (c))
= $\sqrt{c^2}\sqrt{\mathbf{u} \cdot \mathbf{u}} = |c| ||\mathbf{u}||$

4. (a) If $\mathbf{u} = \mathbf{0}$, then it is obvious. Assume $\mathbf{u} \neq \mathbf{0}$. Let $a = \mathbf{u} \cdot \mathbf{u}$, $b = 2(\mathbf{u} \cdot \mathbf{v})$, $c = \mathbf{v} \cdot \mathbf{v}$ and let t be any real number.

$$0 \le (t\boldsymbol{u} + \boldsymbol{v}) \cdot (t\boldsymbol{u} + \boldsymbol{v})$$

= $t^2(\boldsymbol{u} \cdot \boldsymbol{u}) + 2t(\boldsymbol{u} \cdot \boldsymbol{v}) + (\boldsymbol{v} \cdot \boldsymbol{v})$
= $at^2 + bt + c$

Thus the polynomial $at^2 + bt + c$ has either no real roots or repeated roots. This means that $b^2 - 4ac < 0$. In other words,

$$4(\boldsymbol{u} \cdot \boldsymbol{v})^{2} \leq 4(\boldsymbol{u} \cdot \boldsymbol{u})(\boldsymbol{v} \cdot \boldsymbol{v})$$

$$\Rightarrow (\boldsymbol{u} \cdot \boldsymbol{v})^{2} \leq (\boldsymbol{u} \cdot \boldsymbol{u})(\boldsymbol{v} \cdot \boldsymbol{v})$$

$$\Rightarrow |(\boldsymbol{u} \cdot \boldsymbol{v})| \leq \sqrt{\boldsymbol{u} \cdot \boldsymbol{u}}\sqrt{\boldsymbol{v} \cdot \boldsymbol{v}} = ||\boldsymbol{u}|| ||\boldsymbol{v}||$$

(b)
$$||\boldsymbol{u} + \boldsymbol{v}||^2 = (\boldsymbol{u} + \boldsymbol{v}) \cdot (\boldsymbol{u} + \boldsymbol{v}) = \boldsymbol{u} \cdot \boldsymbol{u} + \boldsymbol{v} \cdot \boldsymbol{v} + 2\boldsymbol{u} \cdot \boldsymbol{v}$$

$$\leq \boldsymbol{u} \cdot \boldsymbol{u} + \boldsymbol{v} \cdot \boldsymbol{v} + 2|\boldsymbol{u} \cdot \boldsymbol{v}|$$

$$\leq ||\boldsymbol{u}||^2 + ||\boldsymbol{v}||^2 + 2||\boldsymbol{u}||||\boldsymbol{v}|| \qquad \text{by (a)}$$

$$= (||\boldsymbol{u}|| + ||\boldsymbol{v}||)^2$$

So $||u+v|| \le ||u|| + ||v||$. Geometrically, this means that in any triangle, the sum of the length of any two sides is always greater than or equal to the length of the third side.

(c) In (b), substitute \boldsymbol{u} and \boldsymbol{v} by $\boldsymbol{u} - \boldsymbol{v}$ and $\boldsymbol{v} - \boldsymbol{w}$ respectively. We have $||\boldsymbol{u} - \boldsymbol{w}|| \le ||\boldsymbol{u} - \boldsymbol{v}|| + ||\boldsymbol{v} - \boldsymbol{w}||$. So $d(\boldsymbol{u}, \boldsymbol{w}) \le d(\boldsymbol{u}, \boldsymbol{v}) + d(\boldsymbol{v}, \boldsymbol{w})$.

5. (a)
$$||\mathbf{u} + \mathbf{v}||^2 + ||\mathbf{u} - \mathbf{v}||^2 = (\mathbf{u} + \mathbf{v}) \cdot (\mathbf{u} + \mathbf{v}) + (\mathbf{u} - \mathbf{v}) \cdot (\mathbf{u} - \mathbf{v})$$

 $= 2(\mathbf{u} \cdot \mathbf{u}) + 2(\mathbf{v} \cdot \mathbf{v}) + 2\mathbf{u} \cdot \mathbf{v} - 2\mathbf{u} \cdot \mathbf{v}$
 $= 2||\mathbf{u}||^2 + 2||\mathbf{v}||^2$

Geometric interpretation: For a parallelogram with u and v as sides, the sum of the squares of the four sides is equal to the sum of squares of the two diagonals.

(b)
$$\frac{1}{4}(u+v)\cdot(u+v) - \frac{1}{4}(u-v)\cdot(u-v) = \frac{1}{4}(2u\cdot v + 2u\cdot v) = u\cdot v$$

- 6. (a) $\{(x,y) \mid x+y=0\}$, the line y=-x in \mathbb{R}^2 .
 - (b) $\{(x, y, z) \mid x + 3z = 0\}$, the plane x + 3z = 0 in \mathbb{R}^3 .
 - (c) $\{(x, y, z, w) \mid x y + z w = 0\}$
- 7. (a) Let (w, x, y, z) be any vector in W^{\perp} .

$$\left\{ \begin{array}{l} (1,0,1,1) \cdot (w,x,y,z) = 0 \\ (1,-1,0,2) \cdot (w,x,y,z) = 0 \\ (1,2,3,-1) \cdot (w,x,y,z) = 0 \end{array} \right. \Leftrightarrow \left\{ \begin{array}{l} w + y + z = 0 \\ w - x + 2z = 0 \\ w + 2x + 3y - z = 0 \end{array} \right.$$

A general solution of the linear system is w=-s-t, x=-s+t, y=s, z=t where $s,t\in\mathbb{R}$. So $W^{\perp}=\{s(-1,-1,1,0)+t(-1,1,0,1)\mid s,t\in\mathbb{R}\}.$

(b) Let $\{w_1, \ldots, w_k\}$ be a basis for W.

$$\mathbf{u} \in W^{\perp} \quad \Leftrightarrow \quad \begin{cases} \mathbf{w_1} \cdot \mathbf{u} = 0 \\ \vdots \\ \mathbf{w_k} \cdot \mathbf{u} = 0 \end{cases} \quad \Leftrightarrow \quad \begin{pmatrix} \mathbf{w_1} \\ \vdots \\ \mathbf{w_k} \end{pmatrix} \mathbf{u}^{\mathrm{T}} = \mathbf{0}$$

So W^{\perp} is a solution set of a homogeneous system of linear equations. By Theorem 3.3.6, W^{\perp} is a subspace of \mathbb{R}^n .

Alternative proof: Since $\boldsymbol{w} \cdot \mathbf{0} = 0$ for all $\boldsymbol{w} \in W$, $\mathbf{0} \in W^{\perp}$. So W^{\perp} is nonempty. Let \boldsymbol{u} and \boldsymbol{v} be any vectors in W^{\perp} , i.e. $\boldsymbol{w} \cdot \boldsymbol{u} = 0$ and $\boldsymbol{w} \cdot \boldsymbol{v} = 0$ for all $\boldsymbol{w} \in W$, and let $a, b \in \mathbb{R}$. Then for all $\boldsymbol{w} \in W$, $\boldsymbol{w} \cdot (a\boldsymbol{u} + b\boldsymbol{v}) = a(\boldsymbol{w} \cdot \boldsymbol{u}) + b(\boldsymbol{w} \cdot \boldsymbol{v}) = 0 + 0 = 0$. Hence $\boldsymbol{u} + \boldsymbol{v} \in W^{\perp}$. By Remark 3.3.8, W^{\perp} is a subspace of \mathbb{R}^n .

- 8. (a) Clearly span $(T) \subseteq \text{span}(S)$. We just need to show span $(S) \subseteq \text{span}(T)$. Since $\mathbf{u_1} = \mathbf{v_3}$, $\mathbf{u_2} = \frac{3}{5}\mathbf{v_1} + \frac{4}{5}\mathbf{v_2}$, $\mathbf{u_3} = \frac{4}{5}\mathbf{v_1} \frac{3}{5}\mathbf{v_2}$, span $(S) \subseteq \text{span}(T)$ follows.
 - (b) Since S is orthonormal, $\mathbf{v_1} \cdot \mathbf{v_1} = \frac{9}{25}(\mathbf{u_2} \cdot \mathbf{u_2}) + \frac{16}{25}(\mathbf{u_3} \cdot \mathbf{u_3}) + \frac{24}{25}(\mathbf{u_2} \cdot \mathbf{u_3}) = 1$. Likewise, it can be shown that $\mathbf{v_2} \cdot \mathbf{v_2} = \mathbf{v_3} \cdot \mathbf{v_3} = 1$, $\mathbf{v_1} \cdot \mathbf{v_2} = \mathbf{v_1} \cdot \mathbf{v_3} = \mathbf{v_2} \cdot \mathbf{v_3} = 0$. Hence T is also orthonormal.

9.
$$||\boldsymbol{u_1} + \dots + \boldsymbol{u_n}||^2 = (\boldsymbol{u_1} + \dots + \boldsymbol{u_n}) \cdot (\boldsymbol{u_1} + \dots + \boldsymbol{u_n})$$

 $= (\boldsymbol{u_1} \cdot \boldsymbol{u_1}) + \dots + (\boldsymbol{u_n} \cdot \boldsymbol{u_n}) \text{ since } \boldsymbol{u_i} \cdot \boldsymbol{u_j} = 0 \text{ for } i \neq j$
 $= ||\boldsymbol{u_1}||^2 + \dots + ||\boldsymbol{u_n}||^2$

For n = 2, it is Pythagoras' Theorem.

- 10. (a) It is easy to check that $u_i \cdot u_j = 0$ for $i \neq j$.
 - (b) $S' = \{ \frac{1}{\sqrt{10}} (1, 2, 2, -1), \frac{1}{2} (1, 1, -1, 1), \frac{1}{2} (-1, 1, -1, -1), \frac{1}{\sqrt{10}} (-2, 1, 1, 2) \}$
 - (c) Yes
 - (d) $(\boldsymbol{w})_S = (\frac{3}{10}, \frac{1}{2}, -1, \frac{9}{10})$ and $(\boldsymbol{w})_{S'} = (\frac{3}{\sqrt{10}}, 1, -2, \frac{9}{\sqrt{10}}).$
 - (e) A vector \boldsymbol{v} is orthogonal to V if and only if $\boldsymbol{v} = t(-1, \frac{1}{2}, \frac{1}{2}, 1)$ for some $t \in \mathbb{R}$, i.e. $\boldsymbol{v} \in \text{span}\{(-1, \frac{1}{2}, \frac{1}{2}, 1)\}.$
 - (f) $(\frac{9}{5}, \frac{1}{10}, \frac{11}{10}, \frac{6}{5})$
- 11. (a) It is easy to check that $\mathbf{u}_i \cdot \mathbf{u}_j = 0$ for $i \neq j$.
 - (b) For any $x \in \mathbb{R}^3$, by Theorem 5.2.8.

$$x=rac{x\cdot u_1}{u_1\cdot u_1}u_1+rac{x\cdot u_2}{u_2\cdot u_2}u_2+rac{x\cdot u_3}{u_3\cdot u_3}u_3=v+w$$

where
$$\boldsymbol{v} = \frac{\boldsymbol{x} \cdot \boldsymbol{u_1}}{\boldsymbol{u_1} \cdot \boldsymbol{u_1}} \boldsymbol{u_1} + \frac{\boldsymbol{x} \cdot \boldsymbol{u_2}}{\boldsymbol{u_2} \cdot \boldsymbol{u_2}} \boldsymbol{u_2} \in V \text{ and } \boldsymbol{w} = \frac{\boldsymbol{x} \cdot \boldsymbol{u_3}}{\boldsymbol{u_3} \cdot \boldsymbol{u_3}} \boldsymbol{u_3} \in W.$$

(i)
$$\mathbf{v} = (\frac{1}{3}, -\frac{1}{3}, \frac{1}{3})$$
 and $\mathbf{w} = (-\frac{1}{3}, \frac{1}{3}, \frac{2}{3})$.

(ii)
$$\mathbf{v} = (1, 1, 0)$$
 and $\mathbf{w} = (0, 0, 0)$.

12. (a)
$$\left\{ \frac{1}{\sqrt{2}}(1,0,1), \frac{1}{\sqrt{3}}(-1,1,1), \frac{1}{\sqrt{6}}(1,2,-1) \right\}$$

(b)
$$\left\{ \frac{1}{\sqrt{3}}(1,1,1), \frac{1}{\sqrt{6}}(1,-2,1), \frac{1}{\sqrt{2}}(1,0,-1) \right\}$$

13.
$$\left\{\frac{1}{\sqrt{5}}(2,1,0,0), \frac{1}{\sqrt{30}}(-1,2,0,5), \frac{1}{\sqrt{10}}(1,-2,-2,1), \frac{1}{\sqrt{15}}(1,-2,3,1)\right\}$$

- 14. (a) A general solution to x + y z = 0 is x = t s, y = s, z = t where $s, t \in \mathbb{R}$. So $\{(-1, 1, 0), (1, 0, 1)\}$ is a basis for the solution space. Using Gram-Schmidt process, we transform this basis into an orthonormal basis $\{\frac{1}{\sqrt{2}}(-1, 1, 0), \frac{1}{\sqrt{6}}(1, 1, 2)\}$.
 - (b) $(\frac{1}{3}, -\frac{2}{3}, -\frac{1}{3})$

sis for W.

- (c) Since (1, 1, -1) is orthogonal to the plane x + y z = 0, it is orthogonal to the vectors in the basis obtained in (a). So $\{\frac{1}{\sqrt{2}}(-1, 1, 0), \frac{1}{\sqrt{6}}(1, 1, 2), \frac{1}{\sqrt{3}}(1, 1, -1)\}$ is an orthonormal basis for \mathbb{R}^3 .
- 15. (a) We first show that u_2 and u_5 are linear combinations of u_1, u_3, u_4 .

$$\begin{pmatrix} 1 & 1 & 3 & 1 & -1 \\ 1 & 0 & 1 & 0 & -1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & -1 \end{pmatrix} \text{Gauss-Jordan} \begin{pmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 & 2 \\ 0 & 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} = \mathbf{R}$$

Thus $u_2 = -u_1 - u_3 + u_4$ and $u_5 = 2u_3 - u_4$. We have span $\{u_1, u_3, u_4\} = W$. Since the first three columns of the matrix R above are linearly independent, by Theorem 4.1.11, u_1, u_3, u_4 are linearly independent. Hence they form a basis for W.

(b)
$$v_1 = u_1(1, 1, 0, 0)$$

 $v_2 = u_3 - \frac{u_3 \cdot v_1}{v_1 \cdot v_1} v_1 = (\frac{1}{2}, -\frac{1}{2}, 1, 0)$
 $v_3 = u_4 - \frac{u_4 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{u_4 \cdot v_2}{v_2 \cdot v_2} v_2 = (\frac{1}{3}, -\frac{1}{3}, -\frac{1}{3}, 1)$
So $\{\frac{1}{\sqrt{2}}(1, 1, 0, 0), \frac{1}{\sqrt{6}}(1, -1, 2, 0), \frac{1}{\sqrt{12}}(1, -1, -1, 3)\}$ is an orthonormal ba-

(c) $\begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 3 & 1 & 1 & 1 \end{pmatrix}$ Gaussian $\begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{pmatrix}$

Let $\mathbf{w} = (0, 0, 0, 1)$. Then span $\{\mathbf{u_1}, \mathbf{u_3}, \mathbf{u_4}, \mathbf{w}\} = \mathbb{R}^4$. We continue the Gram-Schmidt Process in (b):

$$m{v_4} = m{w} - rac{m{w} \cdot m{v_1}}{m{v_1} \cdot m{v_1}} m{v_1} - rac{m{w} \cdot m{v_2}}{m{v_2} \cdot m{v_2}} m{v_2} - rac{m{w} \cdot m{v_3}}{m{v_3} \cdot m{v_3}} m{v_3} = (-rac{1}{4}, rac{1}{4}, rac{1}{4}, rac{1}{4}).$$

Thus $\{\frac{1}{\sqrt{2}}(1,1,0,0), \frac{1}{\sqrt{6}}(1,-1,2,0), \frac{1}{\sqrt{12}}(1,-1,-1,3), \frac{1}{2}(-1,1,1,1)\}$ is an orthonormal basis for \mathbb{R}^4 .

16. When a=1, $\mathbf{V}=\mathrm{span}\{(1,1,1)\}$ and hence $\left\{\left(\frac{1}{\sqrt{3}},\frac{1}{\sqrt{3}},\frac{1}{\sqrt{3}}\right)\right\}$ is an orthonormal basis for \mathbf{V} . The projection of (5,3,1) onto V is (3,3,3).

Suppose $a \neq 1$. Let $\mathbf{v_1} = (1, 1, 1)$ and $\mathbf{v_2} = (1, a, a) - \frac{(1, a, a) \cdot (1, 1, 1)}{(1, 1, 1) \cdot (1, 1, 1)} (1, 1, 1) = \frac{1-a}{3}(2, -1, -1)$. Then $\left\{\frac{1}{||\mathbf{v_1}||}\mathbf{v_1}, \frac{1}{||\mathbf{v_2}||}\mathbf{v_2}\right\} = \left\{\left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right), \left(\frac{2}{\sqrt{6}}, -\frac{1}{\sqrt{6}}, -\frac{1}{\sqrt{6}}\right)\right\}$ is an orthonormal basis for \mathbf{V} . The projection of (5, 3, 1) onto V is (5, 2, 2).

An alternatively basis for $a \neq 1$: We can write $\mathbf{V} = \text{span}\{(1,0,0), (0,1,1)\}$ and hence $\{(1,0,0), (0,\frac{1}{\sqrt{2}},\frac{1}{\sqrt{2}})\}$ is an orthonormal basis for \mathbf{V} .

17. (a)
$$\mathbf{w_1} = \frac{1}{\sqrt{3}}(1, 1, 1, 0)^{\mathrm{T}}, \ \mathbf{w_2} = (0, 0, 0, 1)^{\mathrm{T}}, \ \mathbf{w_3} = \frac{1}{\sqrt{6}}(-1, -1, 2, 0)^{\mathrm{T}}.$$

(b)
$$u_1 = \sqrt{3}w_1$$
, $u_2 = \sqrt{3}w_1 + w_2$, $u_3 = \frac{1}{\sqrt{3}}w_1 + w_2 + \frac{\sqrt{2}}{\sqrt{3}}w_3$.

(c) By (b),
$$\mathbf{A} = \begin{pmatrix} \mathbf{u_1} & \mathbf{u_2} & \mathbf{u_3} \end{pmatrix} = \begin{pmatrix} \mathbf{w_1} & \mathbf{w_2} & \mathbf{w_3} \end{pmatrix} \begin{pmatrix} \sqrt{3} & \sqrt{3} & \frac{1}{\sqrt{3}} \\ 0 & 1 & 1 \\ 0 & 0 & \frac{\sqrt{2}}{\sqrt{3}} \end{pmatrix}$$
.

Let
$$\mathbf{Q} = (\mathbf{w_1} \ \mathbf{w_2} \ \mathbf{w_3}) = \begin{pmatrix} \frac{1}{\sqrt{3}} & 0 & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & \frac{2}{\sqrt{6}} \\ 0 & 1 & 0 \end{pmatrix}$$
 and $\mathbf{R} = \begin{pmatrix} \sqrt{3} & \sqrt{3} & \frac{1}{\sqrt{3}} \\ 0 & 1 & 1 \\ 0 & 0 & \frac{\sqrt{2}}{\sqrt{3}} \end{pmatrix}$.

Then the columns of Q are orthonormal, R is an upper triangular matrix and A = QR.

18. Suppose $u = n_1 + p_1 = n_2 + p_2$ where n_1, n_2 are orthogonal to V and $p_1, p_2 \in V$. We need to show that $n_1 = n_2$ and $p_1 = p_2$.

Observe that $\mathbf{n}_i \cdot \mathbf{p}_j = 0$ for i, j = 1, 2.

By $n_1 + p_1 = n_2 + p_2$, we have $n_1 - n_2 = p_2 - p_1$. Thus

$$||n_1 - n_2||^2 = (n_1 - n_2) \cdot (n_1 - n_2)$$

= $(n_1 - n_2) \cdot (p_2 - p_1)$
= $n_1 \cdot p_2 - n_1 \cdot p_1 - n_2 \cdot p_2 + n_2 \cdot p_1 = 0$.

By Theorem 5.1.5.5, $n_1-n_2=0$ and hence $n_1=n_2$. Also, $p_2-p_1=n_1-n_2=0$ and hence $p_1=p_2$.

- 19. (a) $(\mathbf{A}\mathbf{u}) \cdot \mathbf{v} = (\mathbf{A}\mathbf{u})^{\mathrm{T}}\mathbf{v} = \mathbf{u}^{\mathrm{T}}\mathbf{A}^{\mathrm{T}}\mathbf{v} = \mathbf{u}^{\mathrm{T}}\mathbf{A}\mathbf{v} = \mathbf{u} \cdot (\mathbf{A}\mathbf{v}).$
 - (b) Since $\boldsymbol{A}(\boldsymbol{A}\boldsymbol{w}) = \boldsymbol{A}^2\boldsymbol{w} = \boldsymbol{A}\boldsymbol{w},\, \boldsymbol{A}\boldsymbol{w} \in V.$

Let $\mathbf{v} = \mathbf{w} - \mathbf{A}\mathbf{w}$. For any $\mathbf{u} \in V$,

$$u \cdot v = u \cdot w - u \cdot (Aw) = u \cdot w - (Au) \cdot w = u \cdot w - u \cdot w = 0.$$

So \boldsymbol{v} is orthogonal to V.

Since we can write $\mathbf{w} = A\mathbf{w} + \mathbf{v}$ where $A\mathbf{w} \in V$ and \mathbf{v} is orthogonal to V, $A\mathbf{w}$ is the projection of \mathbf{w} onto V.

- 20. (a) False. For example, let $\mathbf{u} = (1,0)$, $\mathbf{v} = (0,1)$, $\mathbf{w} = (2,0)$.
 - (b) True. Since \boldsymbol{w} is orthogonal to both \boldsymbol{u} and \boldsymbol{v} , $||\boldsymbol{u} + \boldsymbol{w}|| = \sqrt{||\boldsymbol{u}||^2 + ||\boldsymbol{w}||^2}$ and $||\boldsymbol{v} + \boldsymbol{w}|| = \sqrt{||\boldsymbol{v}||^2 + ||\boldsymbol{w}||^2}$.
 - (c) True. Since u is orthogonal to both v and w, $u \cdot (v + w) = u \cdot v + u \cdot w = 0$.
 - (d) False. For example, let u = (1,0), v = (0,1), w = (2,0).
- 21. (a) The line is spanned by (1,1). The projection of (1,5) onto the line is $\frac{(1,5)\cdot(1,1)}{(1,1)\cdot(1,1)}(1,1)=(3,3)$. So the distance from (1,5) to the line is $d((1,5),(3,3))=||(1,5)-(3,3)||=||(-2,2)||=\sqrt{8}$.
 - (b) The standard method is first to find the projection \boldsymbol{p} of \boldsymbol{w} onto the plane 2x + y 2z = 0. Then the distance from \boldsymbol{w} to the plane is $d(\boldsymbol{w}, \boldsymbol{p})$. However, the computation is quite tedious. In the following, we present an alternative method:

The distant from the point $\mathbf{w} = (1, 0, -2)$ to the plane 2x + y - 2z = 0 is equal to the length of the projection of \mathbf{w} onto the line perpendicular to the plane, i.e. the line spanned by $\mathbf{u} = (2, 1, -2)$. So the distant is

$$\left\| \frac{\boldsymbol{w} \cdot \boldsymbol{u}}{\boldsymbol{u} \cdot \boldsymbol{u}} \boldsymbol{u} \right\| = \frac{|\boldsymbol{w} \cdot \boldsymbol{u}|}{\boldsymbol{u} \cdot \boldsymbol{u}} ||\boldsymbol{u}|| = 2.$$

- (c) The line is spanned by (1,2,2). The projection of (1,0,-2) onto the line is $\frac{(1,0,-2)\cdot(1,2,2)}{(1,2,2)\cdot(1,2,2)}(1,2,2)=(-\frac{1}{3},-\frac{2}{3},-\frac{2}{3})$. So the distance from (1,0,-2) to the line is $d((1,0,-2),(-\frac{1}{3},-\frac{2}{3},-\frac{2}{3}))=||(1,0,-2)-(-\frac{1}{3},-\frac{2}{3},-\frac{2}{3})||=2$.
- 22. (a) $\begin{cases} C + D = 3 \\ C + 2D = 5 \\ C + 3D = 6 \end{cases}$

(b)
$$C = \frac{5}{3}$$
 and $D = \frac{3}{2}$.

- 23. Let x, y and z be the amount of money that Jack, Jim and John received respectively.
 - (a) The conditions are

$$\begin{cases} x + 2y &= 300 \\ y + z &= 300 \\ x & -2z &= 300. \end{cases}$$

The system is inconsistent. So there are no solution to the distribution problem.

- (b) The least squares solution to the system in (a) is x = 200 + 2t, y = 100 t and z = t where t is arbitrary. However, to make sure that x, y and z are all non-negative, we need to have $0 \le t \le 100$.
- 24. (a) It is easy to check.

(b)
$$x = 1, y = -\frac{2}{3}, z = 1.$$

25. (a)
$$x = \frac{1}{3}, y = \frac{1}{3}, z = \frac{1}{3}$$
.

(b)
$$\begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ -1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{3} \\ \frac{1}{3} \\ \frac{1}{3} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

26. (a)
$$\begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 0 \\ 0 & 1 & -2 \\ 1 & 2 & 3 \end{pmatrix}$$
Gaussian
$$\longrightarrow$$
Eliminaiton
$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

So $\{(1,0,1), (0,1,-2)\}$ is a basis for V.

(b) (i) Applying the Gram-Schmidt Process to the basis obtained in (a), we obtain an orthonormal basis $\{u_1, u_2\}$ for the column space of \boldsymbol{A} where $u_1 = \frac{1}{\sqrt{2}}(1,0,1)$ and $u_2 = \frac{1}{\sqrt{3}}(1,1,-1)$. Then the projection of \boldsymbol{w} onto V is $(\boldsymbol{w} \cdot \boldsymbol{u_1})u_1 + (\boldsymbol{w} \cdot \boldsymbol{u_2})u_2 = (\frac{4}{3}, \frac{1}{3}, \frac{2}{3})$.

(ii) The least squares solution to
$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
 is $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{4}{3} \\ \frac{1}{3} \end{pmatrix}$.

Since
$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} \frac{4}{3} \\ \frac{1}{3} \end{pmatrix} = \begin{pmatrix} \frac{4}{3} \\ \frac{1}{3} \\ \frac{2}{3} \end{pmatrix}$$
, the projection of \boldsymbol{w} onto V is $(\frac{4}{3}, \frac{1}{3}, \frac{2}{3})$.

- 27. (a) For both (i) and (ii), $x = (2, 1)^{T}$.
 - (b) Let v be a solution of Ax = b, i.e. Av = b. Since $A^{T}Av = A^{T}b$, v is also a solution of $A^{T}Ax = A^{T}b$. Then

the solution set of
$$(Ax = b) = \{u + v \mid u \in \text{the nullspace of } A\}$$

= $\{u + v \mid u \in \text{the nullspace of } A^{T}A\}$
= the solution set of $(A^{T}Ax = A^{T}b)$.

28. (a) It is easy to check that U and V are orthogonal. Since $\dim(\mathbb{R}^3) = 3$, by Remark 5.2.6, U and V are bases for \mathbb{R}^3 .

(b)
$$U' = \{\frac{1}{\sqrt{5}}(2,1,0), (0,0,1), \frac{1}{\sqrt{5}}(-1,2,0)\}$$

 $V' = \{\frac{1}{\sqrt{5}}(0,-1,2), \frac{1}{\sqrt{6}}(-1,2,1), \frac{1}{\sqrt{30}}(5,2,1)\}$

(c)
$$\mathbf{P} = \begin{pmatrix} \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0\\ 0 & 0 & 1\\ -\frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} & 0 \end{pmatrix}$$
 and $\mathbf{Q} = \begin{pmatrix} -\frac{1}{5} & \frac{2}{\sqrt{5}} & -\frac{2}{5}\\ 0 & \frac{1}{\sqrt{6}} & \frac{5}{\sqrt{30}}\\ \frac{12}{5\sqrt{6}} & \frac{1}{\sqrt{30}} & -\frac{1}{5\sqrt{6}} \end{pmatrix}$.

(d) Yes.

29. Let
$$\mathbf{R} = \begin{pmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$$
.

(a)
$$\mathbf{R}^{\mathrm{T}} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 + \frac{\sqrt{3}}{2} \\ \frac{1}{2} - \sqrt{3} \end{pmatrix}$$

(b)
$$\mathbf{R} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 - \frac{\sqrt{3}}{2} \\ \frac{1}{2} + \sqrt{3} \end{pmatrix}$$

(c)
$$\begin{pmatrix} 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 1 \Leftrightarrow \begin{pmatrix} 1 & 1 \end{pmatrix} \mathbf{R} \begin{pmatrix} x' \\ y' \end{pmatrix} = 1 \Leftrightarrow (1 + \sqrt{3})x' + (1 - \sqrt{3})y' = 2$$

30.
$$\mathbf{A} = \begin{pmatrix} \cos(\theta) & \sin(\theta) & 0 \\ -\sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

31. (a)
$$(\boldsymbol{u})_{S_1} = (1,4), (\boldsymbol{v})_{S_1} = (-1,1), (\boldsymbol{u})_{S_1} \cdot (\boldsymbol{v})_{S_1} = 3.$$

 $(\boldsymbol{u})_{S_2} = (-\frac{7}{3}, \frac{5}{3}), (\boldsymbol{v})_{S_2} = (-1,0), (\boldsymbol{u})_{S_2} \cdot (\boldsymbol{v})_{S_2} = \frac{7}{3}.$
 $(\boldsymbol{u})_{S_3} = (\frac{5}{\sqrt{2}}, \frac{3}{\sqrt{2}}), (\boldsymbol{v})_{S_3} = (0,\sqrt{2}), (\boldsymbol{u})_{S_3} \cdot (\boldsymbol{v})_{S_3} = 3.$
Note that $(\boldsymbol{u})_{S_1} \cdot (\boldsymbol{v})_{S_1} = (\boldsymbol{u})_{S_3} \cdot (\boldsymbol{v})_{S_3} \neq (\boldsymbol{u})_{S_2} \cdot (\boldsymbol{v})_{S_2}.$ See (b) for an explanation.

(b) Let \boldsymbol{P} be the transition matrix from S to T. Since S and T are orthonormal bases, P is orthogonal, i.e. $\boldsymbol{P}^{\mathrm{T}}\boldsymbol{P} = \boldsymbol{I}$. (To use the transition matrix, it is more convenient to write the coordinate vectors as column vectors, i.e. we use $[\boldsymbol{u}]_S$, $[\boldsymbol{v}]_S$, $[\boldsymbol{u}]_T$ and $[\boldsymbol{v}]_T$ in the following computation.)

$$[\boldsymbol{u}]_T \cdot [\boldsymbol{v}]_T = ([\boldsymbol{u}]_T)^{\mathrm{T}} [\boldsymbol{v}]_T = (\boldsymbol{P}[\boldsymbol{u}]_S)^{\mathrm{T}} (\boldsymbol{P}[\boldsymbol{v}]_S)$$
$$= ([\boldsymbol{u}]_S)^{\mathrm{T}} \boldsymbol{P}^{\mathrm{T}} \boldsymbol{P} [\boldsymbol{v}]_S = ([\boldsymbol{u}]_S)^{\mathrm{T}} [\boldsymbol{v}]_S = [\boldsymbol{u}]_S \cdot [\boldsymbol{v}]_S.$$

32. (a) $||A\boldsymbol{u}||^2 = (A\boldsymbol{u})^{\mathrm{T}}(A\boldsymbol{u}) = \boldsymbol{u}^{\mathrm{T}}A^{\mathrm{T}}A\boldsymbol{u} = \boldsymbol{u}^{\mathrm{T}}\boldsymbol{u} = ||\boldsymbol{u}||^2$. Since both $||\boldsymbol{u}||$ and $||A\boldsymbol{u}||$ are nonnegative, we have $||A\boldsymbol{u}|| = ||\boldsymbol{u}||$.

(b)
$$d(Au, Av) = ||Au - Av|| = ||A(u - v)|| = ||u - v|| = d(u, v)$$

(c)
$$(Au) \cdot (Av) = (Au)^{\mathrm{T}} Av = u^{\mathrm{T}} A^{\mathrm{T}} Av = u^{\mathrm{T}} v = u \cdot v$$
. So

the angle between
$$m{u}$$
 and $m{v} = \cos^{-1}\left(\frac{m{u}\cdot m{v}}{||m{u}||\,||m{v}||}\right)$
$$= \cos^{-1}\left(\frac{(m{A}m{u})\cdot (m{A}m{v})}{||m{A}m{u}||\,||m{A}m{v}||}\right)$$
$$= \text{the angle between } m{A}m{u} \text{ and } m{A}m{v}.$$

- 33. (a) Since \boldsymbol{A} is invertible, by Question 3.30(b)(i), T is linearly independent. So T is a basis for \mathbb{R}^n by Theorem 3.6.7.
 - (b) See Question 5.32.
 - (c) Yes.
- 34. (a) True. Note that $c_i \cdot c_j = 0$ if $i \neq j$ and $c_i \cdot c_i = 1$.

$$oldsymbol{A}^{ ext{ iny T}}oldsymbol{A}^{ ext{ iny T}}egin{pmatrix} oldsymbol{c_1} & \cdots & oldsymbol{c_k} \end{pmatrix} = egin{pmatrix} oldsymbol{c_1} \cdot oldsymbol{c_1} & \cdots & oldsymbol{c_1} \cdot oldsymbol{c_1} & \cdots & oldsymbol{c_k} \cdot oldsymbol{c_k} \end{pmatrix} = oldsymbol{I}_k.$$

- (b) False. For example, let $\mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$.
- (c) False. For example, let $\boldsymbol{A} = \boldsymbol{I}_2, \, \boldsymbol{B} = -\boldsymbol{I}_2.$
- (d) True. $(AB)^{\mathrm{T}}(AB) = B^{\mathrm{T}}A^{\mathrm{T}}AB = B^{\mathrm{T}}B = I$.