

Review 2.5 - 3.2

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Cofactor Expansion

Recalled that

$$\det(A) = a_{11}A_{11} + \cdots + a_{1n}A_{1n}, \quad A_{ij} = (-1)^{i+j} \det(M_{ij}).$$

A_{ij} is called the **cofactor** of a_{ij} , $\det(M_{ij})$ is called the **minor** of a_{ij} .

Theorem

For an $n \times n$ matrix $A = (a_{ij})$,

$$\det(A) = a_{i1}A_{i1} + \cdots + a_{in}A_{in}, \quad (\text{Along the } i\text{th row}).$$

Or

$$\det(A) = a_{1j}A_{1j} + \cdots + a_{nj}A_{nj}, \quad (\text{Along the } j\text{th column}).$$

Mathematical Induction

- Goal: To prove that a property $P(n)$ holds for every natural number n . (Sometime can be extended to all integers.)
- Steps.
 - ① The Initial Step: Prove that the statment holds for the first natural number n . (eg. $n = 0$ or $n = 1$ or larger one.)
 - ② The Induction Step: Assume that the statement holds for some natrual number k , and prove that then the statement hold for $k + 1$,
 - ③ The Conclusion Step: Hence, $P(n)$ is true for every $n \geq 0$ (or $n \geq 1$).

A example for illustrating mathematical induction

Theorem

If A is a square matrix, then $\det(A) = \det(A^T)$.

Proof.

First we restate the statement. For all $n \geq 1$, and A is a square matrix of order n , we have that $\det(A) = \det(A^T)$ holds.

- ❶ **The initial step.** *The first number is 1. So if A is 1×1 matrix, then A is a number, so $A = A^T$. Therefore, $\det(A) = A = A^T = \det(A^T)$.*
- ❷ **The induction step.** *Assume that the statement hold for $n = k$, i.e., $\det(A) = \det(A^T)$ holds for any $k \times k$ matrix. Now for $n = k + 1$, which means that A is $(k + 1) \times (k + 1)$ matrix. Then we expand along the first row of A to get $\det(A)$ and expand the first column of A^T to get $\det(A^T)$. And find that $\det(A) = \det(A^T)$ by assumption for $n = k$. So the statement holds for $n = k + 1$.*
- ❸ **The conclusion step.** *The statement holds for all $n \geq 1$.*



Determinants of Elementary Matrices

$$E_i(k) = \begin{bmatrix} \mathbb{I}_{i-1} & & \\ & k & \\ & & \mathbb{I}_{n-i} \end{bmatrix}, E_{ij} = \begin{bmatrix} \mathbb{I}_{i-1} & & & & \\ & 0 & & & 1 \\ & & \ddots & & \\ & 1 & & 0 & \\ & & & & \mathbb{I}_{n-j} \end{bmatrix},$$
$$E_{ij}(k) = \begin{bmatrix} \mathbb{I}_{i-1} & & & & \\ & 1 & & & \\ & & \ddots & & \\ & & & k & \\ & & & & 1 \\ & & & & & \mathbb{I}_{n-j} \end{bmatrix}$$

- 1 (Multiply i th row by a constant k) $\det(E_i(k)) = k$.
- 2 (Interchange i th row and j th row) $\det(E_{ij}) = -1$.
- 3 (Add a multiple of i th row to j th row) $\det(E_{ij}(k)) = 1$.

The most important theorem of determinant

Theorem

Let A be a square matrix and E be a elementary matrix of the same size of A . Then

$$\det(EA) = \det(E)\det(A).$$

- 1 If B obtained from A by multiplying i th row of A by a constant k , then $\det(B) = \det(E_i(k)A) = \det(E_i(k))\det(A) = k\det(A)$.
- 2 If B obtained from A by interchanges i th and j th rows of A , then $\det(B) = \det(E_{ij}A) = \det(E_{ij})\det(A) = -\det(A)$.
- 3 If B obtained from A by adding k times of i th row of A to j th row, then $\det(B) = \det(E_{ij}(k)A) = \det(E_{ij}(k))\det(A) = \det(A)$.
- 4 If the i th row and j th row of A are equal, then $\det(A) = \det(E_{ij}A) = -\det(A)$. So $\det(A) = 0$.
- 5 $\det(AB) = \det(A)\det(B)$.

Determinants of Row Equivalent Matrices

If A and B are row equivalent, i.e., B be obtained from A by perform a sequence of elementary row operations. Which means there exist a sequence of elementary matrices E_1, \dots, E_k such that

$$B = E_k \cdots E_1 A.$$

Hence,

$$\det(B) = \det(E_k) \cdots \det(E_1) \det(A).$$

Consequently:

- ① $\det(A) = 0$ if and only if $\det(B) = 0$.
- ② A is invertible (I and A are row equivalent) if and only if $\det(A) \neq 0$.
- ③ See Q1, Q2 and Q4.

The Adjoint of Matrix

Let $A = (a_{ij})_{n \times n}$, we consider $b_{ij} = a_{i1}A_{j1} + \cdots + a_{in}A_{jn}$.

- ① If $i = j$, then by the definition of determinant, $b_{ij} = \det(A)$.
- ② If $i \neq j$, suppose that $i < j$, consider

$$B = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{i1} & \cdots & a_{in} \\ \vdots & & \vdots \\ \textcolor{red}{a_{i1}} & \cdots & \textcolor{red}{a_{in}} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix}$$

cofactor expanding along j th row of B , then we can find that $b_{ij} = \det(B) = 0$ (since B has two rows identical).

The Adjoint of Matrix

Definition

Let A be a square matrix of order n . Then the *adjoint* of A is the $n \times n$ matrix

$$\text{adj}(A) = \begin{bmatrix} A_{11} & A_{12} & \cdots & A_{1n} \\ A_{21} & A_{22} & \cdots & A_{2n} \\ \vdots & \vdots & & \vdots \\ A_{n1} & A_{n2} & \cdots & A_{nn} \end{bmatrix}^T = \begin{bmatrix} A_{11} & A_{21} & \cdots & A_{n1} \\ A_{12} & A_{22} & \cdots & A_{n2} \\ \vdots & \vdots & & \vdots \\ A_{1n} & A_{2n} & \cdots & A_{nn} \end{bmatrix}$$

Theorem

Let A be a square matrix, if A is invertible. Then

$$A^{-1} = \frac{1}{\det(A)} \text{adj}(A).$$

Cramer's Rule

Let A is of order n , then if A is invertible, the unique solution of linear system $Ax = b$ can be written as

$$x = A^{-1}b = \frac{1}{\det(A)} \text{adj}(A)b.$$

Let

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

Then we have

$$x_i = \frac{b_1 A_{i1} + \cdots + b_n A_{ni}}{\det(A)} = \frac{\det(A_i)}{\det(A)}.$$

Where A_i is the matrix obtained from A by replacing the i th column of A by b . See Q3 (a), (b) and (c).

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Linear Combinations and Linear Spans

Definition

Let u_1, u_2, \dots, u_k be vectors in \mathbb{R}^n . For any real numbers c_1, c_2, \dots, c_k , the vector

$$c_1 u_1 + c_2 u_2 + \dots + c_k u_k$$

is called a *linear combination* of u_1, u_2, \dots, u_k .

Definition

Let $S = \{u_1, u_2, \dots, u_k\}$ be a set of vectors in \mathbb{R}^n . Then the set of all linear combinations of u_1, u_2, \dots, u_k ,

$$\{c_1 u_1 + c_2 u_2 + \dots + c_k u_k \mid c_1, c_2, \dots, c_k \in \mathbb{R}\},$$

is called the *linear span* of S , denoted by $\text{span}(S)$ ($\text{span}\{u_1, u_2, \dots, u_k\}$).

Determine if $x \in \text{span}(S)$.

Let $S = \{u_1, u_2, \dots, u_k\}$, and $u_i = (u_{i1}, u_{i2}, \dots, u_{in})$.

- 1 Write all the vector u_1, u_2, \dots, u_k in \mathbb{R}^n in the column form. Denote by $u_i^T, 1 \leq i \leq k$.
- 2 Then find c_1, \dots, c_k by solving the following linear system

$$c_1 u_1^T + c_2 u_2^T + \dots + c_k u_k^T = x^T.$$

- 3 Write the linear system in (2) in the matrix form,

$$\begin{bmatrix} u_{11} & u_{21} & \cdots & u_{k1} \\ u_{12} & u_{22} & \cdots & u_{k2} \\ \vdots & \vdots & & \vdots \\ u_{1n} & u_{2n} & \cdots & u_{kn} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_k \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_k \end{bmatrix}.$$

- 4 If the linear system is not consistent, then $x \notin \text{span}(S)$. Otherwise, c_1, \dots, c_k is a solution to the above linear system.