Question 1:

(a)

$$\begin{pmatrix} 0 & 1 & -b & | & 1 \\ 1 & a & 0 & | & 1 \\ a & 1 & b & | & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & a & 0 & | & 1 \\ 0 & 1 & -b & | & 1 \\ a & 1 & b & | & 1 \end{pmatrix} \xrightarrow{R_3 - aR_1} \begin{pmatrix} 1 & a & 0 & | & 1 \\ 0 & 1 & -b & | & 1 \\ 0 & 1 - a^2 & b & | & 1 - a \end{pmatrix}$$

Thus the linear system has infinitely many solutions if and only if

$$b(2-a^2) = 0$$
 and $a^2 - a = 0 \Leftrightarrow a = 0, b = 0$ or $a = 1, b = 0$.

(b) (i) We find a linear system such that a general solution to the system is

$$\begin{cases} x = 2+t \\ y = 1-t \\ z = t, t \in \mathbb{R} \end{cases}$$

A row-echelon form of the system's augmented matrix can be

$$\left(\begin{array}{cc|c} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \end{array}\right)$$

So the two planes can be $P_1: x-z=2$ and $P_2: y+z=1$.

(ii) We want ax + by + cz = d such that the reduced row-echelon form of

$$\begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \\ a & b & c & d \end{pmatrix} \quad \text{is} \quad \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \\ a & b & c & d \end{pmatrix} \xrightarrow{R_3 - aR_1} \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & b & c + a & d - 2a \end{pmatrix} \xrightarrow{R_3 - bR_2} \xrightarrow{}$$

$$\begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & c + a - b & d - 2a - b \end{pmatrix} = \mathbf{R}.$$

Since we want x = 1, y = 2, z = -1 to be the unique solution, we can choose a, b, c, d such that c+a-b=1 and d-2a-b=-1. For example a=b=c=1 and d=2. Verifying

$$\mathbf{R} = \begin{pmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & -1 \end{pmatrix} \xrightarrow{R_1 + R_3} \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -1 \end{pmatrix}.$$

We thus have $P_3: x + y + z = 2$.

Question 2

(iii)

(i)
$$\begin{pmatrix} 1 & -2 & 1 & 1 & 0 & 0 \\ 2 & -5 & 1 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 - 2R_1} \begin{pmatrix} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 1 & 2 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 + R_2} \xrightarrow{\boldsymbol{E}_2} \begin{pmatrix} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & -1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{pmatrix} \xrightarrow{\boldsymbol{E}_3} \begin{pmatrix} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{pmatrix} \xrightarrow{R_1 - R_3} (\boldsymbol{E}_4) \xrightarrow{\boldsymbol{E}_3} \begin{pmatrix} 1 & -2 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 2 & -1 & 0 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{pmatrix} \xrightarrow{R_2 - R_3} (\boldsymbol{E}_5)$$

$$\begin{pmatrix} 1 & -2 & 0 & 3 & -1 & -1 \\ 0 & 1 & 0 & 4 & -2 & -1 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{pmatrix} \xrightarrow{\boldsymbol{E}_6} \begin{pmatrix} 1 & 0 & 0 & 11 & -5 & -3 \\ 0 & 1 & 0 & 4 & -2 & -1 \\ 0 & 0 & 1 & -2 & 1 & 1 \end{pmatrix}.$$
So $\boldsymbol{A}^{-1} = \begin{pmatrix} 11 & -5 & -3 \\ 4 & -2 & -1 \\ -2 & 1 & 1 \end{pmatrix}.$

(ii)
$$E_6E_5\cdots E_2E_1A=I$$
. So,
$$\det(E_6)\cdots\det(E_1)\det(A)=1\Rightarrow -\det(A)=1\Rightarrow \det(A)=-1.$$

$$\operatorname{adj}(\boldsymbol{A}) = -\boldsymbol{A}^{-1} \Rightarrow \operatorname{adj}(\boldsymbol{A})^{-1} = -\boldsymbol{A}.$$
So
$$\operatorname{adj}(\boldsymbol{A})\boldsymbol{x} = \begin{pmatrix} 1\\0\\-1 \end{pmatrix} \Leftrightarrow \boldsymbol{x} = \operatorname{adj}(\boldsymbol{A})^{-1} \begin{pmatrix} 1\\0\\-1 \end{pmatrix} = -\begin{pmatrix} 1&-2&1\\2&-5&1\\0&1&2 \end{pmatrix} \begin{pmatrix} 1\\0\\-1 \end{pmatrix} = \begin{pmatrix} 0\\-1\\2 \end{pmatrix}.$$

(iv) Note that $\mathbf{E_2}\mathbf{E_1}\mathbf{A} = \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & -1 \\ 0 & 0 & 1 \end{pmatrix} = \mathbf{U}$, an upper triangular matrix.

$$\mathbf{A} = \mathbf{E_1}^{-1} \mathbf{E_2}^{-1} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \\
= \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \\
= \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \\
= \mathbf{L}\mathbf{U}$$

where $\mathbf{L} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$ is a lower triangular matrix.

Question 3

(i) Let $\mathbf{A} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. If \mathbf{A} is anti-symmetric, then

$$\boldsymbol{A} = -\boldsymbol{A}^T \Leftrightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} -a & -c \\ -b & -d \end{pmatrix} \Leftrightarrow a = -a, d = -d, b = -c \Leftrightarrow a = d = 0, b = -c.$$

Thus $\mathbf{A} = \begin{pmatrix} 0 & b \\ -b & 0 \end{pmatrix}$. Since \mathbf{A} is non zero, $b \neq 0$. The determinant of \mathbf{A} is $b^2 \neq 0$, so \mathbf{A} is invertible.

(ii) $\mathbf{A} = -\mathbf{A}^T \Rightarrow \det(\mathbf{A}) = (-1)^n \det(\mathbf{A}^T) = -\det(\mathbf{A}^T)$ (since n is odd)

But since $\det(\mathbf{A}^T) = \det(\mathbf{A})$, we have $\det(\mathbf{A}) = -\det(\mathbf{A})$ which implies that $\det(\mathbf{A}) = 0$. So \mathbf{A} is singular.

Question 4

(a) (i)

$$S_1 = \{(t, s-t, s) \mid s, t \in \mathbb{R}\}$$

= \{t(1,-1,0) + s(0,1,1) \| s, t \in \mathbb{R}\}
= \span\{(1,-1,0),(0,1,1)\}

Thus S_1 is a subspace of \mathbb{R}^3 .

- (ii) Let $\mathbf{u} = (0, 1, 2)$, $\mathbf{v} = (1, 0, 0)$. Then both \mathbf{u}, \mathbf{v} belongs to S_2 . But $\mathbf{u} + \mathbf{v} = (1, 1, 2)$ which does not belong to S_2 . So S_2 is not a subspace of \mathbb{R}^3 .
- (b) (i) Note that $(1,0) \in U$ (since $(1,0) \in V$) and $(0,2) \in U$ (since $(0,2) \in W$). But (1,0)+(0,2)=(1,2) which does not belong to U since (1,2) does not belong to V nor W. Thus U is not a subspace.
 - (ii) If W is the zero space, the U=V which is a subspace of \mathbb{R}^2 . If $W=\mathbb{R}^2$, then we also have $U=\mathbb{R}^2$, which is a subspace of \mathbb{R}^2 .