

LECTURE 6: PRIORITY QUEUES & BINARY HEAPS

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ADMINISTRATIVE ISSUES

Discussion/Tutorial group sheets are on Piazza.

Which part of the DG/Tutorial was most challenging?

- A. Nothing. It was all good. ©
- B. The sorting invariants! Yuck!
- C. The recurrence relations / asymptotic analysis.
- D. Definitely Guess-the-Number.
- E. OMG! All so difficult! Halp! 🕾
- F. What's a "discussion group"?

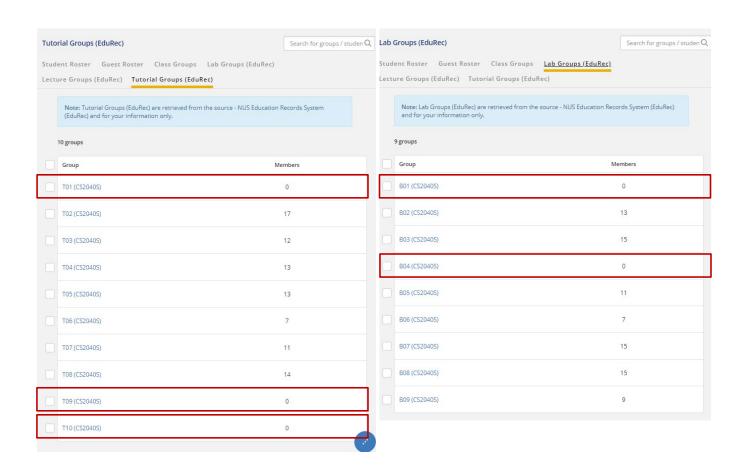
TUTORIALS AND LABS/DISCUSSION GROUPS

New allocations on Luminus.

Effective immediately.

Cancelled Groups:

- Labs: B01, B04
- Tutorials: T01, T09, T10







Quiz 1 is tomorrow

- Wednesday (4th Sept) during Lecture
- Both MCQ and Open-ended
- 3 Multipart questions.
- Open-book quiz
- No magnifying glass.
- No electronic equipment allowed.

QUIZ ADVICE

Don't panic!

Go through Visualgo and the lecture notes.

Sleep well the night before.

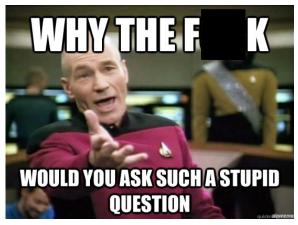
Sometimes, questions just look hard.

Don't spend too long on any one question.

If you are unsure about something, raise your hand and ask.







1. Understand the Problem

- Understand what the problem is.
- Read through it carefully.

2. Analyze the Problem

- Analyze the problem:
- What type of problem is it?
- Have I seen something like it before?

3. Figure out a Solution.

- Is the solution apparent?
- Draw upon what you have learnt.
- If not, use one of the strategies taught before, e.g.,
 - Derive the most straightforward correct solution (baseline).

4. Analyze the Solution

 What are the performance characteristics of the solution?

5. Describe the solution.

- Write the down neatly and clearly.
- Explain the method and also the performance characteristics.

6 Improve the solution

- What operations are expensive? Can I use a data structure to improve these operations?
- Can I trade memory for time?
- Is there structure (ordered, semiordered)?
- Divide and Conquer?
- Etc.

ADVICE:

Understanding + Analyzing the problem is usually 50-90% of the battle.

The solution may *not* be obvious at first.

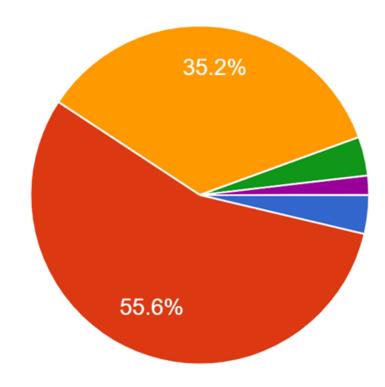
It may take some hard thinking to "see" it.

The **best solution** is **often not obvious** at first.

You have the tools to do all 6 steps.

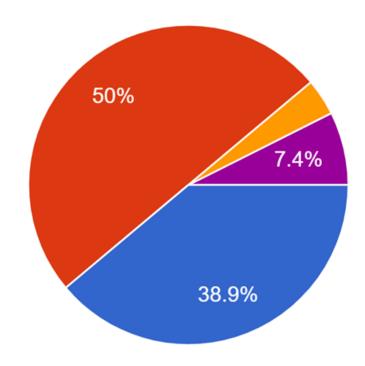
LECTURE FEEDBACK

How do you find the speed of the lectures?



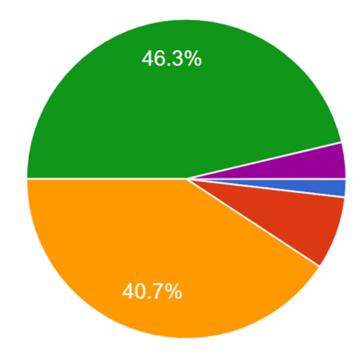
- It's too fast and I find it difficult to understand anything
- it's ok, but can be a little too fast at points
- It's just right. I understand most/all of the material
- it's a little slow. I think we can go faster.
- It's very slowwww. Yaaawwwnnn.Please speed up!

We are focussing on problem solving in class. Do you like the current style of teaching? (v.s. regular lectures)



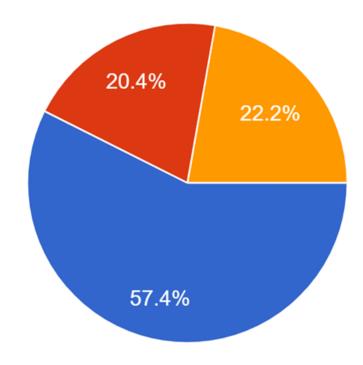
- Yes, I like the current approach
- Yes, but I think more explanation would help me understand better
- Meh. I'm neutral about it.
- No, I think we are spending too much time on problem solving
- No, I prefer just regular lectures.
 Leave problem solving to assignments and tutorials

How difficult is the material?



- Too Easy. I think you should increase material complexity and depth.
- Easy enough; could be a little more challenging
- It's ok. I'm neutral about this.
- The material is a little challenging.
 Some portions are difficult to understand
- It's *much* too difficult. I'm having a tough time understanding anything

Do you think the "Extra" material is helpful?



- Yes. It helps me become aware of the more advanced concepts.
- Mostly yes. But I don't always see how the information fits in.
- I'm neutral about this.
- Mostly no. I don't see the point.
- No, definitely not. Leave it to the higher-level courses.

LECTURE FEEDBACK: MAIN COMMENTS

Webcasts:

Will test webcasts out. :P

"please enable WEBCASTS!...."

"Having webcast will be better, currently it is hard to revise lecture material with just the lecture slides."

"There can be webcast for lectures, to allow for better revision after the lectures."

"I would personally prefer webcast so that I can refer to it again if I have doubts. Maybe delay webcast broadcast by 2 to 3 sessions so as to prevent students from skipping lectures?"

Many many more...

EXTRA MATERIALS

There's already a section. We'll post more stuff!

"...the "extra" materials are really interesting but a little bit difficult to understand and just a tiny bit more explanation would go a really long way... the depth covered in class is a little lacking and rushed... But perhaps that is your goal, to pique our interest, but to have us not completely understand so we can look it up ourselves? If that is the case, you've succeeded but at the same time left me feeling a little cheated:("

"Maybe there can also be an extra extra section for more readings/links to resources that are interesting/go more in depth"

DIFFICULTY

- Labs will often revise the weeks (or previous week's material)
- Problem sets have easy and challenge problems
 - See Tips and Hints on piazza.
- Tutorials are meant to train on-the-spot thinking.

"the lab is really really really very hard.... the stuff taught in the lecture and the lab feel very different. The algo that the lab question is trying to test is not very obvious..."

"I find the lectures okay, but the assignment I think is way too difficult."

"Hopefully, tutorials can be released before the actual tutorial because the pace of tutorial is too fast for me and I needed more time to think about approaching the qns etc."

POLLING TIME

Will try to adjust polling time.

"I don't really like the poll in lectures as i feel it wastes quite a bit of time"

"i think the breaks for answering are a bit long sometimes."

"I think we could possibly save some time if we cut down the "waiting time" for closing the polls."

If you have any other feedback, please share it with me or the Tas.

QUESTIONS?



LEARNING OUTCOMES

By the end of this session, students should be able to:

- Describe the priority queue ADT and its operations
- Describe the binary heap data structure and explain how it works
- Analyze the performance of the binary heap data structure
- Describe the heapsort algorithm and explain how it works
- Analyze the performance of heapsort

PROBLEM: PRIORITIZING PATIENTS AT THE HOSPITAL

Each patient assigned a priority score.

Doctors need to see the highest priority patients first!



DESIGN AN ABSTRACT DATA TYPE FOR THIS PROBLEM



What operations would we need to support?







Operations:

- insert(x) : inserts x
- max(): returns element with the highest priority
- extractMax(): returns and remove the highest priority element
- size(): returns the size of the queue
- buildHeap(A): creates a priority queue from an array of patients





Operations:

- insert(x)
- max()
- extractMax()
- size()
- buildHeap(A)

What is the worst-case time complexity of insert followed by extractMax if we use a singly linked list?

A. O(1)

B. O(n)

C. $O(\log n)$

D. $O(n^2)$

E. I predict there will be complexity questions in the quiz.





Operations:

- insert(x)
- max()
- extractMax()
- size()
- buildHeap(A)

Have to scan through the array to find the max (or the next maximum) or inserts have to maintain sorted order What is the worst-case time complexity of insert followed by extractMax if we use a singly linked list?

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What is the worst-case time complexity of insert followed by extractMax if <u>we use an array</u>?

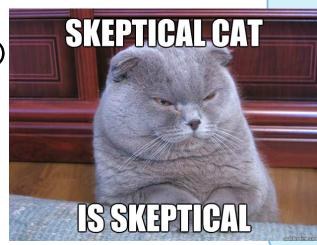
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Unsorted array



Insert: O(1)

Max: O(n)

Search: O(n)





Insert: O(n)

Max: O(1)

Search: O(logn)

Unordered

Ordered

The more "ordered" your structure:

 the more prior information you can exploit to speed up certain operations.

But: you will likely have to pay to maintain this order.

 some operations (e.g., that change the data) will become more expensive



Unsorted array



Insert: O(1)

Max: O(n)

Search: O(n)





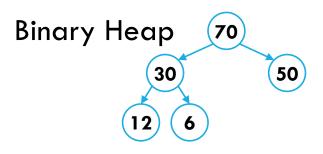
Insert: O(n)

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Ordered







Insert: O(1)

Max: O(n)

Search: O(n)



Insert: O(logn)

Max: O(1)

Search: O(n)

Sorted array



Insert: O(n)

Max: O(1)

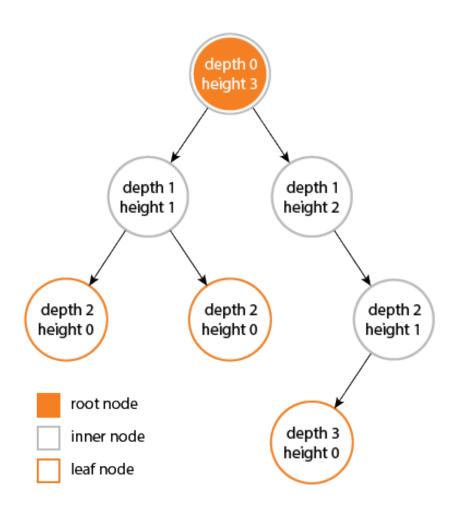
Search: O(logn)

Unordered

Ordered





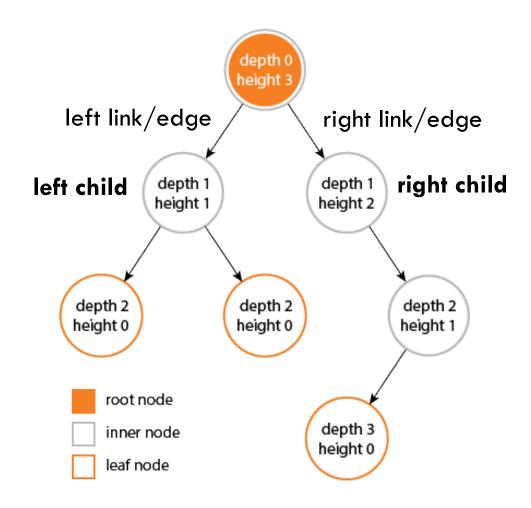


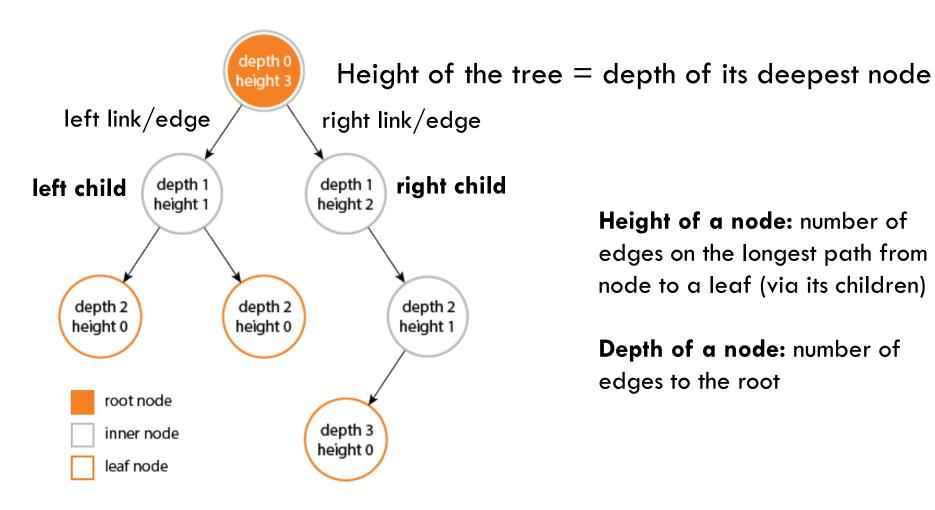
Remark. A picture like this is called a *tree*. (This is not a formal definition; that will follow later.) If you want to know why the tree is growing upside down, ask the computer scientists who introduced this convention. (The conventional wisdom is that they never went out of the room, and so they never saw a real tree.)

depth 0 height 3 depth 1 depth 1 height 1 height 2 depth 2 depth 2 depth 2 height 0 height 0 height 1 root node depth 3 inner node height 0 leaf node

Discrete Mathematics: Elementary and Beyond

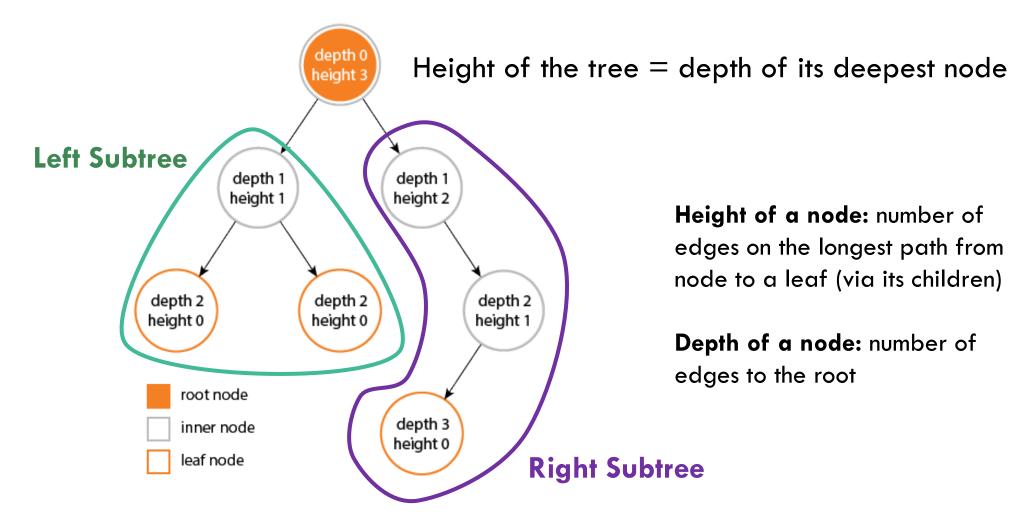
By László Lovász, József Pelikán, Katalin Vesztergombi

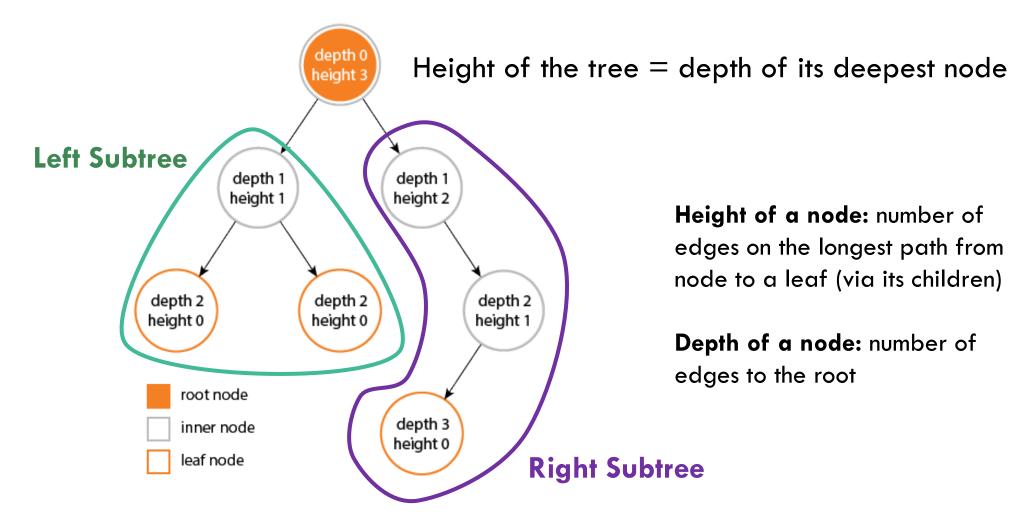




Height of a node: number of edges on the longest path from node to a leaf (via its children)

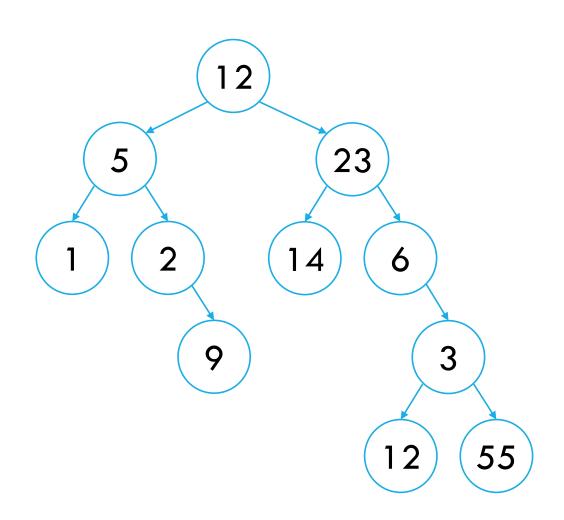
Depth of a node: number of edges to the root







A BINARY TREE

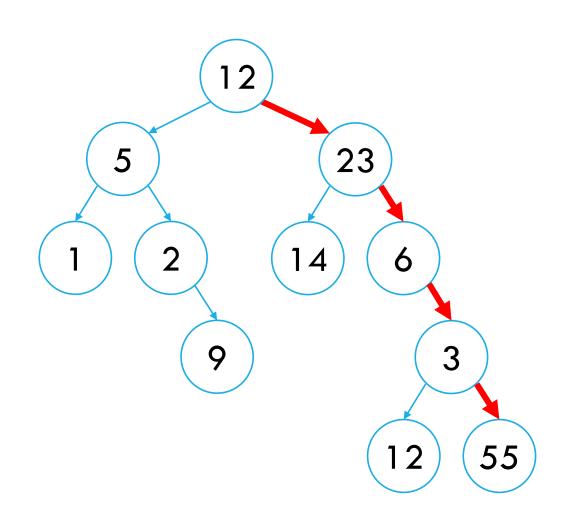


What is the height of the tree?

- A. 1
- B. 3
- C. 4
- D. 5
- E. Height.. depth.. why is the tree upside down?!



A BINARY TREE



What is the height of the tree?

- **A.** 1
- B. 3
- **C**. 4
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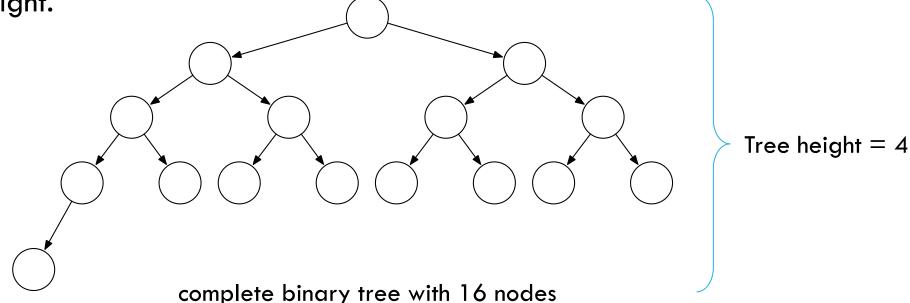
COMPLETE BINARY TREE

Binary Tree: nodes with links to left and right binary trees (or empty)

Complete tree: Perfectly balanced, except for bottom level

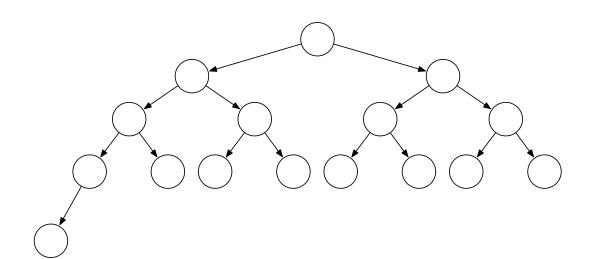
all levels completely filled except possibly last level where the keys are filled from

left to right.





COMPLETE BINARY TREE



What is the height *h* of a complete binary tree with n nodes?

A.
$$h = n$$

B.
$$h = 2^n$$

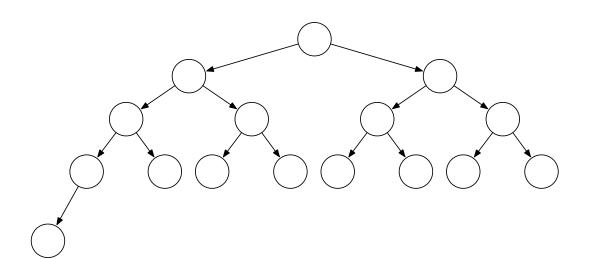
C.
$$h = \log n$$

D.
$$h = \lfloor \log n \rfloor$$

E. None of the above



COMPLETE BINARY TREE



What is the height *h* of a complete binary tree with n nodes?

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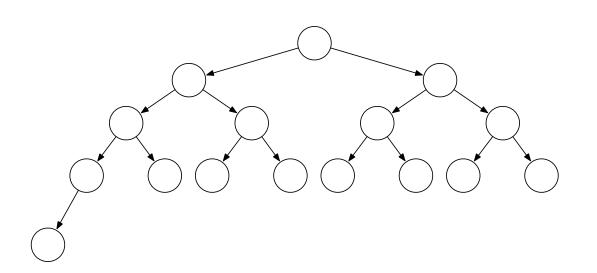
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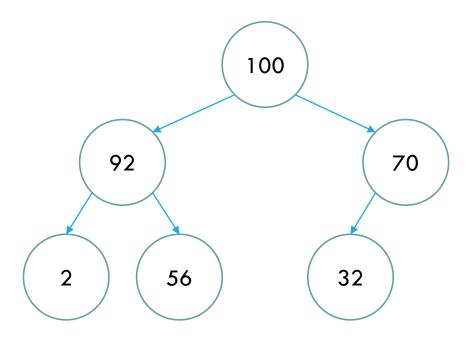
E. None of the above

HEIGHT OF A COMPLETE BINARY TREE



# Nodes	$\log n$	$h = \lfloor \log n \rfloor$
1	0.00	0
2	1.00	1
3	1.58	1
4	2.00	2
7	2.81	2
8	3.00	3
15	3.91	3
16	4.00	4





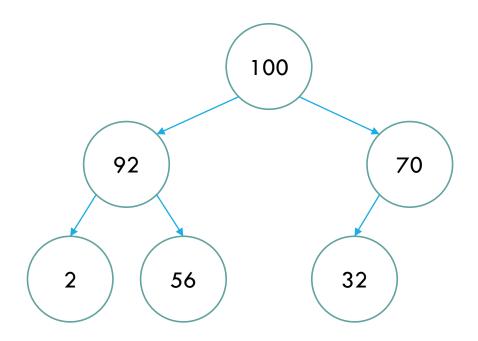
Max heap property:

 the key of each node is larger than or equal to the keys in its children

- A. Yes.
- B. No, there is a violation.
- C. Maybe yes.. Maybe no...
- D.







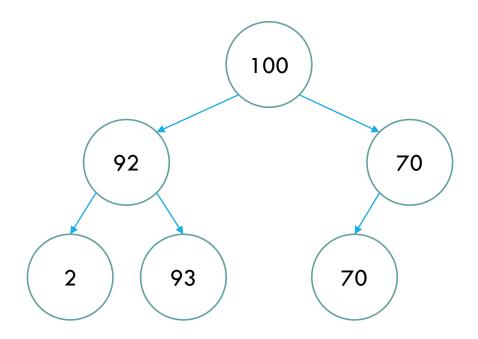
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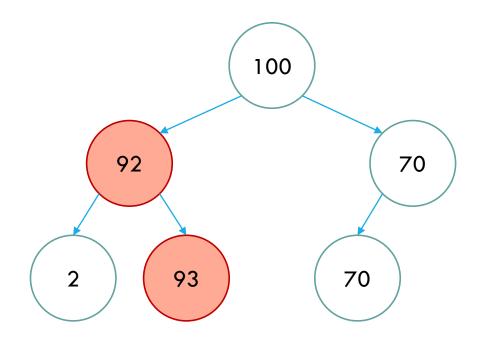
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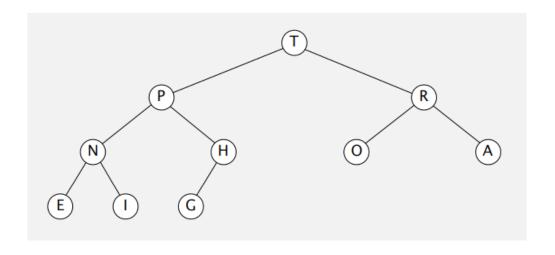
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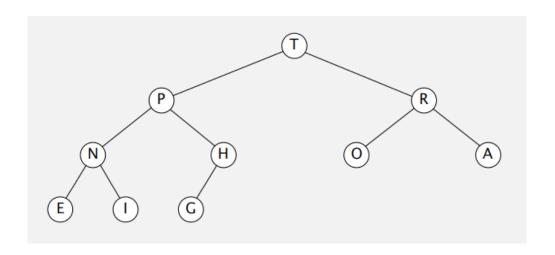


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- D. Where did the numbers go?
- E. Depends on how we define our comparator.





Max heap property:

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TREE REPRESENTATION

Class Node

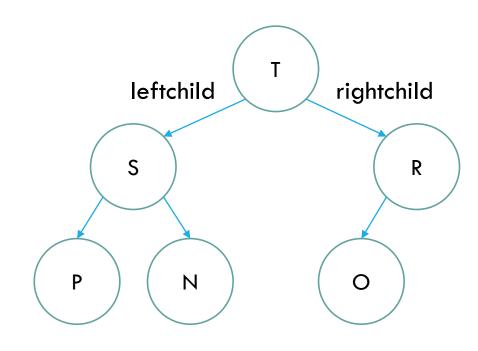
Object key

Object data

Node leftchild

Node rightchild

Node parent



ARRAY REPRESENTATION



Indices start at 1

Take nodes in level order

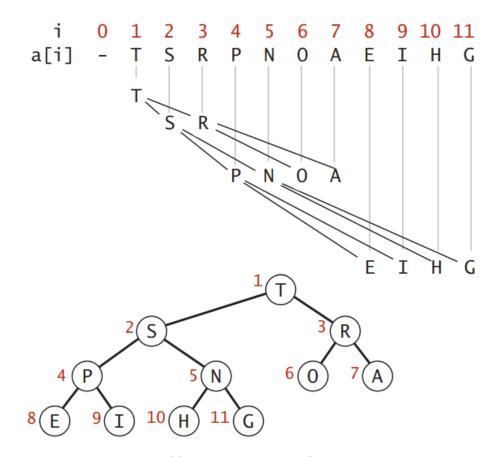
No links needed

Parent of node k is at _____

Children of node k are at:

Left Child: _____

Right Child: _____



Heap representations

ARRAY REPRESENTATION



Indices start at 1

Take nodes in level order

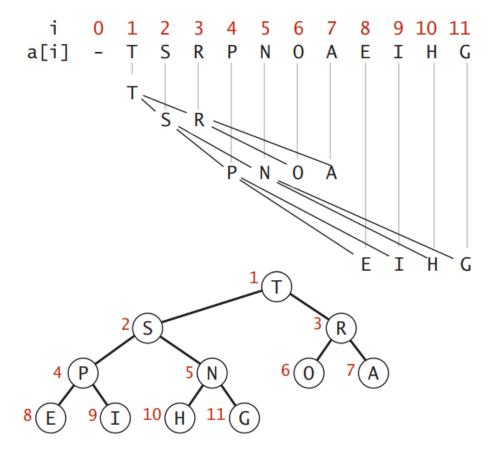
No links needed

Parent of node k is at k/2

Children of node k are at:

Left Child: _____

Right Child: _____



Heap representations

ARRAY REPRESENTATION



Indices start at 1

Take nodes in level order

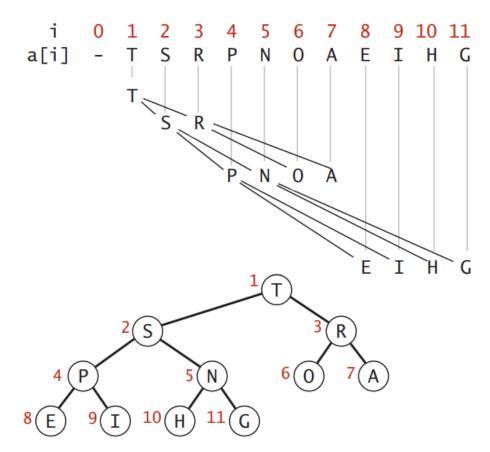
No links needed

Parent of node k is at k/2

Children of node k are at:

Left Child: 2k

Right Child: 2k + 1



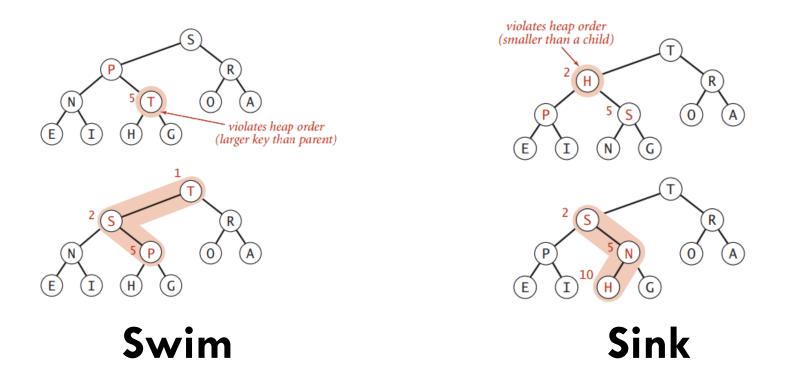
Heap representations

TWO IMPORTANT OPERATIONS: SWIM & SINK



We use these operations to correct binary trees to satisfy the max heap property

TWO IMPORTANT OPERATIONS: SWIM & SINK



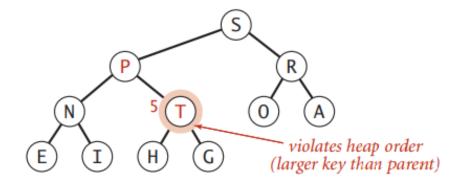
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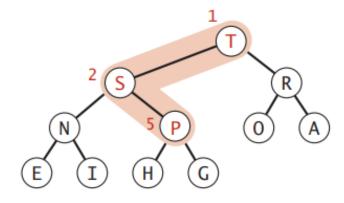
SWIM or (SHIFTUP, BUBBLEUP, INCREASEKEY)

Problem: A key becomes larger than its parent's key.

Solution:

- Swap child with parent
- Repeat until heap order restored





SWIM or (SHIFTUP, BUBBLEUP, INCREASEKEY)

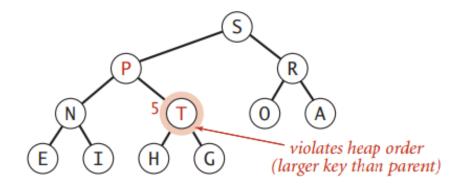
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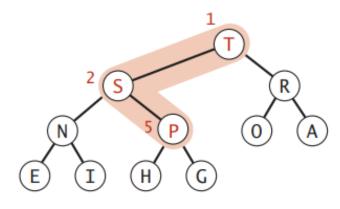
Solution:

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Pseudocode for array implementation

```
function swim(A, k)
while (k > 1) and A[k/2].key < A[k].key
swap(A[k], A[k/2])
<math>k = k/2
```





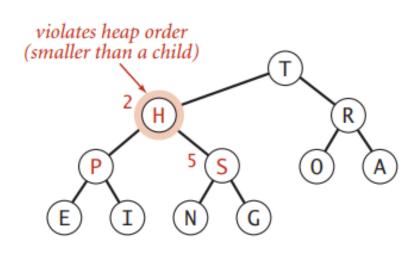


SINK or (SHIFTDOWN, BUBBLEDOWN, HEAPIFY)

Problem: A key becomes smaller than one (or both) of its children's keys.

Solution:





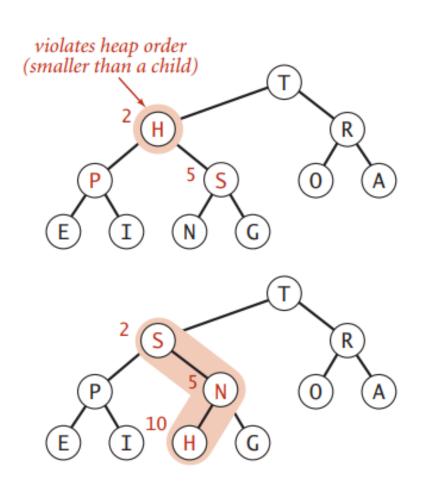


SINK or (SHIFTDOWN, BUBBLEDOWN, HEAPIFY)

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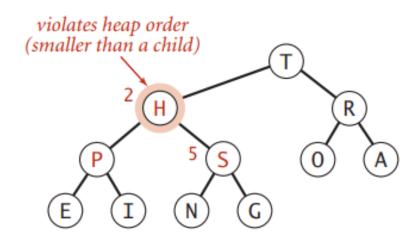
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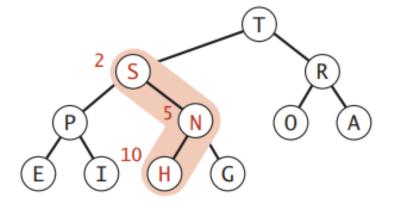
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Pseudocode for array implementation





THE (MAX) PRIORITY QUEUE ADT

Operations:



- insert(x) : inserts x
- max(): returns element with the highest priority
- extractMax(): returns and remove the highest priority element
- size(): returns the size of the queue
- buildHeap(A): creates a priority queue from an array of patients



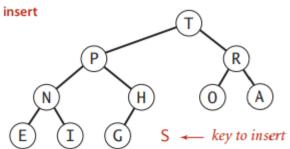
BINARY HEAP: INSERTION

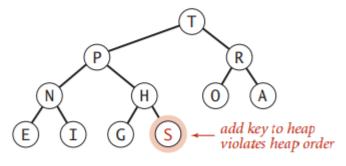
Idea:

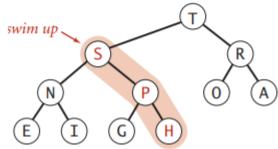
- Add at node at the "end" (first available leaf)
- Swim it up

What is the cost of insertion?

- A. O(n)
- B. O(1)
- C. $O(\log n)$
- D. So, so confusing!









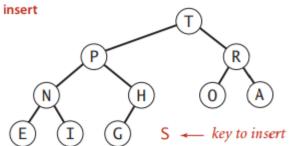
BINARY HEAP: INSERTION

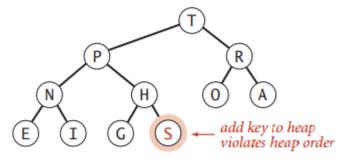
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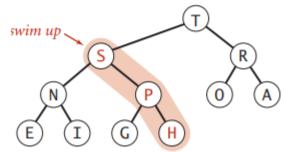
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THE (MAX) PRIORITY QUEUE ADT

Operations:

insert(x) : inserts x

Just return the root! O(1)



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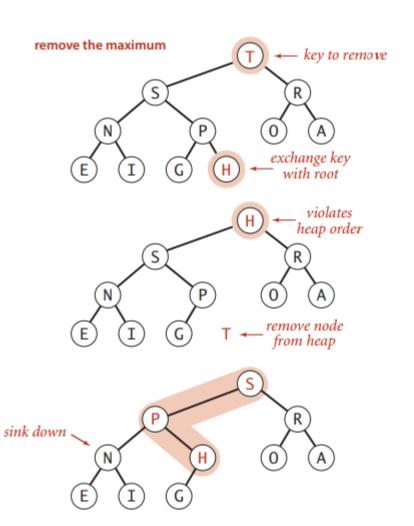
BINARY HEAP: EXTRACTMAX

Idea:

- Remove the root
- Exchange last element with root
- Sink it down.

What is the cost of extractMax?

- A. O(n)
- B. O(1)
- C. $O(\log n)$
- D. I love these asymptotic analysis questions!





BINARY HEAP: EXTRACTMAX

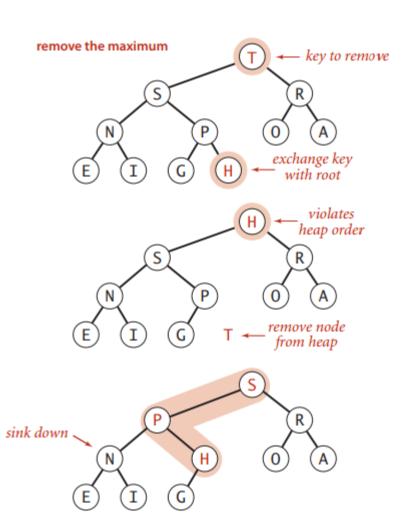
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- B. O(1)
- C. $O(\log n)$
- D. I love these asymptotic analysis questions!

Why?



THE (MAX) PRIORITY QUEUE ADT

Operations:

- insert(x):inserts x
- max(): returns element with the highest priority
- extractMax(): returns and remove the highest priority element
- size(): returns the size of the queue
- buildHeap(A): creates a priority queue from an array of patients



CREATE

Given an unsorted array A of elements, how long do we need to create a binary heap?

What is the time cost of buildHeap?

- A. $O(n \log n)$
- B. O(1)
- C. O(n)
- D. The answer has to be A.



CREATE

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What is the time cost of buildHeap?

- A. $O(n \log n)$
- B. O(1)
- C. O(n)
- D. The answer has to be A.

The idea:

Insert each element one by one. Each insert takes $O(\log n)$ time. Total for n elements is $O(n \log n)$

CLEVER CREATION IN O(n) TIME



Invented by Robert Floyd in 1964

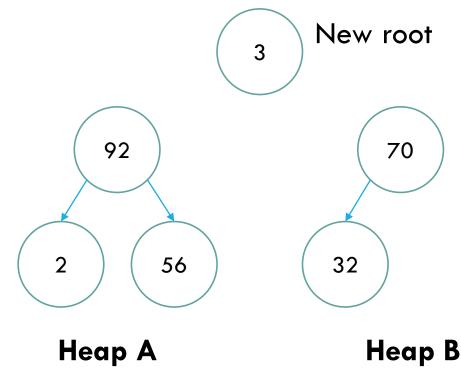
- invented invariants (among other things)
- we'll hear about him again in when we meet graphs!

The idea:

- View the input array as a binary tree
- "Bottom up" fixing of the tree to satisfy MaxHeap property

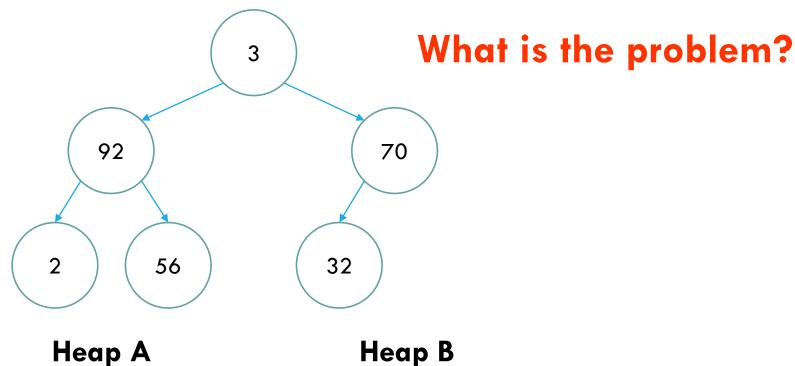
CLEVER CREATION IN O(n) TIME

Say we have two binary heaps we want to "combine" with a new root node.



CLEVER CREATION IN O(n) TIME

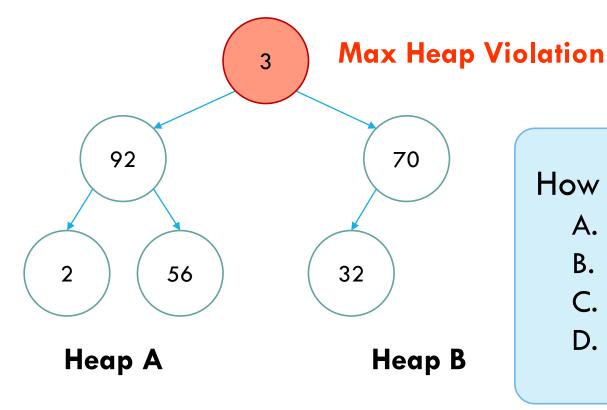
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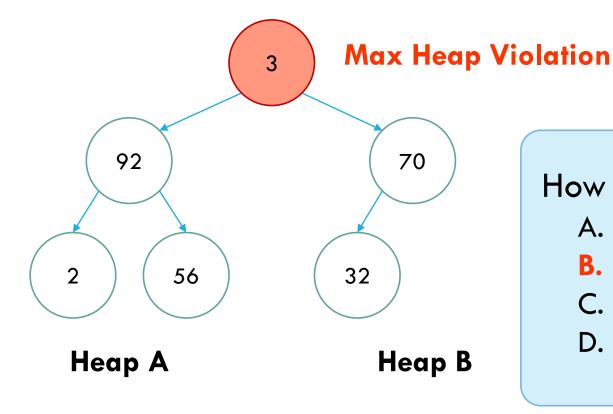
- A. Swim!
- B. Sink!
- C. Sink and swim!
- D. Naruto and I are not good swimmers.





Say we have two binary heaps we want to "combine" with a new

root node.

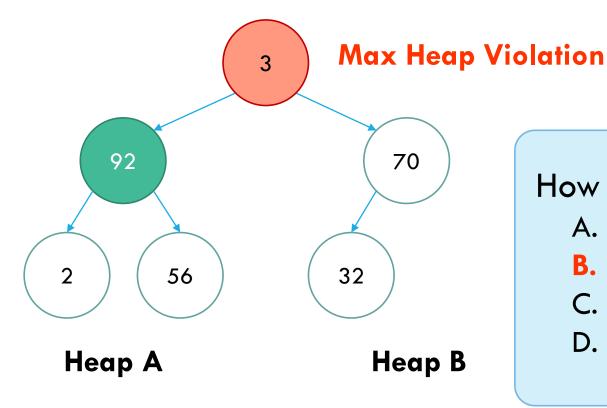


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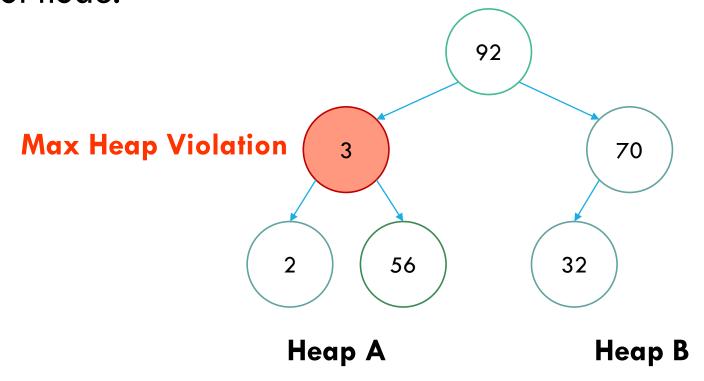


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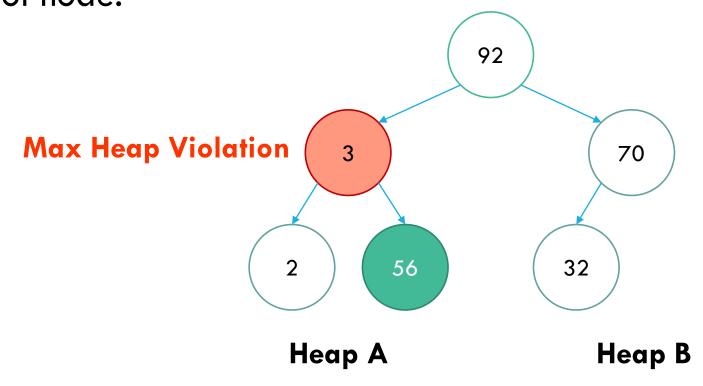


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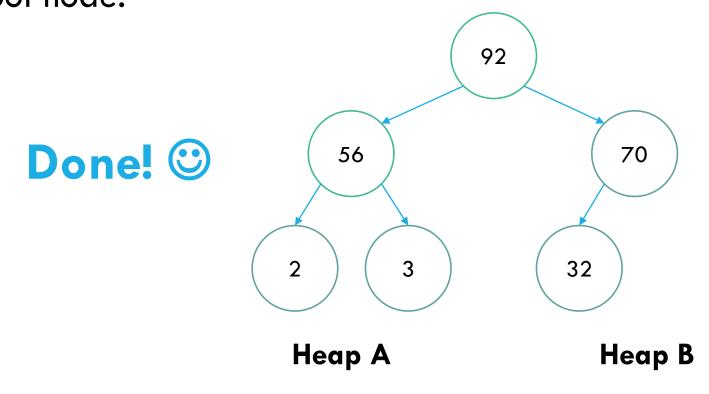


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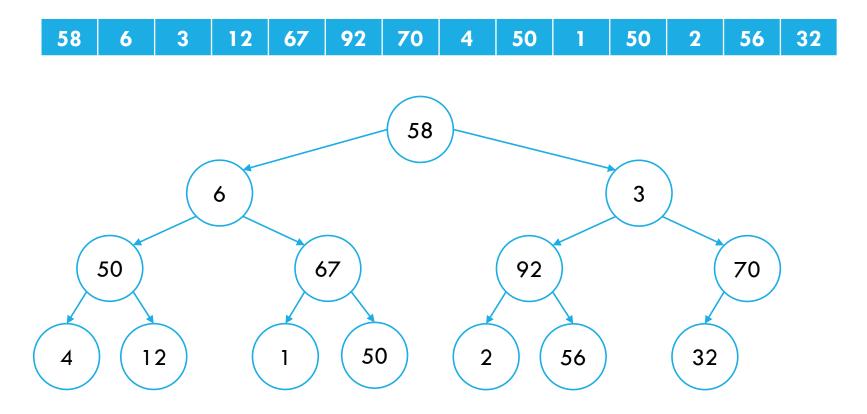


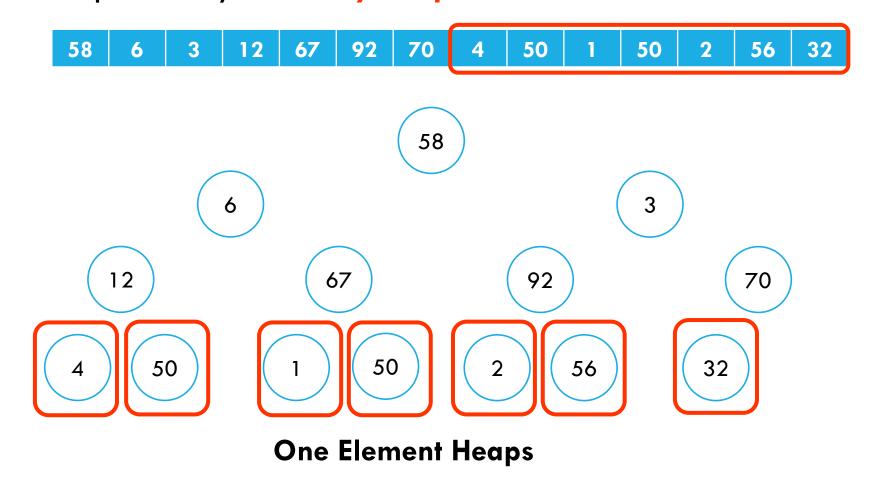
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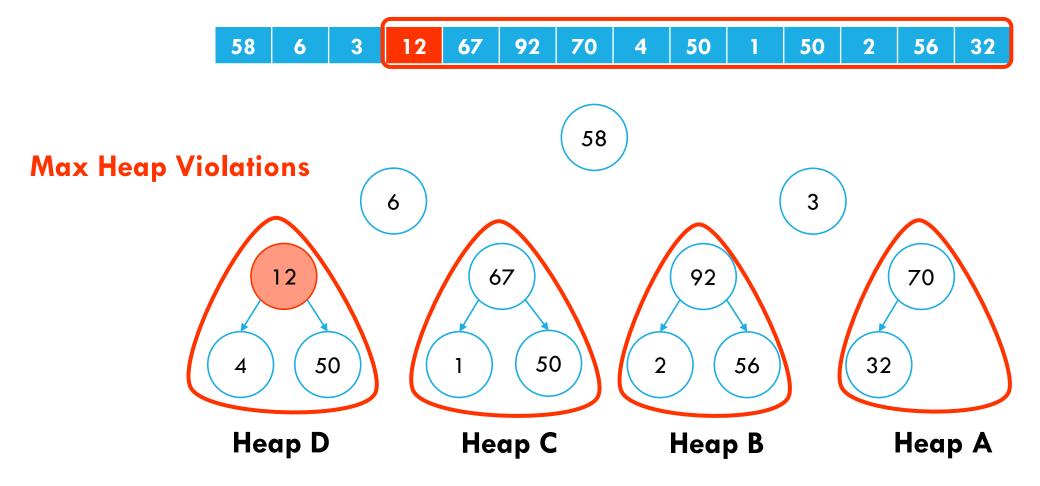


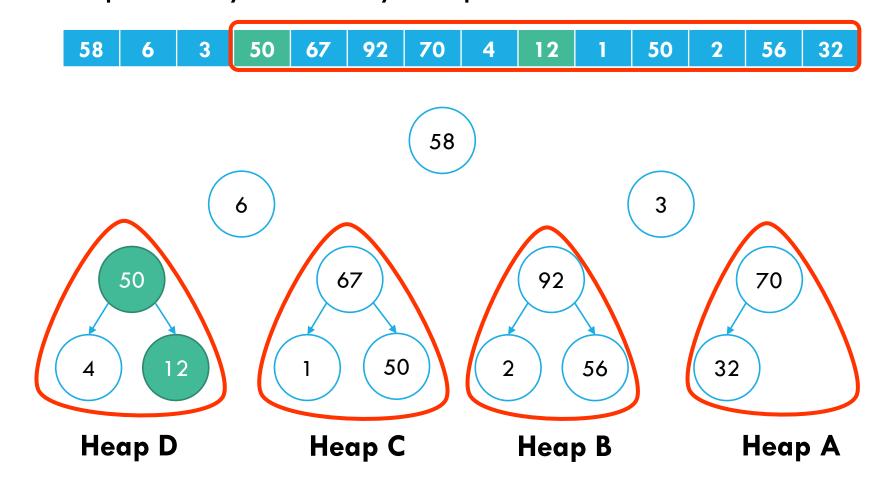
- A. Swim!
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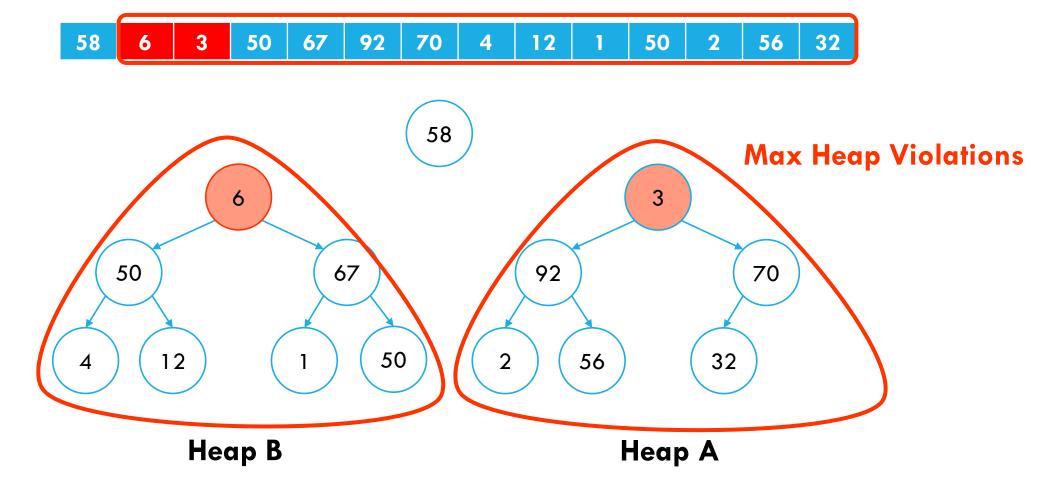
58	6	3	12	67	92	70	4	50	1	50	2	56	32
----	---	---	----	----	----	----	---	----	---	----	---	----	----

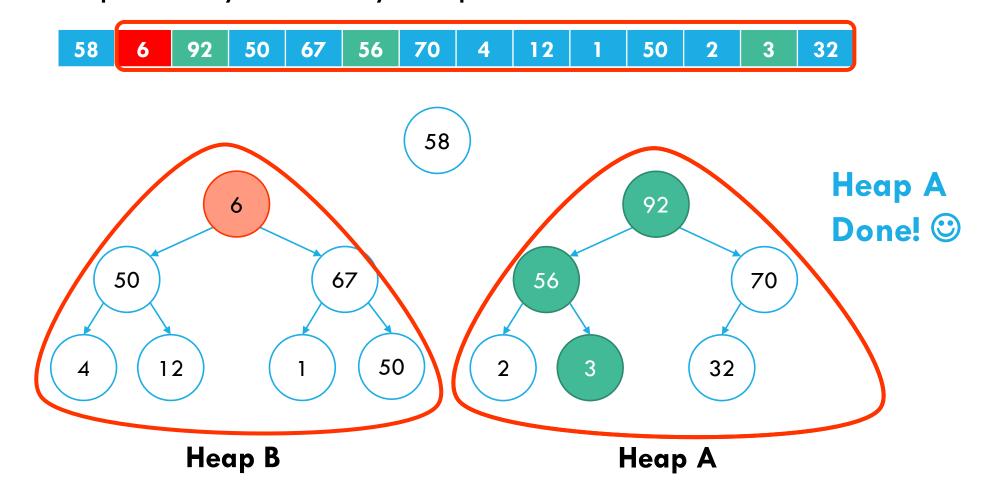


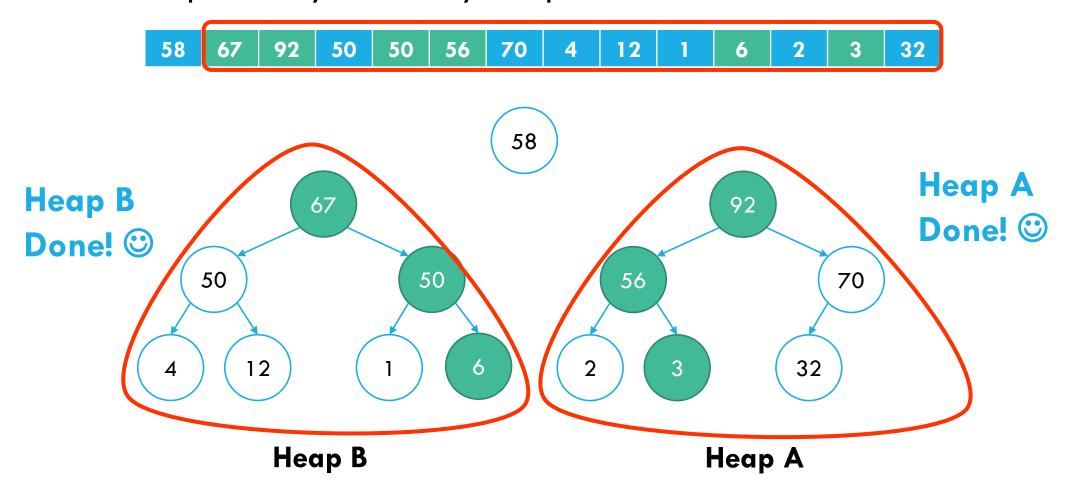


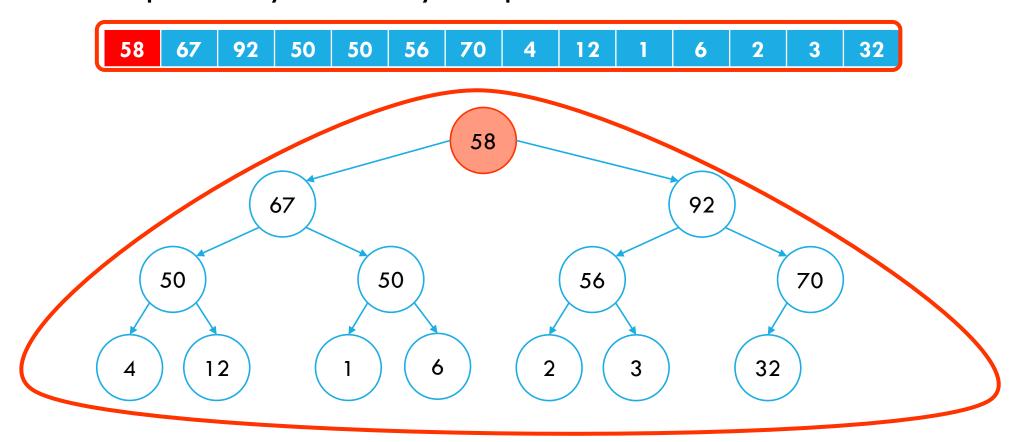




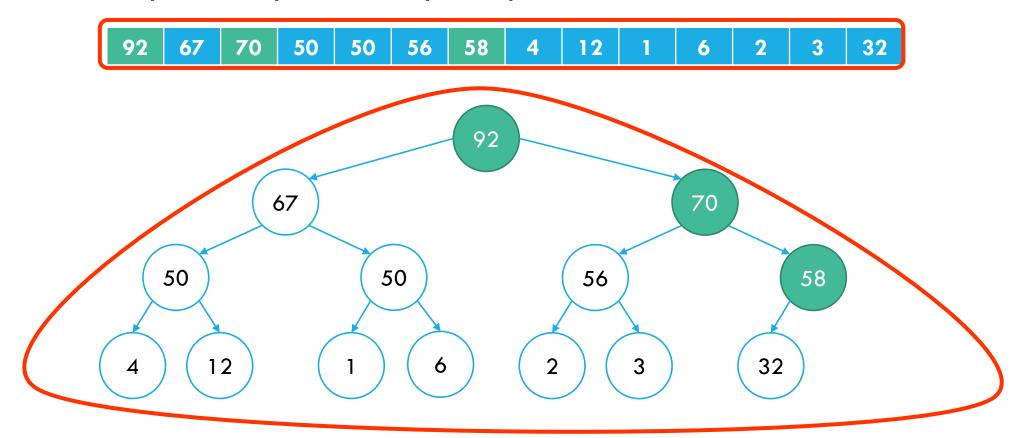




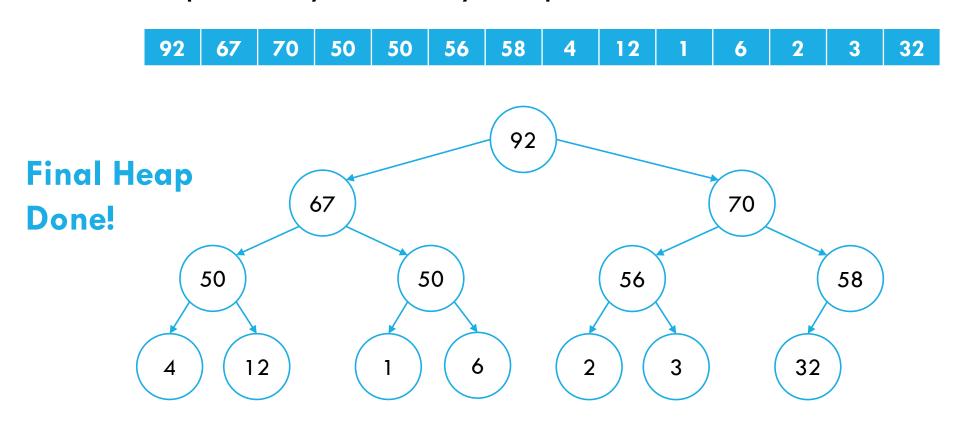




Final Heap



Final Heap



Final Heap

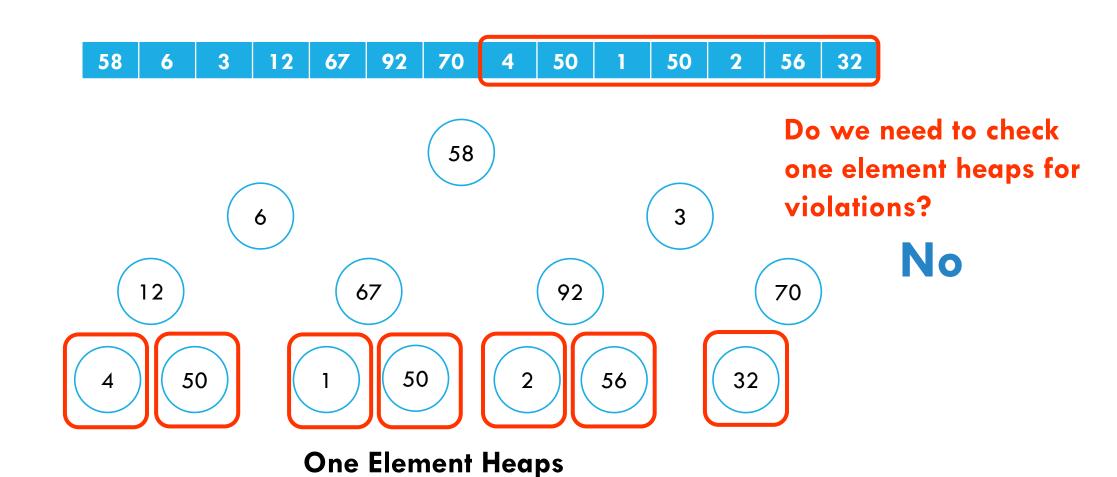
CODE FOR CREATION IN O(n) TIME

function buildHeap(A)
 for i from A.length/2 to 1
 sink(i)



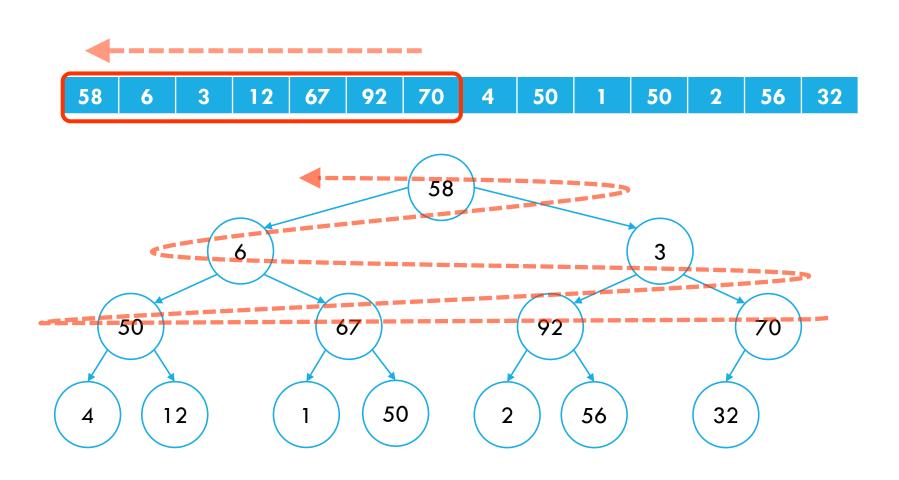
function create(A)
 for i from A.length/2 to 1
 sink(i)

CLEVER CREATION IN O(n) TIME



function create(A)
 for i from A.length/2 to 1
 sink(i)

CLEVER CREATION IN O(n) TIME

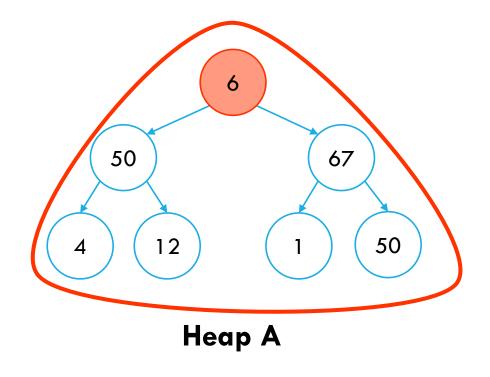


BUT WAIT, I THOUGHT YOU SAID O(n)?

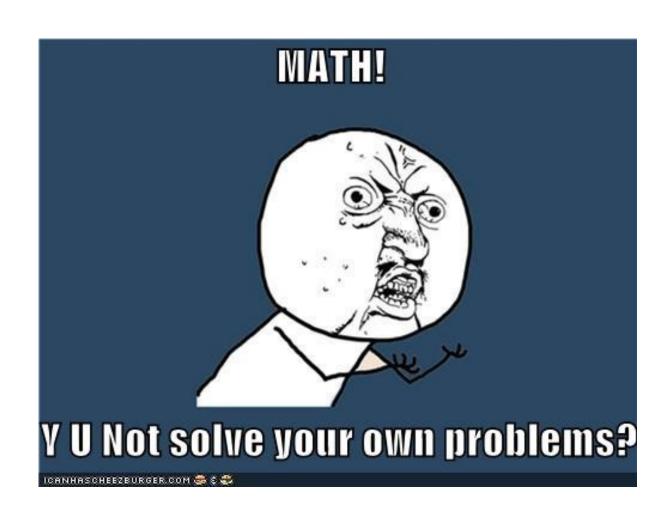
It looks like $O(n \log n)$ time?

For each violation, we sink to a possible depth of $h = \log n$

Almost correct, but the analysis is too loose.

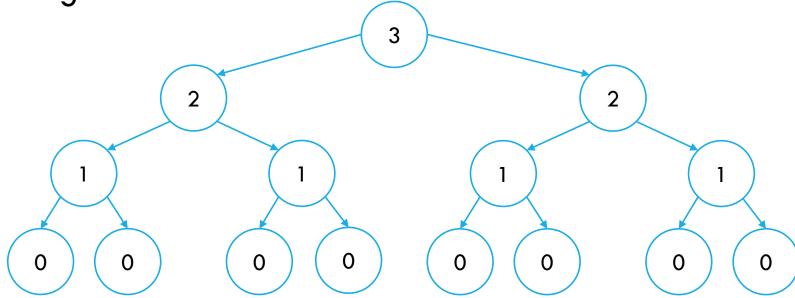


COMPLEXITY ANALYSIS: HERE COMES THE MATH



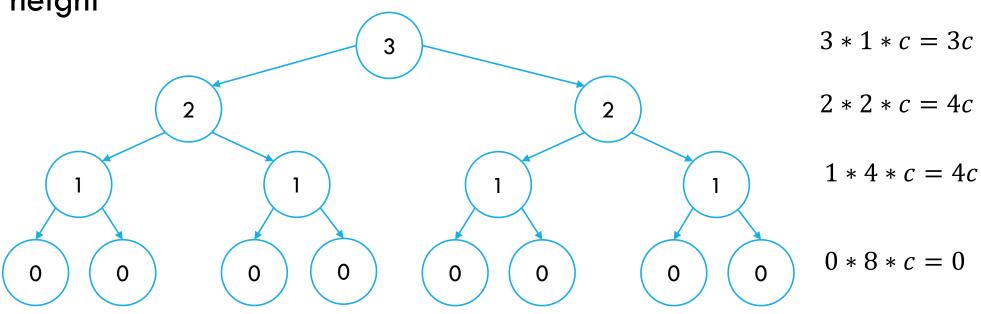
Assume a full binary tree and let $n=2^{H+1}-1$

H is the height



Assume a full binary tree and let $n=2^{H+1}-1$

H is the height



Work Done

(h x num nodes)

At each level h, there are 2^{H-h} nodes so, work done per level is $ch2^{H-h}$

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$$T(n) = \sum_{h=0}^{H} ch2^{H-h}$$

Work done per level is $ch2^{H-h}$

$$T(n) = \sum_{h=0}^{H} ch2^{H-h} = \sum_{h=0}^{H} ch\frac{2^{H}}{2^{h}}$$

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$$T(n) = \sum_{h=0}^{H} ch2^{H-h} = \sum_{h=0}^{H} ch\frac{2^{H}}{2^{h}} = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}}$$

$$T(n) = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}}$$

$$T(n) = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}} \le c2^{H} \sum_{h=0}^{\infty} \frac{h}{2^{h}}$$

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$$T(n) = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}} \le c2^{H} \sum_{h=0}^{\infty} \frac{h}{2^{h}} \le c2^{H} \cdot 2$$

$$T(n) = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}} \le c2^{H} \sum_{h=0}^{\infty} \frac{h}{2^{h}} \le c2^{H} \cdot 2 = c2^{H+1}$$

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Remember that $n = 2^{H+1} - 1$ so, $n + 1 = 2^{H+1}$

WHY BUILDHEAP IS
$$O(n)$$

$$\sum_{h=0}^{\infty} h(\frac{1}{2})^{h} = (\frac{1}{2})/(1 - \frac{1}{2})^{2} = 2$$

$$T(n) = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}} \le c2^{H} \sum_{h=0}^{\infty} \frac{h}{2^{h}} \le c2^{H} \cdot 2 = c2^{H+1}$$

Remember that
$$n = 2^{H+1} - 1$$
 so, $n + 1 = 2^{H+1}$

$$T(n) \le c2^{H+1}$$

$$\sum_{h=0}^{H} h \left(\frac{1}{2} \right) - \left(\frac{1}{2} \right) / \left(1 - \frac{1}{2} \right) = 2$$

$$T(n) = c2^{H} \sum_{h=0}^{H} \frac{h}{2^{h}} \le c2^{H} \sum_{h=0}^{\infty} \frac{h}{2^{h}} \le c2^{H} \cdot 2 = c2^{H+1}$$

Remember that $n = 2^{H+1} - 1$ so, $n + 1 = 2^{H+1}$

$$T(n) \le c2^{H+1} = c(n+1) = O(n)$$
 Done!

THE (MAX) PRIORITY QUEUE ADT

Operations:

- insert(x):inserts x
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- size(): returns the size of the queue
- buildHeap(A): creates a priority queue from an array of patients

PROBLEM SOLVED: PRIORITIZING PATIENTS

AT THE HOSPITAL

Your startup gets a nice paycheck

and you helped sick people get the help they needed!





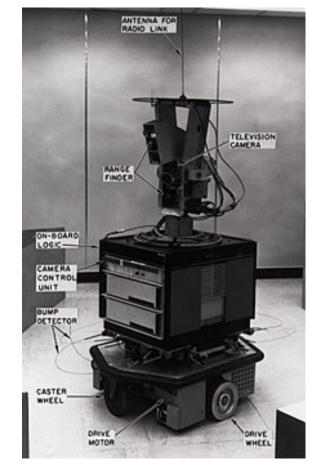
PRIORITY QUEUE'S MANY APPLICATIONS

Artificial Intelligence: A*search

Graph searching: Dijkstra's algorithm, Prim's alg

Simulation: Patient Queues, Colliding particles

Statistics: Online median in a data stream



Shakey the robot which uses A* search for planning

QUESTIONS?







CAN WE SORT USING A BINARY HEAP?

What is the computational complexity of sorting using a binary heap?

- A. O(n)
- B. $O(n^2)$
- C. $O(n \log n)$
- D. $O(2^{\log n})$
- E. Impossible to do!





CAN WE SORT USING A BINARY HEAP?

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THE STRAIGHTFORWARD IDEA

```
function heapsort(A)
    n = length(A)
    sorted = new Array[n]

binheap = buildHeap(A)
    for i = n-1 to 0
        a = binheap.extractMax()
        sorted[i] = a
```

Can we do better?

- A. Yes, we can!
- B. No, this is optimal.
- C. Judging from your past questions, I think you're going to say "Yes" so, I pick A.
- D. I pass.



THE STRAIGHTFORWARD IDEA

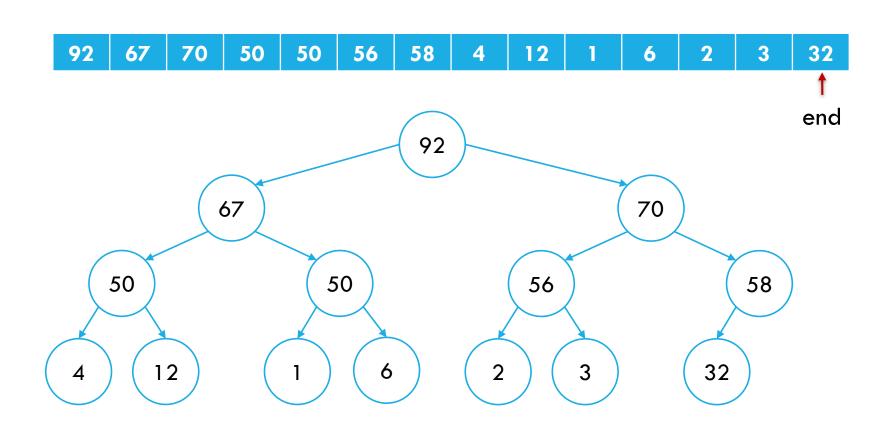
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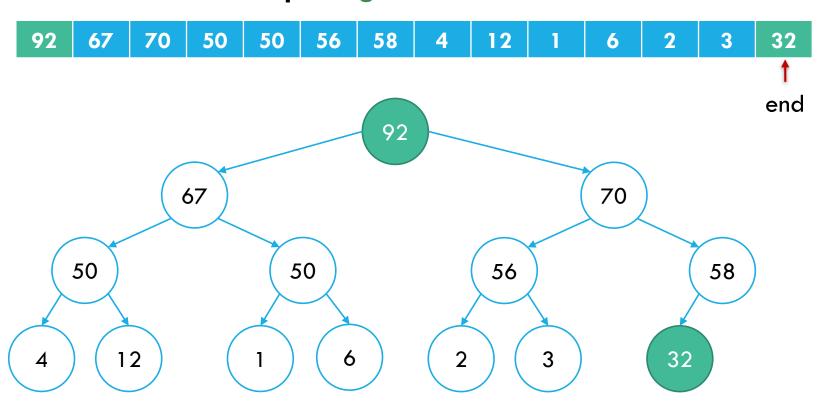
how much space does this take? O(n)

Can we do better?

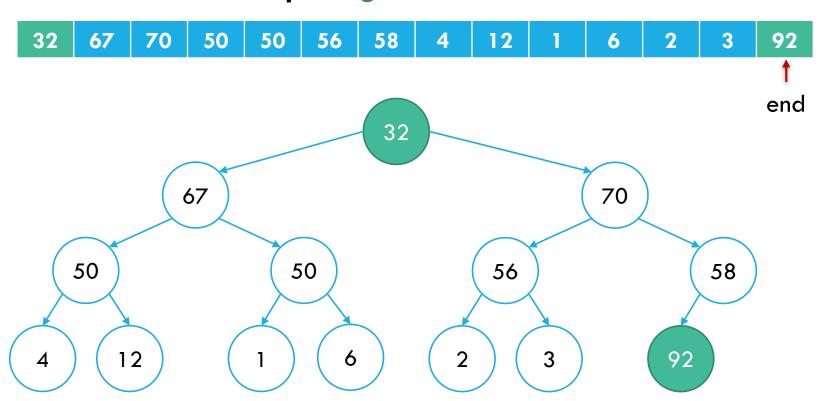
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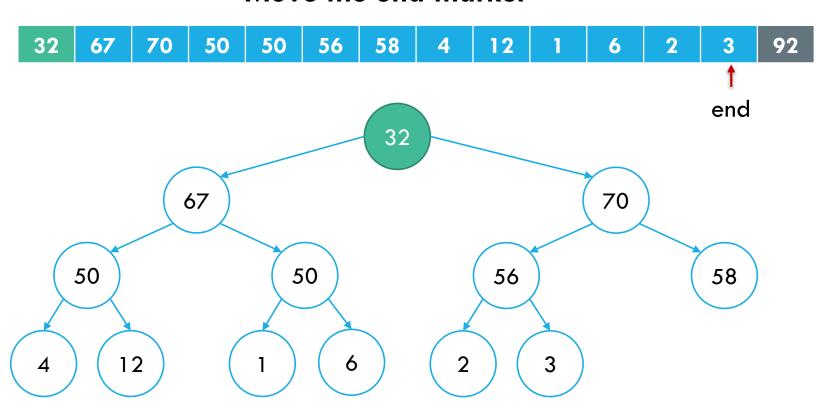
Swap the green elements



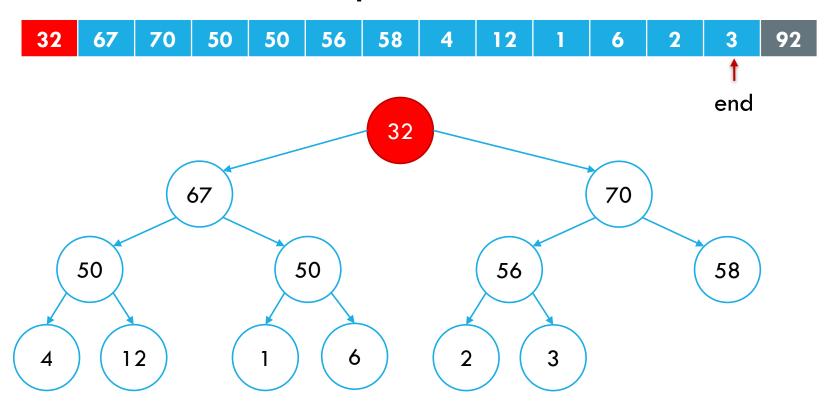
Swap the green elements



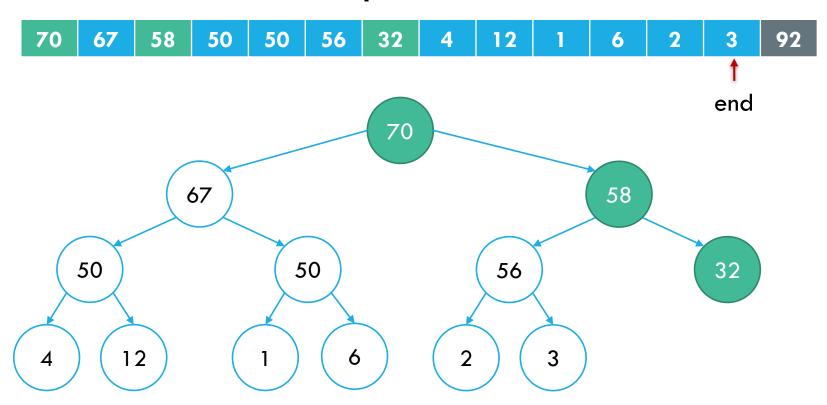
Move the end marker



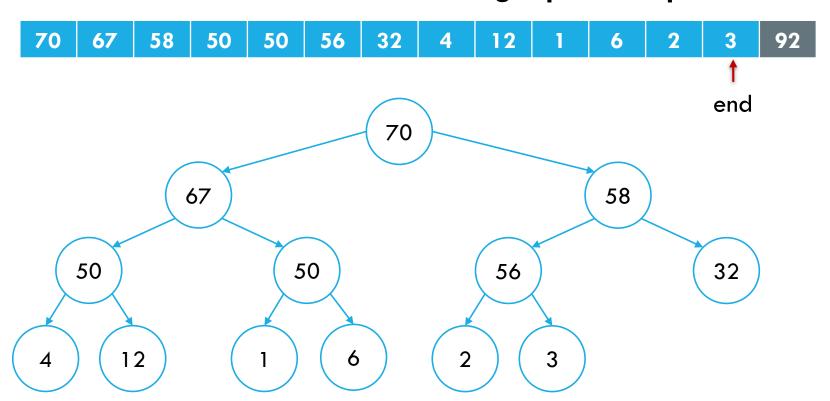
Fix MaxHeap violation. How?



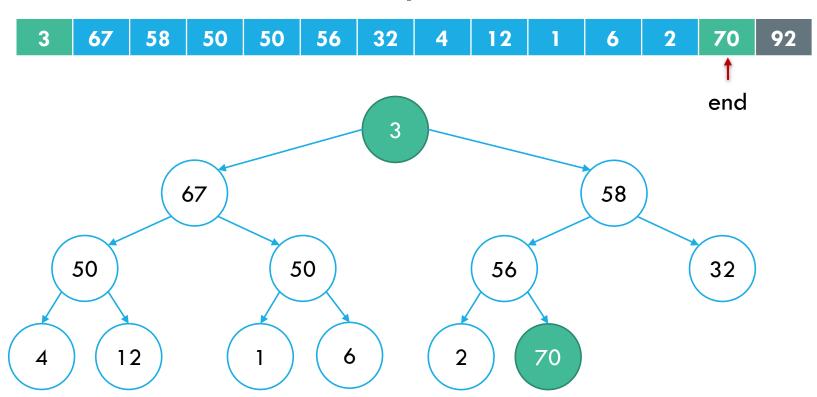
Fix MaxHeap violation. Sink!



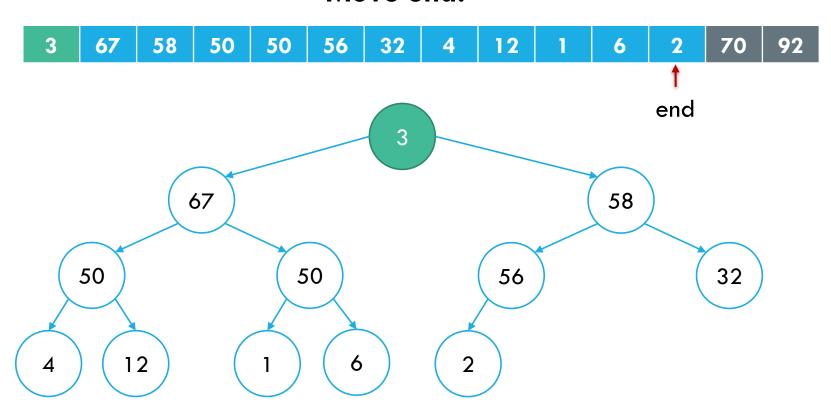
You now have 1 element in the right place. Repeat!



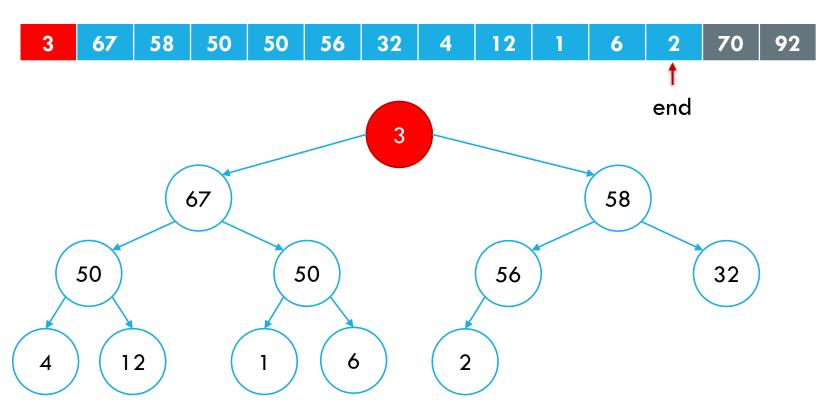




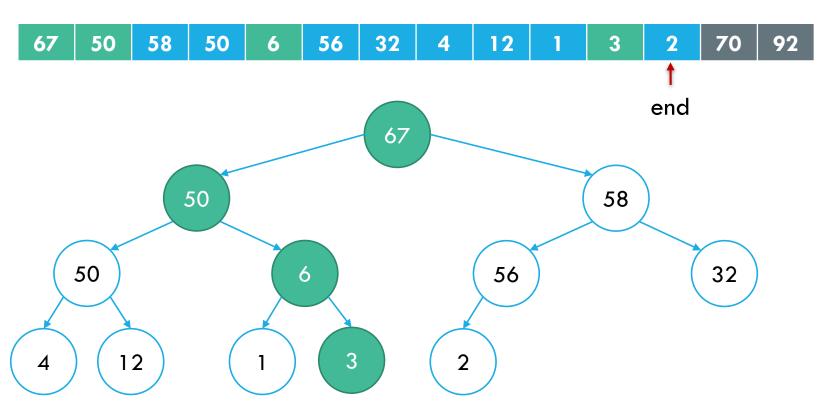
Move end.



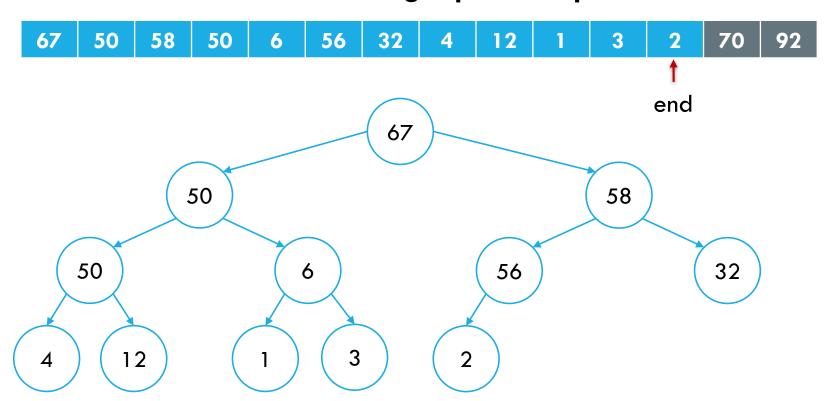




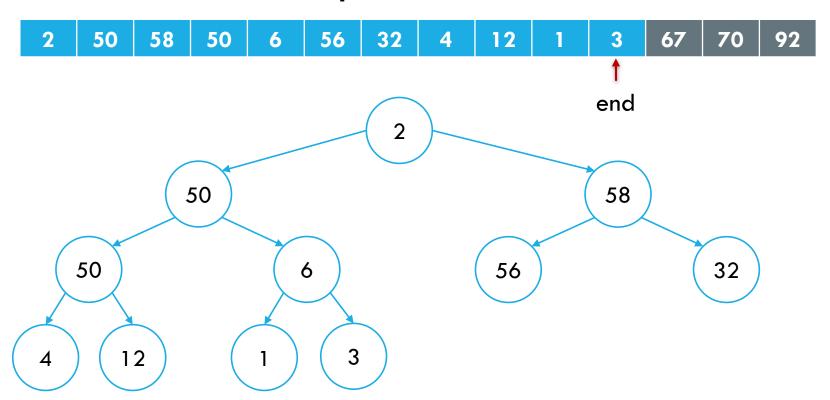




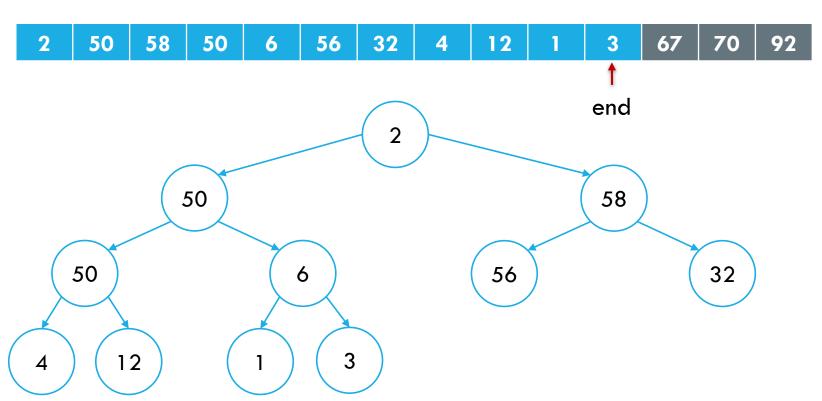
2 elements in the right place! Repeat!

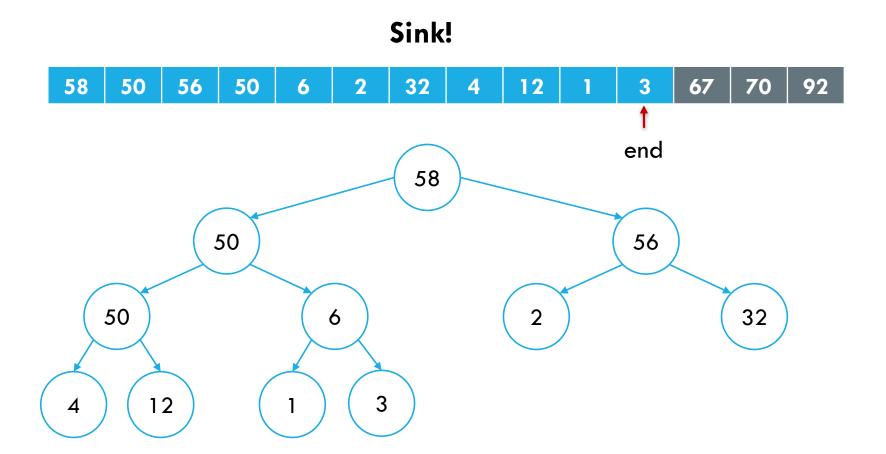


Swap and Move.

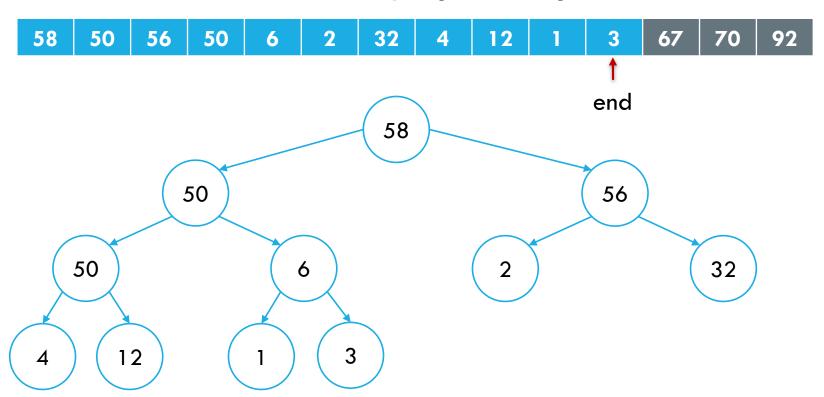








3 elements in the right place! Repeat...



SOME TIME LATER...

All elements in the right place! Be Happy!



```
function heapsort(A)
n = A.length
// create the binary heap
for \ i = n/2 \ to \ 1
sink(A, \ k, \ n)
// swap and sink
while \ (n > 1)
swap(A, \ 1, \ n);
sink(A, \ 1, \ --n);
Creating a binary heap in place takes O(n)
Swapping and Sinking takes <math>O(n \log n)
```



```
function heapsort(A)
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```

How much additional space does heapsort require?

```
A. O(n)
```

B.
$$O(n^2)$$

C.
$$O(n \log n)$$

D.
$$O(2^{\log n})$$

E.
$$O(1)$$



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```
A. O(n)
```

B.
$$O(n^2)$$

C.
$$O(n \log n)$$

D.
$$O(2^{\log n})$$

$$\mathbf{E.} \quad \boldsymbol{O}(1)$$

HEAPSORT COMPARED TO QUICKSORT

Heapsort is optimal for time and space but:

- inner loop is longer than quicksort.
- bad caching (children are "far" from parents).
- not stable.

Quicksort is still faster in practice.

INTROSORT: IMPROVING QUICKSORT!

Introsort:

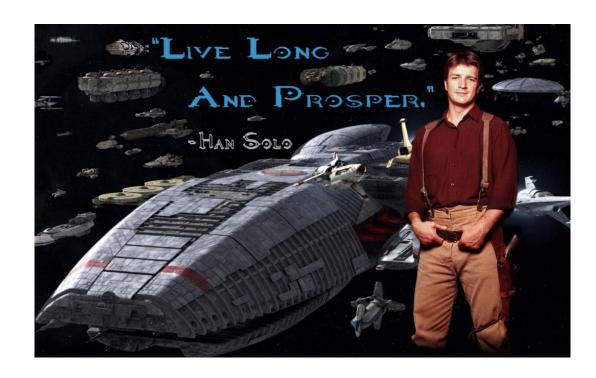
- As fast as quicksort in practice
- $O(n \log n)$ worst case!

Idea:

- Run quicksort
- Cutoff to heapsort if stack depth exceeds $2 \log n$
- Cutoff to insertion sort for n = 16

Used in C++ STL, Microsoft .NET

Also check out Timsort (mergesort + insertion sort)



Sorting algorithms: summary

	inplace?	stable?	best	average	worst	remarks
selection	V		½ n ²	½ n ²	½ n ²	n exchanges
insertion	V	V	n	½ n ²	½ n ²	use for small n or partially ordered
shell	V		$n \log_3 n$?	$c n^{3/2}$	tight code; subquadratic
merge		V	½ n lg n	$n \lg n$	$n \lg n$	n log n guarantee; stable
timsort		V	n	$n \lg n$	$n \lg n$	improves mergesort when preexisting order
quick	V		$n \lg n$	$2 n \ln n$	½ n ²	$n \log n$ probabilistic guarantee; fastest in practice
3-way quick	V		n	$2 n \ln n$	½ n ²	improves quicksort when duplicate keys
heap	V		3 n	$2 n \lg n$	$2 n \lg n$	n log n guarantee; in-place
?	V	~	n	$n \lg n$	$n \lg n$	holy sorting grail

VARIATIONS: MIN HEAP

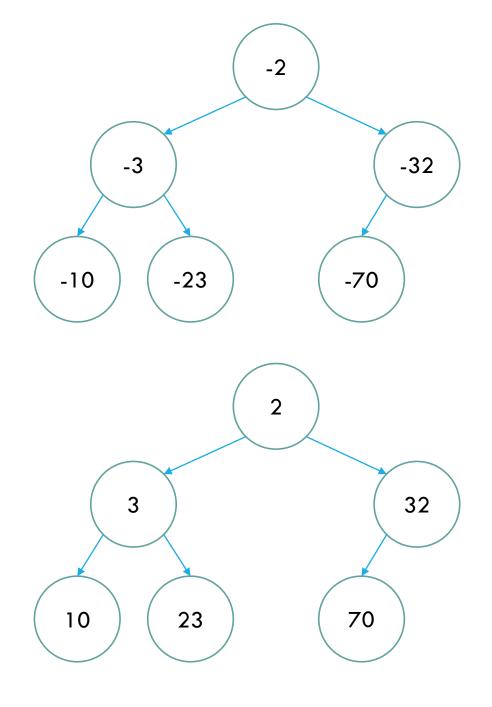
What if we want the minimum item?

Easy hack:

(provided only non-negative integer keys)
 negate all keys, e.g., 10 becomes -10

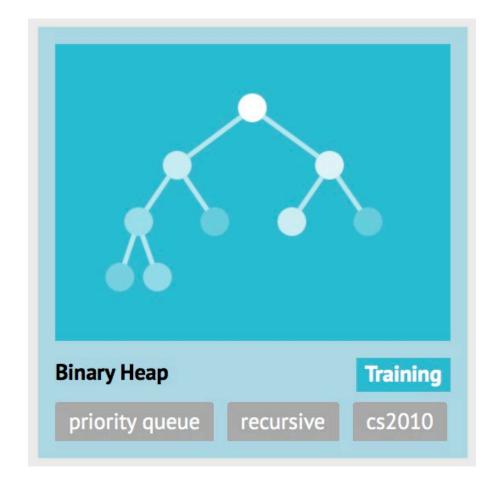
More Correct:

- Modify heap maintenance methods
 - This is a nice exercise (and not difficult)
- Or change the comparator



BINARY HEAP AND HEAPSORT

More info and visualizations on Visualgo.net!



QUESTIONS?



SUMMARY: LEARNING OUTCOMES

By the end of this session, students should be able to:

- Describe the priority queue ADT and its operations
- Describe the binary heap data structure and explain how it works
- Analyze the performance of the binary heap data structure
- Describe the heapsort algorithm and explain how it works
- Analyze the performance of heapsort





Quiz 1 is tomorrow

- Wednesday (4th Sept) during Lecture
- Open-book quiz
- No magnifying glass.
- No electronic equipment allowed.

BEFORE LECTURE NEXT WEEK

Go to Visualgo.net and do the Binary Search Tree (BST)Module:

- https://visualgo.net/en/bst
- Review: 1-14 (AVL Tree)
- Optional: 15

