# Analysis and Design of Algorithms



CS3230 CS3230 Week 11 (Part-1)
NP-Completeness

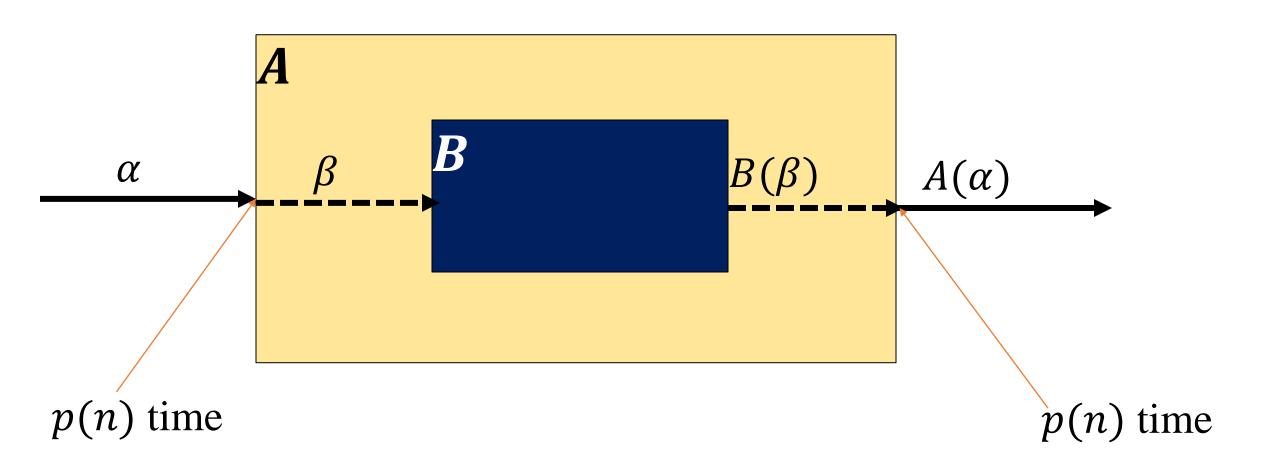
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Ken Sung

## Recap

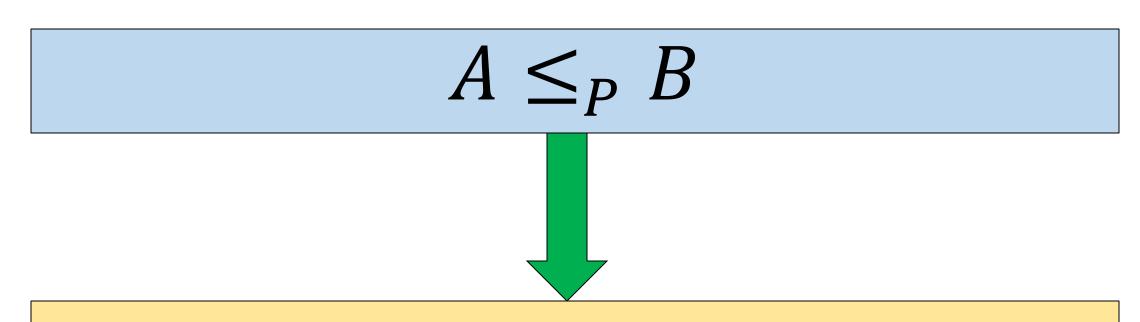
 Reductions are a basic tool in algorithm design: using an algorithm for one problem to solve another.

• If you have a poly time reduction from A to B and you also have a poly time algorithm for B, then you get a poly time algorithm for A.

## p(n)-time Reduction

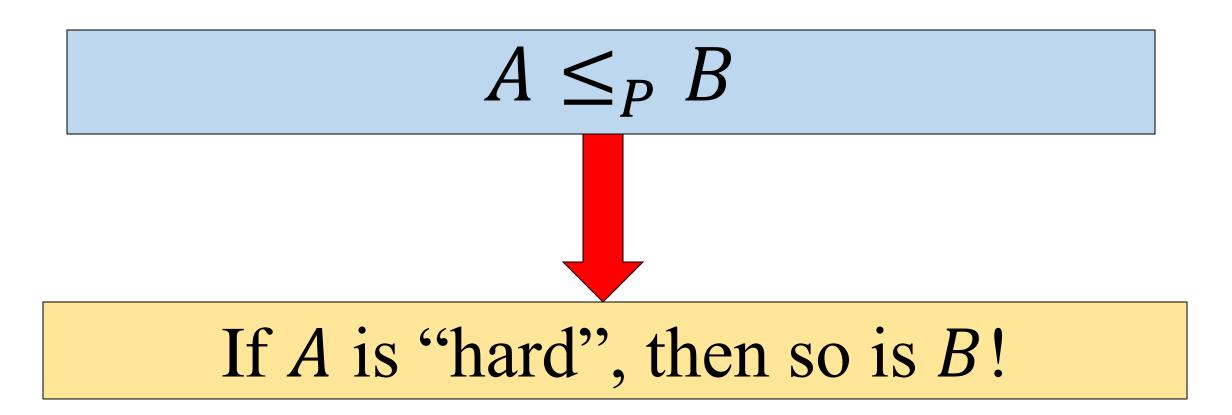


## Poly-time Reduction



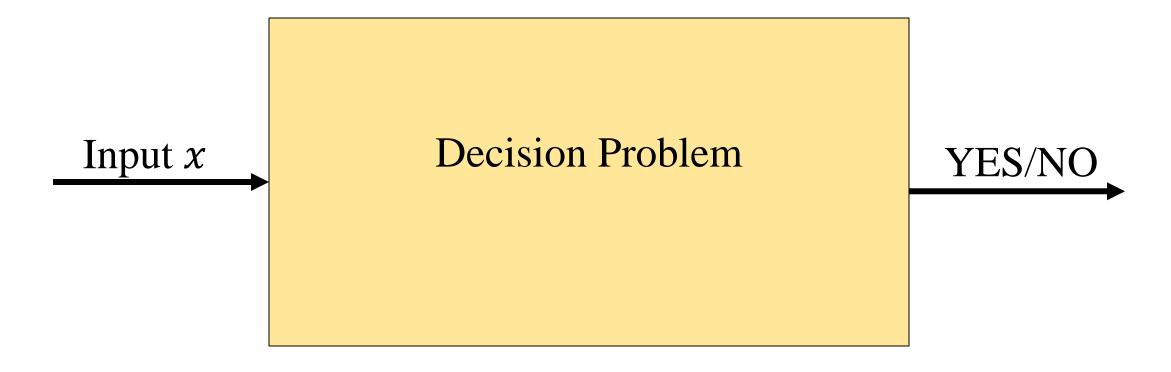
If B has a polynomial time algorithm, then so does A!

## Poly-time Reduction



#### **Decision Problems**

A **decision problem** is a function that maps an instance space *I* to the solution set {YES, NO}.



#### Reductions between Decision Problems

Given two decision problems A and B, a **polynomial time** reduction from A to B, denoted  $A \leq_P B$ , is a transformation from instances  $\alpha$  of A to instances  $\beta$  of B such that:

- 1.  $\alpha$  is a YES-instance for A if and only if  $\beta$  is a YES-instance for B.
- 2. The transformation takes polynomial time in the size of  $\alpha$ .

## Confusion about Running Time

 We should always count the running time in terms of the number of bits in the input.

• Strictly speaking, we should always let n be the input length in terms of number of bits.

• In algorithm design we generally consider word-RAM model. So input is stored in an array of words, and each arithmetic or logical operation (+, -, \*, /, OR, AND, NOT) involving a constant number of words takes constant number of cycles (time). We count only number of instructions as running time.

## NP A class of problems

and how it came into existence

## How does any scientific theory/definition get developed?

Unexplained facts in a field of science

Persistent search for the truth

A collective effort for many years or decades

Similar is the history behind the development of the class NP.

### Go back to 1960's

**Efficient algorithm** No Efficient algorithm was found till date **Shortest Path** Longest Path Travelling salesman Pro Minimum spanning Tree Hamiltonian cycle Euler tour Min Cut **Balanced Cut** Independent Set on trees Independent Set Bipartite matching 3D matching **Linear Programming Integer Programming** 

It was quite surprising and even frustrating to be unable to find efficient algorithm for so many problems when their similar looking versions had very efficient algorithms.

#### Longest path problem

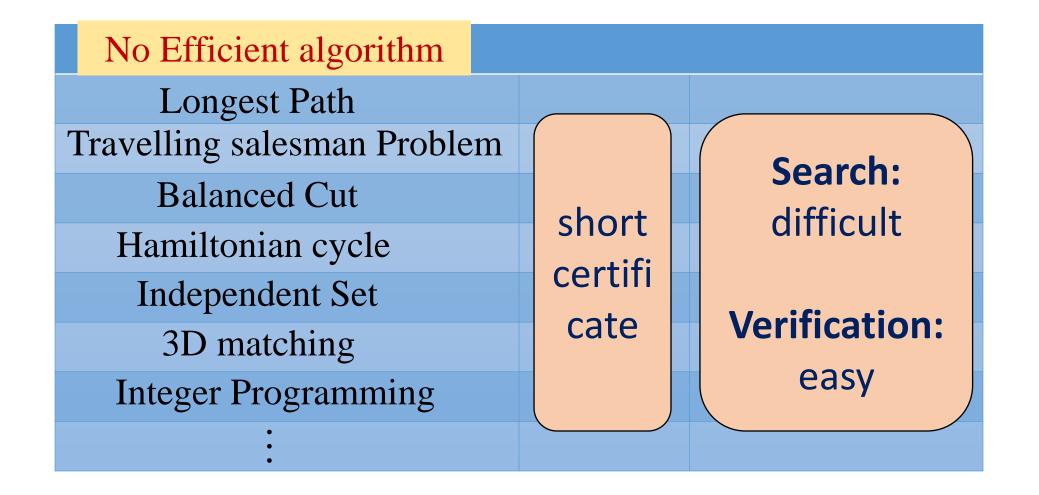
**Decision version**: Given a graph G, does there exist a path of length at least k.

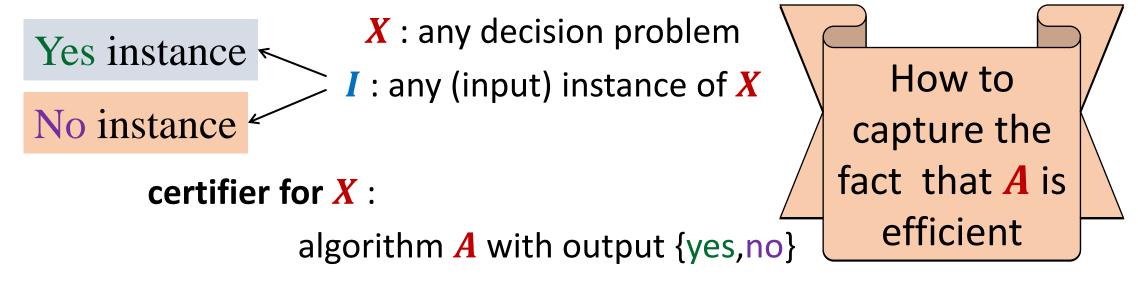
<u>Searching</u> for a path of length at least k appears to be difficult. But what about <u>verifying</u> whether a given path is of length at least k? It is quite easy  $\odot$ .

#### Vertex cover

**Decision version**: Given a graph G, does there exist a vertex cover of size  $\leq k$ .

<u>Searching</u> for a subset of k vertices that is a vertex cover of G appears difficult. But what about <u>verifying</u> whether a given subset of k vertices is a vertex cover? It is quite easy G.





- Input : (I, s)
  Proposed solution
- **Behavior**: **A** can <u>verify</u> if proposed solution **s** is right or wrong.

Yes instance

I: any decision problem

How to capture the fact that s is short

A polynomial time algorithm A with output {yes,no}

- Input : (*I*, *s*)
  Proposed solution
- Behavior: There is a polynomial function p such that I is yes-instance of X if and only if there exists a string s with  $|s| \le p(|I|)$  such that A outputs yes on input (I, s).

#### **Definition (NP):**

The set of all <u>decision</u> problems which have **efficient certifier**.

NP: "Non-deterministic polynomial time"

## Example: HAM-CYCLE

Recall: In Ham-Cycle, given a graph G, problem is to decide whether there is a simple cycle that visits each vertex exactly once.

Certificate is the cycle itself. Verifier checks in polynomial time whether it is a cycle and visits each vertex once.

Hence, HAM-CYCLE is in NP.

#### **Definition (NP):**

The set of all <u>decision</u> problems which have **efficient certifier**.

NP: "Non-deterministic polynomial time"

#### **Definition (P):**

The set of all decision problems which have **efficient** (poly-time) algorithm.

Is there any Relation between P and NP?

Yes instance

X: any decision problem in P

I: any (input) instance of X

No instance

Let **Q** be a polynomial time algorithm for solving **X**.

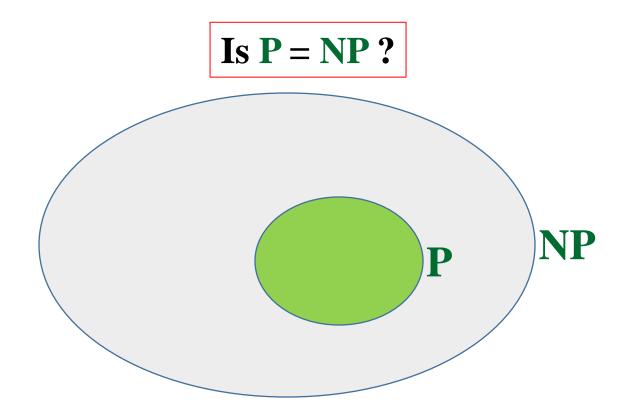
#### Efficient certifier for X:

A polynomial time algorithm A with output {yes,no}

• Input : (I, s)
Proposed solution

• **Behavior**: On getting input (*I*, *s*), just ignore *s*, and execute the algorithm *Q* on input *I*. If the answer is yes, output yes; if the answer is no, output no.

#### NP versus P



Verifying a proposed solution versus finding a solution

# NP Complete A class of problems

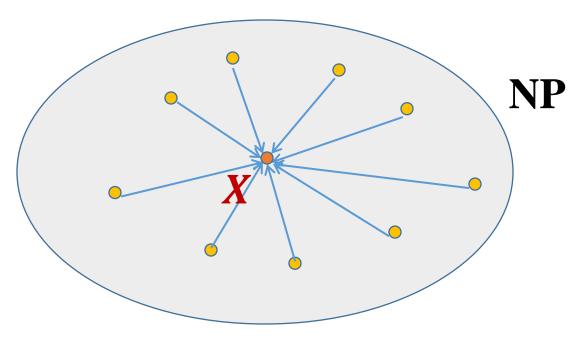
and how it came into existence

## NP-complete

## If **X** is not known to be in **NP**, then we say **X** is just **NP-hard**

• A problem X in NP class is NP-complete if for every  $A \in NP$ 

$$A \leq_{P} X$$



## Does any NP-complete problem exist?

It really needs

- courage to ask such a question and
- great insight to pursue its answer

#### **Because:**

- Every problem, known as well <u>unknown</u>, from class NP has be reducible to this problem.
- Such a problem would indeed be the hardest of all problems in NP.

But only such great questions in science lead to great inventions.

## Does any NP-complete problem exist?

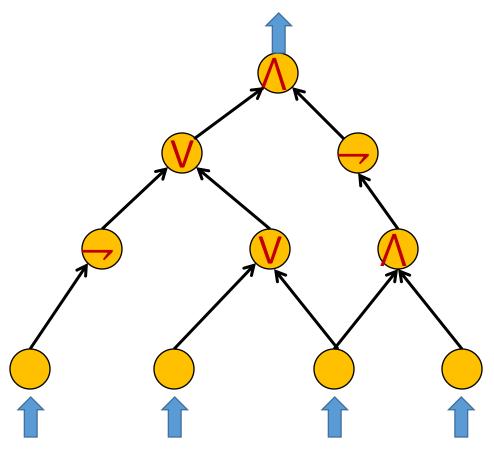
#### **Circuit satisfiability problem:**

[Cook and Levin, 1971]

A DAG with nodes corresponding to **AND**,**NOT**,**OR** gates and *n* binary inputs,

does there exist any binary input which gives output 1?





## This slide is optional (meant for the student whose aim is beyond just a good grade)

Question: How can every problem from NP be reduced to circuit satisfiability?

#### **Answer**:

Consider any problem  $X \in \mathbb{NP}$ .

What we know is that it has an efficient certifier, say Q.

Any algorithm which outputs yes/no can be represented as a DAG

- Where internal nodes are gates.
- Leaves are binary inputs
- Output is 1/0.

So Cook & Levin essentially  $\underline{\text{transform}}$  Q into the corresponding DAG. And thus  $\underline{\text{simulates}}$  Q on the proposed solution.

[This is just a sketch. Interested students should study it sometime in future.]

## Satisfiability (CNF-SAT)

- Literal: A Boolean variable or its negation.  $x_i, \bar{x}_i$
- Clause: A disjunction (OR) of literals.  $C_j = x_1 \vee \overline{x_2} \vee x_3$
- Conjunctive Normal Form (CNF): a formula  $\Phi = C_1 \wedge C_2 \wedge C_3 \wedge C_4$  $\Phi$  that is a conjunction (AND) of clauses
- **CNF-SAT**: Given a CNF formula  $\Phi$ , does it have a satisfying truth assignment?

#### 3-SAT

SAT where **each clause contains exactly 3 literals** corresponding to different variables.

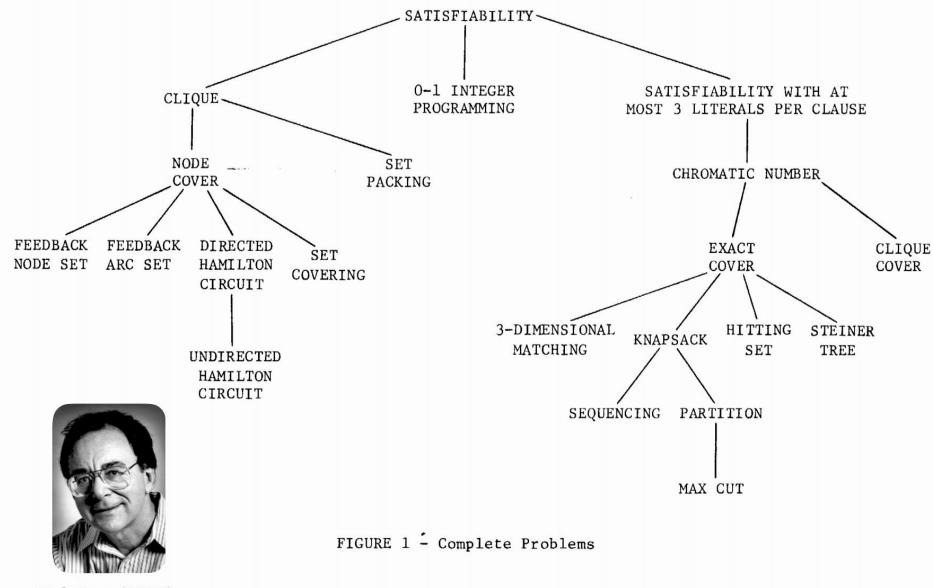
$$\Phi = (\overline{x_1} \lor x_2 \lor x_3) \land (x_1 \lor \overline{x_2} \lor x_3) \land (\overline{x_1} \lor x_2 \lor x_4)$$

Satisfying assignment:  $x_1 = \text{True}, x_2 = \text{True}, x_3 = \text{False}, x_4 = \text{True}$ 

Unsatisfying assignment:  $x_1 = \text{True}, x_2 = \text{False}, x_3 = \text{False}, x_4 = \text{False}$ 

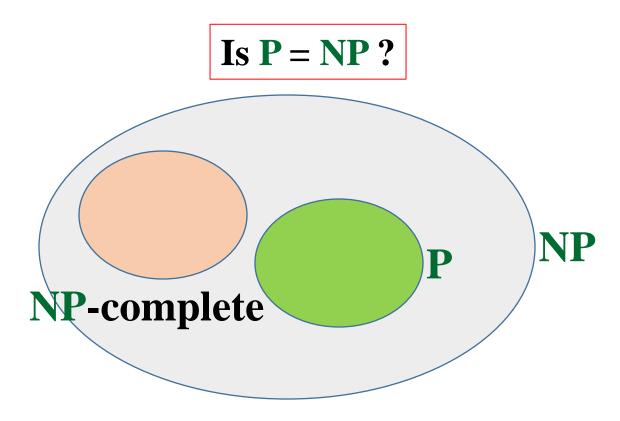
## Circuit Satisfiability $\leq_P \text{CNF-SAT} \leq_P 3\text{-SAT}$

So 3-SAT is NP-complete



Dick Karp (1972) 1985 Turing Award

#### NP versus P



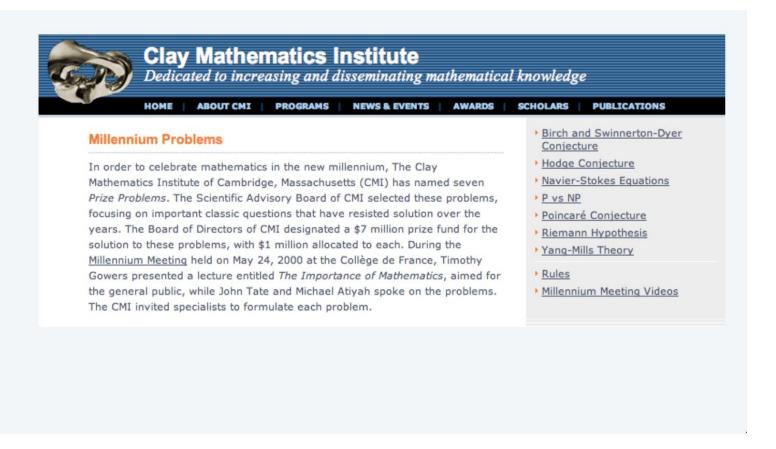
If any NP-complete problem is solved in polynomial time

$$\rightarrow$$
 P = NP

#### Millennium Prize

\$1 million dollars for resolution of P=NP or  $P\neq NP$ 





## Some Quotes

"I conjecture that there is no good algorithm for the traveling salesman problem. My reasons are the same as for any mathematical conjecture: (i) It is a legitimate mathematical possibility and (ii) I do not know." — Jack Edmonds (1966)

"If I had to bet now, I would bet that P is not equal to NP. I estimate the half-life of this problem at 25–50 more years, but I wouldn't bet on it being solved before 2100." — Robert Tarjan (2002)

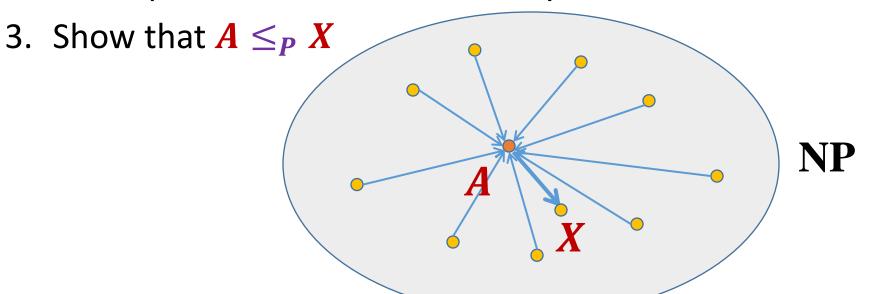
## Some Quotes

"I think that in this respect I am on the loony fringe of the mathematical community: I think (not too strongly!) that P=NP and this will be proved within twenty years. Some years ago, Charles Read and I worked on it quite bit, and we even had a celebratory dinner in a good restaurant before we found an absolutely fatal mistake. "— Béla Bollobás (2002)

## How to show a problem to be NP-complete?

Let X be a problem which we wish to show to be NP-complete

- 1. Show that  $X \in \mathbb{NP}$
- 2. Pick a problem A which is already known to be NP-complete



#### 3-SAT

SAT where **each clause contains exactly 3 literals** corresponding to different variables.

$$\Phi = (\overline{x_1} \lor x_2 \lor x_3) \land (x_1 \lor \overline{x_2} \lor x_3) \land (\overline{x_1} \lor x_2 \lor x_4)$$

Satisfying assignment:  $x_1 = \text{True}, x_2 = \text{True}, x_3 = \text{False}, x_4 = \text{True}$ 

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#### INDEPENDENT-SET

**Definition**: Given an undirected graph G = (V, E), a subset  $X \subseteq V$  is said to be an **independent** set if

For each  $u,v\in X$  ,  $(u,v)\notin E$  .

Optimization version: compute Independent set of Largest size.

**Decision version**: Does there exist an independent set of size >k?

## $3-SAT \leq_P INDEPENDENT-SET$

# Simple Exercise: To show in NP

Given an instance  $\Phi$  of 3-SAT, goal is to construct an instance (G, k) of INDEPENDENT-SET so that G has an independent set of size k if and only if  $\Phi$  is satisfiable.

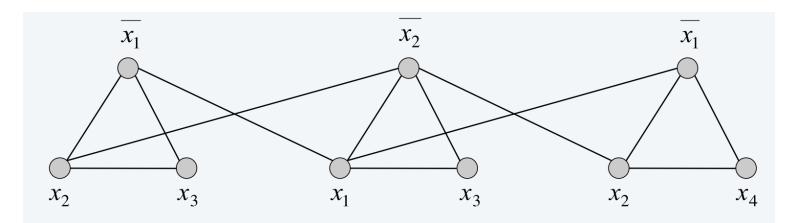
To think: why it suffices to show for exactly k, not >k

#### $3-SAT \leq_P INDEPENDENT-SET$

Given an instance  $\Phi$  of 3-SAT, goal is to construct an instance (G, k) of INDEPENDENT-SET so that G has an independent set of size k if and only if  $\Phi$  is satisfiable.

#### Reduction

- G contains 3 vertices for each clause, one for each literal
- Connect 3 literals in clause in a triangle
- Connect literal to each of its negations
- Set k = number of clauses



$$(\overline{x_1} \lor x_2 \lor x_3)$$

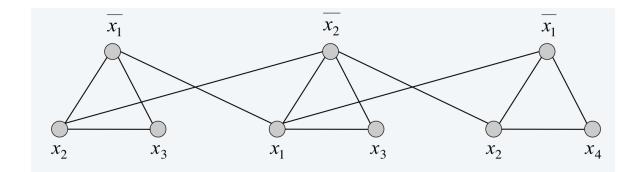
$$\land (x_1 \lor \overline{x_2} \lor x_3)$$

$$\land (\overline{x_1} \lor x_2 \lor x_4)$$

## $3-SAT \leq_{P} INDEPENDENT-SET$

#### **Reduction**

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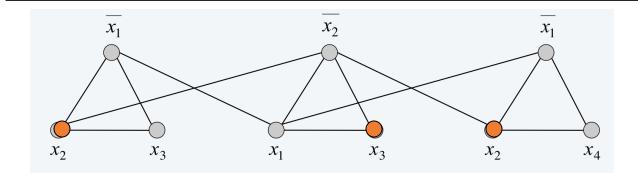
$$\land (\overline{x_1} \lor x_2 \lor x_4)$$

Reduction clearly runs in linear time.

### $3-SAT \leq_{P} INDEPENDENT-SET$

#### Reduction

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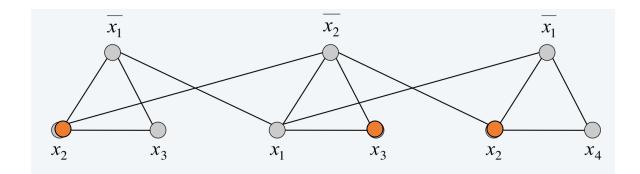
$$\land (\overline{x_1} \lor x_2 \lor x_4)$$

Suppose  $\Phi$  is a YES-instance. Take any satisfying assignment for  $\Phi$  and select a true literal from each clause. Corresponding k vertices form an independent set in G.

### $3-SAT \leq_{P} INDEPENDENT-SET$

#### Reduction

- G contains 3 vertices for each clause, one for each literal
- Connect 3 literals in clause in a triangle
- Connect literal to each of its negations
- Set k = number of clauses



$$(\overline{x_1} \lor x_2 \lor x_3)$$

$$\land (x_1 \lor \overline{x_2} \lor x_3)$$

$$\land (\overline{x_1} \lor x_2 \lor x_4)$$

Suppose (G, k) is a YES-instance. Let S be the independent set of size k. Each of the k triangles must contain exactly one vertex in S. Set these literals to true, so all clauses satisfied.

# **Worst Case Analysis**

• Proof shows that **some** instances of INDEPENDENT-SET are as hard to solve as the 3-SAT problem. This does **not** mean that all instances of the INDEPENDENT-SET problem are hard!

• So, if there is no poly time algorithm that solves 3-SAT on *all* instances, there is no poly time algorithm that solves INDEPENDENT-SET on *all* instances.

#### Status of SAT

• Fastest algorithm known for 3-SAT runs in time  $\approx 1.308^n$ . It is believed that there is no  $2^{o(n)}$ -time algorithm for 3-SAT (**Exponential Time Hypothesis**).

 Often very convenient to reduce from 3-SAT to other problems, showing that those will also be hard if 3-SAT is hard.

#### Question 1

Suppose 3-SAT  $\leq_P A$  for some decision problem A. Assume the exponential time hypothesis that there is no  $2^{o(n)}$ -time algorithm for 3-SAT. Then, there is no  $2^{o(n)}$ -time algorithm for A.

- True
- False

#### Question 1: Solution

False.

If the reduction runs in time  $n^c$ , then a  $2^{o(n^{1/c})}$ -time algorithm for A implies a  $2^{o(n)}$ -time algorithm for 3-SAT. So, by the assumption, there are no  $2^{o(n^{1/c})}$ -time algorithms for A. The lower bound for A depends on the running time of the reduction.

### **Extent and Impact**

• Garey and Johnson's book, "Computers and Intractability", includes over 300 NP-complete problems and is the #1 cited reference in computer science!

• NP-completeness is used in more than 6,000 publications per year (more than "compiler", "OS", "database").

• Main intellectual export of computer science.

#### More...

• There are problems that are provably harder than NP-complete problems, problems that require polynomial space, problems that require large circuits, problems that are unsolvable even with unlimited time!

Enter the world of complexity theory...

Attend Computational Complexity course!!!

# Fine-grained Hardness: An emerging field

- Prove computational hardness using conjectures like...
- There is no  $2^{o(n)}$ -time algorithm for 3-SAT (Exponential Time Hypothesis), or even stronger (Strong Exponential Time Hypothesis).

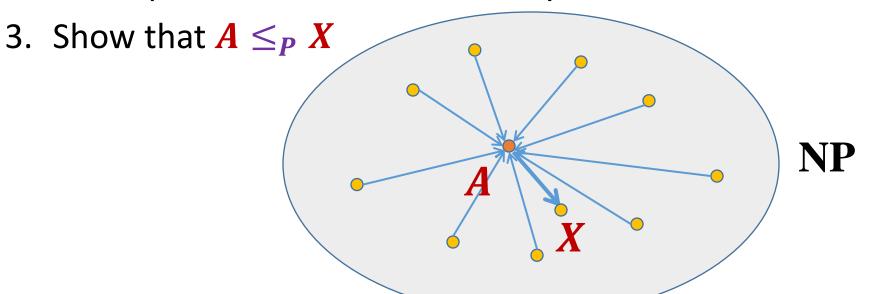
- We can prove more fine-grained hardness like
- LCS can not be solved in time  $O(n^{2-\mathcal{E}})$  for any  $\mathcal{E} > 0$
- And many more...

Attend **Advanced Algorithms** course in the next semester!!!

## How to show a problem to be NP-complete?

Let X be a problem which we wish to show to be NP-complete

- 1. Show that  $X \in \mathbb{NP}$
- 2. Pick a problem A which is already known to be NP-complete



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