CS3243: Introduction to Artificial Intelligence

Semester 2, 2020

First-Order Logic (FOL)

AIMA Chapter 8

Outline

- Why FOL?
- Syntax and semantics of FOL
- Using FOL
- Wumpus world in FOL
- Knowledge engineering in FOL

Propositional Logic

Pros

- Declarative: tells agent what it needs to know to operate in its environment. No need to specify exact behavior
- Allows partial information via disjunction and negation (unlike many other data structures)
- Compositional: meaning of $A \wedge B$ derived from meanings of A and B.
- Context independent and unambiguous

Cons

• Limited expressive power: cannot concisely say "pits cause breezes in adjacent squares".

First-Order Logic

- Propositional logic assumes that the world contains facts
- First-order logic (like natural language) assumes that the world contains
 - Objects: people, houses, numbers, colors, baseball games, wars, ...
 - Relations: unary relations or properties such as red, round, prime, ..., or more general n-ary relations such as brother of, bigger than, part of, comes between, ...
 - Functions: father of, best friend, one more than, plus, ...

Syntax of FOL: Basic Elements

Туре	Examples
Constants	John, 2, NUS,
Predicates (relations)	Brother(x, y), x > y,
Functions	\sqrt{x} , LeftLeg(x),
Variables	x, y, a, b
Connectives	$\neg, \land, \lor, \Rightarrow, \Leftrightarrow$
Equality	=
Quantifiers	∀,∃

Atomic Sentences

Term: constant or variable or $function(x_1,...,x_n)$

Functions can be viewed as complex names for constants

Atomic sentence: $predicate(x_1, ..., x_n)$ or $x_1 = x_2$

E.g.,

- Brother(John, Richard)
- Length(LeftLeg(Richard)) = Length(LeftLeg(John))

Complex Sentences

Constructed from atomic sentences via connectives

$$\neg \alpha, \alpha_1 \land \alpha_2, \alpha_1 \lor \alpha_2, \alpha \Rightarrow \beta, \alpha \Leftrightarrow \beta$$

E.g.,

- $Sibling(John, Richard) \Rightarrow Sibling(Richard, John)$
- $(a \le b) \lor (a > b)$
- $(1 > 2) \land \neg (1 > 2)$

Truth in First-Order Logic

- Sentences are true in a model
- Model comprises a set of objects (domain elements) and an interpretation
- Interpretation specifies referents for

Objects → Constants

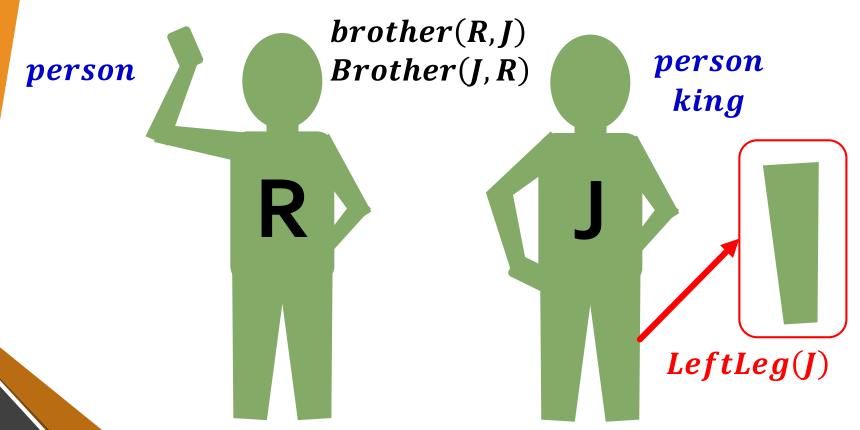
Relations → Predicates

Functional Relations → Function Symbols

• An atomic sentence $predicate(x_1, ..., x_n)$ is true in a given model if the relation referred to by predicate holds among the objects referred to by $x_1, ..., x_n$.

Models for FOL: Example 1

Model contains 5 objects, 2 binary relations (black), 3 unary relations (blue), 1 unary function (red)



Universal Quantification

- ∀< variables >: < sentence >
- e.g., everyone at NUS is smart: $\forall x : x \in NUS \Rightarrow Smart(x)$
- $\forall x$: P(x) is true in a given model if P is true with x referring to each possible object in the model
- Roughly speaking, it is equivalent to the conjunction of instantiations of P

```
Alice \in NUS \Rightarrow Smart(Alice)
 \land Bob \in NUS \Rightarrow Smart(Bob)
 \land Claire \in NUS \Rightarrow Smart(Claire)
```

A Common Mistake to Avoid

- Typically, \Rightarrow is the main connective with \forall
- Common mistake: using ∧ as the main connective with ∀:

 $\forall x : x \in NUS \land Smart(x)$

What does the above mean?

Existential Quantification

∃< vars >: < sentence >

e.g., someone at NUS is smart: $\exists x : x \in NUS \land Smart(x)$

- $\exists x : P$ is true in a given model if P is true with x referring to at least one object in the model
- Roughly speaking, it is equivalent to the disjunction of instantiations of P

 $Alice \in NUS \land Smart(Alice)$ $\lor Bob \in NUS \land Smart(Bob)$ $\lor Claire \in NUS \land Smart(Claire)$

_ _

Another Common Mistake to Avoid

- Typically, ∧ is the main connective with ∃
- Common mistake: using ⇒ as the main connective with ∃:

 $\exists x : x \in NUS \Rightarrow Smart(x)$

What does this mean?

Negation

- Negation of $\forall x : P(x)$ is $\exists x : \neg P(x)$
- Negation of $\exists x : P(x)$ is $\forall x : \neg P(x)$

$$\forall x: (\exists y: P(x,y)) \lor (\forall z: \exists y: (Q(x,y,z) \land P(y,z)))$$



$$\exists x : (\forall y : \neg P(x, y)) \land (\exists z : \forall y : (\neg Q(x, y, z) \lor \neg P(y, z)))$$

Equality

- $x_1 = x_2$ is true under a given interpretation iff x_1 and x_2 refer to the same object
- With function: e.g., Father(John) = Henry
- With negation: e.g., definition of Sibling in terms of Parent:

```
\forall x, y : Sibling(x, y)

\Leftrightarrow (\neg(x = y))

\land (\exists m, f : \neg(m = f) \land Parent(m, x))

\land Parent(f, x) \land Parent(m, y)
```

Interacting with FOL KBs

A Wumpus-world agent is using a FOL KB and perceives a smell, a breeze, and glitter at t=5:

TELL(KB, Percept([Smell, Breeze, Glitter, None, None], 5))

ASK(KB, $\exists a \ BestAction(a, 5)$)

- Quantified query: does the KB entail some best action at t=5? Answer: Yes.
- ASKVARS(KB, S) returns the binding list or substitutions such that KB ⊢ S
 - e.g., AskVars(KB, $\exists a \ BestAction(a, 5)$)

Answer: $\{a = Grab\} \leftarrow \text{substitution}$ (binding list)

KB for the Wumpus World

- Perception rule
 - Process agent's inputs
 - "If observed a glitter at time t, set Glitter(t) = True"
- Reflex rule
 - Process agent's outputs
 - $\forall t$: Glitter $(t) \Rightarrow \text{BestAction}(Grab, t)$
- Above rules yield BestAction(Grab, 5)

How would we write the above rule in propositional logic?

KB for the Wumpus World

Properties of squares:

•
$$\forall x, y, a, b$$
: Adjacent($[x, y], [a, b]$) \Leftrightarrow

$$(x = a \land (y = b - 1 \lor y = b + 1))$$

$$\lor (y = b \land (x = a - 1 \lor x = a + 1))$$

• $\forall s, t : At(Agent, s, t) \land Breeze(t) \Rightarrow Breezy(s)$

Squares are breezy near a pit:

• $\forall s$: Breezy $(s) \Leftrightarrow \exists r$: Adjacent $(r, s) \land Pit(r)$

Knowledge Engineering in FOL

- 1. Identify the task
- 2. Assemble the relevant knowledge
- Decide on a vocabulary of predicates, functions, and constants
- 4. Encode general knowledge about the domain
- 5. Encode a description of the specific problem instance
- 6. Pose queries to the inference procedure and get answers
- 7. Debug the knowledge base

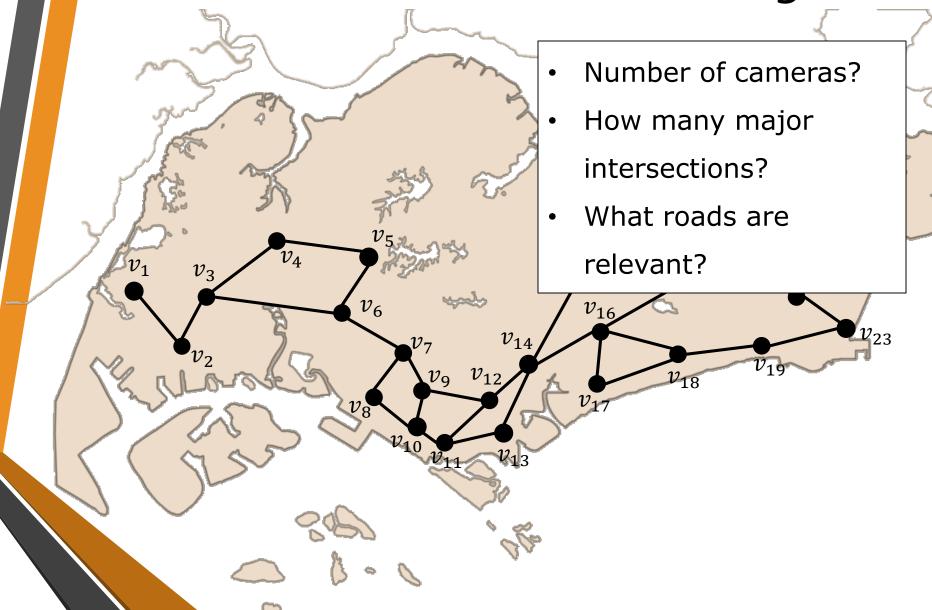
Optimal Traffic Management

- We are approached by the Singapore Police
- Want to optimally position traffic cameras in major intersections so as to cover all relevant roads.
- A camera in an intersection also covers adjacent ones.
- Please help!



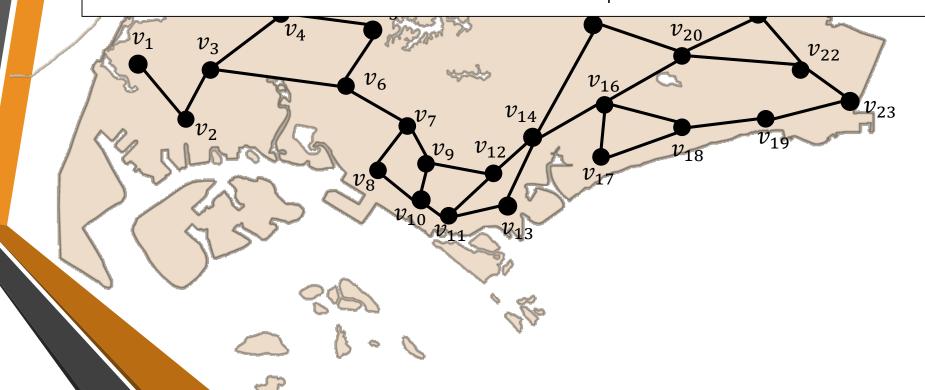


Assemble Relevant Knowledge



Decide on Vocabulary

- *V* set of intersections
- $edge(u, v) \in \{0,1\}$ is there a road connecting u and v
- $c(v) \in \{0,1\}$ there is a camera in location v.
- Maximal number of cameras $k \in \mathbb{Z}_+$



Encode General Domain Knowledge

Edges are bidirectional –

$$\forall u, v : \text{edge}(u, v) \Leftrightarrow \text{edge}(v, u)$$

Coverage property –

Covered
$$(u, v) \Leftrightarrow c(v) \lor c(u)$$

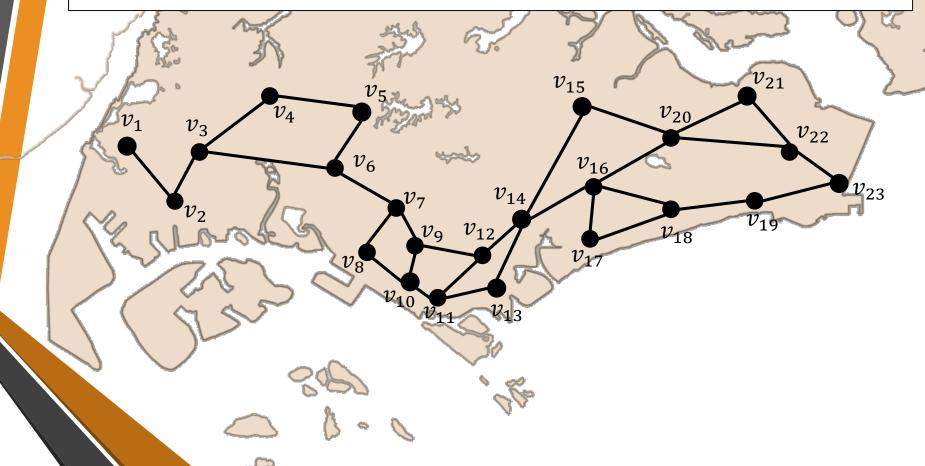
- Total coverage TotalCover $(V) \Leftrightarrow \forall e = \{u, v\} \in E$: Covered(e)
- Is $U \subseteq V$ providing total coverage?

$$IsCovering(U) \Leftrightarrow \left(\bigwedge_{u \in U} c(u)\right) \land \left(\bigwedge_{v \in V \setminus U} \neg c(v)\right) \land TotalCover(V)$$



Encode the Specific Instance

- $V = \{v_1, \dots, v_{23}\}$
- $edge(v_1, v_2)$, $edge(v_2, v_3)$, $edge(v_3, v_4)$, $edge(v_3, v_6)$, ...



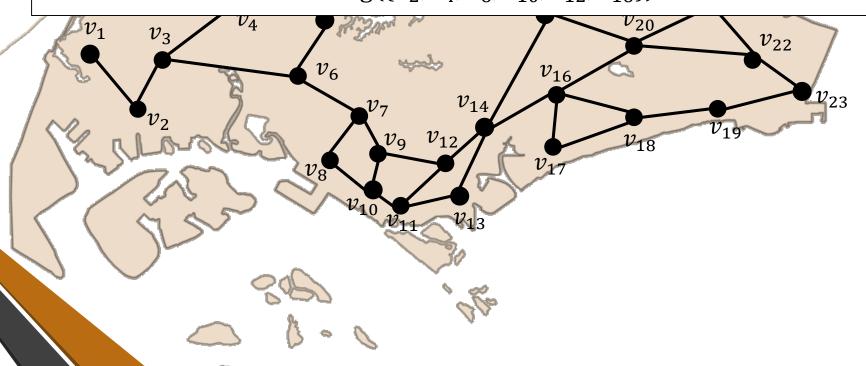
Pose Queries

Is there a solution using k cameras?

 $\exists u_1, \dots, u_k$: IsCovering($\{u_1, \dots, u_k\}$)

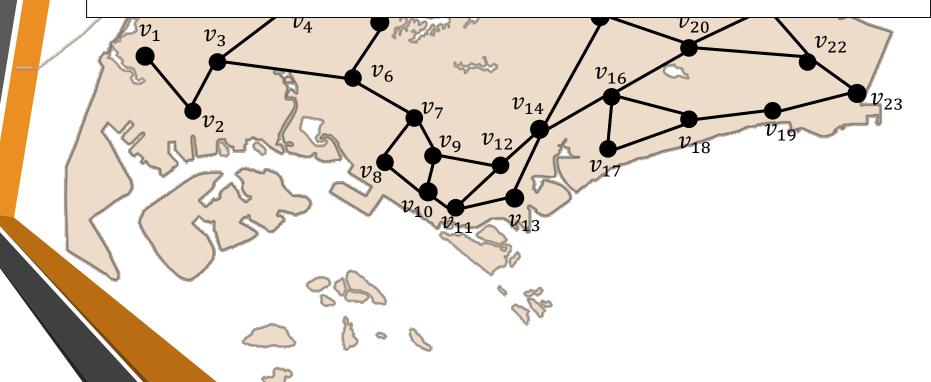
Will a specific solution work?

IsCovering($\{v_2, v_4, v_6, v_{10}, v_{12}, v_{16}\}$)



Debug Database

- $\forall u, v : \text{edge}(u, v) \Rightarrow u \in V \land v \in V$
- $\forall u, v : edge(u, v) \Rightarrow u \neq v$
- $\forall v : c(v) \Rightarrow v \in V$
- ...



Waste Disposal

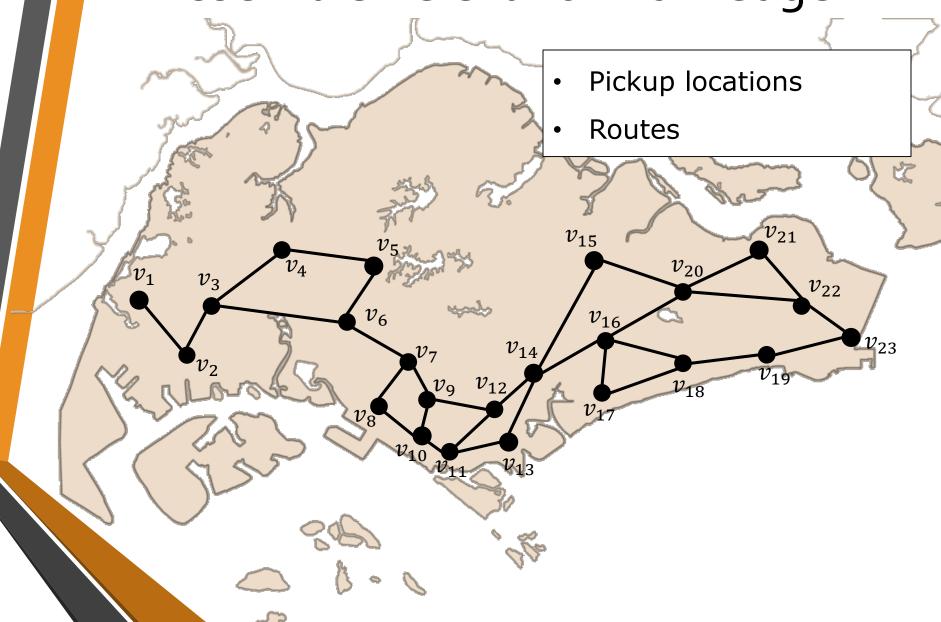
- We are approached by a Waste Disposal Service
- Want to optimally collect garbage from various locations.

Don't want to visit same location twice



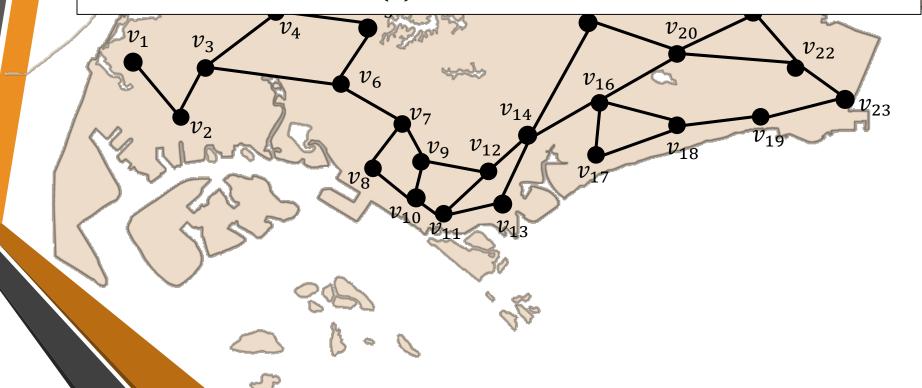


Assemble Relevant Knowledge



Decide on Vocabulary

- V set of locations
- $edge(u, v) \in \{0,1\}$ is there a road connecting u and v
- $next(u, v) \in \{0,1\}$: we move from u to v.
- Start location: start(v)



Encode General Domain Knowledge

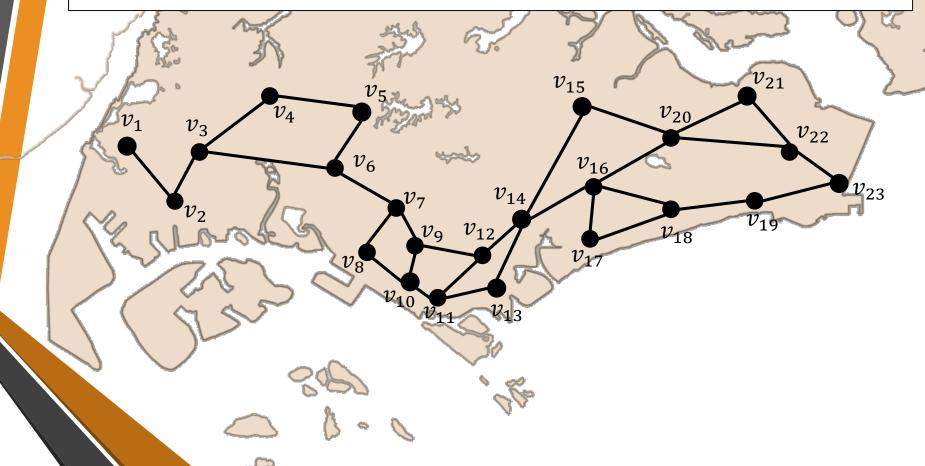
- edge $(u, v) \in \{0,1\}$: there is an edge between u and v.
- Start location is unique:

$$\exists v_0 : (v_0 \in V \land \operatorname{start}(v_0)) \land (\forall v : \operatorname{start}(v) \Rightarrow (v = v_0))$$

- Can only travel on edges: $next(u, v) \Rightarrow edge(u, v)$
- Visited $(v) \Leftrightarrow \exists u : \text{next}(u, v) \lor \text{start}(v)$
- Successor $(u, v) \Leftrightarrow \text{next}(u, v) \lor \exists w : \text{next}(u, w) \land \text{Successor}(w, v)$
- VisitedOnce $(v) \Leftrightarrow \text{Visited}(v) \land \neg \text{Successor}(v, v)$

Encode the Specific Instance

- $V = \{v_1, \dots, v_{23}\}$
- $edge(v_1, v_2)$, $edge(v_2, v_3)$, $edge(v_3, v_4)$, $edge(v_3, v_6)$, ...

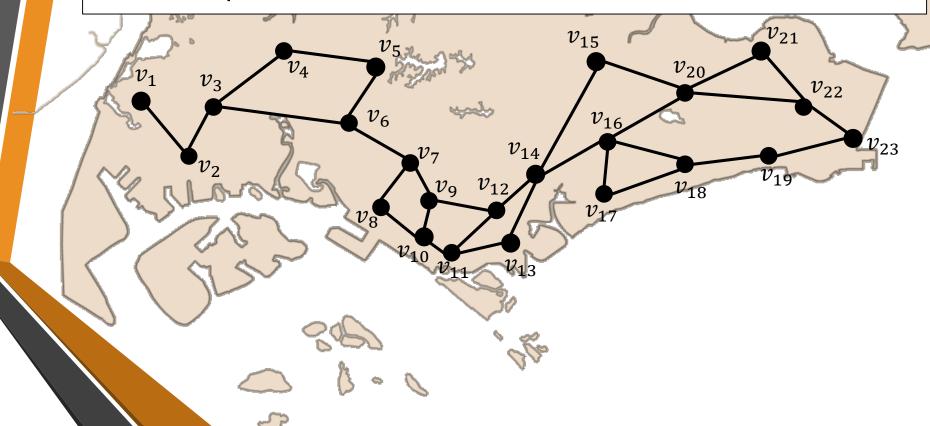


Pose Queries

• Is there a solution covering all vertices exactly once?

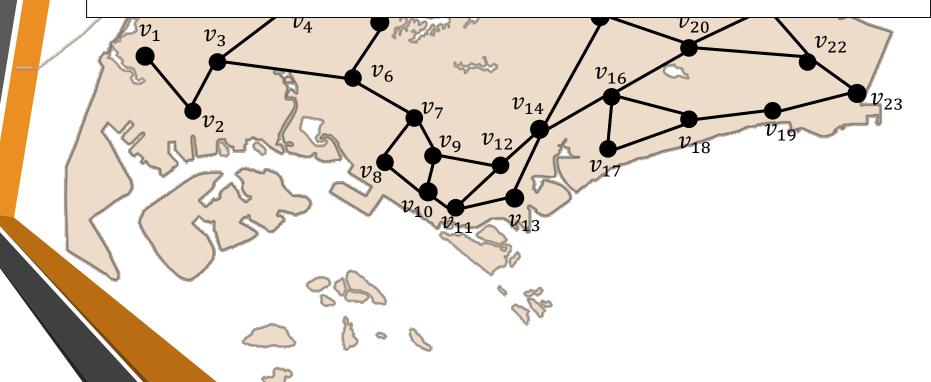
$$\forall v : (v \in V) \Rightarrow \text{VisitedOnce}(v)$$

Will a specific solution work?



Debug Database

- $\forall u, v : \text{edge}(u, v) \Rightarrow u \in V \land v \in V$
- $\forall u, v : edge(u, v) \Rightarrow u \neq v$
- $\forall v : c(v) \Rightarrow v \in V$
- ...



Summary

- First-order logic:
 - objects and relations are semantic primitives
 - syntax: constants, functions, predicates, equality, quantifiers
- Increased expressive power over propositional logic: sufficient to define many non-trivial problems