

Review of 4.2 - 5.2

Liang Ling
E0220121@...

MATH@NUS

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Basis for column space and basis for row space

- Recalled that we have two methods to find a basis for $V = \text{span}(S)$, $S = \{u_1, \dots, u_k\}$ (consider row space and column space respectively).
- A be a matrix and R is its row-echelon form, then row space of A is equal to that of R (Remark 4.1.9), dimension of row space of A is equal to dimension of row space of R , which is the number of non-zero rows in R .
- The number of non-zero rows in R equals to the number of pivot columns in R . By Remark 4.1.13, it is the same as the dimension of column space of A .

Theorem (4.2.1)

The row space and column space of a matrix have the same dimension.

Definition (Rank)

The *rank* of a matrix A is the dimension of its row space (or column space). Denoted by **rank**(A).

For concise, for any $m \times n$ matrix A we have

- ① $\text{rank}(A) = \dim(\text{column space of } A)$.
- ② $\text{rank}(A) = \dim(\text{row space of } A)$.
- ③ $\text{rank}(A) \leq \min\{m, n\}$, if equality holds then A is said to have *full rank*.
- ④ A square matrix A has full rank if and only if $\det(A) \neq 0$.
- ⑤ $\text{rank}(A) = \text{rank}(A^T)$.
- ⑥ A linear system $Ax = b \Leftrightarrow b$ is in the column space of $A \Leftrightarrow \text{rank}(A) = \text{rank}(A|b)$,

Theorem (4.2.8)

Let A and B be $m \times n$ and $n \times p$ matrices respectively. Then

$$\text{rank}(AB) \leq \min\{\text{rank}(A), \text{rank}(B)\}.$$

Theorem (Q1)

Let A and B be two matrices of the same size, then

$$\text{rank}(A + B) \leq \text{rank}(A) + \text{rank}(B).$$

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Nullspace and Nullities

Definition (4.3.1)

Let A be an $m \times n$ matrix. The solution space of $Ax = 0$ is called the *nullspace* of A . And the dimension of the nullspace is called the *nullity* of A .

Question: How to find the nullspace and nullity of A ?

- 1 Write down the augmented matrix of $Ax = 0$, and use the Gauss-Jordan Algorithm to solve this linear system.
- 2 Write the general solution as

$$x = t_1 u_1 + \cdots + t_k u_k.$$

- 3 Then the solution space $V = \text{span}(S)$, where $S = \{u_1, \dots, u_k\}$. And u_1, \dots, u_k are linear independent. Hence $\dim(V) = k$.
- 4 By the definition of nullity, we have the nullity of A is exactly k .

Properties for Nullspace — 1

Theorem (4.3.4 (Dimension Theorem for Matrices))

Let A be a matrix with n columns. Then

$$\text{rank}(A) + \text{nullity}(A) = n.$$

Proof.

$\text{nullity}(A)$ = number of arbitrary variables = number of columns minus number of non-zero rows. Which is $n - \text{rank}(A)$. □

Properties for Nullspace — 2

Suppose now we have a particular solution u for $Ax = b$, then if v is any solution for the homogeneous linear system, we have

$$A(u + v) = Au + Av = b + 0 = b.$$

So $u + v, \forall v$ in the solution space of $Ax = 0$ is a solution of $Ax = b$.

Theorem (4.3.6)

Suppose that the system of linear equations $Ax = b$ has a solution v . Then the solution set of the system is given by

$$M = \{u + v \mid u \text{ is an element of the null space of } A\}.$$

That is, $Ax = b$ has a general solution

$$x = (\text{a general solution for } Ax = 0) + (\text{one particular solution of } Ax = b).$$

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The dot product

Let $u = (u_1, \dots, u_n) \in \mathbb{R}^n$ and $v = (v_1, \dots, v_n) \in \mathbb{R}^n$.

① (*Dot Product or Inner Product*)

$$u \cdot v = \sum_{i=1}^n u_i v_i = u_1 v_1 + \dots + u_n v_n.$$

② (*Norm*)

$$\|u\| = \sqrt{u \cdot u} = \sqrt{\sum_{i=1}^n u_i^2} = \sqrt{u_1^2 + \dots + u_n^2}.$$

③ (*Distance*)

$$d(u, v) = \|u - v\| = \sqrt{\sum_{i=1}^n (u_i - v_i)^2} = \sqrt{(u_1 - v_1)^2 + \dots + (u_n - v_n)^2}.$$

④ (*Angle between u and v*)

$$\theta = \cos^{-1}\left(\frac{u \cdot v}{\|u\| \|v\|}\right).$$

Theorem

Let $u, v \in \mathbb{R}^n$ and c is a scalar, then we have

- 1 $\|u\| = 0 \Leftrightarrow u = \mathbf{0}$.
- 2 $\|cu\| = |c|\|u\|$.
- 3 (Triangle Inequality)

$$\|u + v\| \leq \|u\| + \|v\|.$$

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Definition (5.2.1)

- 1 Two vectors u and v in \mathbb{R}^n are called *orthogonal* if $u \cdot v = 0$.
- 2 A set of vectors S in \mathbb{R}^n is called *orthogonal* if every pair of distinct vectors in S are orthogonal.
- 3 A set of vectors S in \mathbb{R}^n is called *orthonormal* if S is orthogonal and every vector in S is a unit vector.

If u and v are orthogonal, then

$$\|u + v\|^2 = (u + v) \cdot (u + v) = (u \cdot u) + u \cdot v + v \cdot u + (v \cdot v) = \|u\|^2 + \|v\|^2.$$