Creating ROS Publisher and Subscriber Nodes Communicating Through String Messages

Summary:

I created two nodes, publisher and subscriber that communicate with the topic "string_message", where the publisher sends the message "hello there", and the subscriber replies with "I heard".

Publisher code:

```
#!/usr/bin/env python3
import rospy
from std_msgs.msg import String
def subscriber():
           pub = rospy.Publisher('string_message', String, queue_size=10) #topic name is string_message
           rospy.init_node('publisher', anonymous=True) #node name is publisher
           rate = rospy.Rate(10) #the rate is 10 messages/second
           while not rospy.is_shutdown():
                     hello_str = "hello there %s" % rospy.get_time()
                     rospy.loginfo(hello_str)
                     pub.publish(hello_str)
                     rate.sleep()
if __name__ == '__main__':
          try:
                     publisher()
           except rospy.ROSInterruptException:
                     pass
```

Subscriber code:

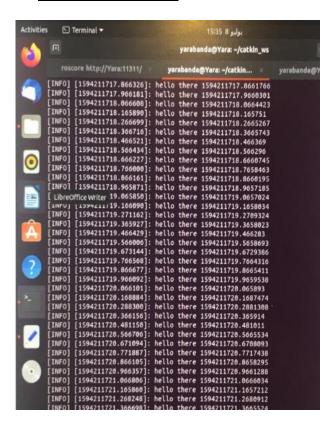
```
#!/usr/bin/env python3
import rospy
from std_msgs.msg import String
```

```
def callback(data):
    rospy.loginfo(rospy.get_caller_id() + " I heard %s", data.data)

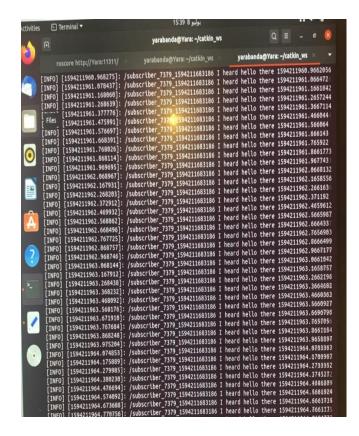
def subscriber():
    rospy.init_node('subscriber', anonymous=True)
    rospy.Subscriber("string_message", String, callback)
    rospy.spin()

if __name__ == '__main__':
    subscriber()
```

Publisher node terminal:



Subscriber node Terminal:



Rqt graph:

