

# PHY 131 HW Set #9

Ch. 15: 4, 6, 13, 14, 16, 24, 30, 35, 43, 49

**15:4** A 0.12 kg body undergoes simple harmonic motion of amplitude  $x_{\max} = 8.5 \text{ cm}$  and period  $T = 0.20 \text{ s}$ . a) What is the magnitude of the maximum force acting on it?

$$F_{\max} = m a_{\max}, \text{ with } a_{\max} = -\omega^2 x_{\max} \text{ for simple harmonic motion}$$

$$\text{Because } T = 2\pi/\omega, \omega = \frac{2\pi}{T} = \frac{2\pi}{0.2} = 10\pi = 31.4 \text{ rad/s}$$

$$\text{Hence } |F_{\max}| = (0.12 \text{ kg})(31.4)^2(0.085 \text{ m}) = 10.1 \text{ N} = \underline{10 \text{ N}}$$

b) If the oscillations are produced by a spring, what is the spring constant  $k$ ?

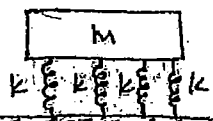
$$\text{Approach 1 } \omega = \sqrt{\frac{k}{m}} \therefore k = m\omega^2 = (0.12 \text{ kg})(31.4)^2 = 118 \text{ N/m} = \underline{120 \text{ N/m}}$$

$$\text{Approach 2 } F_{\max} = -k x_{\max}, \therefore k = \left| \frac{F_{\max}}{x_{\max}} \right| = \frac{10 \text{ N}}{0.085 \text{ m}} = 118 \text{ N/m} = \underline{120 \text{ N/m}}$$

**15:6**

Car supported on 4 identical springs

$$m = 1450 \text{ kg} \quad f = 3.00 \text{ Hz}$$



a) What is  $k$  of each spring?

These four springs are arranged in parallel, so a given displacement  $x$  will produce a restoring force  $F_{\text{each}} = -kx$  from each. Hence the total force is four times that of a single spring, and together they behave like a single spring of  $k_{\parallel} = 4k$ .

$$\text{Now } \omega = \sqrt{\frac{k}{m}}, \text{ so } k_{\parallel} = m\omega^2, \text{ where } \omega = 2\pi f, \text{ hence}$$

$$k_{\text{parallel}} = m(2\pi)^2 f^2 = (1450 \text{ kg})(2\pi)^2 (3.00 \text{ Hz})^2 = 5.15 \times 10^5 \text{ N/m}$$

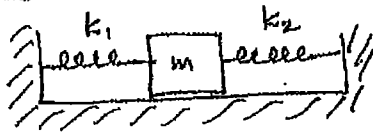
$$\text{Hence } k = \frac{k_{\text{parallel}}}{4} = \underline{1.29 \times 10^5 \text{ N/m}}$$

b) What will be the oscillation frequency if five passengers, averaging 73.0 kg each, ride in the car with an even distribution of mass?

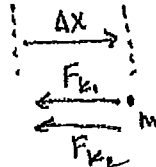
$$\text{Now } m = 1450 \text{ kg} + 5 \times 73.0 \text{ kg} = 1815 \text{ kg}$$

$$\text{So } \omega = \sqrt{\frac{k_{\text{total}}}{1815}} = \sqrt{\frac{4(1.29 \times 10^5 \text{ N/m})}{1815 \text{ kg}}} = 16.85 \text{ rad/s} \text{ and so } f = \frac{\omega}{2\pi} = \underline{2.68 \text{ Hz}}$$

15-13



$m = 0.245 \text{ kg}$   
 $k_1 = k_2 = 7580 \text{ N/m}$



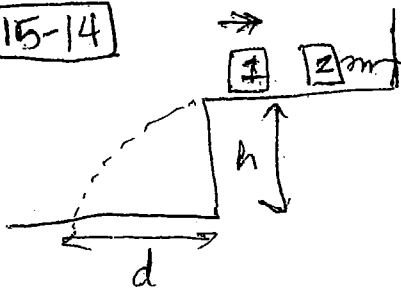
These two springs are effectively in parallel, because if you displace the mass by a distance  $x$  the two forces add in the same direction

so  $F_{\text{effective}} = F_1 + F_2$   
 $= -k_1 x - k_2 x$   
 $F_{\text{effective}} = -(k_1 + k_2) x$

Here  $k_1 = k_2 = k$ , so the combination behaves like a spring of constant  $k_{\text{effective}} = 2k$ .

Hence  $\omega = \sqrt{\frac{k_{\text{eff}}}{m}} = \sqrt{\frac{2(7580 \text{ N/m})}{(0.245 \text{ kg})}} = 249 \text{ rad/s}$   
 $\therefore f = \frac{\omega}{2\pi} = 39.59 \text{ Hz}$   
 $= \underline{\underline{39.6 \text{ Hz}}}$

15-14



$m_1: v_{0i} = 8 \text{ m/s}$   
 $m_1 = 0.2 \text{ kg}$

SPRING:  
 $K = 1208.5 \text{ N/m}$

$m_2: v_{0f} = 0$   
 $m_2 = ?$

$T = 0.14 \text{ s}$

$h = 4.9 \text{ m}$   
 $d = ?$

• We are given the period of oscillation and  $K$ , so we can find  $m_2$

• "the spring doesn't affect collision" gives us permission to treat this as an elastic collision

•  $T = 2\pi \sqrt{\frac{m_2}{K}}$

$\rightarrow m_2 = \frac{T^2 K}{4\pi^2}$

$m_2 = 0.6 \text{ kg}$

AMPAD

# 15:14 (cont.)

- Elastic collision : conserve momentum & KE

$$P: m_1 v_1 + m_2 v_2 = m_1 v_1' + m_2 v_2' \quad (1)$$

$$K: v_2 - v_1 = -(v_2' - v_1') \quad (2)$$

$$(1) m_1(v_1 - v_1') = m_2 v_2' \quad (2) v_2' = v_1 + v_1'$$

$$m_1(v_1 - v_1') = m_2(v_1 + v_1')$$

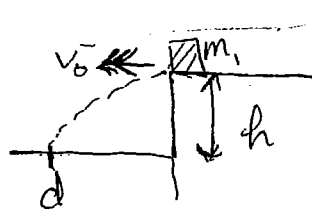
$$m_1 v_1 - m_1 v_1' = m_2 v_1 + m_2 v_1'$$

$$(m_1 - m_2) v_1 = (m_1 + m_2) v_1'$$

$$v_1' = \left( \frac{m_1 - m_2}{m_1 + m_2} \right) v_1 = \left( \frac{2 - 4}{2 + 4} \right) (8 \text{ m/s}) = -4 \text{ m/s}$$

$m_1$  moves to the left at 4 m/s

this is initial speed for projectile motion.



$$y_0 = h = 4.9 \text{ m}$$

$$y_f = 0$$

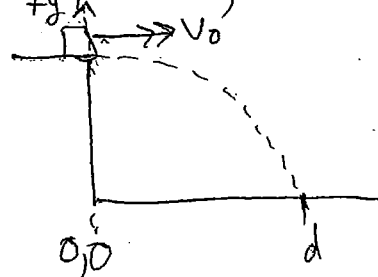
$$a_y = -9.8 \text{ m/s}^2$$

$$v_{y0} = 0$$

$$v_{yf} = ?$$

$$\Delta t = ?$$

free to choose a coordinate system, so I choose



$\rightarrow +x$

$$x_0 = 0$$

$$x_f = d = ?$$

$$v_{0x} = +4 \text{ m/s}$$

$$v_{fx} = +4 \text{ m/s}$$

$$a_x = 0$$

$$\Delta t = ?$$

I can find  $\Delta t$  from

y - eqns

I can then find  $\Delta x$

$$y_f = y_0 + v_{0y} t + \frac{1}{2} a_y t^2 = 4.9 \text{ m} - \frac{1}{2} (9.8 \text{ m/s}^2) t^2$$

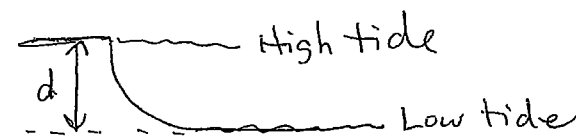
$$t = \sqrt{\frac{4.9 \text{ m}}{4.9 \text{ m/s}^2}} = 1 \text{ s}$$

$$x_f = x_0 + v_{0x} t + \frac{1}{2} a_x t^2$$

$$x_f = (4 \text{ m/s})(1 \text{ s})$$

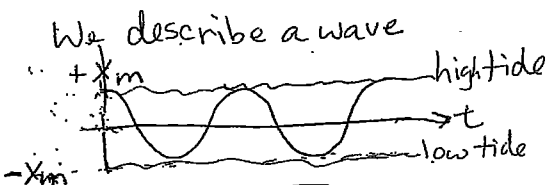
$$x_f = 4 \text{ m}$$

15:16



rise & fall  
 $T = 12.5 \text{ h}$

Note! This is the time to rise, fall, and rise again



$$A \cos(\omega t + \phi)$$

$$A = x_m$$

picture the oscillating wave going from  $+x_m$  to  $-x_m$  periodically.

$d = 2x_m$ , the distance from low tide to high tide

$$T = 12.5 \text{ h} = \frac{2\pi}{\omega}$$

$$\omega = \frac{2\pi}{T} = 0.5 \text{ rad/h}$$

$\phi = 0$  if we say at time  $t=0$   $x = x_m$   
so  $x(t) = (\frac{1}{2}d) \cos(0.5t)$

where is  $x(t) = \frac{1}{4}d$ ? when  $\cos(0.5t) = \frac{1}{2}$

$$\text{let } 0.5t \equiv \phi \rightarrow \cos \phi = \frac{1}{2}$$

MUST BE RADIANS

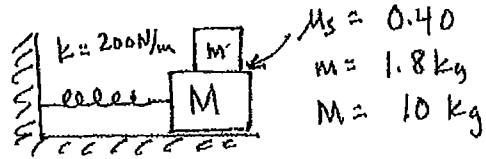
$$\phi = \cos^{-1}(\frac{1}{2})$$

$$\phi = 1.05 \text{ rad} = 0.5t$$

$$t = \frac{1.05}{0.5}$$

$$t = 2.09 \text{ hours}$$

15:24



What maximum amplitude of simple harmonic motion puts the smaller block on the verge of slipping over the larger block?

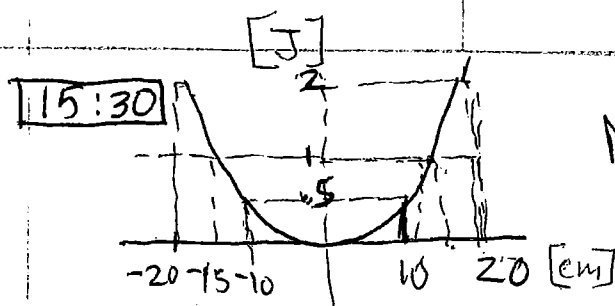
$$\text{Maximum } f_{\text{static}} = \mu_s N = \mu_s mg = (0.40)(1.80)(9.8) = 7.06 \text{ N} \quad [7.2 \text{ N}]$$

Now  $|a_{\text{max}}| = \omega^2 x_{\text{max}}$  for simple harmonic motion.

$$\text{Here } a_{\text{max at verge of slipping}} = \frac{F}{m} = \frac{f_s}{m} = \frac{7.06 \text{ N}}{1.80 \text{ kg}} = 3.92 \text{ m/s}^2 \quad [4.0 \text{ m/s}^2]$$

$$\text{We also need } \omega = \sqrt{\frac{k}{M+m}} = \sqrt{\frac{200 \text{ N/m}}{10 \text{ kg} + 1.8 \text{ kg}}} = 4.12 \text{ rad/s} \quad \therefore \omega^2 = 16.95 \text{ rad}^2/\text{s}^2$$

$$\text{Solve for } x_{\text{max}} = \frac{(a_{\text{max}})}{\omega^2} = \frac{3.92}{16.95} = 0.23 \text{ m} \quad [0.24 \text{ m}]$$



Note that  $U_{\text{SCALE}} = 2 \text{ J}$   
reading the graph:

$$U = 2 \rightarrow x = 20 \text{ cm}$$

$$U = 1 \rightarrow x = 15 \text{ cm}$$

$$U = 0.5 \rightarrow x = 10 \text{ cm}$$

$$m = 2 \text{ kg}$$

$$v = 85 \text{ cm/s @ } x = 0$$

The total mechanical energy,  $K + U$  is a constant. When the particle passes through  $x = 0 \rightarrow$  equilibrium  $\rightarrow$  the energy is all Kinetic, so

$$E = \frac{1}{2}mv^2 = \frac{1}{2}(2 \text{ kg})(.85 \text{ m/s})^2$$

$$E = 0.72 \text{ J}$$

This energy will be all potential at the turning points. Elsewhere, the sum of  $K + U$  will always be  $E_{\text{mech}} = 0.72 \text{ J}$

Where will the potential energy =  $0.72 \text{ J}$ ? This will be the turning point for this particle. We know

$$U(x) = bx^2 \text{ and we see } U(10) = 0.5 \text{ J}$$

$$\text{Solve for } b: \quad b = \frac{U(x)}{x^2} = \frac{0.5 \text{ J}}{100 \text{ cm}^2} = .005 \text{ J/cm}^2$$

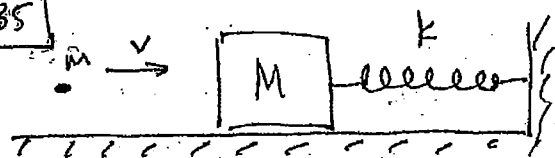
$$U(x) = (.005 \text{ J/cm}^2)x^2 = 0.72 \text{ J @ turning points}$$

$$x = \sqrt{\frac{0.72}{0.005}} = 12 \text{ cm}$$

So, YES, the particle turns back before reaching  $x = 15 \text{ cm}$ .

$x = 12 \text{ cm}$  is the turning pt

15:35



$$m = 9.5 \times 10^{-3} \text{ kg}$$

$$k = 6000 \text{ N/m}$$

$$v = 630 \text{ m/s}$$

frictionless surface

$$M = 5.4 \text{ kg}$$

Totally inelastic collision, assume spring doesn't compress until bullet is embedded.

a) Find the speed of the block just after the collision.

Momentum is conserved (no outside forces act)

$$P_{\text{before}} = P_{\text{after}}$$

$$mv = (M+m)v_{\text{block}}$$

$$\therefore v_{\text{block}} = \frac{mv}{M+m} = \frac{(9.5 \times 10^{-3})(630)}{5.4 + 9.5 \times 10^{-3}} = \underline{\underline{1.11 \text{ m/s}}}$$

b) Find the amplitude of the resulting simple harmonic motion.

The block, initially at rest, must start from its equilibrium position. Thus just after the collision, its total mechanical energy is all kinetic:

$$\begin{aligned} E_{\text{just after collision}} &= \underbrace{KE} + \underbrace{PE}_0 \\ &= \frac{1}{2}(M+m)(v_{\text{block}})^2 \\ &= \frac{1}{2}(5.4 + 9.5 \times 10^{-3})(1.11)^2 \\ &= 3.31 \text{ J} \end{aligned}$$

Later, as the spring compresses, this KE goes down as energy is put into the potential energy of the spring; eventually  $KE = 0$  at  $x_{\text{max}}$ :

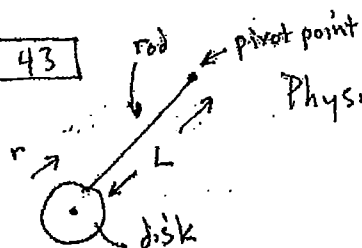
$$E_{\text{after}} = \underbrace{KE}_0 + \underbrace{PE}_{\frac{1}{2}kx_{\text{max}}^2}$$

$$\text{So } \frac{1}{2}kx_{\text{max}}^2 = 3.31 \text{ J}$$

$$x_{\text{max}}^2 = \frac{2(3.31)}{6000 \text{ N/m}} = 1.10 \times 10^{-3}$$

$$\therefore \underbrace{x_{\text{max}}}_{\text{amplitude}} = 0.033 \text{ m} = \underline{\underline{3.3 \text{ cm}}}$$

15:43



Physical pendulum

$$r = 10.0 \text{ cm} = 1.00 \times 10^{-2} \text{ m}$$

$$L = 500 \text{ mm} = 5.00 \times 10^{-1} \text{ m}$$

$$M_{\text{disk}} = 500 \text{ g} = 0.500 \text{ kg}$$

$$M_{\text{rod}} = 270 \text{ g} = 0.270 \text{ kg}$$

- a) Calculate the rotational inertia of the pendulum about the pivot point.

$$I_{\text{total}} = I_{\text{rod about end}} + I_{\text{disk about c.m.}} + M_{\text{disk}} h^2$$

$$\text{with } h = L + r$$

$$= \frac{1}{3} M_{\text{rod}} L^2 + \frac{1}{2} M_{\text{disk}} r^2 + M_{\text{disk}} (L + r)^2$$

$$= \frac{1}{3} (0.270) (0.5)^2 + \frac{1}{2} (0.500) (0.10)^2 + (0.500) (0.600)^2$$

$$= 0.0225 + 2.5 \times 10^{-3} + 0.180$$

$$= \underline{0.205 \text{ kg m}^2}$$

- b) What is the distance between the pivot point and the center of mass of the pendulum? (We need this to find the restoring torque).

Call  $x=0$  the pivot point. Then the c.o.m. of the rod lies at  $L/2$ , and the c.o.m. of the disk lies at  $r+L$ .

$$\text{Hence } M_{\text{cm}} X_{\text{cm}} = m_1 x_1 + m_2 x_2$$

$$= M_{\text{rod}} \left( \frac{L}{2} \right) + M_{\text{disk}} (r + L)$$

$$= \underbrace{(0.270) \left( \frac{0.500}{2} \right)}_{0.0675} + \underbrace{(0.500) (0.500 + 0.100)}_{0.300}$$

$$\text{Thus } X_{\text{cm}} = \frac{0.3675}{(0.500 + 0.270)} = \frac{0.3675}{0.770} = \underline{0.477 \text{ m}} \text{ from pivot}$$

- c) Calculate the period of oscillation.

Just as  $\omega = \sqrt{\frac{K}{I}}$ , here we have  $\omega = \sqrt{\frac{K}{I}}$  where  $K$  is

the restoring torque constant, as in  $\tau = -K\theta$ . The torque is provided by the weight of the center of mass at the distance

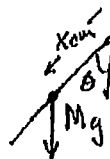
$$X_{\text{cm}}: \vec{\tau} = \vec{r} \times \vec{F} = -r_{\text{cm}} M g \sin \theta$$

$$\approx - \underbrace{X_{\text{cm}} M g}_{K} \theta$$

(small angle approximation)  
 $\sin \theta \approx \theta$

**15:43** (cont.)

$$\begin{aligned}\text{Then } \omega &= \sqrt{\frac{X_{cm} M g}{I}} \\ &= \sqrt{\frac{(0.477)(0.770)(9.8)}{0.205}} = 4.19 \text{ rad/s}\end{aligned}$$



$$\text{and so } T = 2\pi / \omega = \frac{2\pi}{4.19} = 1.4995 \text{ s} = \underline{\underline{1.50 \text{ s}}}$$

[1.48 s if  $g=10$ ]

If you don't like this analogy, we could look at the restoring

torque  $\vec{\tau} = \vec{r} \times \vec{F} = -X_{cm} M g \sin \theta$

Take the small angle approximation ( $\sin \theta \approx \theta$ ) so  $\tau = -X_{cm} M g \theta$

Apply Newton's 2nd for torques:

$$\tau = I \alpha = I \frac{d^2 \theta}{dt^2}$$

and write the equation like so:

$$-X_{cm} M g \theta = I \frac{d^2 \theta}{dt^2}$$

$$I \frac{d^2 \theta}{dt^2} + X_{cm} M g \theta = 0$$

which is identical to either the mass-spring or simple pendulum equation.

We assume  $\theta(t) = A \cos \omega t$

$$\frac{d\theta}{dt} = -\omega A \sin \omega t$$

$$\frac{d^2 \theta}{dt^2} = -\omega^2 A \cos \omega t$$

and substitute:

$$I (-\omega^2 A \cos \omega t) + X_{cm} M g (A \cos \omega t) = 0$$

which implies that

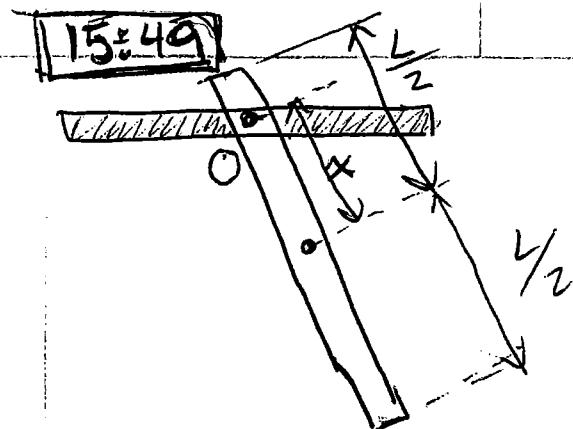
$$-\omega^2 I + X_{cm} M g = 0$$

$$\text{or } \omega^2 = \frac{X_{cm} M g}{I}$$

$$\text{so } \omega = \sqrt{\frac{X_{cm} M g}{I}}$$

as before.





- Stick of length  $L = 1.85 \text{ m}$  oscillates about point  $O$ .
- COM is located at  $L/2$
- We can vary the distance  $x$  between the COM and point  $O$

a) What distance  $x$  (between pivot and COM) will provide the LEAST period?

- We will have to minimize  $T$ , so we must write an expression for it in terms of  $x$ .

For a physical pendulum  $T = 2\pi \sqrt{\frac{I}{mgh}}$

- $h$  is  $x$  in this eqn.
- $I$ , the moment of inertia, is ALSO a function of  $x$

By parallel axis thm:  $I = I_{\text{com}} + mh^2$

$I_{\text{com}}$  of thin rod about its center is  $\frac{1}{12} ML^2$

$$I = \frac{1}{12} ML^2 + Mx^2$$

$$= M \left( \frac{L^2}{12} + x^2 \right)$$

$$\text{so } T = 2\pi \sqrt{\frac{M \left( \frac{L^2}{12} + x^2 \right)}{Mg x}} = 2\pi \sqrt{\frac{\left( \frac{L^2}{12} + x^2 \right)}{g x}} = 2\pi \sqrt{\frac{L^2 + 12x^2}{12gx}}$$

$$T^2 = 4\pi^2 \left( \frac{L^2 + 12x^2}{12gx} \right)$$

$$\frac{12gxT^2}{4\pi^2} = \frac{L^2}{x} + 12x$$

$$\frac{d}{dx} ( ) = 0 \text{ for minimum}$$

15:49 (cont)

T is minimum for  $T^2$  minimum

$$\frac{d}{dx} \left[ \frac{12gT^2}{4\pi^2} \right] = 0 = \frac{d}{dx} \left[ \frac{L^2}{x} + 12x \right]$$

$$0 = -\frac{L^2}{x^2} + 12$$

$$x = \sqrt{\frac{L^2}{12}}$$

$$x = \frac{1.85}{\sqrt{12}} = 0.53 \text{ m}$$

b) For  $L = 1.85$  and  $x = 0.53 \text{ m}$

$$T = 2\pi \sqrt{\frac{M \cdot 0.566}{M(9.8)(.53)}}$$

$$T = 2.07 \text{ s}$$

$$I = M \left( \frac{(1.85)^2}{12} + .53^2 \right) \\ = M(.566)$$