

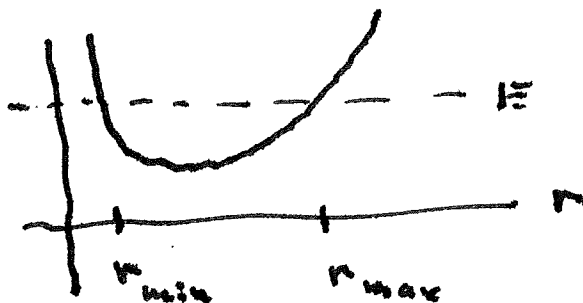
1. Two point masses of masses  $m_1$  and  $m_2$  are attracted by a central potential given by

$$U = \frac{1}{2}kr^2$$

where  $k$  is a positive constant.

- Make a plot of the effective potential  $U_{\text{eff}}$  vs.  $r$ . Based on this plot what can one conclude about the motion?
- For bound orbits obtain an expression for the minimum and maximum separations between the bodies.
- What inequality relating to energy and angular momentum is implied by your answer to part b?
- Suppose the bodies move so that the distance between them is constant. Obtain an expression for this distance in terms of  $k$ , the angular momentum and the masses of the bodies.

a) 
$$U_{\text{eff}} = \frac{L^2}{2\mu r^2} + \frac{1}{2}kr^2$$



$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

will move between  $r_{\text{min}}$  &  $r_{\text{max}}$



All motions are bound.

b)

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{L^2}{2\mu r^2} + \frac{1}{2} k r^2$$

$$r_{\min} \neq r_{\max} \Rightarrow \dot{r} = 0$$

$$E = \frac{L^2}{2\mu r^2} + \frac{1}{2} k r^2$$

$$0 = \frac{1}{2} k r^4 - E r^2 + \frac{L^2}{2\mu}$$

$$0 = r^4 - \frac{2E}{k} r^2 + \frac{L^2}{k\mu}$$

$$\begin{matrix} r_{\min} \\ r_{\max} \end{matrix} \rightarrow r^2 = \frac{\frac{2E}{k} \pm \sqrt{\left(\frac{2E}{k}\right)^2 - 4 \frac{L^2}{k\mu}}}{2}$$

$$r^2 = \frac{E}{k} \pm \sqrt{\left(\frac{E}{k}\right)^2 - \frac{L^2}{k\mu}}$$

$$r_{\min}^2 = \frac{E}{k} - \sqrt{\left(\frac{E}{k}\right)^2 - \frac{L^2}{k\mu}}$$

$$r_{\max}^2 = \frac{E}{k} + \sqrt{\left(\frac{E}{k}\right)^2 - \frac{L^2}{k\mu}}$$

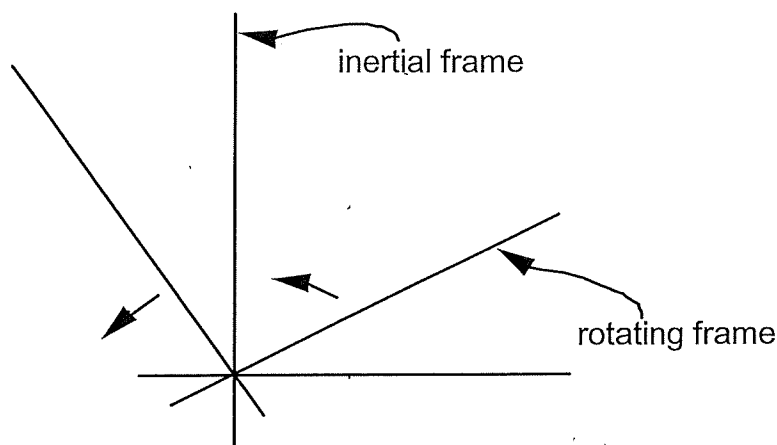
c) must have  $\left(\frac{E}{k}\right)^2 \geq \frac{L^2}{k\mu}$

d) must have  $\left(\frac{E}{k}\right)^2 = \frac{L^2}{k\mu} \Rightarrow r^2 = \frac{2E}{k}$   
 $r^2 = \frac{L}{\sqrt{k\mu}}$

2. We showed that the acceleration observed by an inertial observer  $\vec{a}_I$  is related to the acceleration seen by a non-inertial observer by:

$$\vec{a}_I = \vec{R} + \vec{a} + 2\vec{\omega} \times \vec{v} + \vec{\omega} \times (\vec{\omega} \times \vec{r}) + \vec{\omega} \times \vec{r}$$

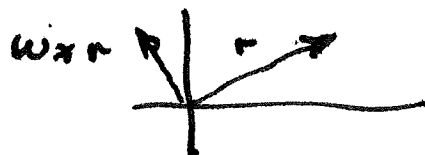
You should be familiar with the other quantities in this relation. The figure below shows an inertial coordinate system and a rotating coordinate system. The coordinate systems are placed so that their origins coincide. The rotating system rotates at a constant rate  $\omega$  about an axis perpendicular to the page.



- A point mass of mass  $m$  is seen by the rotating observer as being at rest at a distance  $r_0$  from the origin. Using the above relation, find the force acting on this object and show that it is in agreement with well-known results of Intro. Physics (PHY 131).
- A second mass point, also of mass  $m$ , is seen by the rotating observer to move in a circle concentric with the origin of a radius  $r_0$  and an angular velocity  $\omega$  in a clockwise direction. Using the above relation, find the force on this body. Show that it, too, is consistent with what is learned in Intro. Physics (PHY 131).

$$a) \quad \vec{a}_I = 0 + 0 + 0 + \vec{\omega} \times (\vec{\omega} \times \vec{r}) + 0$$

$$\vec{F} = m\vec{a}_I = m\vec{\omega} \times (\vec{\omega} \times \vec{r})$$



$\omega$  out

$$\vec{\omega} \times (\vec{\omega} \times \vec{r}) = -\omega^2 \vec{r}$$

$$\text{So } \vec{F} = -m\omega^2 \vec{r}$$

From intro for body moving in  $\odot$   $a = r\omega^2$  inward  
 $F = mr\omega^2$

b)

~~ALL OVER~~

Since the mass goes around in a clockwise direction it is moving opposite to the original  $\omega$ .

$$v = \frac{dr}{dt} = (-\omega) \times r = -\omega \times r$$

$$a = \frac{dv}{dt} = (-\omega) \times (-\omega \times r) = \omega \times (\omega \times r)$$

so

$$a_I = \underbrace{\ddot{R}}_0 + a + 2\omega \times v + \underbrace{\omega \times (\omega \times r)}_{=0} + \underbrace{\dot{\omega} \times r}_{=0}$$

$$= \omega \times (\omega \times r) + 2\omega \times (-\omega \times r) + \omega \times (\omega \times r)$$

$$a_I = 0$$

In fact the mass is at rest in the inertial frame & Force = 0