Solutions to Problem Set 21

Problem 1a: In order to compute $[T]^{\varepsilon_2}_{\alpha}$, we need to compute each of $[T(x^2)]_{\varepsilon_2}$, $[T(x)]_{\varepsilon_2}$, and $[T(1)]_{\varepsilon_2}$. We have

$$T(x^{2}) = \begin{pmatrix} 0^{2} \\ 2^{2} \end{pmatrix}$$
$$= \begin{pmatrix} 0 \\ 4 \end{pmatrix}$$
$$= 0 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 4 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

so

$$[T(x^2)]_{\varepsilon_2} = \begin{pmatrix} 0\\4 \end{pmatrix}.$$

We also have

$$\begin{split} T(x) &= \begin{pmatrix} 0 \\ 2 \end{pmatrix} \\ &= 0 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 2 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \end{split}$$

 \mathbf{SO}

$$[T(x)]_{\varepsilon_2} = \begin{pmatrix} 0\\2 \end{pmatrix},$$

and

$$T(1) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
$$= 1 \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

so

$$[T(1)]_{\varepsilon_2} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

It follows that

$$[T]_{\alpha}^{\varepsilon_2} = \begin{pmatrix} 0 & 0 & 1 \\ 4 & 2 & 1 \end{pmatrix}.$$

Problem 1b: In order to compute $[T]^{\beta}_{\alpha}$, we need to compute each of $[T(x^2)]_{\beta}$, $[T(x)]_{\beta}$, and $[T(1)]_{\beta}$. We have

$$T(x^{2}) = \begin{pmatrix} 0 \\ 4 \end{pmatrix}$$
$$= 2 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + (-2) \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix},$$

so

$$[T(x^2)]_{\beta} = \begin{pmatrix} 2 \\ -2 \end{pmatrix}.$$

We also have

$$T(x) = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$
$$= 1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + (-1) \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix},$$

so

$$[T(x)]_{\beta} = \begin{pmatrix} 1 \\ -1 \end{pmatrix},$$

and

$$T(1) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
$$= 1 \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 0 \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix},$$

so

$$[T(1)]_{\beta} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.$$

It follows that

$$[T]_{\alpha}^{\beta} = \begin{pmatrix} 2 & 1 & 1 \\ -2 & -1 & 0 \end{pmatrix}.$$

Problem 2: We have

$$T\begin{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$T\begin{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = 0 \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$T\begin{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = 0 \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$T\begin{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = 0 \cdot \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + 0 \cdot \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Therefore,

$$[T]^{\alpha}_{\alpha} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

Problem 3: Consider the 4×5 matrix with the given 5 vectors as columns:

$$\begin{pmatrix} 1 & 2 & 3 & 1 & -4 \\ 3 & 6 & 9 & 3 & -7 \\ 0 & 1 & 1 & -1 & 0 \\ 2 & -1 & 1 & 7 & -3 \end{pmatrix}.$$

Applying elementary row operations to this matrix, we obtain

$$\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
3 & 6 & 9 & 3 & -7 \\
0 & 1 & 1 & -1 & 0 \\
2 & -1 & 1 & 7 & -3
\end{pmatrix}
\rightarrow
\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
0 & 0 & 0 & 0 & 5 \\
0 & 1 & 1 & -1 & 0 \\
0 & -5 & -5 & 5 & 5
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
0 & 0 & 0 & 0 & 5 \\
0 & 1 & 1 & -1 & 0 \\
0 & 0 & 0 & 5
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
0 & 0 & 0 & 0 & 5 \\
0 & 1 & 1 & -1 & 0 \\
0 & 0 & 0 & 0 & 5
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
0 & 1 & 1 & -1 & 0 \\
0 & 0 & 0 & 0 & 5 \\
0 & 0 & 0 & 0 & 5
\end{pmatrix}$$

$$\begin{pmatrix}
R_2 \leftrightarrow R_3 \\
(R_2 \leftrightarrow R_3) \\
(R_2 \leftrightarrow R_3)
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
0 & 1 & 1 & -1 & 0 \\
0 & 0 & 0 & 0 & 5 \\
0 & 0 & 0 & 0 & 5
\end{pmatrix}$$

$$\rightarrow
\begin{pmatrix}
1 & 2 & 3 & 1 & -4 \\
0 & 1 & 1 & -1 & 0 \\
0 & 0 & 0 & 0 & 5 \\
0 & 0 & 0 & 0 & 5
\end{pmatrix}$$

$$(-R_3 + R_4).$$

Notice that this last matrix is in echelon form, and that the first, second, and fifth columns have leading entries. Using Proposition 5.2.10, we conclude that

$$\left(\begin{pmatrix} 1\\3\\0\\2 \end{pmatrix}, \begin{pmatrix} 2\\6\\1\\-1 \end{pmatrix}, \begin{pmatrix} -4\\-7\\0\\-3 \end{pmatrix} \right)$$

is a basis for W. We have found a basis for W with 3 vectors, so $\dim(W) = 3$.

Problem 4a:

$$[T] = \begin{pmatrix} 1 & 0 & 2 & -1 \\ 3 & 1 & 9 & -5 \\ -1 & 2 & 4 & -2 \end{pmatrix}$$

Performing elementary row operations on this matrix, we obtain

$$\begin{pmatrix} 1 & 0 & 2 & -1 \\ 3 & 1 & 9 & -5 \\ -1 & 2 & 4 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 2 & -1 \\ 0 & 1 & 3 & -2 \\ 0 & 2 & 6 & -3 \end{pmatrix} \qquad (-3R_1 + R_2)$$

$$\rightarrow \begin{pmatrix} 1 & 0 & 2 & -1 \\ 0 & 1 & 3 & -2 \\ 0 & 0 & 0 & 1 \end{pmatrix} \qquad (-2R_2 + R_3).$$

Now we know form Proposition 5.2.3 that $\operatorname{range}(T)$ is the span of the columns of [T]. Since that last matrix above is in echelon form, we may combine this with Proposition 5.2.10 to conclude that

$$\left(\begin{pmatrix} 1\\3\\-1 \end{pmatrix}, \begin{pmatrix} 0\\1\\2 \end{pmatrix}, \begin{pmatrix} -1\\-5\\-2 \end{pmatrix} \right)$$

is a basis for range(T). Alternatively, we can use Corollary 5.2.4 to conclude that T is surjective, so $\operatorname{range}(T) = \mathbb{R}^3$, and hence

$$\left(\begin{pmatrix}1\\0\\0\end{pmatrix},\begin{pmatrix}0\\1\\0\end{pmatrix},\begin{pmatrix}0\\0\\1\end{pmatrix}\right)$$

is a basis for range(T).

To determine Null(T), we want to find the values of $x, y, z, w \in \mathbb{R}$ such that

$$T\left(\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix}\right) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

Thus, we want to find the values of $x, y, z, w \in \mathbb{R}$ such that

$$\begin{pmatrix} 1 & 0 & 2 & -1 \\ 3 & 1 & 9 & -5 \\ -1 & 2 & 4 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

In other words, we want to solve a homogeneous linear systems whose augmented matrix is given by [T] together with a column of 0's on the right. Omitting this column of 0's and looking at the above computation, we notice the following. First, the last line tells us that w = 0. Since there is no leading entry in the third column, we introduce a parameter z = t. The second line now tells us that y+3z-2w=0, so y=-3z=-3t. Finally, the first line tells us that x+2z-w=0, so x=-2z=-2t. Therefore, we have

$$\operatorname{Null}(T) = \left\{ \begin{pmatrix} -2t \\ -3t \\ t \\ 0 \end{pmatrix} : t \in \mathbb{R} \right\} = \left\{ t \cdot \begin{pmatrix} -2 \\ -3 \\ 1 \\ 0 \end{pmatrix} : t \in \mathbb{R} \right\}.$$

It follows that

$$\operatorname{Null}(T) = \operatorname{Span}\left(\begin{pmatrix} -2\\ -3\\ 1\\ 0 \end{pmatrix}\right).$$

Now the sequence of one vector

$$\left(\begin{pmatrix} -2 \\ -3 \\ 1 \\ 0 \end{pmatrix} \right)$$

is linearly independent because the vector is nonzero (see the discussion on p. 181). Therefore,

$$\left(\begin{pmatrix} -2 \\ -3 \\ 1 \\ 0 \end{pmatrix} \right)$$

is a basis for Null(T).

Problem 4b: Since we found a basis for range(T) consisting of 3 elements, we have rank(T) = 3. Similarly, since we found a basis for Null(T) consisting of 1 element, we have nullity(T) = 1. Notice that rank(T) + nullity(T) = 4 = dim(\mathbb{R}^4), as the Rank-Nullity Theorem tells us must be the case.

Problem 5: We first show that $range(T) = \mathcal{P}_3$, i.e. that range(T) is the set of all polynomial functions of degree at most 3.

• We first show that every element of $\operatorname{range}(T) \subseteq \mathcal{P}_3$. Let $g \in \operatorname{range}(T)$ be arbitrary. Fix $f \in \mathcal{P}_5$ with T(f) = g, so f'' = g. Since $f \in \mathcal{P}_5$, we can fix $a_0, a_1, a_2, a_3, a_4, a_5 \in \mathbb{R}$ such that

$$f(x) = a_5 x^5 + a_4 x^4 + a_3 x^3 + a_2 x^2 + a_1 x + a_0$$

for all $x \in \mathbb{R}$. We then have

$$f'(x) = 5a_5x^4 + 4a_4x^3 + 3a_3x^2 + 2a_2x + a_1$$

for all $x \in \mathbb{R}$, and hence

$$f''(x) = 20a_5x^3 + 12a_4x^2 + 6a_3x + 2a_2$$

for all $x \in \mathbb{R}$. Since g = f'', we conclude that g has degree at most 3, and so $g \in \mathcal{P}_3$.

• We now show that $\mathcal{P}_3 \subseteq \operatorname{range}(T)$. Let $g \in \mathcal{P}_3$ be arbitrary. Fix $a_0, a_1, a_2, a_3 \in \mathbb{R}$ such that

$$g(x) = a_3 x^3 + a_2 x^2 + a_1 x + a_0$$

for all $x \in \mathbb{R}$. Define $f: \mathbb{R} \to \mathbb{R}$ by letting

$$f(x) = \frac{a_3}{20} \cdot x^5 + \frac{a_2}{12} \cdot x^4 + \frac{a_1}{6} \cdot x^3 + \frac{a_0}{2} \cdot x^2$$

for all $x \in \mathbb{R}$ and notice that $f \in \mathcal{P}_5$. We have

$$f'(x) = \frac{a_3}{4} \cdot x^4 + \frac{a_2}{3} \cdot x^3 + \frac{a_1}{2} \cdot x^2 + a_0 x$$

for all $x \in \mathbb{R}$, and hence

$$f''(x) = a_3 x^3 + a_2 x^2 + a_1 x + a_0$$

for all $x \in \mathbb{R}$. Thus, we have f'' = g, and so T(f) = g. It follows that range $(T) \subseteq \mathcal{P}_3$.

Combining the two containments, we have shown that $\operatorname{range}(T) = \mathcal{P}_3$. Since $\dim(\mathcal{P}_3) = 4$ (because $(1, x, x^2, x^3)$) is a basis for \mathcal{P}_3), we conclude that $\operatorname{rank}(T) = 4$.

Now notice that $\dim(\mathcal{P}_5) = 6$, so since $\operatorname{rank}(T) + \operatorname{nullity}(T) = \dim(\mathcal{P}_5)$ by the Rank-Nullity Theorem, we must have $4 + \operatorname{nullity}(T) = 6$. Therefore, $\operatorname{nullity}(T) = 2$. Alternatively, one can argue directly that $\operatorname{Null}(T) = \mathcal{P}_1$ to prove this.