2 Short Answers - 6 points

Precisely describe (using proper terminology) how we can apply results from this class to describe the solution sets of the systems of equations encoded in the following augmented matrices:

$$\bullet \ A = \begin{pmatrix} 0 & 0 & 1 & 4 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Because the matrix is in echelon form and it has a leading entry in the lost column, we know that the system of linear equations that it encodes is incarrishent.

$$\bullet \ B = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 2 & 3 & 4 & 5 \\ 0 & 0 & 3 & 4 & 5 \\ 0 & 0 & 0 & 4 & 5 \end{pmatrix}$$

Because the matrix is in echelou form and less a leading entry in every column except for the last, we know the system of linear equations that it encodes is consistent and has a unique eduction.

$$\bullet \ C = \begin{pmatrix} \mathbf{0} & 2 & 0 & 1 & 1 \\ 0 & 0 & \mathbf{0} & 1 & 3 \end{pmatrix}$$

The nativity is in echelon form and ten last column has no leading entries but there are other columns us out leading entries, so, the encoded system is carristent and less infinitely many solutions.

3 Proofs - 12 points

Prove the following statements. You must formally justify each of your claims by stating the definition or result from which it follows. Do not refer to results by their number in the text, state them completely.

3.1

Let V be a vector space and let $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n, \vec{w} \in V$. Show that the following are equivalent:

- (a) $\operatorname{Span}(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n, \vec{w}) = \operatorname{Span}(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n)$
- (b) $\vec{w} \in \text{Span}(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n)$

(a)
$$\Rightarrow$$
 (b) Suppose Span (ui's, w) = Span (ui's), tren

 $\vec{u} = \hat{\mathcal{E}} \cdot 0 \cdot \vec{u}_i + 1 \vec{\omega} \iff \vec{\omega} \in \text{Span}(\vec{u}_i, \dots, \vec{u}_n, \vec{\omega})$

thus, $\vec{v} \in \text{Span}(\vec{u}_i, \dots, \vec{u}_n)$

(b)=>(a) Suppose
$$\vec{w} \in Spon(\vec{u}_1,...,\vec{u}_n)$$
 (i.e. $\vec{w} = \hat{z}_1 \cdot \vec{u}_1 \cdot z_2 \cdot \vec{u}_1 \cdot z_2 \cdot \vec{u}_2 \cdot z_3 \cdot \vec{u}_1 \cdot z_2 \cdot \vec{u}_1 \cdot z_3 \cdot \vec{u}_2 \cdot z_3 \cdot \vec{u}_1 \cdot z_3 \cdot \vec{u}_2 \cdot \vec{u}_3 \cdot \vec{u}_1 \cdot z_3 \cdot \vec{u}_1 \cdot z_3 \cdot \vec{u}_2 \cdot \vec{u}_3 \cdot \vec{$

$$\vec{x} \in Span(uis) \Rightarrow \exists di w \hat{Z} di \vec{u}_i = \vec{x} = \hat{Z} di u_i + 0.\vec{\omega}$$

 $\vec{x} \in Span(uis) \Rightarrow \vec{x} \in Span(uis) \in Span(uis) \in Span(uis, \vec{\omega})$

$$=\frac{\mathcal{E}(c_i+d_{s_i})\vec{u}_i}{c_{s_i}}$$
 \in Span $(u_i,...,u_n)$

Let V be a vector space and let $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k, \vec{w} \in V$. Suppose that $(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k)$ is linearly independent and that $(\vec{u}_1 + \vec{w}, \vec{u}_2 + \vec{w}, \dots, \vec{u}_k + \vec{w})$ is linearly dependent. Show that $\vec{w} \in \text{Span}(\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k)$.

Notice that $\vec{w} \neq 0$, otherwise $\vec{u}_1 + \vec{w} = \vec{u}_i$ for all $i \in \{1,2,...k\}$ and then $(\vec{u}_1 + \vec{w}_2, \vec{u}_2 + \vec{w}_3, ..., \vec{u}_k + \vec{w}_k) = (u_1, u_2, ..., u_k)$ and counst be both marris independent and linearly dependent.

 $(\ddot{u}_1 + \ddot{w}_1, \dots, u_k + \ddot{w})$ linearly dependent $\exists c_1, c_2, \dots, c_k \in \mathbb{R}$ $v_1 c_1 \neq 0$, for some $i \in \{1, 2, \dots, k\}$, such that $c_1(\ddot{u}_1 + \ddot{w}) + c_2(\ddot{u}_2 + \ddot{w}) + \cdots + c_k(\ddot{u}_k + w) = 0$ Thus

C, \vec{u}_1 + C_2\vec{u}_2 + \dots + C_k\vec{u}_K + (C_1 + C_2 + \dots + C_k)\vec{w} = 0

 $c_1\vec{u}_1 + c_2\vec{u}_2 + \cdots + c_k\vec{u}_k = (-c_1 - c_2 - \cdots - c_k)\vec{w}$. If $-c_1 - c_2 - \cdots - c_k = 0$ then $(-c_1 - \cdots - c_k)\vec{w} = \vec{0}$, and thus $c_1\vec{u}_1 + c_2\vec{u}_2 + \cdots + c_k\vec{u}_k = \vec{0}$.



4 Bonus - 1 Point

Consider the following matrices:

Is A row-equivalent to B? Justify your answer.

it he regard trese as augmented natrices, then trey cannot be now equivelent because now operations preserve solution sets.