

Nerf Architecture

- a forward pass involves 2 rendering pass — coarse
fine

- data structure

- sub.-renderer = {

- coarse:

- ImplicitRenderer (NeRF RaySampler,
raymarcher)

- fine: ImplicitRenderer (ProbabilisticRaySampler,
raymarcher)

- self.-implicit-function = {

- coarse: NeuralRadianceField

- fine: . . .

- }

- forward

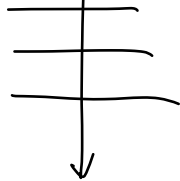
1. coarse rendering pass

ray-sampler

ray-bundles

PE

embeds-features



MLP-architecture
(linear layer + ReLU)

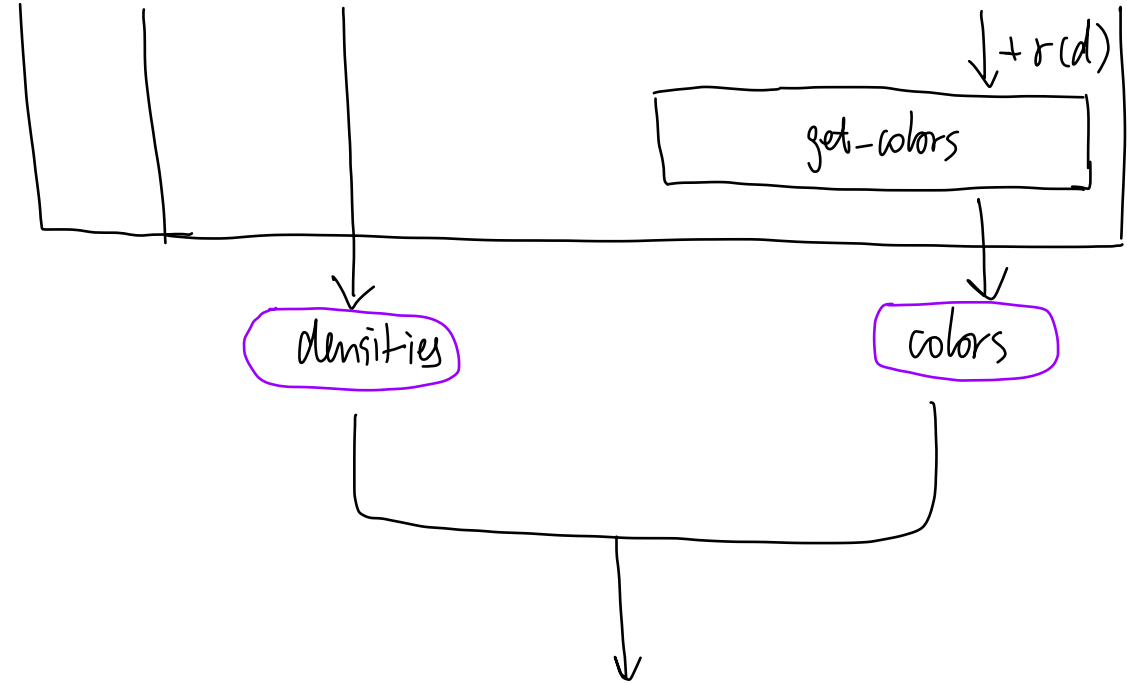
features

volumetric
function

get-densities

raw-densities = density-layer(features)

map $\rightarrow [0, 1]$



ray
marcher

$$C_c = \sum_{i=1}^{N_c} T_i \alpha_i c_i$$

where $T_i = \prod_{j=1}^{i-1} (1 - \alpha_j) \rightarrow \text{absorption}$

$\alpha_i = 1 - e^{-\Delta_i \delta_i} \rightarrow \text{ray density}$

$T_i \rightarrow 1 \Rightarrow \alpha_i$ contributes the most to the color

image

2. fine rendering pass

almost the same, except:

- take coarse-weights
to generate new ray-bundles
via inverse transformation sampling
 $w_i = T_i z_i$

$$- C_f = \sum_{i=1}^{N_f + N_c} w_i c_i$$

→ MSE:

$$\text{loss} = \sum_{r \in R} \|\hat{C}_c(r) - C(r)\|_2^2 + \|\hat{C}_f(r) - C(r)\|_2^2$$



differentiable. \Rightarrow gd, backprop

optimizer: Adam