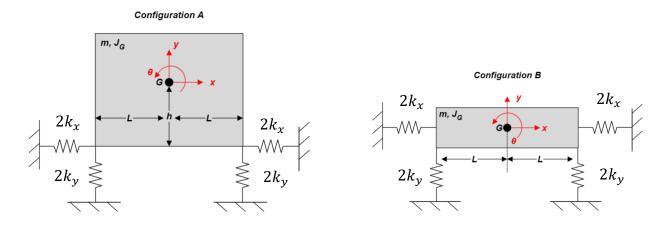
## **Lab 3 Assessment Questions**

Please type your submission and submit your answers as a PDF with the Excel data file separately.

Each configuration of the platform can be modelled as shown:



- 1. (3 **pts**) Determine the system of equations of motion using the coordinates  $\begin{cases} x \\ y \\ \theta \end{cases}$  for Configuration A.
- 2. (1 pt) Determine the system of equations of motion using the coordinates  $\begin{pmatrix} x \\ y \\ \theta \end{pmatrix}$  for Configuration B.

Assume that m = 13 kg, L = 270 mm, and  $k_y = 2.8 \text{ kN/m}$ .

Using your collected data for the platform in Configuration B:

- 3. (1 pt) Estimate the lateral spring stiffness  $k_x$ .
- 4. (1 pt) Estimate the moment of inertia  $J_G$  of the platform.

For your collected data for the platform in Configuration A:

- 5. (2 pts) Use your data to estimate the natural frequencies  $\omega_{n1}$  and  $\omega_{n2}$ . Estimate the frequencies using both the translational acceleration and angular velocity data sets and report your natural frequencies as an average of the two values.
- 6. (2 pts) Calculate the amplitudes of x(t) and  $\theta(t)$  in each mode using their corresponding data sets. Use your calculated amplitudes to estimate the magnitude of the ratio  $\frac{\mathbb{X}}{\Theta}$  in the first and second modes.
- 7. (1 pt) Based on your visual observations of each mode shape and nodal locations for Configuration A, determine the sign of  $\frac{\mathbb{X}}{\Theta}$  (positive or negative) for each mode <u>based on the provided coordinate system.</u>

For the following questions, use your equations of motion from Question 1 and values from Question 3 to Question 7.

- 8. (2 pts) Estimate the value of h using your values for the first mode.
- 9. (2 pts) Estimate the value of h using your values for the second mode.