

Yash Khandelwal

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Education

Indian Institute of Technology, Kharagpur

B-Tech in Chemical Engineering

Minor in Computer Science & Engineering

CGPA - 8.19/10.00

July 2017 - Present

Research Interests

► 2D/3D Computer Vision ► Robotics ▶ Deep Learning Machine Learning Multimodality ► Explainability

Publications

Model-agnostic information biasing for Visual Question Answering in ACM CODS-COMAD 2021: Y Khandelwal, et al. (Accepted, to appear)

Real-time Lane Detection, Fitting and Navigation for Unstructured Environments in International Conference of Image, Video Processing and Artificial Intelligence, Shanghai (2019): Y Khandelwal, et al.

(Link)

A Prototype of an Intelligent Ground Vehicle for constrained environment: Design and Development in IEEE International conference on control and robots, South Korea (2019): Y Khandelwal, et al.

(Link)

Research Experience

Wadhwani Al May'20 - July'20

Research Intern. Advisor: Dr. Rahul Panicker

Aim: To reconstruct new-born babies to correct scale using the Multiview and Geometry information

- Worked on smartphone-based anthropometry tool that will empower health workers to screen low-weight babies
- Created a first of a kind Multiview and Geometry model which can reconstruct moving babies to correct shape
- Incorporated the Geometry information using a reference object, i.e., a checkerboard of fixed size in the scene.
- Deployed model brings down the weight mae by 26% on the validation set and 14.5% on the test set

Student-teacher attention transfer in Visual Question Answering (VQA)

Jan'20 – Present

Advisor: Prof. Abir Das, Dept. of Computer Science, IIT Kharagpur

(Paper) (Github) (WandB)

Aim: To create a model agnostic framework that improves the grounding of existing VQA models

- Proposed a student-teacher attention transfer framework for improving any existing attention-based VQA model
- Devised a novel angle-based gradient update method for simultaneous optimization of multiple objective functions
- Achieved improvement of +0.95% and +0.57% on benchmarking models MFB and BAN, using same amount of data

Research Products

Low-cost social distancing monitoring device

(Blog) (Video) March 2020 - May 2020

- Developed a portable, low-cost device (total cost < \$60) to monitor and encourage social distancing in crowded areas
- Implemented ~4 fps person detection on a custom-trained Mobilenet SSD on a Raspberry Pi with a rotating camera
- Achieved an error of 7 cms/meter for person-to-person ground distance by using a calibrated homographic projection
- Endorsed by Minister of Education and covered by all major media outlets like NDTV, Tribune, Hindustan Times, etc.

Face recognition-based attendance system

(Presentation) September 2019 - November 2019

- Developed a face recognition attendance system with facilities to expand into leave and payroll management systems
- Created a face recognition model based on MTCNN and adjusted it for robustness on Indian faces through fine-tuning
- Sped up the pipeline by ~60% by using k-nearest neighbors search in feature space instead of classification layers
- Deployed a web application to view real-time analytics about attendance and to add/remove/modify users remotely

Autonomous Ground Vehicle Research Group

Feb'18 - Present

(Video)

Advisor: Prof Debashish Chakravarty, Dept. of Mining Engineering, IIT Kharagpur

Lane Detection and Drivable-Region Segmentation:

o Ideated an end to end Deep Learning pipeline which includes a generator network and a segmentation network

- o Designed a Segmentation network with dilation and attention layers inspired by the U-Net and Pyramid network
- o Experimented with models like Embedded-Loss-GAN and Contextual Aggregation Network on the TuSimple dataset

Speed Breaker Detection:

(Video)

- o Designed a deep learning model for real-time speed breaker detection at over 50 frames per second on Intel i7 processor
- o Tested the model in various environmental conditions on Mahindra E20 and obtained a test accuracy of 92%
- o Collected and curated a dataset of 20,000 speed breaker images using various augmentation techniques

GPS & Camera Mapping:

(Video)

- Developed a low-cost mapping tool for efficient storage and real-time retrieval of lane markings
- o Predicted the GPS coordinate of a point on the ground in an image using a camera, filtered GPS, IMU, and odometry data
- o Implemented Robot Localization package to improve the precision of GPS data using Extended Kalman Filter
- o Created a 2D map of nearly 1-acre Mining Department using 2D Lidar and other sensors using G mapping package

Exploratory Research Projects

Anti-Advertisement Recommender System for Electronic Appliances

Feb'19 – July'19

Advisor: Prof K Sreenivasa Rao, Dept. of Computer Science Engineering, IIT Kharagpur

- Predicted a review score using an Aspect based Sentiment Analysis model by taking the weighted mean of sentiments
- Analyzed the trend and seasonality in the price of gadget based on new launches and past behavior of similar activities
- Scraped over 1GB text data of product description, reviews, price, resale value, etc. from blogs, e-commerce websites, etc.

Modelling and Optimization of Naptha Cracking Unit using Learning Methods Advisor: Prof K Sudeshna Sarkar, Dept. of Computer Science Engineering, IIT Kharagpur

Oct'18 - May'19

- Built a greybox model of naphtha cracking process at the Haldia Petrochemicals Ltd. using process data and control logic
- Exhaustively used IOT Techniques and developed a digital twin of the plant by installing latest monitoring sensors
- Formulated prognostic machine learning algorithms for detection of failures using time series anomaly detection methods

Competitions

27th Intelligent Ground Vehicle Competition

(Design Report) (Video)

Organized by Oakland University, Michigan USA

- Secured the 1st position in the qualification round and the 2nd position in the finals of the AutoNav challenge, 2019
- Built a three-wheel differential drive bot capable of following lanes, avoiding obstacles, and reaching a set of GPS target
- Solely created an algorithm which can identify obstacles and lane markings using a camera and 2D Lidar
- Designed an embedded circuit with proper safety equipment and tuned the PID parameters for stable control of the bot

Mahindra Rise Prize Driverless Challenge

(Ongoing)

- Part of the team which got selected amongst the top 13 finalists out of a total of 600 applicants from all over India
- Deployed Urban Lane Detection, Speed Breaker Detection, and Lane Mapping modules on Mahindra E2O electric car
- Designed an Embedded circuit for battery and power management for the sensors and computers on the car

Awards and Achievements

- Got selected among the top 50 students in the Google Research India Al Summer School in the Computer Vision Track
- Awarded the Kishore Vaigyanik Protsahan Yojana (KVPY) fellowship by the Department of Science & Technology, India
- Awarded the 1st position in Pixelation 2018 for developing the fastest autonomous maze traversing robot

Skills & Expertise

Languages	C, C++, Python
Libraries	PyTorch, TensorFlow, Keras, OpenCV, NumPy, Pandas, Selenium, WandB
Frameworks	ROS, Carla Simulator, LaTeX, Git

Relevant Coursework

Computer Science	Machine Learning Information Retrieval Scalable Data Mining Programming and Data Structures Theory and Lab Symbolic Logic Computer Vision Deep Learning (Stanford University- CS231N)
Mathematics	Linear Algebra Matrix Algebra Transform Calculus Numerical Solutions of Partial Differential Equations Probability and Statistics