

System Program →

System Program

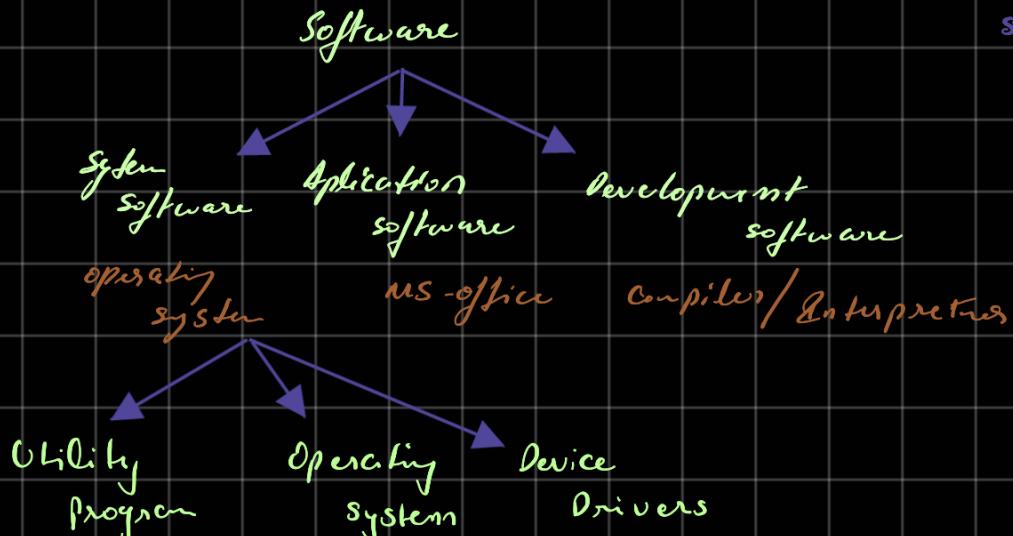
- Compiler

Application Program

- Editor "Pytharm".

System Call →

METHOD OF INTERACTION WITH OPERATING SYSTEM VIA PROGRAM.
PROGRAM REQUESTS SEVERAL SERVICES, AND "OS" RESPONDS BY INVOKING A SERIES OF SYSTEM CALLS TO SATISFY THE REQUEST.



Memory →

Abbreviation for core programs.

inc → increase by one.

Kernel →

Is a computer program at the core of computer's "OS" and has complete control over every thing in system.

• System Software →

Operating System →

OS consists of the master system of programs that manages the basic operations of the computer.

Utility software →

It is a system software that helps to maintain proper and smooth functioning of a computer system.

Device Driver →

A software that helps a peripheral device establish communication with computer.

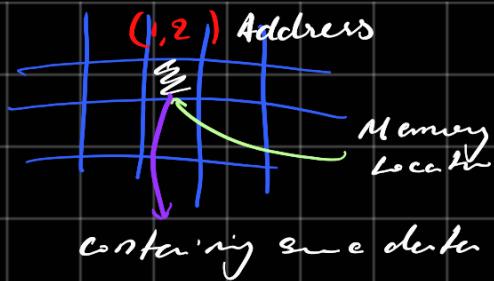
System software →

Coordinates the activities and function of hardware and programs.

General Machine Structured →

Memory Address Register (MAR) →

Contains the address of memory location.
To be read from.



Memory Buffer Register (MBR) →

Contains the copy of memory location whose address is stored in "MAR".

Memory Controller →

Transfer the data of "MBR" to core memory location whose address is stored in "MAR".

General Machine Structure →

I/O → MC

— MAR

MBR

LC
Data

WR

→ II

II → Instruction Interpreter

ZR → Copy the content of LC stored in ZR.

LC → Points to the current instruction.

WR → scratch pad for II

GR → used by the programmers.

- Working Register
- General Register

Assembler →

- Is a low level language.
- Considered as a second-generation language.
- for writing "OS" and desktop applications.

High-level Language →

- easy to understand, user friendly.
 - requires compiler to convert the code, so the system can understand.
- ex → C, C++, Java

Company Top Source Code Management software →

- **Github** Enables large development teams to collaborate, review, and manage software or application code
 - Offers free trial
 - Team: \$4 per user/month
 - Enterprise: \$21 per user/month
- **Bitbucket** One-stop solution for versioning, project management, and collaboration across teams of any size
 - Free for small teams with up to 5 members
 - Standard and Premium come at \$3 and \$6 per user/month, respectively
- **Gitlab** Used for end-to-end project lifecycle with git-based tools: version control, project management, CI/CD
 - Free for individuals
 - Premium and Ultimate editions come at a cost of \$19 and \$99 per user/month, respectively
- **Team Foundation Server** Enterprise-grade source control management tool that supports integration with most of the existing IDEs
 - Offers free trial
 - Basic Plan: \$2 per user/month
 - Azure Pipelines: \$15 per parallel job
- **Apache Subversion** Open-source version control system supporting file locking and merge tracking
 - Open source: deployed on premise and is free to use

Levels of system software →

- System software is a set of programs that handles all the basic internal working of a computer.

Levels of System Software are

1. Operating System

An operating system is system software that controls the working of computer hardware and software. Moreover, it acts as a common connection between the computer hardware and software. In other words, we can also call it an interface between the hardware and the users.

Some important tasks performed by the operating system are:

- Scheduling
- Memory Management
- File Management
- Security
- Protects data and other software from unauthorized access .

2. Language Processors

It is a special type of system software that converts the source code into machine code. The input given has to be in object code only hence, we use language processors. Also, the machine code executes faster as compared to the source code.

- Source Code
- Object Code

- Different Types of Language Processors are:
Assembler It converts assembly language to machine language.
Interpreter It is a type of system software that executes the program line by line.
Compiler It is also a type of system software that executes the whole program at once.

3. Utility Software

- Application Software
- System Utilities

These types of system software are used for the proper and smooth functioning of the computer system. They perform functions like removing outdated files, recover data which is accidentally lost, finding information, arranging data and files in an orderly manner, compress disk drive, install and uninstall programs, etc.

- Different types of utility software are:

1. Antivirus Software They are used to protect the system from viruses. Some examples are Quick Heal, McAfee, etc.

2. Compression Tools They help compress large files. The files can be changed to the original form when we require it. Examples are WinRAR, PeaZip, etc.

3. Disk Management Tools

They are used to manage data on the disks efficiently so that the system performance can enhance. Examples are Disk Cleanup Tool, Backup Utility, etc.

4. Device Drivers

- These types of system software are used for the operation of the peripheral devices. Each device connected to the computer has its own driver. These drivers basically contain instructions that tell the operating system how to operate the device.
- Some drivers are pre-installed on the computer while some others are installed when a new device is added. The audio device, video device, scanner, camera, etc. all require a driver. A driver tells the operating system how to use the device.

Assembler Design →

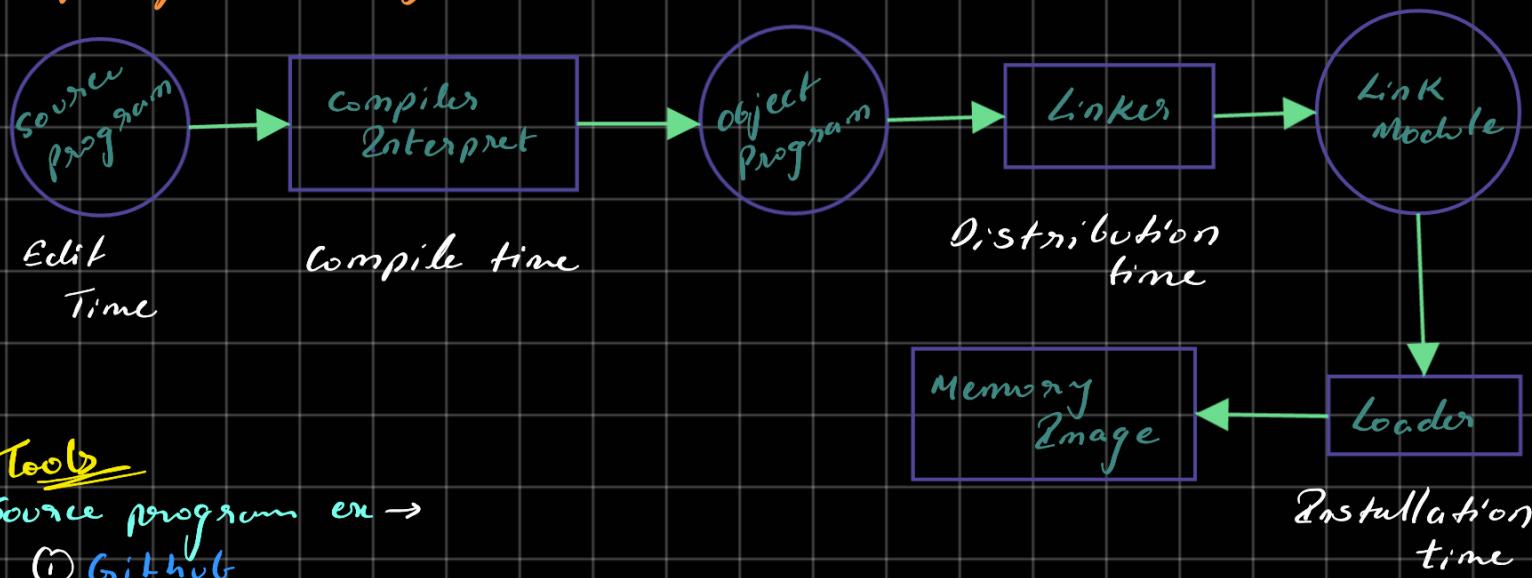
- Scanning
- Parsing (Syntax Analysis)
- Forward Referencing
- Symbol Table
- Machine Code Generation

Operating System functions →

- User interface and input/output management →
 - User interface : allows individuals to access and command the computer system.
 - Command - based user interface : requires short text commands to be given to the computer to perform basic activities.
 - Graphical user interface : uses icons and menus displayed on screen to send commands to the computer system.
- Hardware independence →
 - Application software : allows applications to make use of the operating system.
- Memory Management →
- Processing Tasks →
 - Multitasking
 - Time-slicing
 - Scalability
- File Management →
- Security →

`.py` → *translator* → `.obj` → `.exe`
 Source Compiler Object executable
 Program Program form.

life cycle of source program →



Tools

Source program ex →

- ① GitHub
- ② Team foundation server
- ③ Apache subversion

Application Software

open for all

- ① Horizontal application software (General purpose)
- ② Vertical application software (Particular / personal purpose)

System Software Development

1. Requirement Analysis and Resource planning / finalizing .

2. Design and Prototyping .

- Algorithm

- Flow chart / DFD

Turkey {
 α - developer end
 β - user end

3. Software Development / coding / Implementing

4. Testing / Deployment of software

5. Maintenance

Recent Trends in Software Development

1. Progressive Web-Application (PWA)

2. DevOps (Development operations)

3. Cyber security

4. Cloud Native Apps

5. IoT (Internet Of Behaviour)

Assembler →

Converts assembly language to machine level language.

- Pass 1 (one pass assembler)

- Pass 2 (2 - pass assembler)

HLL → Human language

ALL → symbol

MLL → Machine

Elements of Assembly Language →

The various elements that are possible are →

① Labels

symbols (names)

② Operands / operands

(logical / mathematical)

③ Directives

(Assembler Directives) EQU & SET

④ Comments

symbols written in Capital

letters . ex → EQU

Assembly language should start with
any of these .

→ SET

should have space , commas and end with ';' .

Advanced Assembler Directives →

- Origin (xyz)

address will be assigned from +xyz onwards.

- LTORG

Literals in the literal table will only be assigned address after LTORG only.

Literal	Address	}
→ '4'	-	
→ '2'	-	

LTORG is called.

after → Address

→ '4' 206

→ '2' 207

• Advanced Assembler directives:-

① ORIGIN

② LTORG

③ EQU

<Label> EQU <addr>

X EQU Y

"X is set to the addr of Y"

	Literal	Addr.
0	= '4'	207
1	= '2'	208

START 200

MOVER BREG = '4'

→ LOOP MOVER AREG N

ADD BREG = '2'

ORIGIN LOOP+5,

NEXT BC ANY, LOOP

LTORG

ORIGIN NEXT+3

N DC 5

END

(LC)

200

201

202

206

207

209

210

- EQU

X EQU Y

Label/variable X is set to the address of Y.

Data Structures in Pass-1

I Assembly Prg.

II M/C opcode Table (MOT)

III Symbol table:

Symbol	addr

IV Literal table:

Literal	addr

V Pool Table:-

Mnemonic	Class	m/code	length
STOP	IS	00	1
		01	
ADD	IS	02	1
SUB	IS	03	1
MULTI	IS	04	1
MOVER	IS	05	1
MOVEM	IS	06	1
COMB	IS	07	1
BC	IS	08	1
DIV	IS	09	1
READ	IS	10	1
PRINT	IS	11	1
END	AD	02	-
START	AD	01	-
ORIGIN	AD	03	-
EQU	AD	04	-
LTORG	AD	05	-
DS	DL	01	-
DC	DL	02	1
A - C	RG	01 - 03	-
EQ, LT, GT	CC	01 - 06	-
LE, GE, NE			

Design of Assembler →

- ① specify the problem
- ② specify the Data structure / Define format of data structure
- ③ specify algorithm
- ④ look for modularity

↳ Repeat 1-4 until problem is solved.

1. Pass 1

- ① Defines symbols ST (Symbol Table) literals → same value and name in ALL.
- literals LT (Literal Table)
- MOT (Machine operation)
- LC (Location Counter)

2. Pass 2

Translation of Object code

Put values of symbols

Pass 1 DS

Source Program

LC

MOT

POT (Pseudo Operation Table)

ST

LC

File passed to Pass 2 →

Pass 2 DS

Copy of file from Pass 1

LC

MOT

POT

ST

BT (Base Table)

Pass -1 →

- 1) Symbol Table / Literal Table created, but no address will be provided until until "LORG" or "end" keywords.

Src Code		Pass 1		Intermediate code
		LC	IC	
START	200	-	(AD,01) (CC,200)	
MOVER AREG, =' ^L S'		200	(IS,04) (RG,01) (L,0)	
MOVEM AREG, X ^S		201	(IS,05) (RG,01) (S,0)	
L, MOVER BREG, =' ^L 2'		202	(S,1) (IS,04) (RG,02) (L,1)	
ORIGIN L ₁ + ₂ + ₃ → 205		203	(AD,03) (C, 205)	
LTORG		205	(AD,05) (DL,02) (C,5)	
X DS 1		206	(AD,05) (DL,02) (C,2)	
END		207	(S,0) (DL,01) (C,1)	
		208	(AD,02)	

ST	L T	Pool	DS
S	L A	O	DC
X	205		DL,01
L1	202		DL,02

Address will be assigned after or end

- Separates the symbols, Mnemonic opcodes and operand fields.
 - Build symbol table
 - Perform LC (Location Counter) processing.
 - Construct Intermediate representation

LTOOL → Literal Table
origin.
Sign address for
Literals in Literal Table

DS → Data Storage
assign address for
symbol's in symbol table.

Data Structures →

- OPTAB (Operation table)
 - SYMTAB (Symbol table)
 - LIT TAB (Literal table)
 - POOL TAB (Pool table)
 - MOT (Machine Operation Table)
 - POT (Pseudo Operations Table)
 - LC (Location Counter)

Pass - 2

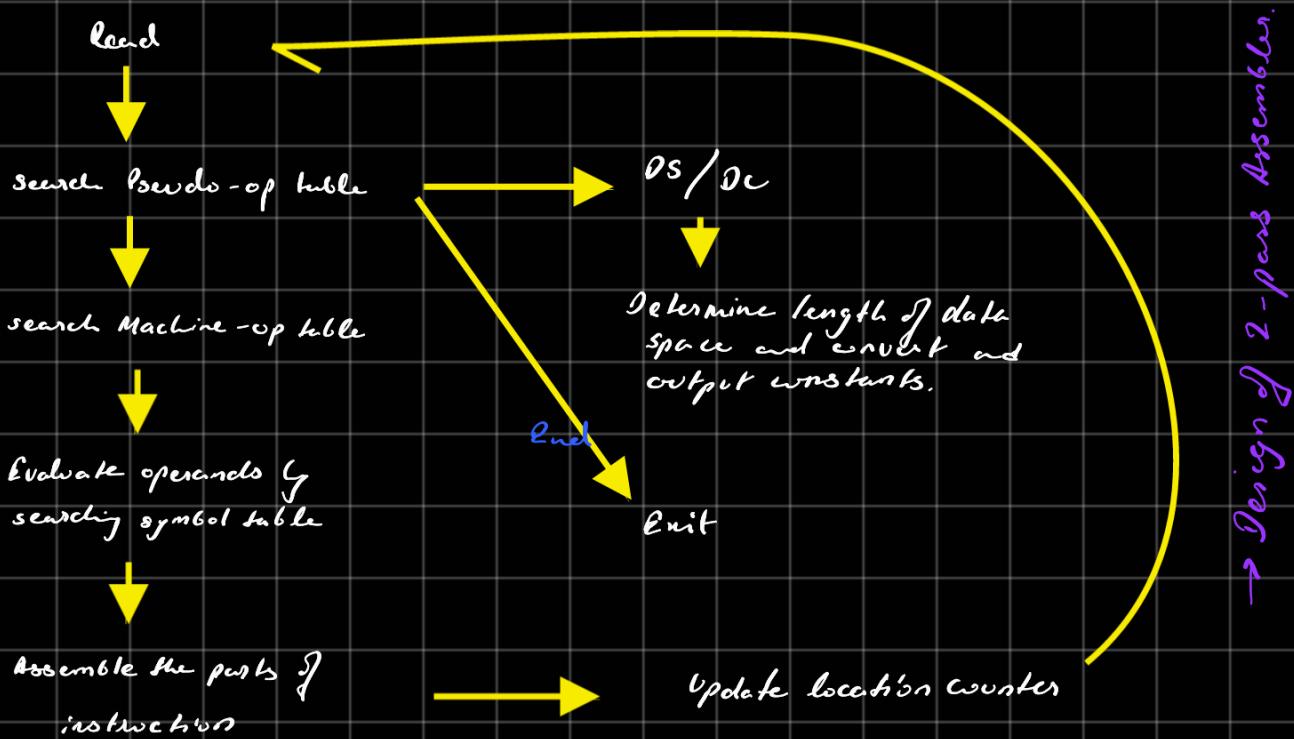
Pass 1 - to machine code

Assembly code	LC	IC	MIC code
START 100	100	(AD,01) (C,00) (IS,09) (S,0)	(09) (00) (109) (04) (02) (104)
READ N	101	(IS,04) (R4,02) (L,0)	(05) (02) (110)
MOVER B, =1'	102	(IS,05) (R4,02) (S,1)	(03) (02) (110)
MOVEM B, TERM	103	(S,2) (IS,03) (R4,02) (S,1)	(00) (00) (001)
A MUL B, TERM	104	(AD,05) (DL,02) (C,1)	(04) (03) (107)
LTORG	105	(IS,04) (R4,03) (L,1)	(05) (02) (108)
MOVER C, =2'	106	(IS,05) (R4,02) (L,2)	(00) (00) (002)
MOVEM B, =5'	107	(AD,05) (DL,02) (C,2)	(00) (00) (005)
LTORG	109	(AD,05) (DL,02) (C,5)	
N DS 1	110	(S,0) (DL,01) (C,1)	
TERM DS 1		(S,1) (DL,01) (C,1)	

for 00

ST		LT		POOL
S	A	L	A	O
0 N	109	0 =1'	104	0
1 TERM	110	1 =2'	107	1
2 A	103	2 =5'	108	3

- 2-pass system is to address the problem of "forwarding references"— references to variables or subroutines that have not yet been encountered when parsing the source code. A strict 1-pass scanner cannot assemble source code which contains forward references. Pass 1 of the assembler scans the source, determining the size and address of all data and instructions; then pass 2 scans the source again, outputting the binary object code.



Working of pass -2

(Symbol Table)

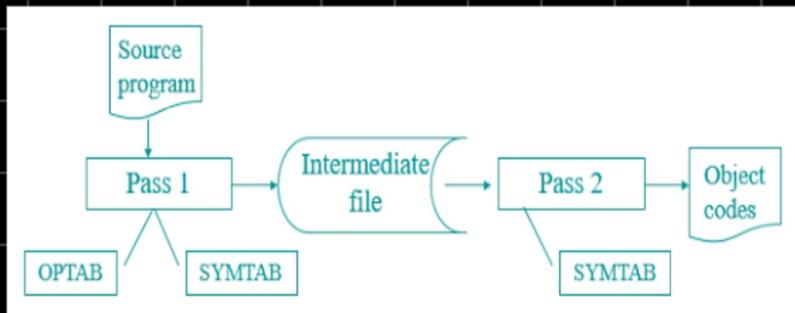
- Generates machine code by converting symbolic-machine-opcode into their respective bit configuration.
- It stores all machine-opcodes in MOT table, with symbolic code, their length and their bit configuration.

It also processes pseudo-ops and store them in POT table (pseudo-op table).

Data Structures →

- MOT table (machine opcode table)
- POT table (pseudo opcode table)
- Base table (storing values of base registers)
- LC (Location Counter)
- ST (symbol Table)

Design of 2-pass Assembler →



One-pass Assembler →

- The assembler reads the source file once.
- During single pass, the assembler handles both label definitions and assembly.
- Only problem is future symbols.

Two-pass Assembler →

- Performs two passes over the source file.
- In "first pass", looks for label definitions.
- All labels are collected, assigned values and placed in symbol table.
- In "second pass", instructions are read again and assembled, using the symbol table.

One pass And Two pass Assembler Implementation →

Label	Opcode	Operands			Address
John	START	200		L1	
	MOV R	$R_1 = '3'$		1 '3'	203
200	MOVE M	$R_1 X$		2 '2'	—
201					
L1	MOVE R	$R_2 = '2'$			
202	L TO RG			ST	Address
203				1 X	204
X	DS			2 L1	202
204	Declaration Statement		1 { forward reference for 'X'		
	END				
205					

single pass 'Assembler for 8086' →

Labels - Reserved Words & Identifiers

Assembler Directive - case Insensitive

Operands - letters, -, #, @

Addressing Modes →

1. Register ADD A,B opcode operand

2. Immediate ADD 5,6 ADD 6,5

3. Memory ADD 0014,0024

① Direct

② Indirect

Data Structure →

① Opcode template

② Operand template

Multipass Assembler →

ALPHA	EQU	BETA	• Alpha and Beta cannot be defined in pass 1.
BETA	EQU	GAMMA	• when doing multipass processing, DELTA so defined in pass 1, BETA in pass 2, Alpha in pass 3.
GAMMA	REGW	1	This is the motivation for only a multipass assembler.

Variants of Assembler →

- ① GNU Assembler
- ② 48xxx Cross Assemblers
- ③ Amsterdam Compiler Kit (ACK)
- ④ single target Assembler

Macro →

Macro represents a commonly used group of statements in the source programming language.

Macro Processor →

Replaces each macro instruction with the correspondingly group of source language statements called "expanding macro".

Label	opcode	operand	Each parameter starts with \$.
	MACRO	\$x, \$y	
	DEF	\$x, \$y	
	DA	\$x	
	MOV	\$B, \$A	
	LOA	\$y	
	ADD	\$B	
	END		



Label	Opcode	Operand
SWAP	MACRO	f_x, f_y
	LOA	f_x
	LOX	f_y
STORE	MACRO	f_x, f_y
	STA	f_y
	STA	f_x
	MEND	
	MEND	



Design of Macro Assembler →

pass 1 →

- Macro definition processing
- SYMTAB construction

Data structures used →

- ① DEF TAB
- ② NAM TAB
- ③ ARG TAB

pass - 2 →

- Macro expansion
- Memory allocation & IC processing.
- Processing of literals
- Intermediate code generation.

pass - 3 →

- Target code generation.

Difference Between Macro Processor and Macro Assembler:

Macro Assembler	Macro Processor
1) It performs Expansion as well as generate object code	It only Performs Expansion
2) Expansion is performed during Design Analysis	It may have its own pass structure
3) It doesn't require separate preprocessor and Assembler	It <u>require</u> separate preprocessor and Assembler
4) From user point of view it is very simple	The user have to run <u>preprocessor first</u> and then assembler to generate object code . So its complicated
Less Time Consuming	More time consuming
Complex Logic	Comparatively easy Logic
Data Structure <u>Used</u> : All data structures used by Macro processor and <u>SYTAB</u> , <u>OPTAB</u> , <u>LITAB</u> etc	Data Structure <u>used</u> : <u>MNT</u> , <u>MDT</u> , <u>PNTAB</u> , <u>EVTAB</u> , <u>SSNTAB</u> , <u>KPDTAB</u> , <u>SSTAB</u>
It has <u>three</u> phases : Macro Definition Processing , Macro Expansion and simple Assembling	It has two <u>Phases</u> : Macro Processing and Macro Expansion

Flow of execution →

- sequential
- conditional
- looping

Macro Expansion → (M_{EC})

Algo while there is no MEND

- a) If normal seq statement
 - i) Expand statement
 - ii) M_{EC} = M_{EC} + 1
- else

M_{EC} = Address of next statement to be expanded

Exit.

Advanced Macro facilities →

1. Expansion time variables

Expansion time
sequencing symbols
SS

Expansion time

statement

ATP, AGO, ANOP

Labels



Nested Macro →

Label	opcode	Operand
SWAP	MACRO	f_x, f_y
	LOA	f_x
	LOX	f_y
STORE	MACRO	f_x, f_y
	STA	f_y
	STX	f_x
	MEND	
	MEND	

Flow control in Macro's →

- ① Sequential
- ② Conditional
- ③ Looping

MEC (Macro Execution Count)

+1 with every single
macro seen.

Advanced Macro facilities →

1. Expansion time sequencing symbols
 $\langle ss \rangle$

2. Expansion time statements

A2F

AGO

ANOP (No operation)

A2F (Expression) $\langle ss \rangle$

AGO $\langle ss \rangle$

$\langle ss \rangle$ ANOP

Test MACRO f_x, f_y, f_z

A2F (f_x Equiv). Only
Move 3 f .

Pass 1

Macro definition

Symbol table constant

Pass 2

Macro expansion

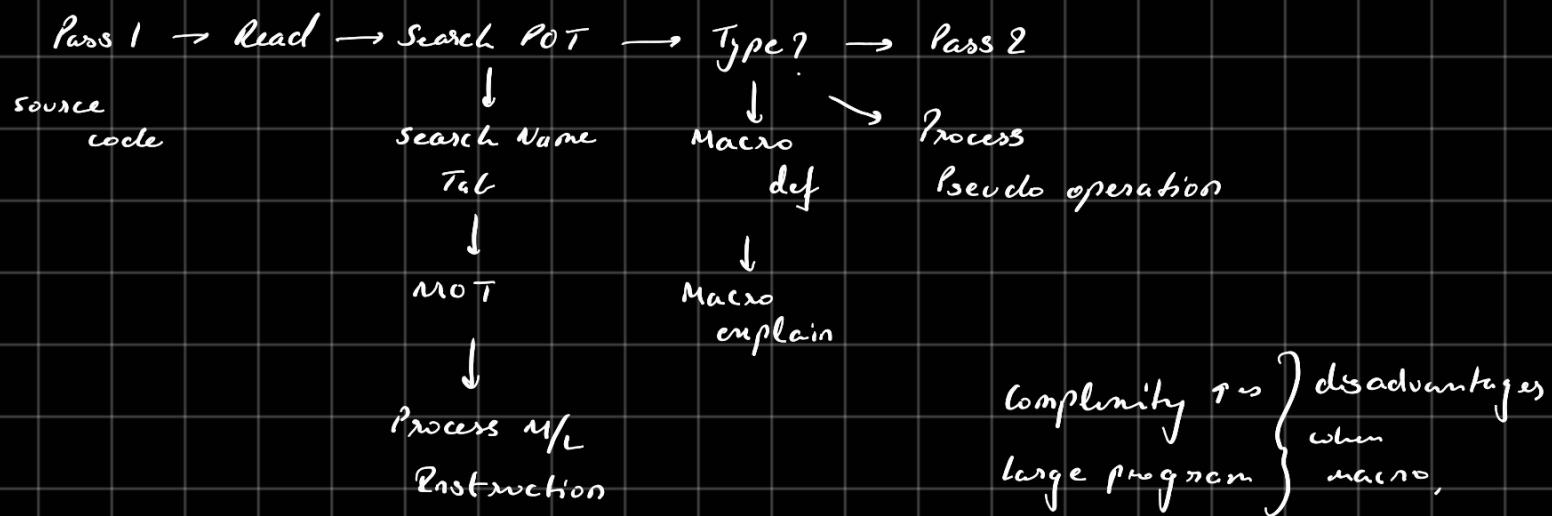
Process symbols/literals

Intermediate code generation

Pass 3

Object code generation

Macro Assembler flowchart



Basic tasks of Macroprocessor

Macro definition

Macro Invocation

Macro expansion

- Basic tasks of Macro processor
- Definition of Macro
 - Invoke the macro
 - Expansion (substitution)
- Name Tab-
definition Tab
ARG Table

label	op code	operands
sum	MACRO	fA, fB
	LD A	fA
	MOV	B
	LD A	B
	ADD	B
	MEND	

Design issues of Macroprocessor

1. Flexible Data Structures
2. Attributes / Parameter Names shouldn't be duplicated
3. Default Argument / Numeric value at Macro definition time.
4. Comments should be clearly specified.

Unit - 2 →

Compiler

- Converts the entire source code into exe. at a time
- Execution time of the code is faster.
- Generates Intermediate object code.
ex → C, C++

Interpreter

- runs the code line by line.
- execution time of code is slow.
- No object code is generated.
ex → Python, Perl

Assembler

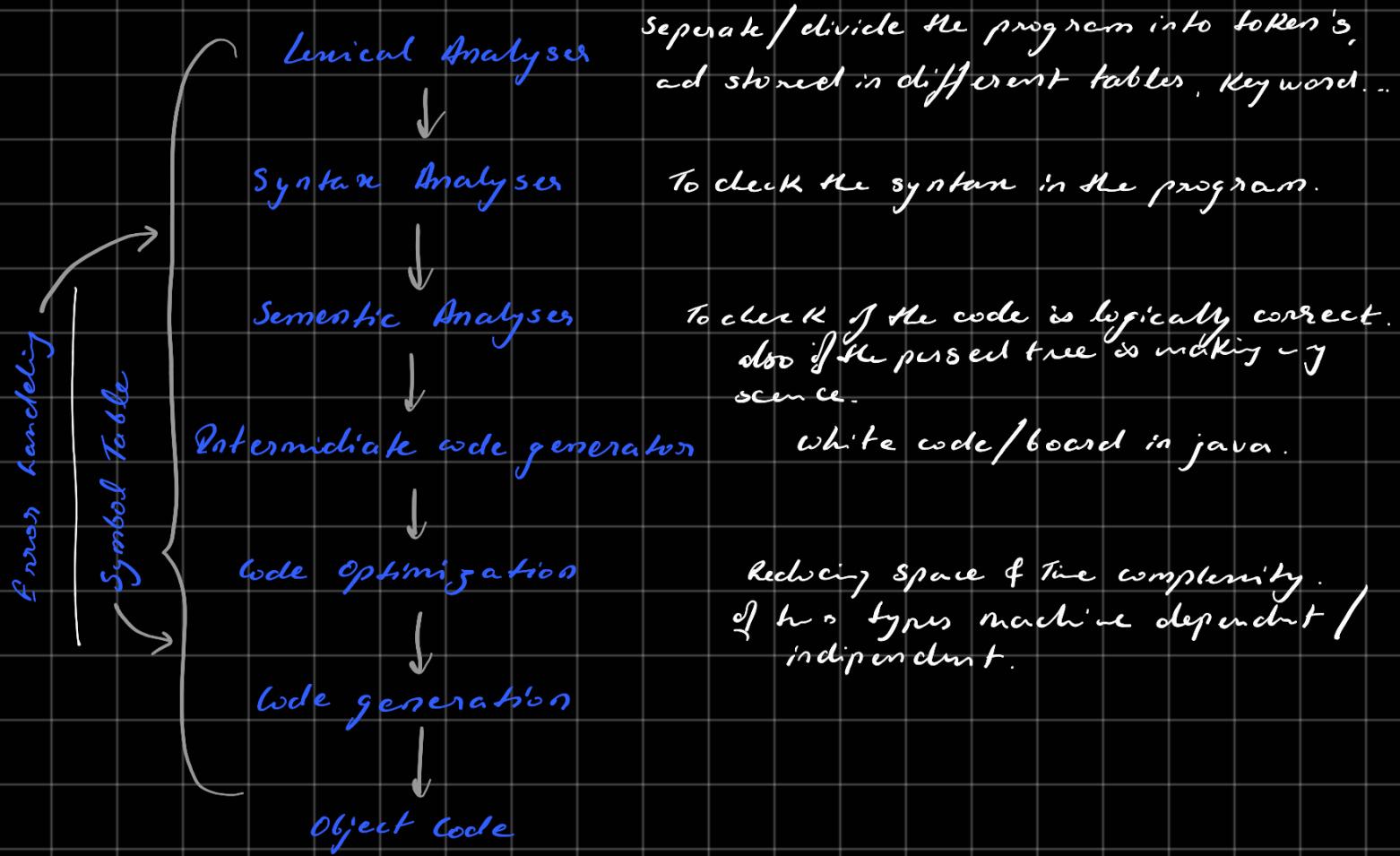
- LLL to MLL
- One to one
- translate entire program before running
- Requirement of memory less
- Used only once to create .exe file.

Interpreter

- HLL to MLL
- One to many
- translate entire program line by line.
- Requirement of memory more.
- Used every time when the program is running.

subroutines →
function is known as subroutine.

Phases in Compiler →



$$c = a + b \times 5$$



Lexical Analysis

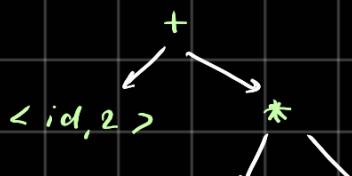
$\langle id, 1 \rangle \langle = \rangle \langle id, 2 \rangle \langle + \rangle \langle id, 3 \rangle \langle * \rangle \langle s \rangle$



Syntax Analysis



$\langle id, 1 \rangle$



$\langle id, 3 \rangle \rightarrow \text{intTofloat}$



↓
S

Intermediate code Generation

$$t_1 = \text{intTofloat}(S)$$

$$t_2 = id_3 * t_1$$

$$t_3 = id_2 + t_2$$

$$id_1 = t_3$$



Code optimizer

$$t_1 = id_3 * 5$$

$$id_1 = id_2 + t_1$$



Code generator

LOF R₂, id₃

MULF R₂, #5.0

LOF R₁, id₂

ADDA R₁, R₂

STF id₁, R₁

Grammar and finite Automata

v → Variable capital letters

Grammar = { V, T, S, P } $\Sigma \Leftrightarrow T \rightarrow$ Terminal small letters, symbols

S → start

P → Production

Finite Automata (FA) is the simplest machine to recognize pattern.
A finite automata consists of the following →

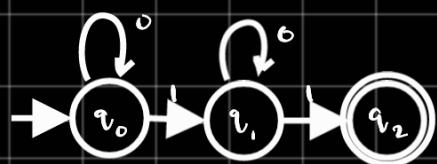
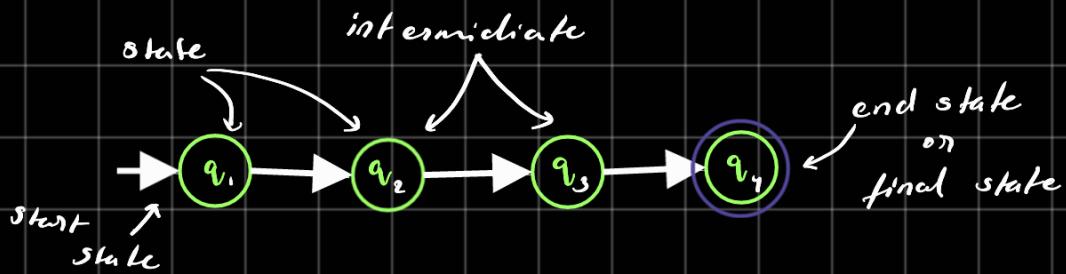
Q : Finite set of states.

Σ : set of input symbols

q_0 : Initial state

F : set of final states

δ : Transition function



$$\begin{aligned}\delta(q_0, 0) &\rightarrow q_0 \\ \delta(q_0, 1) &\rightarrow q_1 \\ \delta(q_1, 0) &\rightarrow q_1 \\ \delta(q_1, 1) &\rightarrow q_2\end{aligned}$$

$$\delta = Q \times \Sigma \rightarrow Q$$

$$Q = \{q_0, q_1, q_2\}$$

$$q_0 = q_0$$

$$\Sigma = \{0, 1\}$$

$$F = \{q_2\}$$

Finite Automata

DFA

NFA

Deterministic Finite
Automata

transitions will lead to
one exact state.

Non Deterministic

Finite Automata

to any different state

Null or ϵ

$$DFA: Q \times \Sigma \rightarrow Q$$

$$NFA: Q \times (\Sigma \cup \{\epsilon\}) \rightarrow 2^Q \setminus \emptyset$$

$$Q = (q_0, q_1, q_2) \quad \Sigma = \{0, 1\}$$

DFA (Q, Σ, q_1, F, S)

$$(q_0, q_1, q_2) \times \{0, 1\}$$

q_0	0
q_0	1
q_1	0
q_1	1
q_2	0

Transition will happen
in one of these states

NFA (Q, Σ, q_1, F, S)

$$(q_0, q_1, q_2) \times \{\phi, 0, 1\}$$

$$q_0 \\ q_1 \\ q_2$$

$$q_0, q_1 \\ q_0, q_2 \\ q_1, q_2 \\ q_0, q_1, q_2$$

$$\phi, q_0, q_1, q_2, q_0 q_1, q_0 q_2, q_1 q_2, q_0 q_1 q_2$$

Transition will happen in any one of
these states.

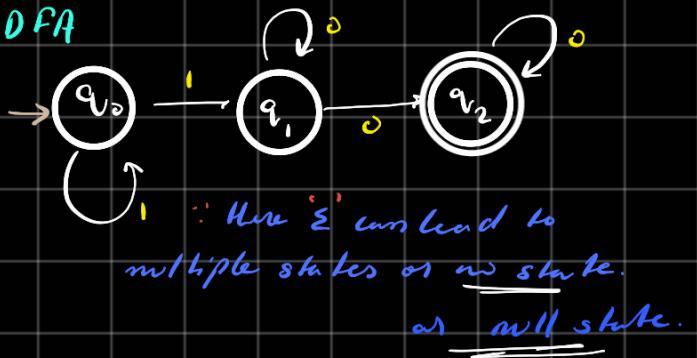
DFA



$\because \Sigma$ will lead from
one state to another.

$$eg \rightarrow q_0 \xrightarrow{1} q_1 \text{ & } q_0 \xrightarrow{0} q_0$$

N DFA



$$eg \rightarrow q_0 \xrightarrow{1} q_1 \text{ & } q_0 \xrightarrow{0} q_0$$

Compiler Bootstrapping

The process of writing a compiler in the source programming language that it
intends to compile.

This type of technique is known as "self-hosting compiler".

Lexical Analyser

- Regular Language (Natural language)

- Staching of the code.
- Breaks the source code into tokens, pattern, lexeme.

— Tokens

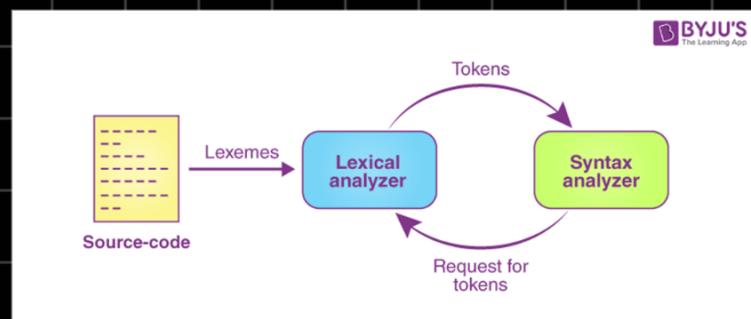
smallest individual unit in source code.

— Patterns

Description used by tokens

— Lexeme

Sequence of characters in the source code.



Syntax Analyzer

— Context free grammar

$$(N^*)^+ \rightarrow 1, +\infty \text{, can't be null i.e., } 1, 2, \dots$$
$$(N^*)^* \rightarrow 0, +\infty \text{, can be null i.e., } 0, 1, 2 \dots$$

Syntax Analyzer →

- Creates syntactic structure of the given source programs
- Syntactic structure is a parse tree.

Syntax of a program is described by a context-free grammar (CFG)

we will use BNF (Backus Naur form) notation in the description of CFG.

Provides a precise specification of program language.

- The syntax analyzer (parser) checks whether a given source program satisfies the rules implied by a context-free grammar.

Two types of parsers →

- Top-Down Parser
- Bottom-Up Parser

} scans the input from left to right

Efficient top-down, bottom-up parser can be

Scary and Parsers →

implemented only for sub-classes of context-free grammars.

Top down - Parsers

• LL for top-down parsing

• LR for bottom-up parsing

$$S = A + B \quad \text{---(1)}$$

$$S = id + id$$

$$= A + id \quad \text{left approach}$$

$$= A + B$$

→ is recursive in nature.

CFG consists of a finite set of grammar rules in a quadruple (N, T, P, S)

N → set of non-terminal symbols. / v → Variable also

T → set of terminals, N ∩ T = Null

P → set of rules / Production Rules (substitution rules)

S → start symbol

- Let any set of production rules in a CFG be
 - $X \rightarrow X+X \mid X^*X \mid X \mid a$
- The **leftmost derivation** for the string "a+a*a" may be –
- $X \rightarrow X+X \rightarrow a+X \rightarrow a + X^*X \rightarrow a+a*X \rightarrow a+a*a$
 - The **rightmost derivation** for the above string "a+a*a" may be –
 - $X \rightarrow X^*X \rightarrow X^*a \rightarrow X+X^*a \rightarrow X+a^*a \rightarrow a+a*a$

- Ambiguous Grammar →

$$\text{Merely ok arg1 arg2. } a = \frac{-b}{-} + \underline{c+d}$$

$$(0) \quad + \quad c \quad d$$

$$(1) \quad - \quad -b \quad -$$

$$(2) \quad \times \quad (0) \quad (1)$$

$$(3) \quad = \quad (2)$$

$$r_1 = -b$$

Interwinded

If a context free grammar G has more than one derivation tree for some string $w \in L(G)$.

Intermediate Code Generation →

During the translation of a source program into the object code for target machine, a compiler may generate a middle-level language code known as intermediate text.

- It should be easy to produce and translate.
- It is a sort of universal assembly language.

- Quadruples
- Tuples
- Indirect tuples

$$a = b + c * d$$



$$\pi_1 = c * d$$

$$\pi_2 = b + \pi_1$$

$$a = \pi_2$$

Op	arg1	arg2	result
*	c	d	r1
+	b	r1	r2
+	r2		a

Example: $a := -b * c + d$

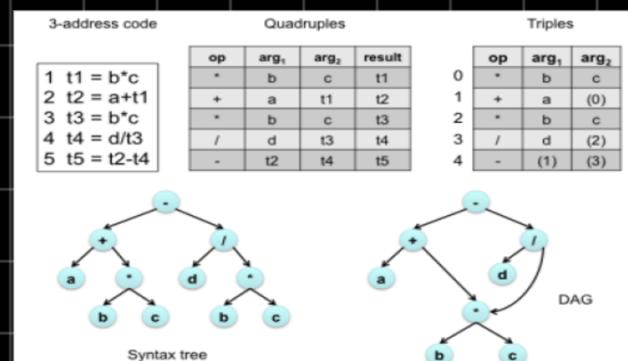
$t_1 := -b$ $t_2 := c + d$ $t_3 := t_1 * t_2$ $a := t_3$

Three address code is as follows:

	Operator	Source 1	Source 2
(0)	uminus	b	-
(1)	+	c	d
(2)	*	(0)	(1)
(3)	:	(2)	-

• Example: The three-address code for $a+b*c-d/(b*c)$ is below

- $t1 = b*c$
- $t2 = a+t1$
- $t3 = b*c$
- $t4 = d/t3$
- $t5 = t2-t4$



Code Optimization Techniques

1) Machine dependent optimization

- After the generation of target code and when the target code is transformed according to machine architecture.
- uses CPU registers and may have absolute memory location.

2) Machine independent optimization

- After the compiler takes intermediate code and transforms it such that it does not
- uses CPU registers and absolute memory location
- relative

3) Induction analysis

4) Loop Optimization

5) Strength reduction

6) Deadlock Elimination

7) Laptal - Deadlock

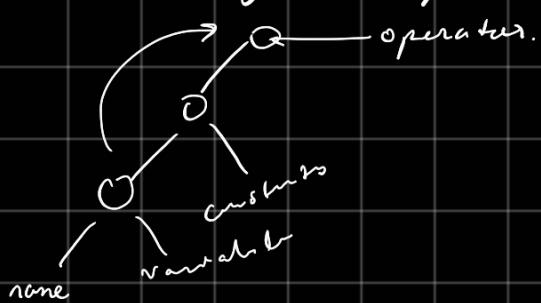
Peephole →

reductions in source code.

Code generator →

1. Target language
2. Selection of Instructions
3. QR \overbrace{w}^r
4. Registers allocation
5. ordering of instructions

DAG (Directed Acyclic Graph)



Descriptor →

The code generator has to keep the track record of register and address.

Register descriptor →

To tell code generators about the register

Address descriptor →

To keep the track of values of identifiers address location.

getReg :- check register and
functions values

LEX (Lexical Analyser Tool)

YACC (Yet Another Code Cook)

Backus Naur Form

$E \rightarrow id$

$x + y * z$ shift

$E \rightarrow E * E$

$x + y * z$ reduce

$E \rightarrow E + E$

$E + y * z$ shift

$E + y . * z$ shift

$E + y . * z$ Reduce

$E + E . * z$ shift

$E + E * z$ shift

$E + E * z$ Reduce

$E + E * E .$ Reduce (Emit *)

$E + E .$ Reduce (Emit +)

$E .$ accept

Not doing $E + E \rightarrow E$ because
'*' has higher precedence
than '+'

Recursive Descent Parsing \rightarrow (Top-Down)

- Input is read from left to right

.

$LL(k)$ \leftarrow number of lookahead parser

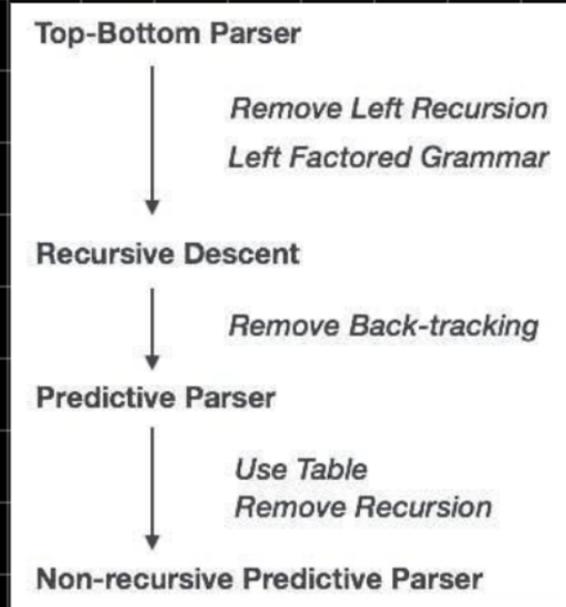
Predictive Parser \rightarrow

Top-down

$LL(k)$

left to right ↗ ↘ *k lookahead symbol.*

left most derivation



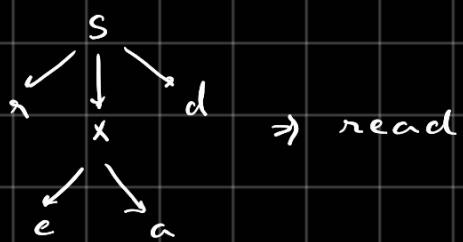
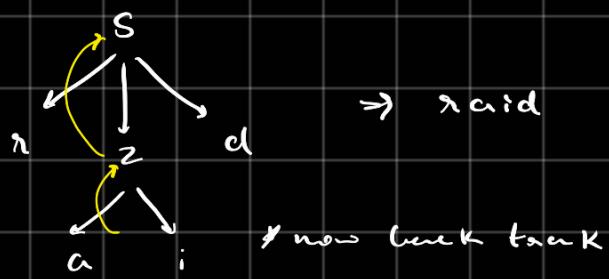
Backtracking \rightarrow Top down

$$S \rightarrow \alpha X d \mid \alpha Z d$$

$$X \rightarrow \alpha a \mid \epsilon a$$

$$Z \rightarrow \alpha i$$

$$S \rightarrow \text{read}$$



Unit - 3 → (Loaders and Linkers)

Function's for Computer Program Execution →

- Allocation
- Linking
- Relocation
- Loading

- loaders →
- Compile and relocates
 - General loader scheme
 - Absolute Loader

loaders →

Loaders are utility programs responsible for allocation, relocation, linking and loading.

- Allocation →

allocating the space for programs in memory, by calculating the size of programs

- Relocation →

Program in secondary memory having relocatable address goes as process in main memory with absolute memory, this process is called relocation.

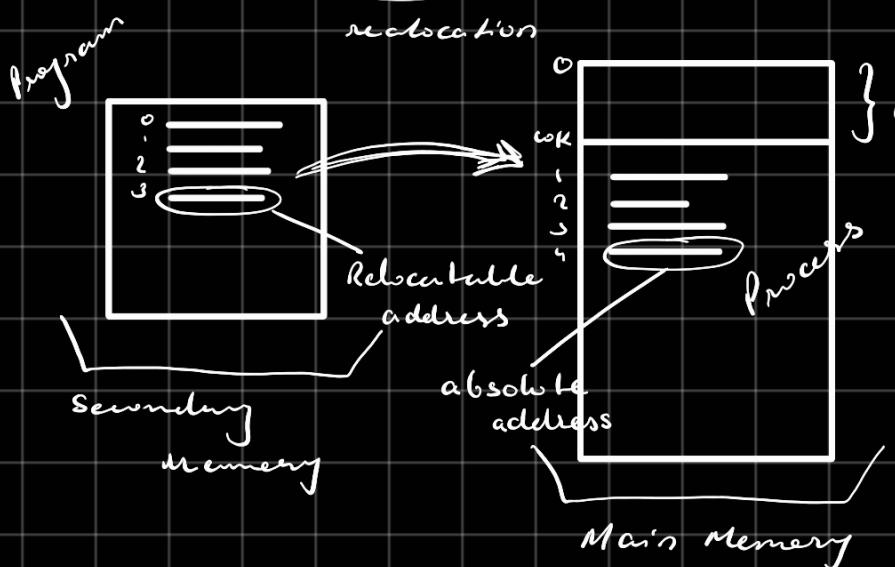
in main memory

in main memory

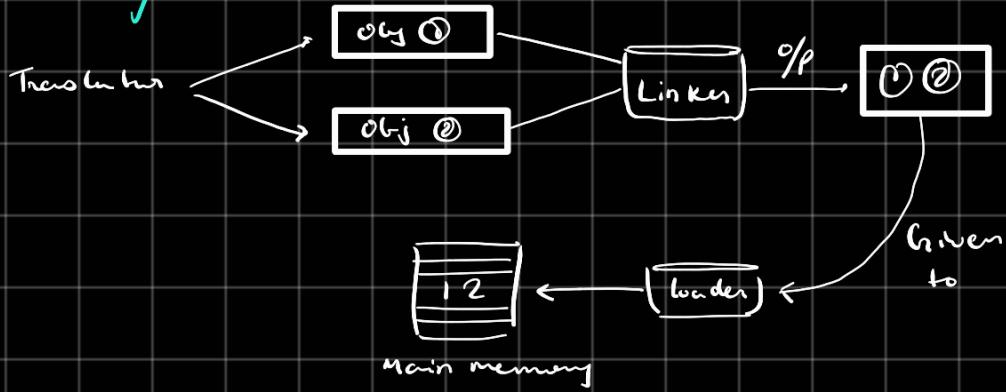
$n - 2000$

$n - 6000$

← can be different

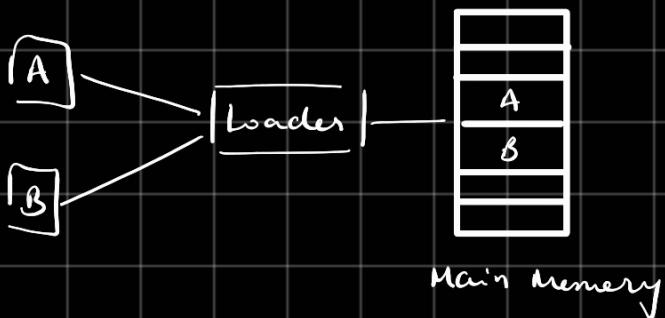


• Linking →



Linker links a number of files to merge and make a single program.

• Loader →



Loader picks the translated file from secondary and load it in main memory for execution.

Loaders Schemes →

1. Compile and Go Loader
2. General Loader Scheme
3. Absolute Loader

- Compile and Go Loader →

The instruction is read line by line, its machine code is obtained and it is directly put in the main memory.

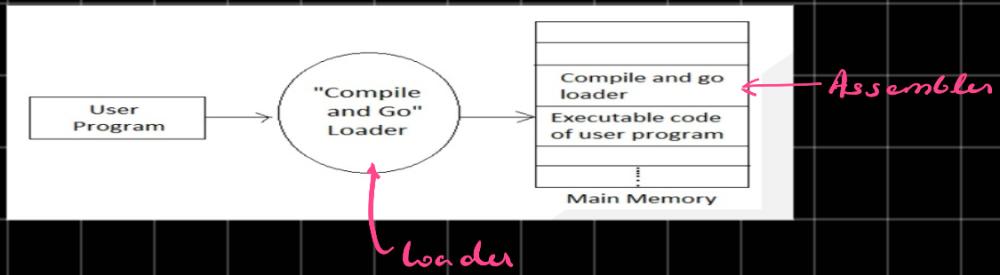
- Assembler runs in one part of the memory

- Assembled machine instructions and data are directly put into assigned memory locations.

Advantages →

- Simple to implement.

Because assembler is placed at one part of the memory and loader simply loads assembled machine instructions into the memory.



Disadvantage →

- Assembler occupies space in memory.
- No obj is created
- Cannot handle multiple programs in multiple languages.



- General Loader Scheme →

The source program is converted to object programs by assembler

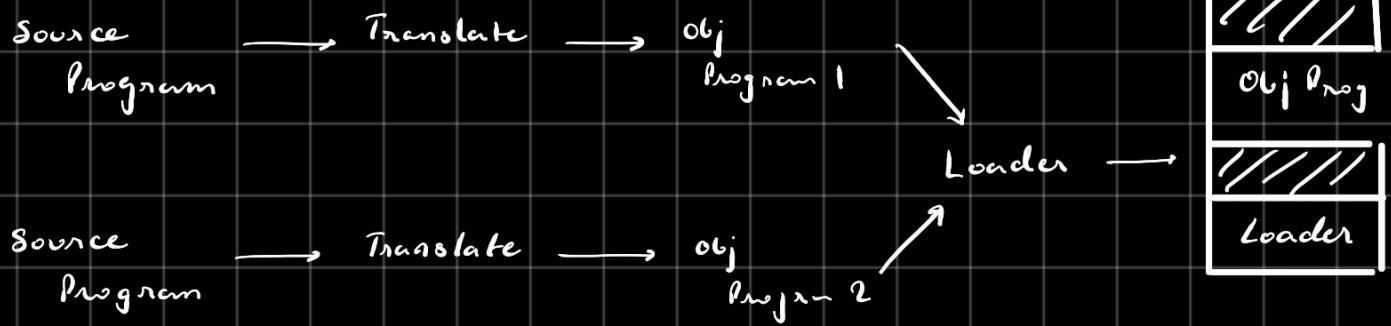
- Loader occupies some portion of main memory.
- Loader accepts obj and puts machine instruction and data at assigned memory.

Advantages →

- Smaller than Assembler
- More memory is available to the user.

Disadvantages →

- Some portion of memory is occupied by the loader.



- Absolute Loader

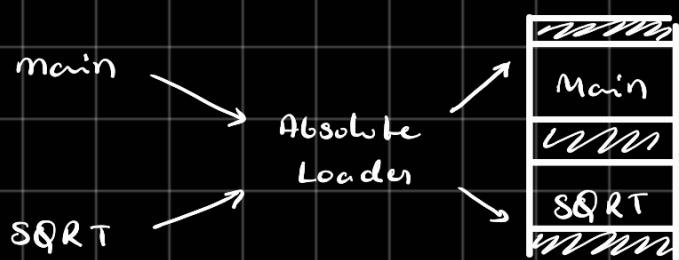
- Relocated object files are created.
- Accepts these files and place them at specified location.
- No reallocation.
- Address interdependent → with $8M$ -

Advantages —

- Simple to implement
- Programmer has to specify the address to assembler.
- Process of execution.

Disadvantage —

- It is necessary for the programmer to know the memory management.



- 1) Allocation → program / assembler
- 2) Linking → program / assembler
- 3) Resolution → assembler
- 4) Loading → loader

- Relocating loader

- Replacing symbols or names with actual usable addresses.
- Like, bwd, loading and allocation list to be done implicitly and manually by the programmer.

main function

SQV ← subroutine.

Editor →

- For performing functions on text file.
- Functions such as →
 - copy
 - paste
 - replacing
 - deleting
 - saving

Need and purpose →

- For editing document
- Transferring of data

Types of Editor →

- Line editor →
 - One line at a time.
- Stream editor →
 - Can write a paragraph.
- Screen editor →
 - User can interact visually with the help of mouse pointer. eg:- Notepad
- Word Processor →
 - Allowed the insertion of image, files, video, font style
- Structure Editor →
 - For writing and editing of code.
eg:- Netbeans IDE

- Full screen Editors →

- Is a full size text editor.
- Only writing screen can be seen.
- Word count a feature.

eg:- Focus writer

- Multiple windows Editor →

- Working on more than one file at a time..
- Cut paste from one file to another.

Booting →

Bootstraping →

loads kernel in main memory.

Dual Booting →

loads 2 operating system

warm Booting →

starting system

cold Booting →

computer restart, due to power cut.

Power on



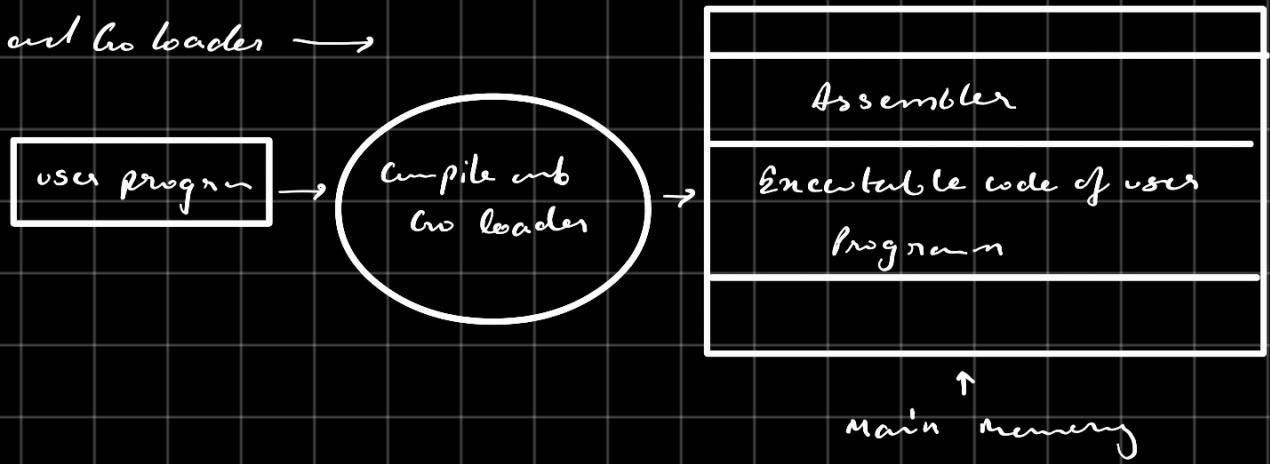
BIOS performs POST



Disk → RAM

loading of
OS.

Compile and Link loader →



General loader scheme →

Absolute Loader →

+ improved

Relocation Loader →

ex → Binary Symbolic subroutine (BSS)

Linker loader →

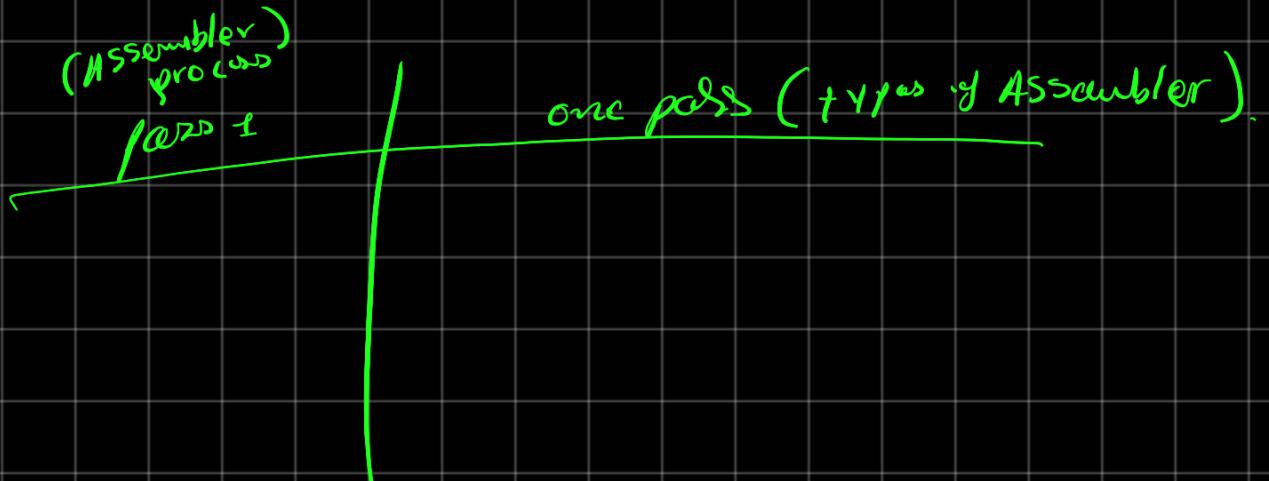
Data structures used → ESTAB (External symbol table)

PROGADDR (Program load address)

CSADDR (Control session address)

MS-DOS linker →

Difference between Linker and Loader →



Unit 1

Definition /short note / block diagram

Assembler parses - detailed description / flowchart / short note

Macro, Macro process - Passes, Macro assembler

Unit 2

compiler all phases complete description

Parsing types - all important - with implementation example

Design finite automata with regular expression

Code optimization

Unit - 3

Booleans and its types

Operating system architecture and functions

Loops types - all

Case studies - V, MS-DOS

JDBC
with MySQL
Driver or → Database
Callable.

RMQ

Rest

