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# Measurement and Analysis

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**ES 100**

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# Agenda

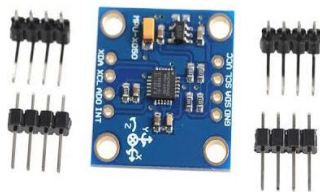
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- **How do we measure things?**
- **How should we analyze the data?**
- **Measurement and Analysis Demos:**
  - **Computer Vision**
  - **Accelerometers**
  - **EEG Data**



# Measuring? Why?

- We want to measure things because we need to quantify and verify goals and targets
- Example: my ES100 project (bicycle electronics charger)
  - Destroyed a cell phone...Why?
  - Didn't measure top speed of bike → didn't know max voltage
- How do we measure things?
  - Cameras → Computer Vision
  - Sensors → Accelerometers, GPS, etc.



3Axis Gyro+6Axis  
Accelerometer  
\$8USD



GPS/GLONASS  
Module  
\$35USD



GoPro Hero 4 (240fps)  
\$400USD



Smartphone  
\$0USD\* (if you own one)

→ Measurement is a fundamental step in QC and verification



# CV Measurement Demo: Chaotic Pendulum

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- What is a double pendulum?
- What do we want to know?
  - Position, angle, velocity, force
- How do we measure its motion?
  - Shaft encoders
  - Accelerometers
  - Computer vision
  - Anything else?
- What are some drawbacks?
  - Shaft encoders add bulk and weight
  - Accelerometers have very limited accuracy (you will see soon)
  - CV may require proper lighting, high framerate, may not be realtime

$$\dot{\theta}_1 = \frac{6}{m\ell^2} \frac{2p_{\theta_1} - 3 \cos(\theta_1 - \theta_2)p_{\theta_2}}{16 - 9 \cos^2(\theta_1 - \theta_2)}$$

and

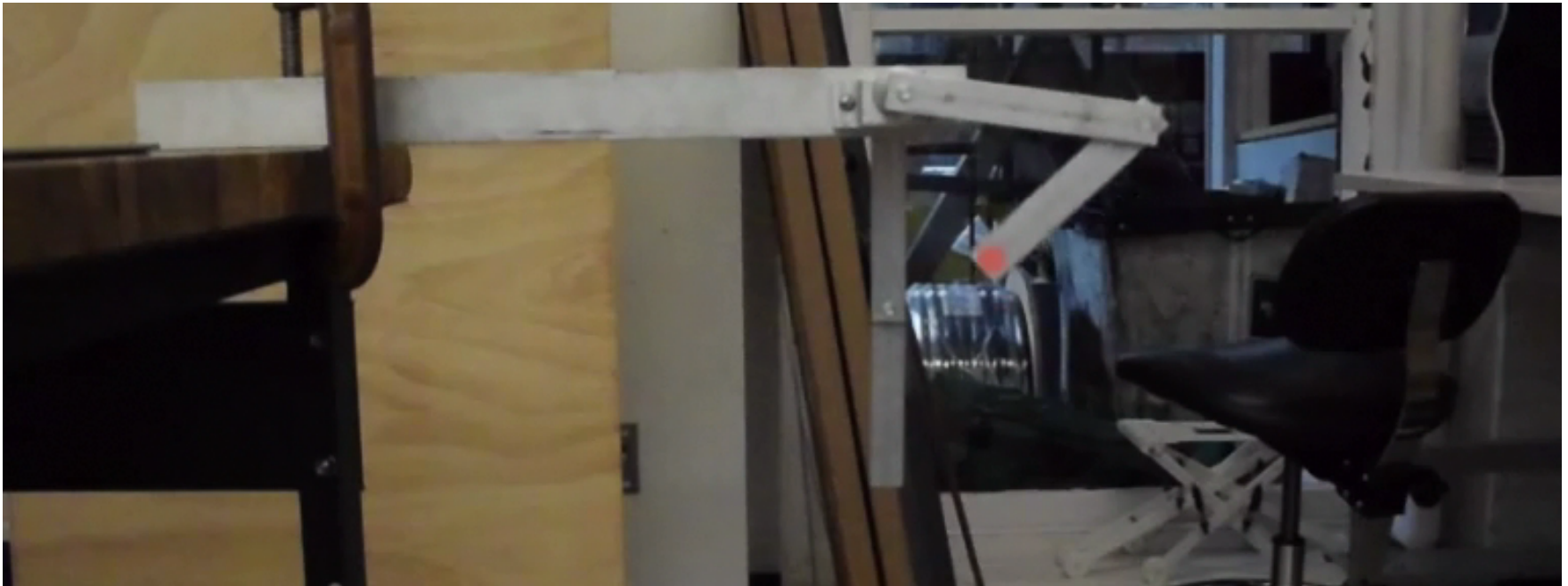
$$\dot{\theta}_2 = \frac{6}{m\ell^2} \frac{8p_{\theta_2} - 3 \cos(\theta_1 - \theta_2)p_{\theta_1}}{16 - 9 \cos^2(\theta_1 - \theta_2)}$$

→ Don't just go out and measure, make sure you have the right tool and setup



# CV Measurement Demo: Chaotic Pendulum

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# CV Measurement Demo: Chaotic Pendulum

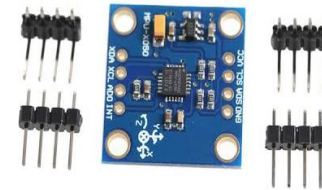
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# Accelerometer Measurement Demo

- Say we want to figure out the position of an object...what do we do?
- What sensor should we use?
  - GPS?
    - Good for  $\sim \pm 3\text{m}$
  - Computer vision?
    - Needs line of sight, have to have camera following it
  - Accelerometer
    - Need to do a double integration
  - Anything else?



3Axis Gyro+6Axis  
Accelerometer  
\$8USD

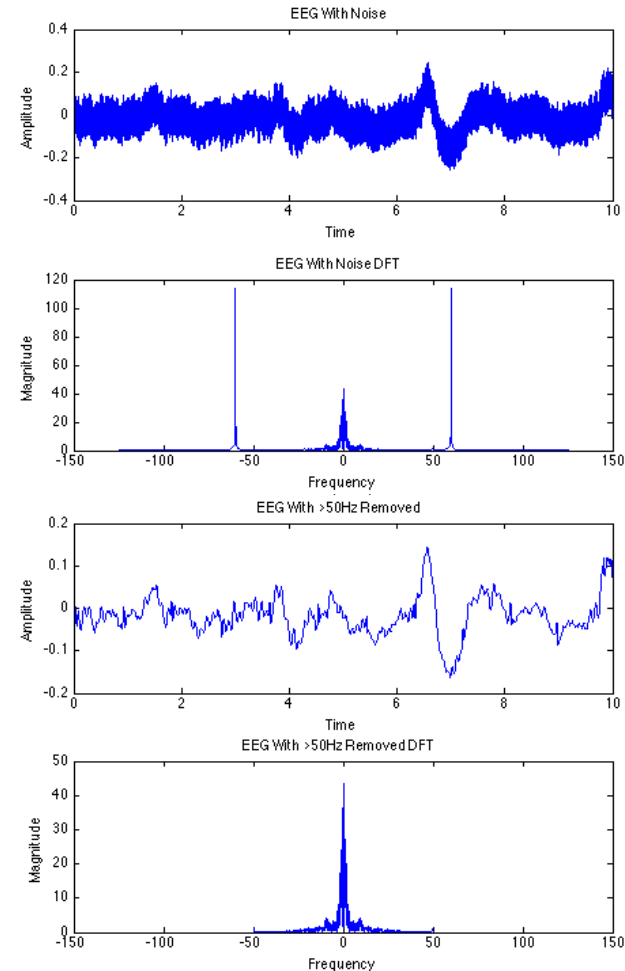
$$\hat{s} = \int \hat{v} \cdot dt = \iint \hat{a} \cdot dt^2$$

→ Use the tools you have at your disposal, but know their drawbacks



# We've measure the data...what now?

- **Analyze the data: find nuances, find interesting experiment errors**
- **Sanity check: does this look right?**
  - Compare to model? Does one exist?
- **Example:**
  - EEG Data: Why is it so fuzzy?
  - What's that at ~ 60Hz?
  - How do I get rid of it?
  - Clean up (filtering,smoothing)



→ Real life data is never cute...you need to analyze!