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# **How to Measure Things**

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**ES 100**

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# How to Measure Things

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- Every ES100 Project must have a [MEASUREMENT] component
- Quantitative measure of performance and/or functionality
  - Speed
  - Strength
  - Weight
  - Efficiency
  - Detection Sensitivity and Selectivity
  - Others?
- Verification/Confirmation of your [DEFINE] [DESIGN] & [BUILD] with quantitative [ANALYSIS]
- Complete demonstration of your Engineering Skills and Knowledge



# Limits of Physical Measurements

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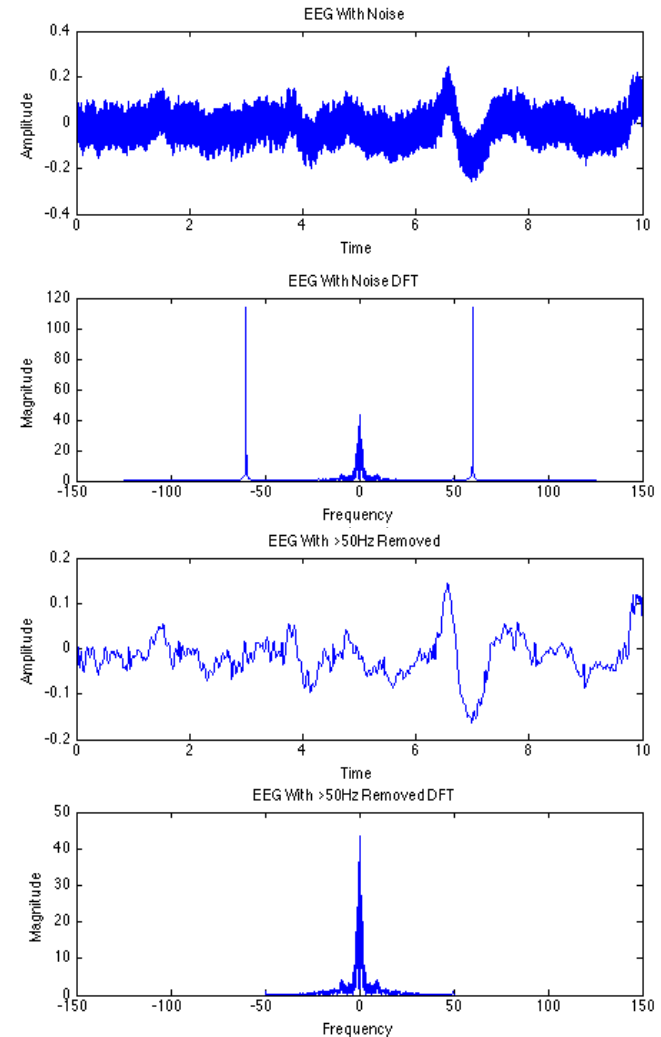
- To **MEASURE** something physical, you usually need a **SENSOR/ TRANSDUCER** to **CONVERT** that something into a **SIGNAL** which can be more easily measured
  - Distance can be directly measured with a tape measure
  - Force can be measured by using a strain gauge that converts force into voltage
  - Speed can be measured by measuring the elapsed time it takes something to traverse a known distance
- All physical measurements have limits. You need to understand and describe and analyze the fundamental limits of your measurements with respect to these factors

- **Noise**
- **Resolution**
- **Dynamic Range**
- **Reproducibility/Calibration**
- **Sampling Rate/Sample Size**



# Noise

- There are many types of noise
  - White/Gaussian
  - Shot Noise/Poisson
  - AC Line interference
- Noise is the undesired part of the signal and interfere or limits the measurement
- Noise can be reduced through filtering and careful experiment setup



**EXAMPLE: 60Hz AC line noise**



# Resolution

- Resolution is the smallest measurable value possible with an instrument
- For a caliper, it could be 1mm, it could be 10 $\mu$ m.
- For a pipette, it could be 1ml, 0.1ml, 0.01ml.





# Dynamic Range

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- Instruments also have limits on the largest possible measurable value
  - For example, values above some maximum are just saturated or beyond the capability of the instrument
- Dynamic Range is the ratio of maximum to minimum measurement

$$\text{Dynamic Range} = \frac{\text{maximum valid measurement}}{\text{minimum valid measurement}}$$



# Reproducibility/Calibration

- Reproducibility is how well the same measurement can be performed repeatedly with the same instrument and/or different instrument
- Calibration is matching the readings of an instrument to given standards



→ Making measurements without calibration will lead to erroneous results



# Sampling Rate / Sample Size

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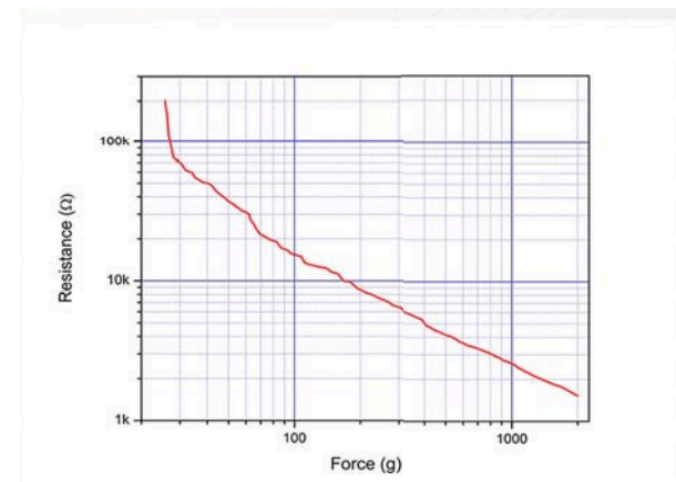
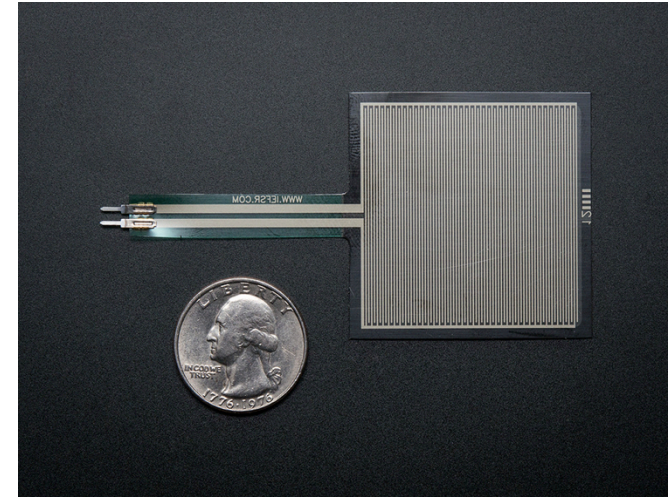
- **Measurements can vary in time. How often must measurements be repeated in time in order to *capture* the time-varying behavior?**
  - **SAMPLING RATE**
    - **Must be fast enough so that you don't miss any details**
    - **Bandlimited Signals → Nyquist Rate**
- **Every measurement is subject to error/noise. Multiple measurements of the same phenomenon can reduce possibility of error/noise (improve statistical significance).**
  - **SAMPLE SIZE**
    - **Must be large enough to demonstrate measurement is statistically significant and valid**





# Force Sensor Exercise

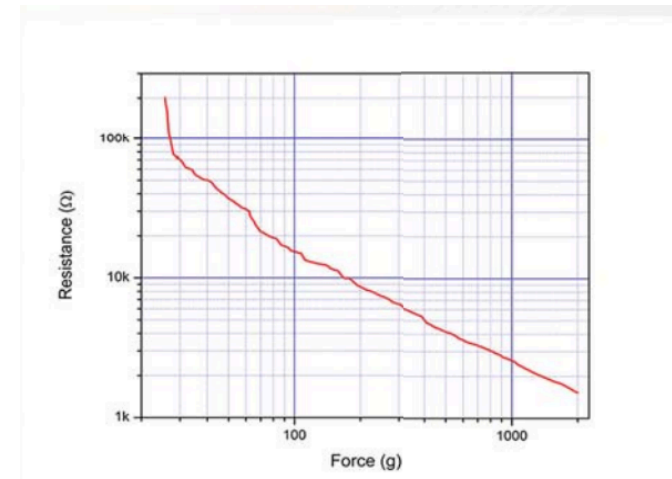
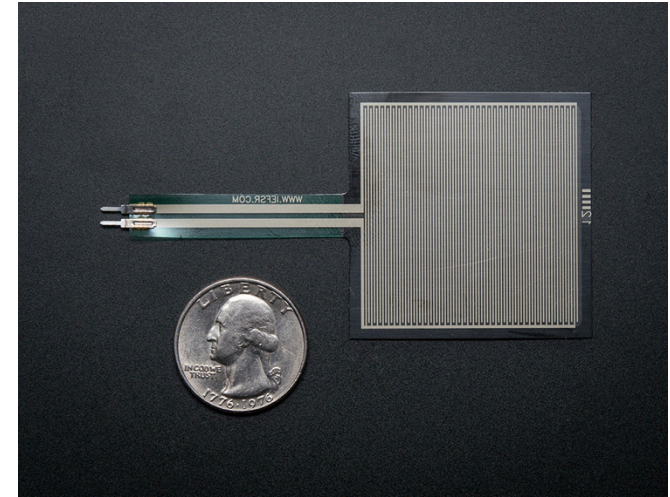
- **Force Sensor Resistors (FSRs)** are sensors that detect pressure, squeezing, and weight
- They use a polymer thick film that is embedded with metal along the traces.
- The FSR decreases in resistance as the metal particles come into contact when compressed
- These sensors do “bottom out”, so they do have limitations to their use
- They can exhibit a bit of hysteresis
- The data sheet can show us its specific characteristics.





# Force Sensor Exercise

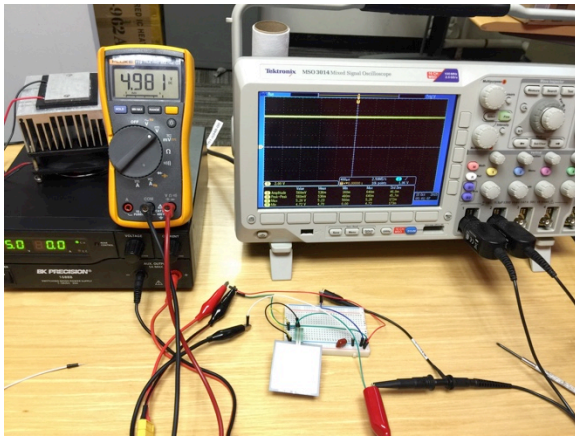
- We won't be measuring the resistance directly, we'll be using a voltage divider and a buffer amplifier to measure the voltage across the FSR.
- On the oscilloscope, we'll be monitoring the change in voltage as we add weight. Where's the fuzziness come from? **NOISE**
- Notice when I add low amounts of weight it doesn't change in voltage...high amounts of weight? What is this? **DYNAMIC RANGE**
- When I put the same weight back on, do I get the same **REPRODUCIBLE** signal?



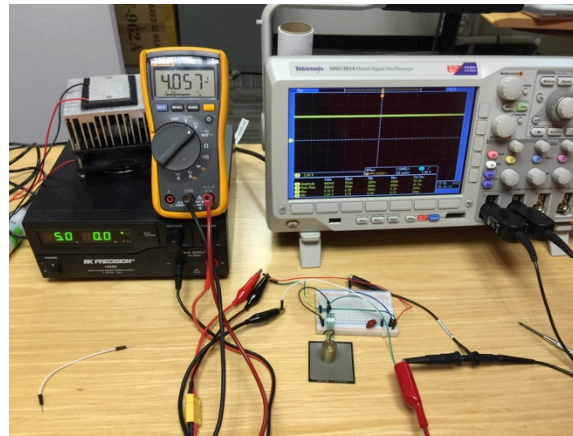




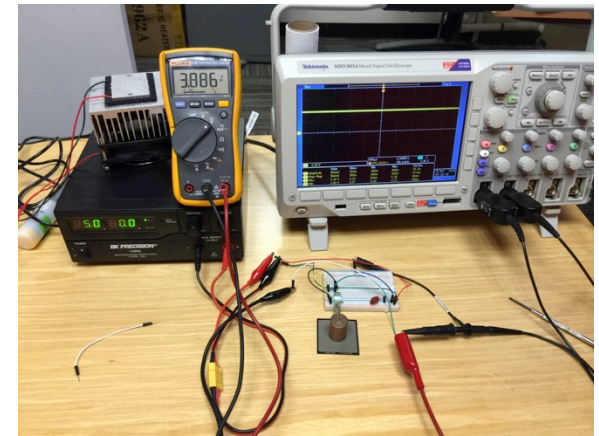
# Force Sensor Exercise (Measurement)



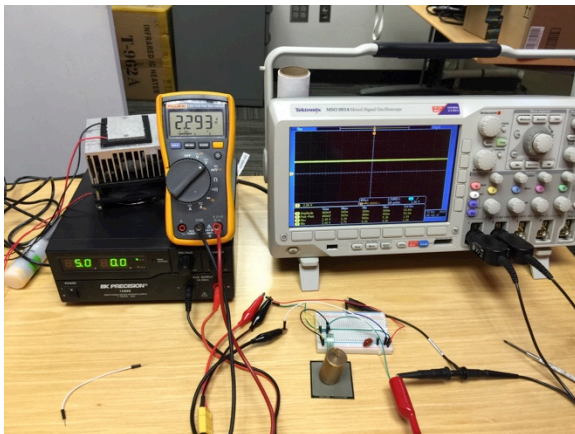
**0 g reading 4.98 V**



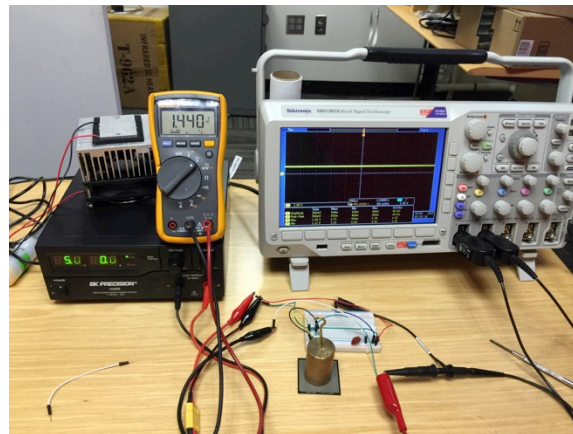
**20 g reading 4.06 V**



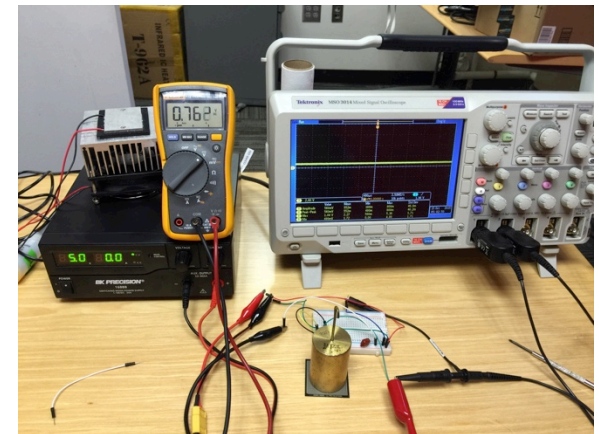
**50 g reading 3.89 V**



**100 g reading 2.29 V**



**200 g reading 1.44 V**

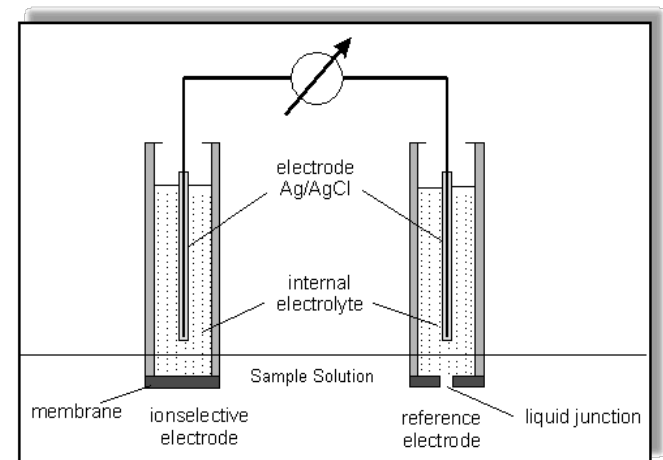


**500 g reading 0.76 V**



# Ion Selective Electrode Exercise

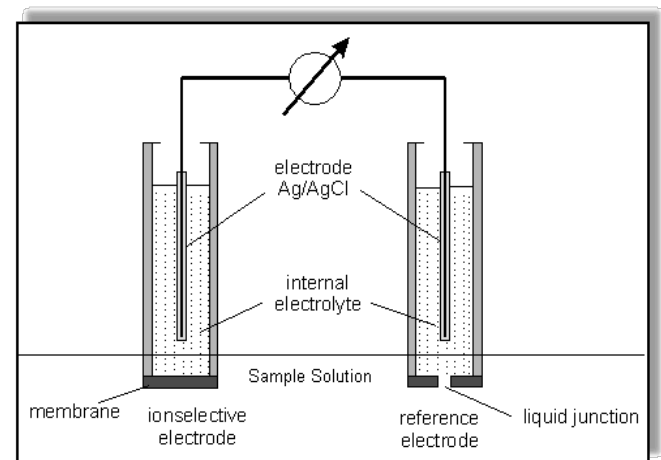
- An Ion Selective Electrode (ISE) is a membrane Electrode that responds selectively to ions
- Transducer converts the activity of a specific ion dissolved in a solution into an electrical potential, which can be measured by a voltmeter or pH meter
- Before making a measurement, the electrode needs to be rinsed off with DI water and calibrated against a known concentration sample
- After each measurement, the electrode needs to be rinsed off with DI water again in order to prevent cross contamination





# Ion Selective Electrode Exercise

- For this exercise, the electrode had been previously **CALIBRATED** against a known sample.
- Before taking a measurement, I must clean off the electrode with DI water (to clean off any contaminants)
- After taking a measurement, I need to clean it off again to ensure the measurement is **REPRODUCEABLE**
- In this case, where can **NOISE** come from?
- What is my **RESOLUTION**? What is my **DYNAMIC RANGE**? For a measurement to be valid, what will my **SAMPLE SIZE** need to be?



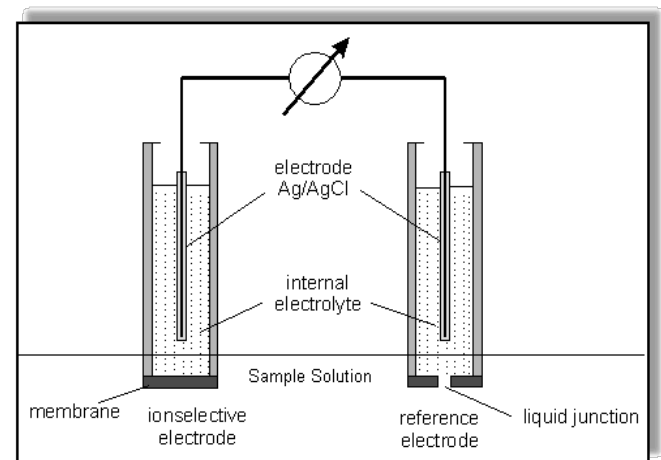


# Ion Selective Electrode Exercise (Calibration and Measurement)

- Below is a link to the specific sensor we will be using:

<http://www.vernier.com/products/sensors/ion-selective-electrodes/cl-bta/>

- In the above link, there is a video that demonstrates how to calibrate and measure using a Vernier probe.





# CV Measurement Exercise : Chaotic Pendulum

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- What is a double pendulum?
- What do we want to know?
  - Position, angle, velocity, force
- How do we measure its motion?
  - Shaft encoders
  - Accelerometers
  - Computer vision
  - Anything else?
- What are some drawbacks?
  - Shaft encoders add bulk and weight
  - Accelerometers have very limited accuracy (you will see soon)
  - CV may require proper lighting, high framerate, may not be realtime

$$\dot{\theta}_1 = \frac{6}{m\ell^2} \frac{2p_{\theta_1} - 3 \cos(\theta_1 - \theta_2)p_{\theta_2}}{16 - 9 \cos^2(\theta_1 - \theta_2)}$$

and

$$\dot{\theta}_2 = \frac{6}{m\ell^2} \frac{8p_{\theta_2} - 3 \cos(\theta_1 - \theta_2)p_{\theta_1}}{16 - 9 \cos^2(\theta_1 - \theta_2)}$$





# CV Measurement Exercise : Chaotic Pendulum

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- So you've watched the two videos:
- Let's go talk about Noise, Resolution, and Sampling Rate (though for every measurement you make, you will need to include details on ALL characteristics)
- How does the NOISE change from the Nikon to the HSC?
- How does the RESOLUTION change from the Nikon to the HSC?
- How does the SAMPLING RATE change from the Nikon to the HSC?

$$\dot{\theta}_1 = \frac{6}{m\ell^2} \frac{2p_{\theta_1} - 3 \cos(\theta_1 - \theta_2)p_{\theta_2}}{16 - 9 \cos^2(\theta_1 - \theta_2)}$$

and

$$\dot{\theta}_2 = \frac{6}{m\ell^2} \frac{8p_{\theta_2} - 3 \cos(\theta_1 - \theta_2)p_{\theta_1}}{16 - 9 \cos^2(\theta_1 - \theta_2)}$$