

# set1

October 16, 2023

```
[ ]: import numpy as np
import matplotlib.pyplot as plt
from numba import njit
```

## 1 Q1)

```
[ ]: @njit
def RD(N, L):
    """Random Deposition

    Args:
        N (int): nnumber of particle
        L (int): size of the system

    Returns:
        1d_array: roughness
    """
    h = np.zeros(L)
    h_mean = np.empty(N)
    w = np.empty(N)

    for t in range(N):
        i = np.random.randint(L)
        h[i] += 1
        h_mean[t] = np.mean(h)
        w[t] = np.sqrt(np.sum((h - h_mean[t])**2) / L)

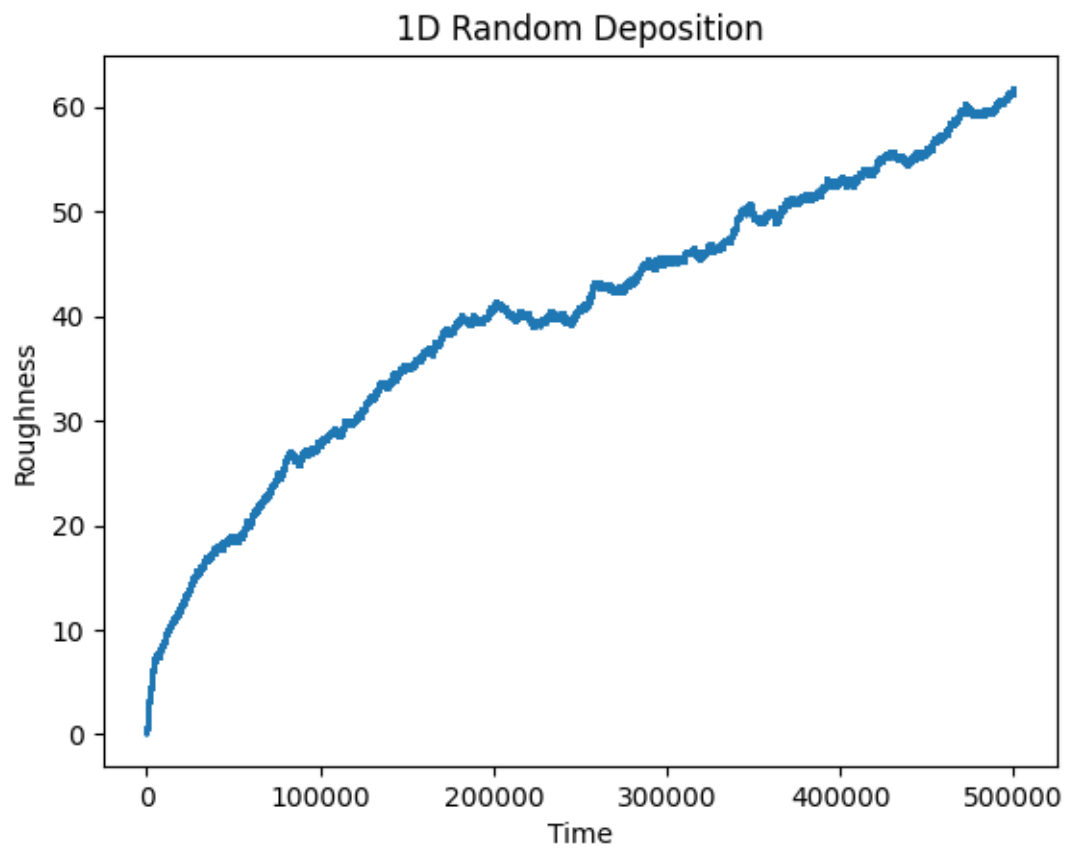
    return w
```

```
[ ]: N = 500000
L = 128
w = RD(N, L)

plt.scatter(range(N), w, marker='.', s=1)

plt.xlabel("Time")
plt.ylabel("Roughness")
```

```
plt.title('1D Random Deposition')
plt.show()
```



## 2 Q2)

```
[ ]: def RDR(N, L):
    """2D Random depostion with relaxation

    Args:
        N (int): nnumber of particle
        L (int): size of the system

    Returns:
        1d_array: roughness
    """
    h = np.zeros((L, L))
    h_mean = np.empty(N)
    w = np.empty(N)
```

```

for t in range(N):
    i = np.random.randint(L)
    j = np.random.randint(L)

    neighbors = np.array([h[(i - 1) % L][j], h[(i + 1) % L][j], h[i][(j -
↪1) % L], h[i][(j + 1) % L], h[i][j]])
    arg = np.where(neighbors == neighbors.min())[0]
    arg = np.random.choice(arg,1)

    if arg == 0:
        h[(i - 1) % L][j] += 1
    elif arg == 1:
        h[(i + 1) % L][j] += 1
    elif arg == 2:
        h[i][(j - 1) % L] += 1
    elif arg == 3:
        h[i][(j + 1) % L] += 1
    else:
        h[i][j] += 1

    h_mean[t] = np.mean(h)
    w[t] = np.sqrt(np.sum((h - h_mean[t])**2) / (L**2))

return w

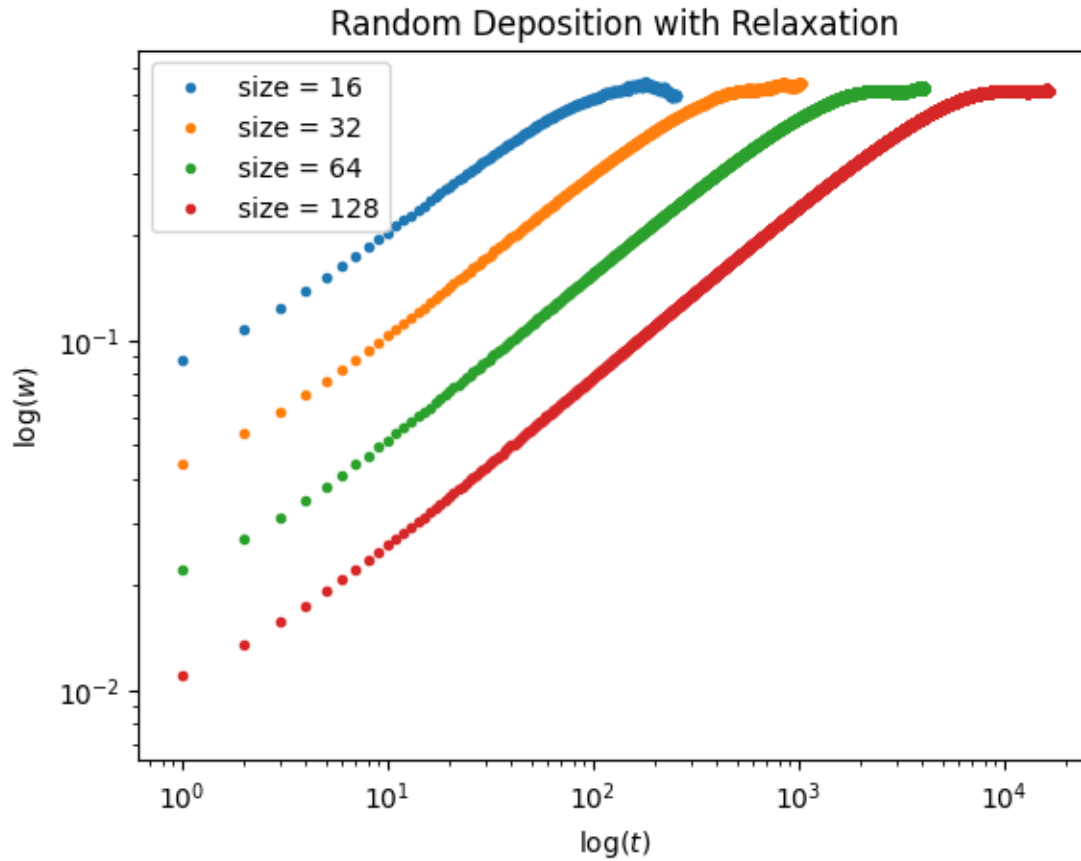
```

```

[ ]: for L in [16, 32, 64, 128]:
    w = RDR(L**2, L)
    plt.scatter(range(L**2), w, marker='.', label=f"size = {L}")

plt.loglog()
plt.xlabel(r"$\log(t)$")
plt.ylabel(r"$\log(w)$")
plt.title('Random Deposition with Relaxation')
plt.legend()
plt.show()

```



### 3 Q3)

```
[ ]: @njit
def BD(N, L):
    """2D Ballistic Deposition (KPZ)

    Args:
        N (int): nnumber of particle
        L (int): size of the system

    Returns:
        1d_array: roughness
    """
    h = np.zeros((L, L))
    h_mean = np.empty(N)
    w = np.empty(N)

    for t in range(N):
```

```

        i = np.random.randint(L)
        j = np.random.randint(L)
        h[i][j] = max([h[(i - 1) % L][j], h[(i + 1) % L][j], h[i][(j - 1) % L],
        ↪ h[i][(j + 1) % L], h[i][j] + 1])
        h_mean[t] = np.mean(h)
        w[t] = np.sqrt(np.sum((h - h_mean[t])**2)/(L**2))

    return w

```

```

[ ]: for L in [16, 32, 64, 128]:
    N = 100000
    w = BD(N, L)
    plt.scatter(range(N), w, marker='.', label=f"size = {L}")

plt.loglog()
plt.xlabel(r"$\log(t)$")
plt.ylabel(r"$\log(w)$")
plt.title('Ballistic Deposition (KPZ)')
plt.legend()
plt.show()

```

