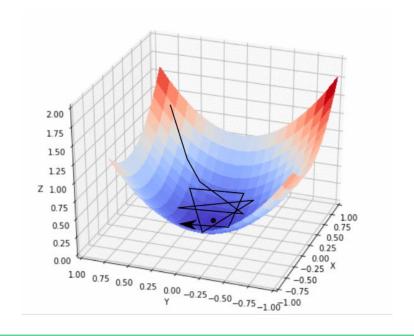
## Parallel Stochastic Gradient Descent

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CSCE 435 - Parallel Computing

## What is gradient descent?

Iterative numerical optimization process conducted by moving in the opposite direction of the gradient (direction of greatest change) until convergence



## Sequential Algorithm

 Randomly initialize weights in linear equation

$$\hat{y} = w_1 x_1 + w_2 x_2 + w_n x_n + b$$

 Iteratively update weights in the opposite direction of the gradient for each sample

#### **Algorithm 1:** Gradient Descent

Result: Write here the result Initialize at step t = 0 to  $\mathbf{w}(0)$ ; for t = 0, 1, 2, ... do Compute the gradient;  $\mathbf{g}_t = \nabla E_{in}(\mathbf{w}(t))$ ;  $\mathbf{v}_t = -\mathbf{g}_t$ ;  $\mathbf{w}(t+1) = \mathbf{w}(t) + \eta \mathbf{v}_t$ ;

 $w(t+1) = w(t) + \eta * sample loss gradient$ 

end

## Parallel Algorithm

 Randomly initialize weights in linear equation

$$\hat{y} = w_1 x_1 + w_2 x_2 + w_n x_n + b$$

 Iteratively update weights in the opposite direction of the gradient for the entire epoch

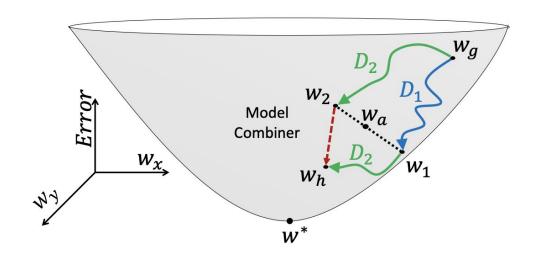
#### **Algorithm 2:** Parallel Gradient Descent

```
Result: Write here the result
Initialize at step t = 0 to \mathbf{w}(0);
for t = 0, 1, 2, ... do
     Each t here, unlike in sequential, has seen all samples;
     \mathbf{v_t} = 0;
     for s = 0, 1, 2, ... do
           Compute the gradient for all samples in parallel;
          \mathbf{g}_{ts} = \nabla E_{in}(\mathbf{w}(t));
         \mathbf{v}_{ts} = -\mathbf{g}_t;
          \mathbf{v}_t = \mathbf{v}_t + \mathbf{v}_{ts};
     end
     \mathbf{w}(t+1) = \mathbf{w}(t) + \eta \frac{\mathbf{v}_t}{|S|};
end
```

$$w(t+1) = w(t) + \eta * (grad 1 + grad 2 + grad 3 + ...)$$

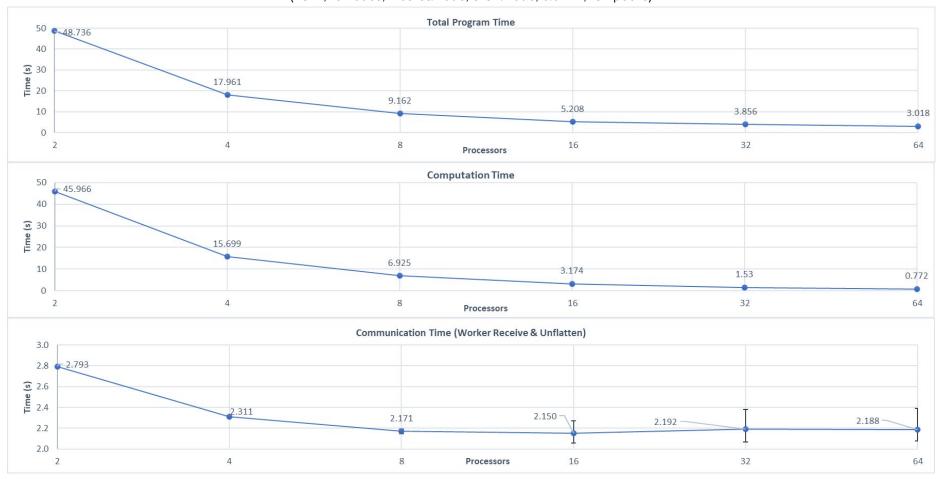
## Parallel Algorithm

- Introduces permutation invariance since there is no randomness to the sequence used to update the weights
  - Can stabilize training process and possibly provide a speedup to convergence



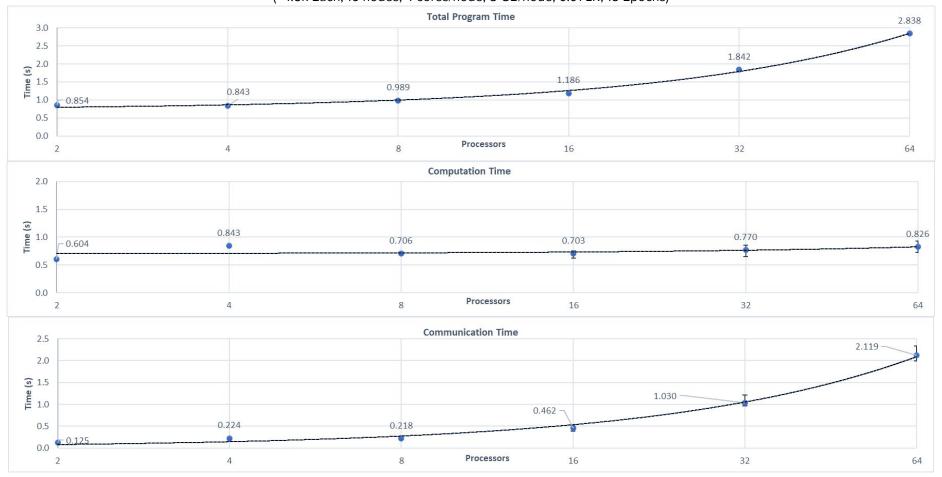
#### Message Passing Interface (MPI): Results (Strong Scaling)

(284k, 16 nodes, 4 cores/node, 8 GB/node, 0.01 LR, 15 Epochs)



#### Message Passing Interface (MPI): Results (Weak Scaling)

(~4.5k Each, 16 nodes, 4 cores/node, 8 GB/node, 0.01 LR, 15 Epochs)

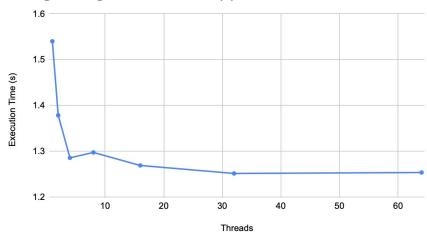


## Message Passing Interface (MPI): Analysis & Findings

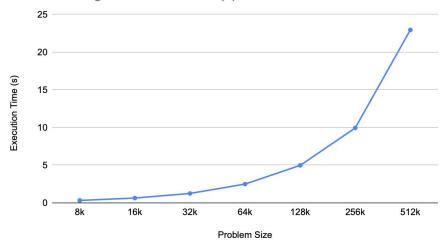
- Based on the empirical results of the experimentation with the MPI implementation, the parallel implementation of Stochastic Gradient Descent scaled with benefit up to 64 processes.
- While each increase in process count resulted in a reduction in total time, the overhead of interprocess communication yielded diminishing returns starting at 8 processes.

### **CUDA**: Results





#### Weak Scaling: Execution Time (s) vs. Problem Size



## CUDA: Analysis & Findings

- Using a one-layer logistic regression mitigates the benefit from parallelism since there are not as many learnable parameters.
- With a very large dataset, different batching techniques may affect model performance. This may be an added benefit of using a GPU over a CPU.
- CUDA memory management for 2D arrays is quite difficult; therefore, we used the common practice of allocating large 1D arrays with i\*N + j indexing.

# Thank you!