GPA: 3.74

<u>yashas.salankimatt@gmail.com</u>

in linkedin.com/in/yashas-s

Education

2019-2022

Texas A&M University- College Station

2022-2024

Bachelor of Science, Computer Engineering (Magna Cum Laude) Master of Science, Computer Science, Specialization in Robotics

Work Experience

Founder and CEO, Proprio Robotics

May 2022 - Current

- o Designed and built a robot arm with the same capabilities as robot arms that are 10x the cost
- o Developing an API to allow coders to develop complex robotics solutions without a robotics background
- o Raised \$110k+ in pre-seed funding (propriorobotics.xyz)

Robotics Research Intern at Carnegie Mellon University, Biorobotics Lab

Jun 2022 - Aug 2022

- o Developed on a hardware in loop (HIL) simulation system for uncooperative satellite docking systems
- o Iterated on a bimanual test stand used to simulate spacecraft docking hardware for Northrop Grumman
- o Implemented impedance matching algorithms on the HIL test stand for space physics simulation
- $\circ \ \ \text{Improved the controllers, estimators, trajectory planning, and optimization systems for satellite docking}$

Software Engineer Intern at Troverlo

Jan 2022 - May 2022

- o Programmed software to automate sensor tags configuration for production environments
- o Developed methods to speed up sensor tag fabrication during prototype phases
- o Fabricated prototype sensor tags and running test suite for proper operation before field testing

Undergraduate Researcher with Dr. Robin Murphy

Aug 2021 - May 2022

- o Developed the next version of the Survivor Buddy robot for disaster relief, telepresence, telemedicine
- o Modeled, fabricated, and assembled the mechanical assembly for the inexpensive robot system
- o Designed and fabricated a custom PCB, wrote face tracking and pose matching code using OpenCV

Honors Undergraduate Research with Mr. Stavros Kalafatis

Aug 2021 - May 2022

- o Programmed model to update indoor maps with new data on changes to environments
- o Implementing the map revision system on a physical robot with LIDAR and an RGB-D camera
- o Validated and tested above system, compared to other implementations, and wrote a thesis on my work

Leadership

TAMUhack, Hardware and Logistics Director

Mar 2020 - May 2022

- o Recruiting sponsorships and maintaining sponsor relations for our hackathons
- o Organizing logistics including prizes, venue, food, live streaming, scheduling, etc.

Awards

July 2022

- Z Fellow (\$10,000 investment into my company and mentorship program)
- April 2022
- Texas A&M Undergraduate Research Scholar
- Mar 2021
- o RowdyHacks 2021 Best Hardware Hack Winner
- Feb 2020
- TAMUmake 2020 Hackathon 1st place & Accessibility Challenge Winner
- Sep 2019
- Kurt Giessler Youth Achievement Ambition Grant Recipient
- Jan 2019
- o Brockman Scholarship Recipient (Full ride and cost of attendance scholarship)

Projects

Creating a Custom 7-Axis Robot Arm

April 2022

- o Developed a 7-axis robot arm with a payload of 3kg, 800mm reach, and sub-mm repeatability for <\$750
- o Modeled and fabricated actuators, electrical system, firmware, sensor systems, and manipulator
- o Created ROS interface and simulated arm for rapid iteration and ML training in simulation

Teddy, automated scheduling/planning for students

Aug 2021

- o Developed a system to help students manage their work and classes by performing automated task planning, fitting around their existing calendars
- o Implemented using React, React Native, Firebase, GCal API, Bootstrap

Creating a Custom, Inexpensive, Heavy Duty CNC Router

Dec 2020

- o Designed and built a CNC router for \$500 with the specs of \$2K hobbyist machines
- o Wrote a custom C firmware branching off of GRBL for smart control of the machine

Skills

Software Engineering

- o C++, Javascript, Python, Java, HTML/CSS, Typescript, React.js, React Native, Tailwind, Firebase
- CE/MechE, Robotics

 o ROS, CAD Modeling, Finite Element Analysis, CNC Machining, Mapping and Localization Systems, TensorFlow, Microcontroller Design, Integrated and General Circuit Design