D.C. MATCHING ERRORS IN THE WILSON CURRENT SOURCE

Indexing term: Constant-current sources

A theoretical formula, accounting for parameter mismatch errors, and experimental measurements establish the necessity for using an additional transistor in the widely used Wilson current source if a direct-current transfer ratio centred on unity is to be achieved.

Introduction: The conventional Wilson current mirror finds wide application in the design of bipolar monolithic linear integrated circuits. A basic parameter of the Wilson configuration is the direct-current transfer ratio λ , which, in precision design work, is often required to have a value of unity with as small a tolerance as possible. The application of the recently discussed early-intercept voltage parameter facilitates the development of a practically useful formula, which is presented here, for estimating the nominal value of λ and the tolerance limits on it, arising from mismatches in the operating conditions and the respective d.c. parameters of the transistors used.

Theory: Fig. 1 shows a standard Wilson current source, comprising closely matched monolithic bipolar transistors T_1 , T_2 , T_3 , driven by an input current I_i and producing an output current I_0 . I_1 is assumed to be small enough to ensure low-level injection conditions in the transistors, but large enough to guarantee operation well above leakage-current levels. $\beta(\alpha)$ with the appropriate number subscript refers to the common-emitter (common-base) direct-current gain of the correspondingly numbered transistor.

The current ratio P is given by

In eqn. 1, the collector current differential $(\delta I)^1$, arising from differences in the respective parameters of T_1 , T_2 when they are operated at the same collector-base voltage, is conveniently expressed in terms of a base-emitter offset voltage of magnitude v_{os} .

By virtue of the logarithmic relationship between collector current and base-emitter voltage, and for the usual case $v_{os} \ll V_T$ (the thermal voltage $\simeq 25$ mV at 290 K), it is easily shown that

$$(\delta I)^1 \simeq \pm I(v_{os}/V_T) \qquad (2)$$

Although v_{os} is frequently attributed to emitter-area differences alone, such factors as basewidth differentials and unequal extrinsic base resistances do have a contributing effect, however secondary.

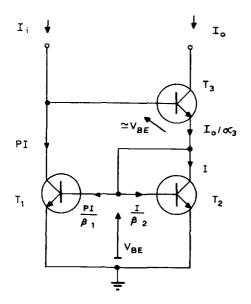


Fig. 1 Standard Wilson current source

 $(\delta I)^{11}$ is the collector-current differential that results from the collector-base voltage difference ($\simeq V_{BE}$) between T_1 and T_2 . It can be expressed in terms of the l.f. output resistance r_o of T_1 . Thus

$$(\delta l)^{11} = (V_{BE}/r_o) = l(V_{BE}/lr_o)$$
 (3)

Now the product Ir_o is independent of I, and, since $V_{BE} < 1 \text{ V}$, it will be sensibly equal in magnitude to the early-intercept voltage² $(V_t)_o$ of T at zero collector-base voltage. Using eqns. 2 and 3, eqn. 1 becomes

$$P = 1 \pm (v_{os}/V_T) + \{V_{BE}/|(V_I)_o|\} \qquad (4)$$

From Fig. 1, by current summation,

or

Eqn. 5a follows from eqn. 5 because $P \simeq 1$ and, by definition, $2/\bar{\beta} = 1/\beta_1 + 1/\beta_2$. Since, normally, β_1 and β_2 do not differ by more than about 10%, $\bar{\beta}$ can be identified as either the geometric or arithmetic mean of β_1 and β_2 .

Using Kirchoff's current law,

$$I_i + I_o = PI + (I_o/\alpha_3).$$
 (6)

Since $\beta_3 \gg 1$, $\alpha_3 \simeq 1 - 1/\beta_3$, eqn. 6 can be rewritten as

$$\{1 - 1/\beta_3\}\{I_i + I_o\} = \{1 - 1/\beta_3\}PI + I_o \quad . \tag{7}$$

Routine algebraic manipulation of eqn. 7, the use of the binominal expansion and appropriate engineering approximations commensurate with the order of magnitude of the terms involved finally yield

$$\lambda = I_o/I_i = 1 - \{V_{BE}/|(V_I)_o|\} \pm 2(\Delta \beta/\bar{\beta}^2) \pm (V_{os}/V_T)$$
 (8)

in which $\Delta \beta = |\beta_3 - \bar{\beta}|$.

The nominal value for λ is less than unity by an amount $V_{BE}/|(V_I)|_o$, which might well approach the magnitude of the tolerance on λ resulting from β and V_{BE} mismatches. Thus, if

$$V_{BE} = 0.7 \text{ V}, \quad [(V_I)_o] = 70 \text{ V}, \quad \beta = 100, \quad (\Delta \beta/\beta) = 0.05,$$

 $v_{os}=0.25\,\mathrm{mV}$, then $\lambda=0.99\pm0.011$. The nominal value can be made to approach unity more closely by the simple addition of the diode-strapped matched transistor T_4 in Fig. 2. This ensures that T_1 , T_2 operate at virtually the same V_{CB} , i.e. zero, and hence sensibly eliminates the V_{BE} term from eqn. 8. This 4-transistor current source has also been used, independently, by Schlotzhauer and Viswanathian, but the error in the nominal value of λ if T_4 is omitted has not previously, as far as the authors are aware, been quantified.

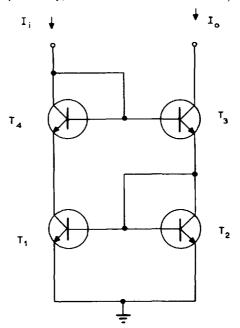


Fig. 2 Improved Wilson current source $T_1+T_2 = \text{mono MAT-01 AH (Precision Monolithics)}$ $T_1+T_4 = \text{mono MAT-01 AH}$

Results: To achieve a current transfer ratio λ close to unity and to demonstrate the benefit of adding an extra transistor to the usual Wilson scheme, the circuit of Fig. 2 was constructed from two selected pairs of matched monolithic transistors of the type indicated. Test results that summarise the comparative performance of the circuits of Figs. 1 and 2 over the current range $10 \,\mu\text{A} < I_1 < 1 \,\text{mA}$ are given in Table 1.

In columns (i) and (ii), λ_1 , λ_2 refer, respectively, to the current transfer ratio of Figs. 1 and 2. λ_1 was actually obtained from measurements on the circuit of Fig. 2 with the base-emitter junction of T₄ short circuited. The values given for λ_1 and λ_2 , to the accuracy stated, remain unchanged for an output voltage variation of 2 to 10 V. The performance of the improved Wilson source facilitated the design of a precision current-splitting circuit which has been described, briefly, elsewhere.4

Discussion and conclusions: Measurements made on the devices used gave $\bar{\beta} \simeq 370$ and $\Delta \beta = 50$ and the manufacturer's data sheet quotes $v_{os} = 0.1 \,\mathrm{mV}$ (maximum) at $I_c = 10 \,\mu\text{A}$. If offset voltage and β mismatch were the sole source of error in the Wilson current source, it would be expected that $\lambda = 1 \pm 0.005$.

Column (i) of Table 1 shows that λ_1 is clearly outside these

Table 1

	(i)	(ii)	(iii)
I_i	λ_1	λ ₂	$V_{BE}/ (V_I)_o $
//A 10	0.984	0·998	0-011
100	0.986	0.998	0.012
1000	0.983	0.996	0.013

tolerance limits, and column (ii) shows that λ_2 is within them. In this case, the major source of error in the departure of λ from unity is clearly the collector-base differential of T1, T2 in the circuit of Fig. 1. Inspection of Table 1 shows that the relationship $\lambda_2 - \lambda_1 = V_{BE}/|(V_I)_o|$ is sensibly valid.

In conclusion, the magnitude of the error obtained with closely matched devices justifies the approximations made in the derivation and use of the formula for the current-mirror transfer ratio λ.

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DOUBLE-ERROR-CORRECTING BCH CODES FOR SOURCE ENCODING

Indexing terms: Encoding, Error-correction codes

It is known that error-correcting codes can be used to encode sources in the sense of data compression. We derive an expression for the average distortion per bit for double-error-correcting narrow-sense primitive BCH codes.

With reference to an equiprobable discrete memoryless source whose output is a sequence over GF(2), let us consider an (n, k) binary group code V with minimum distance d = 2t + 1. One of the ways in which V can be used to compress the output of the source is as follows. Let b represent an n bit sequence coming out of the source. We can choose the codeword v which has the shortest distance from b and transmit, instead of b, the k bit information sequence crelevant to v. At the receiving end, c is again converted into v.

The distance δ between b and v is the distortion. If $\bar{\delta}$ is the average of δ over the set of 2" n bit sequences, the average distortion D per bit is given by δ/n . Using V as one coset,² let us completely partition the set of 2^n n bit sequences into cosets. If there are ψ_{Ω} cosets with leaders of weight ω , D is given by

$$D = \frac{\sum \omega \psi_{\omega}}{2^{n-k} n} \tag{1}$$

where the summation is over all relevant ω . The compression ratio is given by n/k and the rate distortion² R(D) is given by $R(D) = 1 - D \log_2(1/D) - (1 - D) \log_2(1/(1 - D))$. It is known² that D = 1/(n+1) for Hamming codes which are

$$(n = 2^s - 1, k = 2^s - 1 - s)$$

with d = 3 and that D = 0.1238 for the Golay code which is (23, 12) with d = 7. The computation of D in these cases is simple because these codes are perfect.

Shortened-by-1-bit Hamming codes: If V is the

$$(n = 2^s - 2, k = 2^s - s - 2)$$

code obtained by shortening a Hamming code by 1 bit, it is known³ that V is a nearly perfect code. Using this fact it is easy to show, with reference to eqn. 1, that there would be one coset with the leader of weight zero, n cosets with leaders of weight I and one coset with a leader of weight 2, so that eqn. 1 reduces to D = 1/n.

Narrow-sense primitive BCH codes with d = 5: With

$$n=2^s-1,$$

let us consider the $GF(2^s) = \{0, 1, a, a^2, ..., a^{n-1}\}$, where a is a primitive element. Let $F_1(X)$ be the irreducible polynomial with a as a root and $F_2(X)$ the irreducible polynomial with a^3 as a root. First, we establish that n-k=2s.

It is known that $F_1(X)$ has degree s. If we partition the set $\{1, 2, ..., n-1\}$ into cyclotomic cosets, the coset with number 1 would be $1, 2, 2^2, \dots 2^{s-1}$, implying that 3 does not belong to this coset. This means that $F_1(X) \neq F_3(X)$.

If s is even, 3 divides n, so that a^3 has order n/3. If

$$(n/3) = 2^{s_1} - 1$$

for some $s_1 < s$, this would mean that

$$2^{s}-1 = n = 2^{s_1+2}-2^{s_1}-2^2+1$$

This is impossible, since $2^{s}-1=n=1+2+2^{2}+...+2^{s-1}$. Therefore $(n/3) \neq 2^{s_1} - 1$, implying that $F_3(X)$ has degree s.

If s is odd, 3 does not divide n, so that a^3 has order n, implying that $F_3(X)$ has degree s.

Combining all these arguments, we have, in the context of the design of BCH codes, that a narrow-sense primitive BCH

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