

# Mutex Types and Locking Methods

This lesson discusses different types of mutexes and their locking methods.

## WE'LL COVER THE FOLLOWING ^

- `std::shared_timed_mutex`
- Mutex `try_lock` methods

C++ has five different mutexes that can lock recursively (i.e., multiple layers of locking), tentative with and without time constraints.

Method	mutex	recursive_mutex	timed_mutex	recursive_timed_mutex	shared_timed_mutex
<code>m.lock</code>	yes	yes	yes	yes	yes
<code>m.unlock</code>	yes	yes	yes	yes	yes
<code>m.try_lock</code>	yes	yes	yes	yes	yes
<code>m.try_lock_for</code>	no	no	yes	yes	yes
<code>m.try_lock_until</code>	no	no	yes	yes	yes
<code>m.try_lock_shared</code>	yes	no	no	no	yes

<code>m.try_lock_for</code>	no	no	no	no	yes
<code>m.try_lock_shared_for</code>					
<code>m.try_lock_until</code>	no	no	no	no	yes
<code>m.try_lock_shared_until</code>					

## `std::shared_timed_mutex` #

With C++14, we have an `std::shared_timed_mutex` that is the base for reader-writer locks. It solves the infamous [reader-writers problem](#).

The `std::shared_timed_mutex` enables us to implement reader-writer locks which means that we can use it for exclusive or shared locking. We will get an exclusive lock if we put the `std::shared_timed_mutex` into an `std::lock_guard`; you will get a shared lock if we put it into an `std::unique_lock`.

### **i** `std::shared_mutex` with C++17

With C++17, we get a new mutex: `std::shared_mutex`. `std::shared_mutex` is similar to `std::shared_timed_mutex`. Like the `std::shared_timed_mutex`, we can use it for exclusive or shared locking, but we can not specify a time point or a time duration.

## Mutex `try_lock` methods #

The `m.try_lock_for(relTime)` (`m.try_lock_shared_for(relTime)`) method needs a relative time duration; the `m.try_lock_until(absTime)` (`m.try_lock_shared_until(absTime)`) method needs an absolute time point.

`m.try_lock` (`m.try_lock_shared`) tries to lock the mutex and returns immediately. Upon success, it returns true; otherwise, it's false. In contrast, the methods `try_lock_for` (`try_lock_shared_for`) and `try_lock_until` (`try_lock_shared_until`) try to lock until the specified timeout occurs or the lock is acquired, whichever comes first. We should use a steady clock for our time constraint. A steady clock cannot be adjusted.

**Tip:** We should not use mutexes directly; we should put mutexes into locks.

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In the next lesson, we'll discuss deadlocks caused by improper mutex locking in C++.