

Adding Fire

Add fire modules to the model and learn about delayed downsampling.

Chapter Goals:

- Add a multi-fire module block to the model
- Learn about delayed downsampling

A. Delayed downsampling

While reducing the data dimensions via max pooling can help our model training, strategic placement of max pooling layers can improve the SqueezeNet model's accuracy. Rather than applying max pooling within the first fire module (e.g. after the squeeze layer), we instead apply it after the first two fire modules.

Placing the max pooling layers later in the model structure is referred to as *delayed downsampling*. We wait until later in the model structure to *downsample* the data (i.e. reduce height/width dimensions through pooling), so the earlier convolution layers can have a larger dimension input. The creators of SqueezeNet showed that having larger dimension inputs for more layers in the model can help improve its accuracy.

Time to Code!

In this chapter, we'll continue building the `model_layers` function by adding the first multi-fire module.

We'll start by setting the list of parameter tuples to describe our fire modules. The list will contain two tuples representing the `fire_module` arguments. For both fire modules, we use `32` as the squeeze depth and `64` as the expand depth. The first fire module will be named `'fire1'` while the second will be named `'fire2'`.

Set `fire_params1` equal to a list of two tuples with the specified values.

Now we apply the multi-fire module block with our list of tuple parameters.

Set `multi_fire1` equal to `self.multi_fire_module` with `pool1` as the first argument and `fire_params1` as the second argument.

We perform max pooling on the output of the multi-fire module block.

Set `pool2` equal to `self.custom_max_pooling2d` applied with `multi_fire1` as the first argument and `'pool2'` as the `name`.

```
import tensorflow as tf

class SqueezeNetModel(object):
    # Model Initialization
    def __init__(self, original_dim, resize_dim, output_size):
        self.original_dim = original_dim
        self.resize_dim = resize_dim
        self.output_size = output_size

    # Convolution layer wrapper
    def custom_conv2d(self, inputs, filters, kernel_size, name):
        return tf.layers.conv2d(
            inputs=inputs,
            filters=filters,
            kernel_size=kernel_size,
            activation=tf.nn.relu,
            padding='same',
            name=name)

    # Max pooling layer wrapper
    def custom_max_pooling2d(self, inputs, name):
        return tf.layers.max_pooling2d(
            inputs=inputs,
            pool_size=[2, 2],
            strides=2,
            name=name)

    # SqueezeNet fire module
    def fire_module(self, inputs, squeeze_depth, expand_depth, name):
        with tf.variable_scope(name):
            squeezed_inputs = self.custom_conv2d(
                inputs,
                squeeze_depth,
                [1, 1],
                'squeeze')
            expand1x1 = self.custom_conv2d(
                squeezed_inputs,
                expand_depth,
                [1, 1],
                'expand1x1')
            expand3x3 = self.custom_conv2d(
                squeezed_inputs,
                expand_depth,
                [3, 3],
                'expand3x3')
            return tf.concat([expand1x1, expand3x3], axis=-1)
```

```
# Utility function for multiple fire modules
def multi_fire_module(self, layer, params_list):

    for params in params_list:
        layer = self.fire_module(
            layer,
            params[0],
            params[1],
            params[2])
    return layer

# Model Layers
# inputs: [batch_size, resize_dim, resize_dim, 3]
def model_layers(self, inputs, is_training):
    conv1 = self.custom_conv2d(
        inputs,
        64,
        [3, 3],
        'conv1')
    pool1 = self.custom_max_pooling2d(
        conv1,
        'pool1')
    # CODE HERE
```

