

# DBSCAN

Learn about the DBSCAN clustering algorithm.

## Chapter Goals:

- Learn about the DBSCAN algorithm

### A. Clustering by density

The mean shift clustering algorithm in the previous chapter usually performs sufficiently well and can choose a reasonable number of clusters. However, it is not very scalable due to computation time and still makes the assumption that clusters have a "blob"-like shape (although this assumption is not as strong as the one made by K-means).

Another clustering algorithm that also automatically chooses the number of clusters is **DBSCAN**. DBSCAN clusters data by finding *dense* regions in the dataset. Regions in the dataset with many closely packed data observations are considered *high-density* regions, while regions with sparse data are considered *low-density* regions.

The DBSCAN algorithm treats high-density regions as clusters in the dataset, and low-density regions as the area between clusters (so observations in the low-density regions are treated as noise and not placed in a cluster).

High-density regions are defined by *core samples*, which are just data observations with many neighbors. Each cluster consists of several core samples and all the observations that are neighbors to a core sample.

Unlike the mean shift algorithm, the DBSCAN algorithm is both highly scalable and makes no assumptions about the underlying shape of clusters in the dataset.

### B. Neighbors and core samples

The exact definition of "neighbor" and "core sample" depends on what we

want in our clusters. We specify the maximum distance,  $\epsilon$ , between two data observations that are considered neighbors. Smaller distances result in smaller and more tightly packed clusters. We also specify the minimum number of points in the neighborhood of a data observation for the observation to be considered a core sample (the neighborhood consists of the data observation and all its neighbors).

In scikit-learn, we implement DBSCAN with the `DBSCAN` object (part of the `cluster` module). The object is initialized with the keyword arguments `eps` (representing the value of  $\epsilon$ ) and `min_samples` (representing the minimum size of a core sample's neighborhood).

The code below demonstrates how to use the `DBSCAN` object, with  $\epsilon$  equal to 1.2 and a minimum size of 30 for a core sample's neighborhood.

```
from sklearn.cluster import DBSCAN
dbscan = DBSCAN(eps=1.2, min_samples=30)
# predefined data
dbscan.fit(data)

# cluster assignments
print('{}\n'.format(repr(dbscan.labels_)))

# core samples
print('{}\n'.format(repr(dbscan.core_sample_indices_)))
num_core_samples = len(dbscan.core_sample_indices_)
print('Num core samples: {}\n'.format(num_core_samples))
```

In the code above, we used `DBSCAN` to cluster the 150 data observations in `data`. The algorithm found two clusters. In this case all the data observations fit in a cluster, but in general the non-cluster observations would be labeled with `-1`.

The `core_sample_indices_` attribute represents the core sample data observations in `data` (specified by row index).