Types of Locks: std::unique_lock

This lesson gives an overview of std::unique_lock which is a type of lock used in C++.

WE'LL COVER THE FOLLOWING

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- Features
- Methods
 - More on lk.try_lock and lk.release methods
 - How to solve deadlock with std::unique_lock

Features

In addition to what's offered by a std::lock_guard, a std::unique_lock
enables you to

- create it without an associated mutex.
- create it without locking the associated mutex.
- explicitly and repeatedly set or release the lock of the associated mutex.
- move the mutex.
- try to lock the mutex.
- delay the lock on the associated mutex.

Methods

The following table shows the methods of a std::unique_lock lk.

| Method | Description |
|-----------|-----------------------------|
| lk.lock() | Locks the associated mutex. |

Locks atomically the arbitrary number of associated mutexes.

Tries to lock the associated mutex.

Release the mutex. The mutex remains locked.

Swaps the locks.

Returns a pointer to the associated mutex.

Checks if the lock has a mutex.

More on lk.try_lock and lk.release methods

lk.try_lock_for(relTime) needs a relative time duration;
lk.try_lock_until(absTime) needs an absolute time point.

lk.try_lock tries to lock the mutex and returns immediately. On success, it
returns true, but otherwise, it's false. In contrast the methods lk.try_lock_for
and lk.try_lock_until block until the specified timeout occurs or the lock is
acquired, whichever comes first. You should use a steady clock for your time
constraint. A steady clock cannot be adjusted.

The method lk.release() returns the mutex; therefore, you have to unlock it manually.

How to solve deadlock with std::unique_lock

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atomic step; therefore you can overcome deadlocks by locking mutexes in a

different order. Remember the deadlock from the subsection Issues of Mutexes?

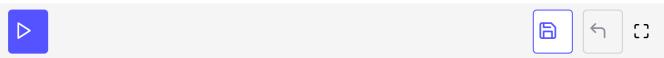
```
// deadlock.cpp
                                                                                           6
#include <iostream>
#include <chrono>
#include <mutex>
#include <thread>
struct CriticalData{
  std::mutex mut;
};
void deadLock(CriticalData& a, CriticalData& b){
  a.mut.lock();
  std::cout << "get the first mutex" << std::endl;</pre>
  std::this_thread::sleep_for(std::chrono::milliseconds(1));
  b.mut.lock();
  std::cout << "get the second mutex" << std::endl;</pre>
  // do something with a and b
  a.mut.unlock();
  b.mut.unlock();
}
int main(){
  CriticalData c1;
  CriticalData c2;
  std::thread t1([&]{deadLock(c1,c2);});
  std::thread t2([&]{deadLock(c2,c1);});
  t1.join();
  t2.join();
}
```

Let's solve the issue. The function deadLock has to lock its mutexes atomically and that's exactly what happens in the following example.

```
// deadlockResolved.cpp

#include <iostream>
#include <chrono>
#include <mutex>
#include <thread>
```

```
using namespace std;
struct CriticalData{
 mutex mut;
};
void deadLock(CriticalData& a, CriticalData& b){
  unique_lock<mutex> guard1(a.mut,defer_lock);
  cout << "Thread: " << this_thread::get_id() << " first mutex" << endl;</pre>
  this_thread::sleep_for(chrono::milliseconds(1));
  unique_lock<mutex> guard2(b.mut,defer_lock);
  cout << " Thread: " << this_thread::get_id() << " second mutex" << endl;</pre>
               Thread: " << this_thread::get_id() << " get both mutex" << endl;</pre>
  cout << "
  lock(guard1,guard2);
  // do something with a and b
}
int main(){
  cout << endl;</pre>
  CriticalData c1;
  CriticalData c2;
  thread t1([&]{deadLock(c1,c2);});
  thread t2([&]{deadLock(c2,c1);});
 t1.join();
  t2.join();
  cout << endl;</pre>
}
```



If you call the constructor of std::unique_lock, with std::defer_lock, the underlying mutex will not be locked automatically. At this point (lines 16 and 21), the std::unique_lock is just the owner of the mutex. Thanks to the variadic template std::lock, the lock operation is performed in an atomic step (line 25). A variadic template is a template which can accept an arbitrary number of arguments. std::lock tries to get all locks in one atomic step, so it either gets all of them or none of them and retries until it succeeds.

In this example, std::unique_lock manages the lifetime of the resources and std::lock locks the associated mutex; you can also do it the other way around. In the first step the mutexes are locked, in the second

std::unique_lock manages the lifetime of resources. Here is an example of the
second approach.

```
std::lock(a.mut, b.mut);
std::lock_guard<std::mutex> guard1(a.mut, std::adopt_lock);
std::lock_guard<std::mutex> guard2(b.mut, std::adopt_lock);
```

Let us see this approach in action:

```
// deadlockResolved.cpp
#include <iostream>
#include <chrono>
#include <mutex>
#include <thread>
using namespace std;
struct CriticalData{
  mutex mut;
};
void deadLock(CriticalData& a, CriticalData& b){
  lock_guard<std::mutex> guard1(a.mut, std::adopt_lock);
  cout << "Thread: " << this_thread::get_id() << " first mutex" << endl;</pre>
  this_thread::sleep_for(chrono::milliseconds(1));
  lock_guard<std::mutex> guard2(b.mut, std::adopt_lock);
  cout << " Thread: " << this_thread::get_id() << " second mutex" << endl;</pre>
  cout << "
               Thread: " << this_thread::get_id() << " get both mutex" << endl;</pre>
  lock(a.mut, b.mut);
  // do something with a and b
}
int main(){
  cout << endl;</pre>
  CriticalData c1;
  CriticalData c2;
  thread t1([&]{deadLock(c1,c2);});
  thread t2([&]{deadLock(c2,c1);});
  t1.join();
  t2.join();
  cout << endl;</pre>
}
```







Resolving the deadlock with a std::scoped_lock

With C++17, the resolution of the deadlock becomes quite easy. We get the std::scoped_lock that can lock an arbitrary number of mutexes atomically - so long as you only have to use a std::lock_guard instead of the std::lock call. That's all. Here is the modified function deadlock .

```
// deadlockResolvedScopedLock.cpp
void deadLock(CriticalData& a, CriticalData& b){

cout << "Thread: " << this_thread::get_id() << " first mutex" << endl;
    this_thread::sleep_for(chrono::milliseconds(1));
    cout << " Thread: " << this_thread::get_id() << " second mutex" << endl;
    cout << " Thread: " << this_thread::get_id() << " get both mutex" << endl;

std::scoped_lock(a.mut, b.mut);
    // do something with a and b
}</pre>
```

With C++14, C++ adds support for std::shared_lock; Let's see this in the next lesson.