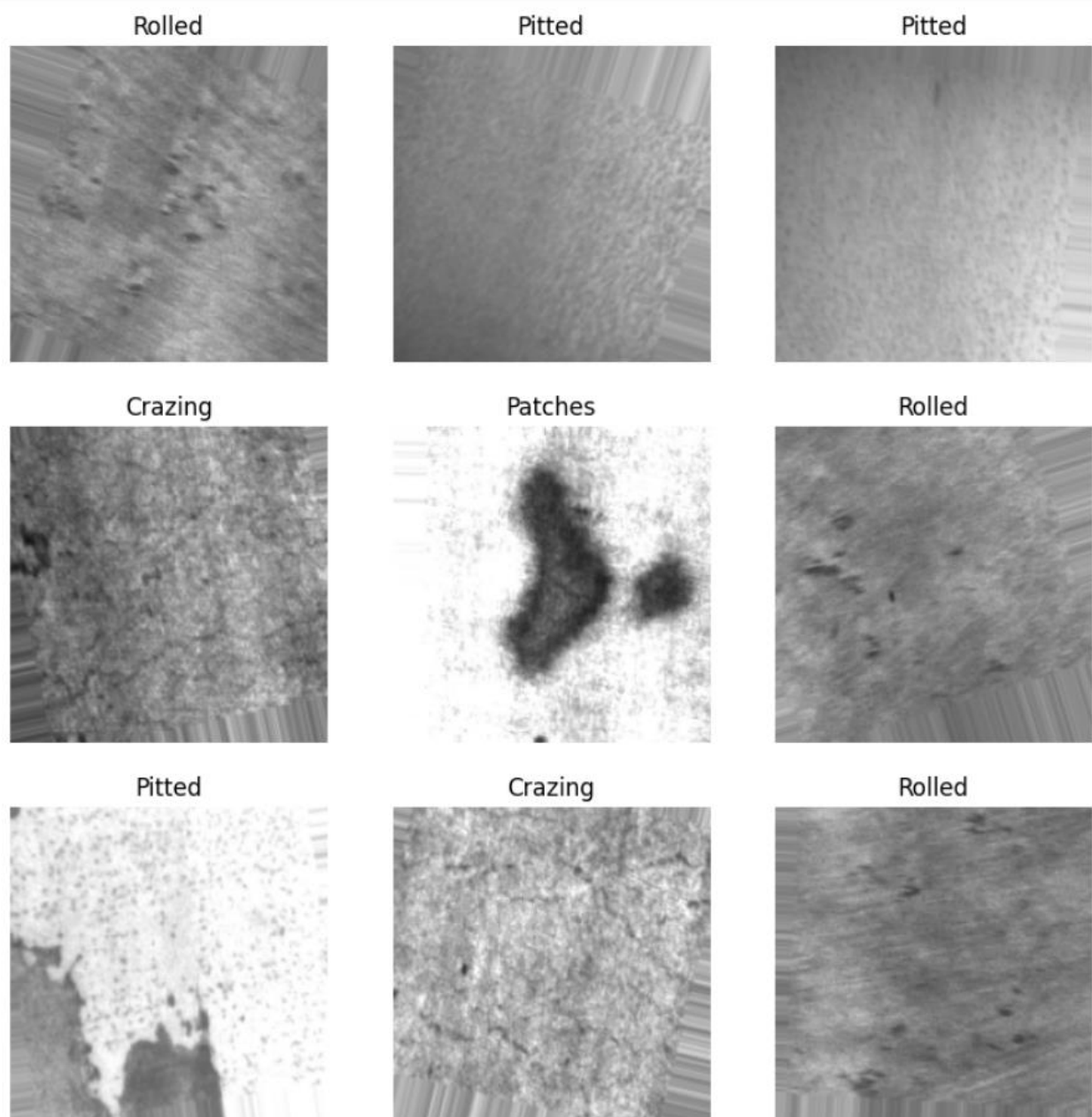


# **Report on NEU-DET Steel Surface Defect Detection**

# 1.Introduction

The objective of the project is to build a Tensorflow Deep Learning model which can identify defect location on steel surface. The model used here is MobileNetV2 with. For this we have used the open surface defect database from Northeastern University(NEU).

In this database, six kinds of typical surface defects of the hot-rolled steel strip are collected, i.e., rolled-in scale (RS), patches (Pa), crazing (Cr), pitted surface (PS), inclusion (In) and scratches (Sc). The images provided in the database are in grayscale and of uniform dimensions 200x200. A snapshot of how the images looks like are shown below:-



The database can be found in the below links:-

[http://faculty.neu.edu.cn/yunhyan/NEU\\_surface\\_defect\\_database.html](http://faculty.neu.edu.cn/yunhyan/NEU_surface_defect_database.html)

<https://drive.google.com/drive/folders/1B4NnQb8AXvbKVC70mQyq6jSYU-LmupYh?usp=sharing>

The description of the database in the above url states that the database includes 1,800 grayscale images: 300 samples each of six different kinds of typical surface defects.

## 2.Requirements

- Software Requirements

Google Colab/ Jupyter Notebook

Numpy

Pandas

Matplotlib

Tensorflow

- Hardware Requirements

GPU

## 3.Methodology

### A] Data Loading:

We load data from our Google Drive into three main sets :- Training Data, Testing Data, Validation Data.

### B] Data Preprocessing:

For data preprocessing we use ImageDataGenerator from tensorflow.keras.preprocessing.image module.

We create two datagen: train\_datagen, test\_datagen.

We apply the following preprocessing on train\_datagen:

```
• rescale=1./255
• rotation_range=20
• width_shift_range=0.1
```

- height\_shift\_range=0.1
- horizontal\_flip=True

On test\_datagen, we only rescale to 1./255

Then using the flow\_from\_directory method, we load our images from our directories and apply the preprocessing and divide the data into batches of 32 and fix the image size as (200,200).

## C] Modelling:

We create 4 models with the model\_summaries as shown below.

- **Model 1**

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 199, 199, 32)	416
max_pooling2d (MaxPooling2D)	(None, 99, 99, 32)	0
conv2d_1 (Conv2D)	(None, 98, 98, 64)	8256
max_pooling2d_1 (MaxPooling2D)	(None, 49, 49, 64)	0
conv2d_2 (Conv2D)	(None, 48, 48, 128)	32896
max_pooling2d_2 (MaxPooling2D)	(None, 24, 24, 128)	0
flatten (Flatten)	(None, 73728)	0
dense (Dense)	(None, 256)	18874624
dropout (Dropout)	(None, 256)	0
dense_1 (Dense)	(None, 6)	1542
Total params: 18917734 (72.17 MB)		
Trainable params: 18917734 (72.17 MB)		
Non-trainable params: 0 (0.00 Byte)		

- **Model 2**

Model: "sequential\_1"

Layer (type)	Output Shape	Param #
conv2d_3 (Conv2D)	(None, 199, 199, 32)	416
max_pooling2d_3 (MaxPooling2D)	(None, 99, 99, 32)	0
conv2d_4 (Conv2D)	(None, 98, 98, 64)	8256
max_pooling2d_4 (MaxPooling2D)	(None, 49, 49, 64)	0
conv2d_5 (Conv2D)	(None, 48, 48, 128)	32896
max_pooling2d_5 (MaxPooling2D)	(None, 24, 24, 128)	0
flatten_1 (Flatten)	(None, 73728)	0
dense_2 (Dense)	(None, 256)	18874624
dropout_1 (Dropout)	(None, 256)	0
dense_3 (Dense)	(None, 6)	1542
Total params: 18917734 (72.17 MB)		
Trainable params: 18917734 (72.17 MB)		
Non-trainable params: 0 (0.00 Byte)		

- **MobileNetV2 Model**

Model: "sequential\_2"

Layer (type)	Output Shape	Param #
mobilenetv2_1.00_224 (Functional)	(None, 7, 7, 1280)	2257984
global_average_pooling2d (GlobalAveragePooling2D)	(None, 1280)	0
dense_4 (Dense)	(None, 256)	327936
dropout_2 (Dropout)	(None, 256)	0
dense_5 (Dense)	(None, 6)	1542
Total params: 2587462 (9.87 MB)		
Trainable params: 329478 (1.26 MB)		
Non-trainable params: 2257984 (8.61 MB)		

We are using Transfer Learning here and we have customised the model according to our required output with keeping only few layers trainable.

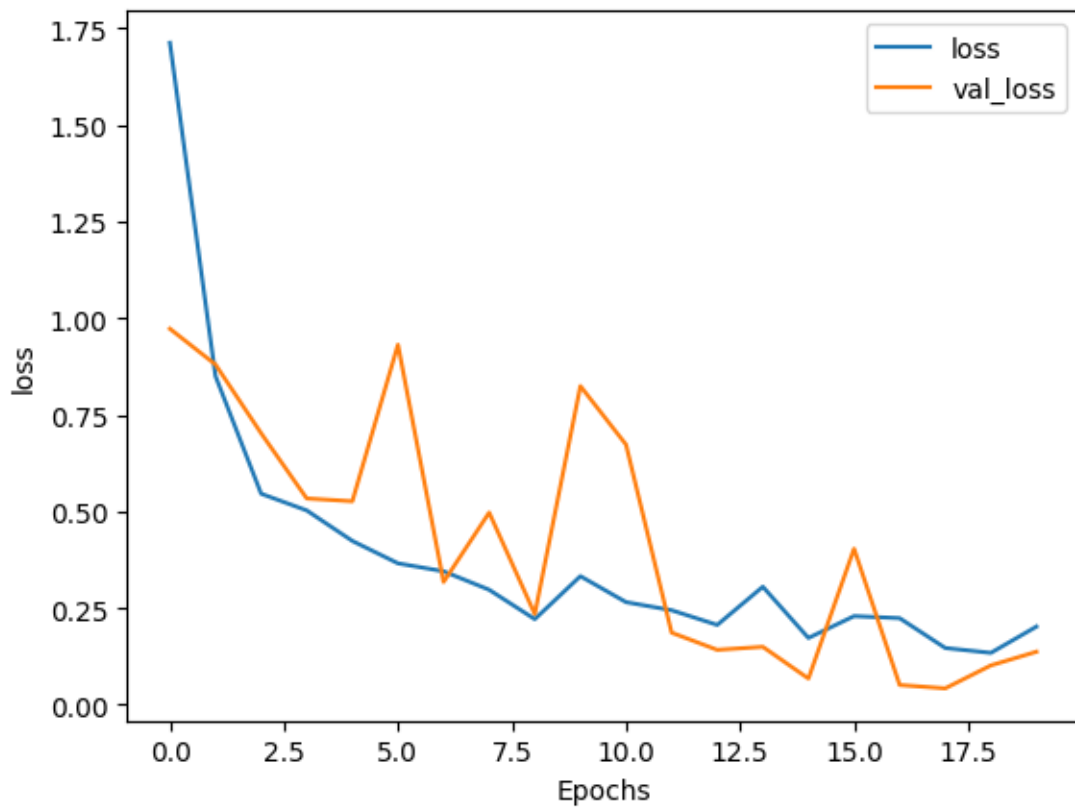
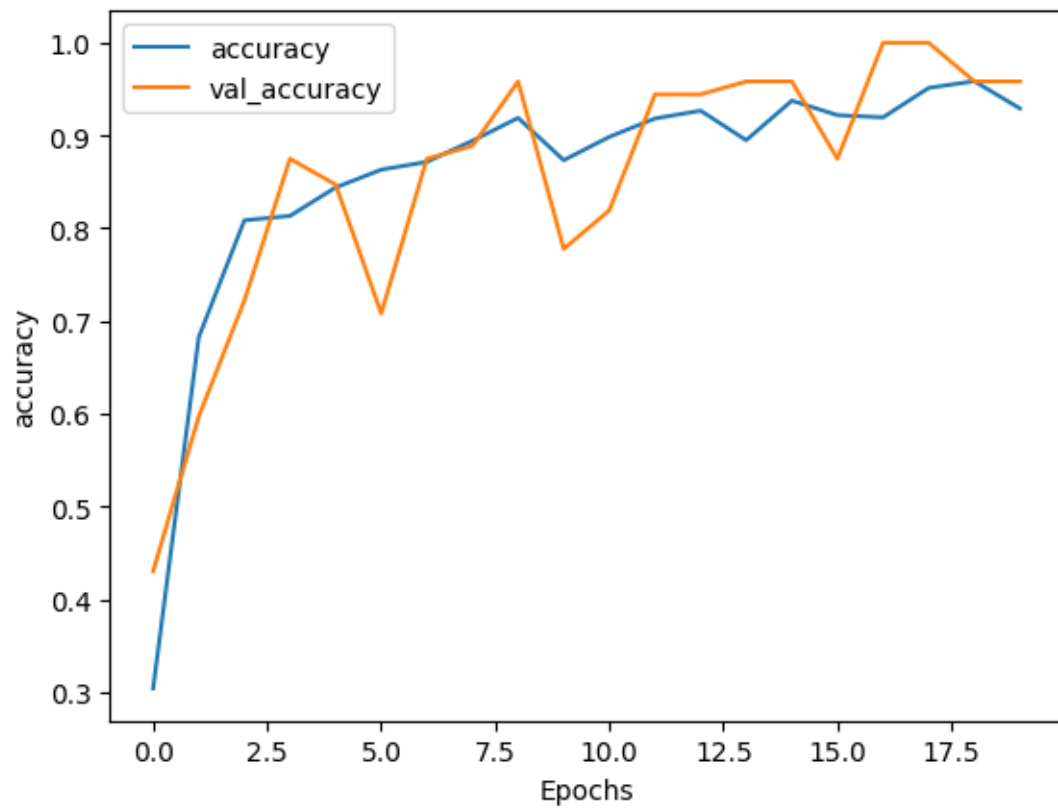
- **EfficientNetB1 Model**

Model: "sequential\_4"

Layer (type)	Output Shape	Param #
efficientnetb1 (Functional)	(None, 7, 7, 1280)	6575239
global_average_pooling2d_2 (GlobalAveragePooling2D)	(None, 1280)	0
dense_8 (Dense)	(None, 256)	327936
dropout_4 (Dropout)	(None, 256)	0
dense_9 (Dense)	(None, 6)	1542
Total params: 6904717 (26.34 MB)		
Trainable params: 329478 (1.26 MB)		
Non-trainable params: 6575239 (25.08 MB)		

## 4. Model Performance

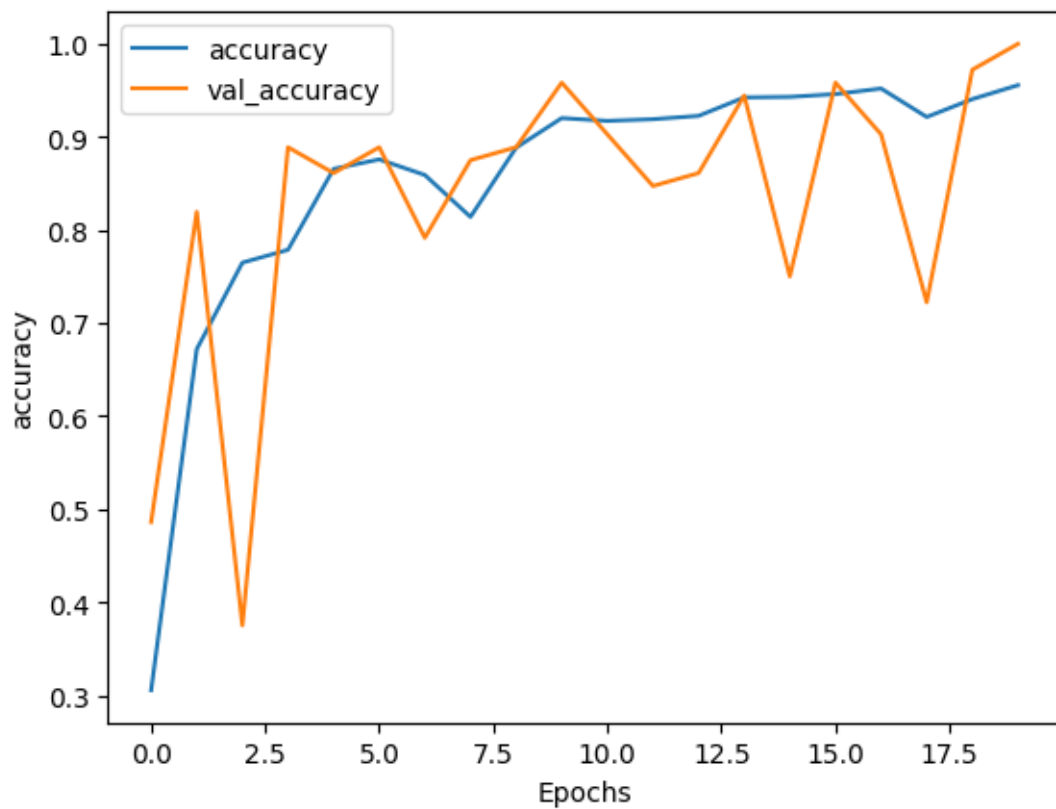
- Model 1:



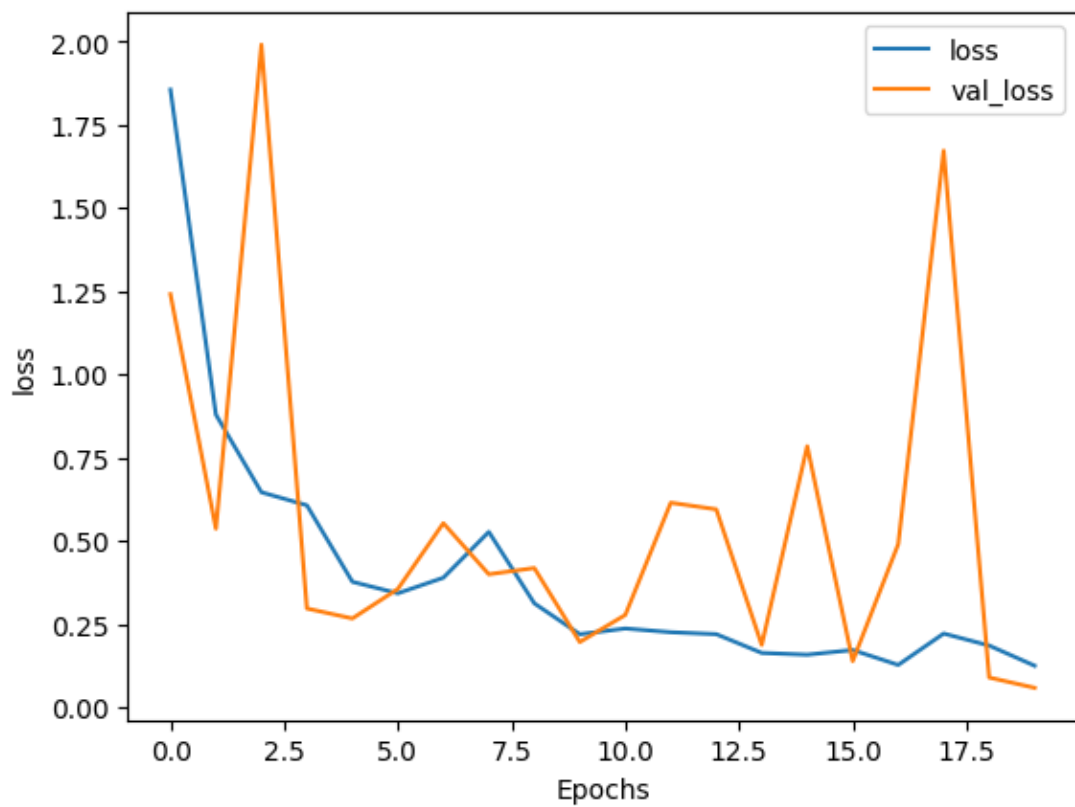
```
[ ] result1 = model1.evaluate(test_generator)
print("Test loss, Test accuracy : ", result1)
```

3/3 [=====] - 0s 71ms/step - loss: 0.3064 - accuracy: 0.8611  
Test loss, Test accuracy : [0.3064206540584564, 0.8611111044883728]

- **Model 2:**



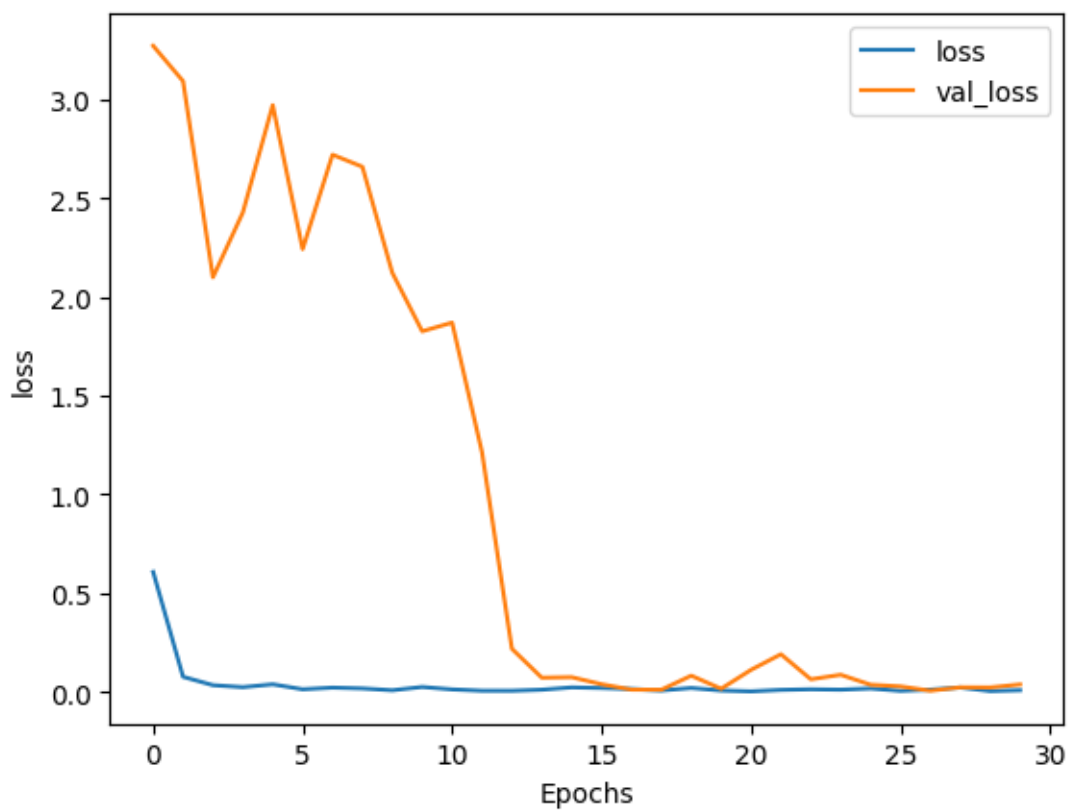
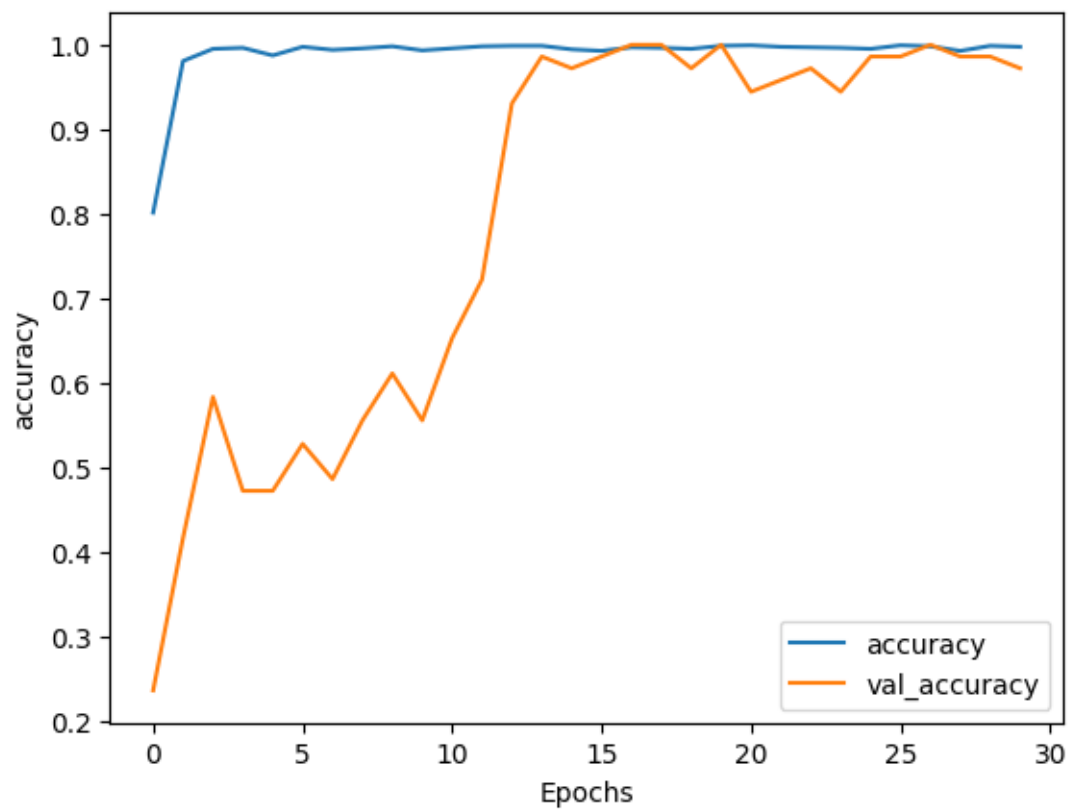




```
result2 = model2.evaluate(test_generator)
print("Test loss, Test accuracy : ", result2)
```

3/3 [=====] - 1s 133ms/step - loss: 0.3472 - accuracy: 0.8750  
Test loss, Test accuracy : [0.3471944034099579, 0.875]

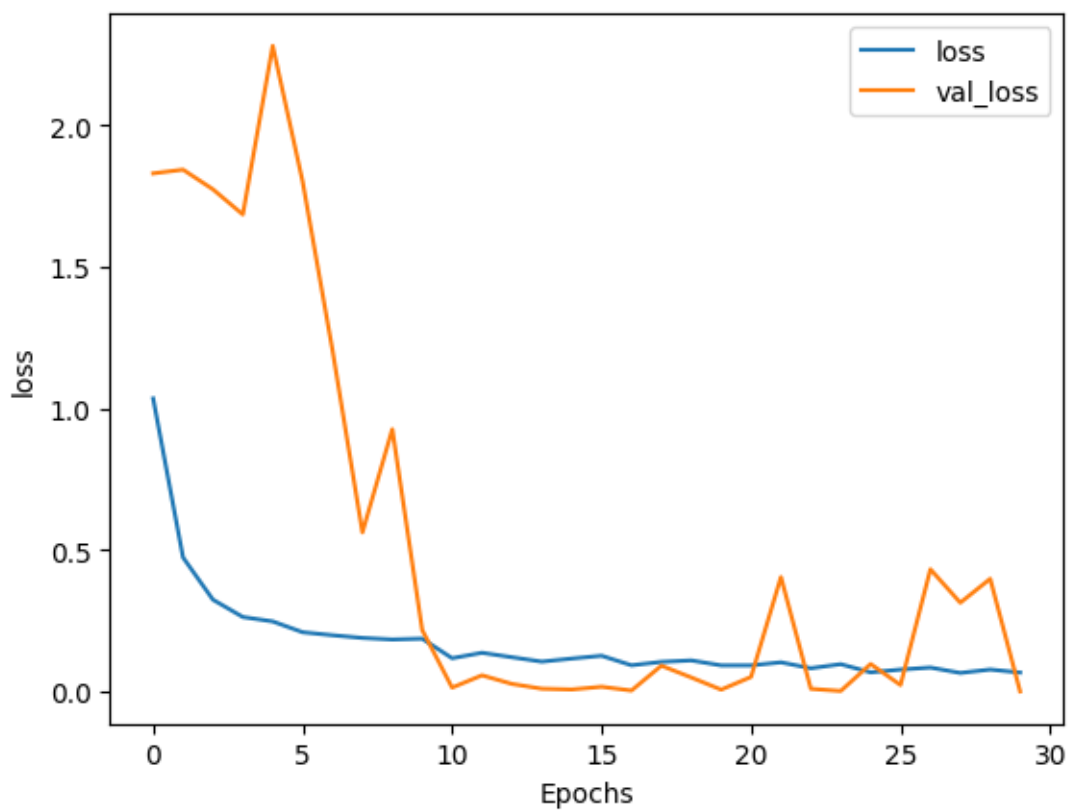
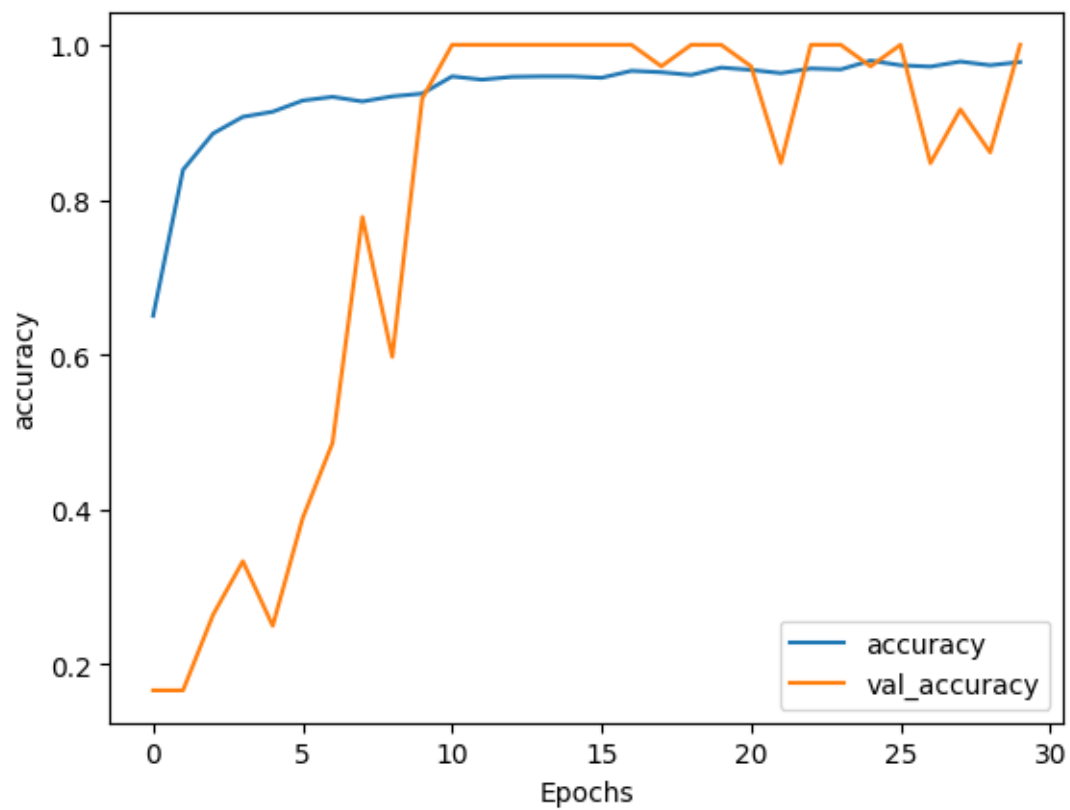
- **MobileNetV2 Model:**



```
result_mobilenet = model_mobilenet.evaluate(test_generator)
print("Test loss, Test accuracy : ", result_mobilenet)
```

3/3 [=====] - 0s 109ms/step - loss: 0.0761 - accuracy: 0.9861  
 Test loss, Test accuracy : [0.0761433020234108, 0.9861111044883728]

- **EfficientNetB1 Model:**



```
result_efficient = model_efficient.evaluate(test_generator)
print("Test loss, Test accuracy : ", result_efficient)
```

3/3 [=====] - 1s 227ms/step - loss: 5.5828e-04 - accuracy: 1.0000  
 Test loss, Test accuracy : [0.0005582821322605014, 1.0]

Comparing between different models, we get:

	Model	Accuracy	Loss
0	Model 1	0.929214	0.202334
1	Model 2	0.955609	0.124339
2	MobileNetV2	0.997600	0.007912
3	EfficientNetB1	0.977804	0.066639

From this, we can infer that MobileNetV2 works best for our objective.

We get maximum accuracy with minimum loss in case of MobileNetV2 so we will use it for our operations.

-----Thank You-----