

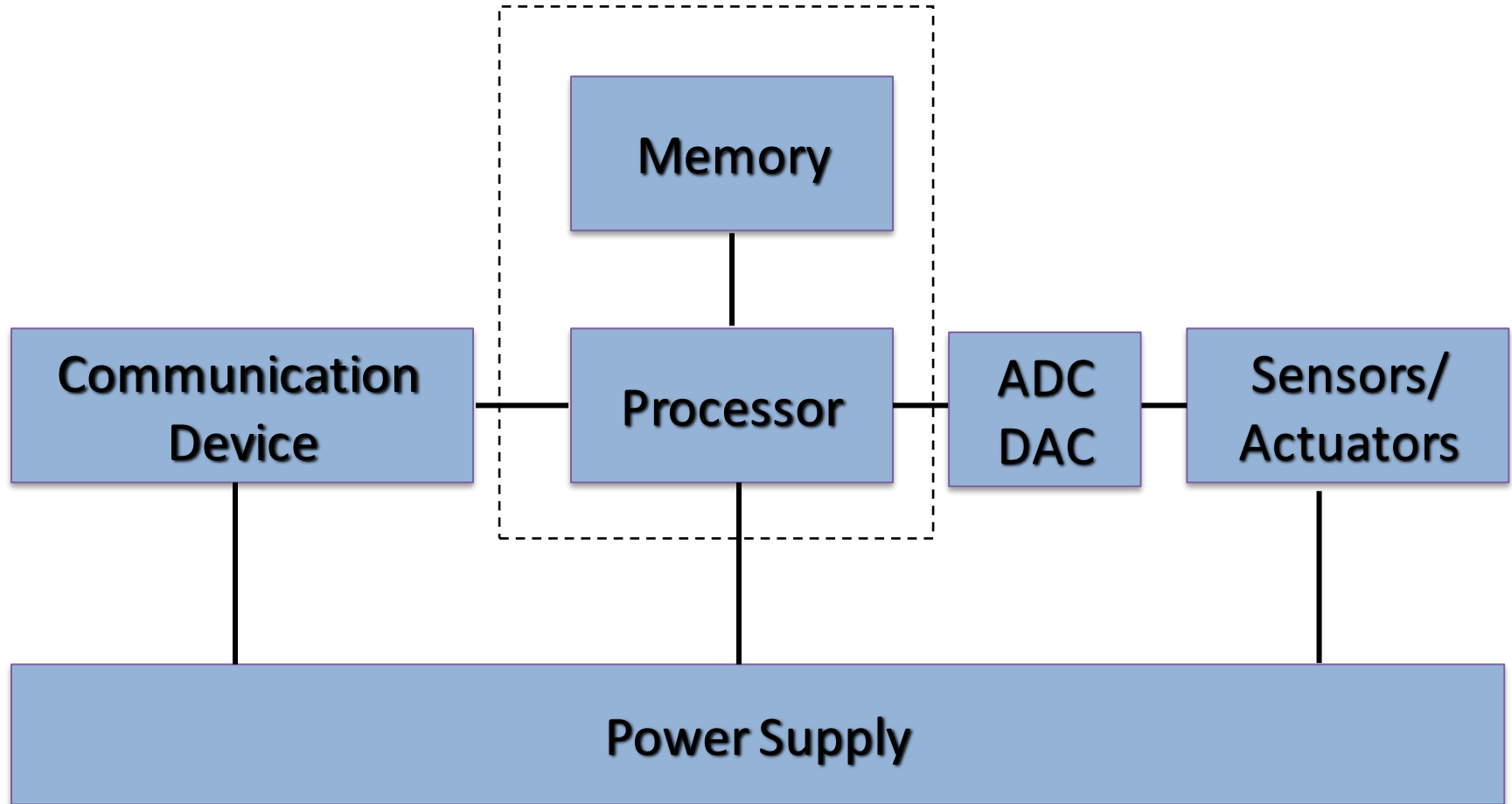
Internet of Things (IoT) Platforms & Devices

Dr Tomasz Szydlo

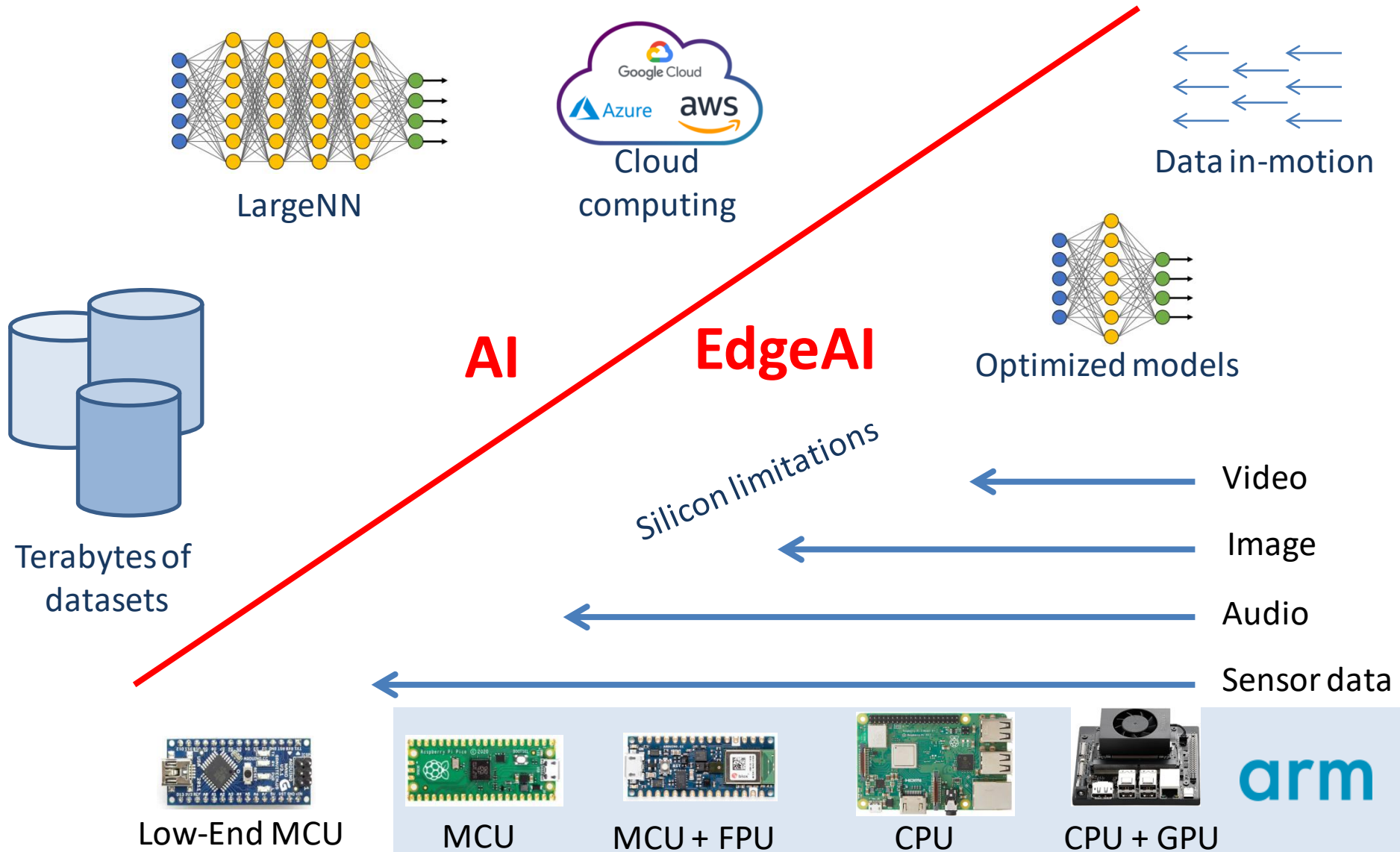
School of Computing

Newcastle University

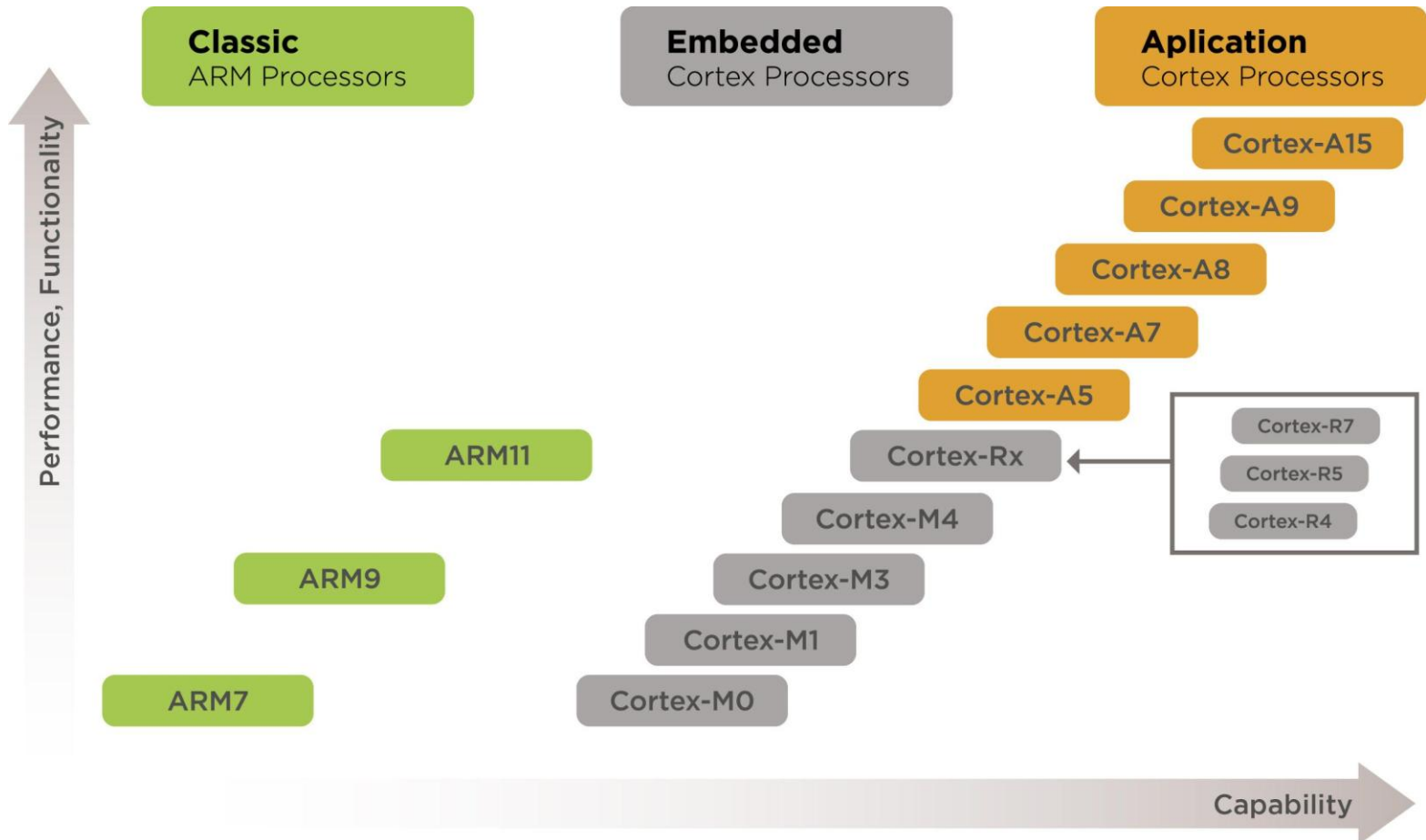
Main components



IoT Miniaturization (AI use case)



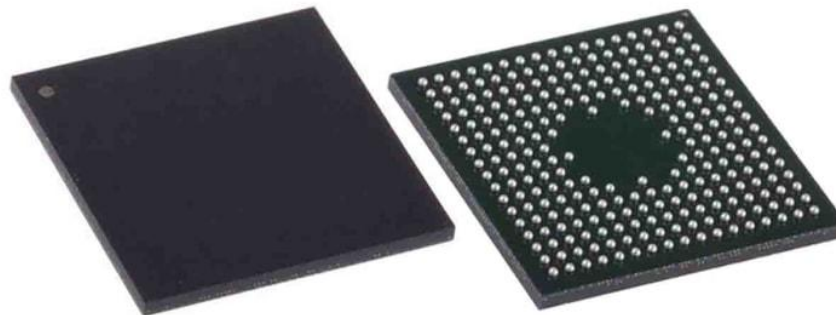
ARM Processors



British semiconductor and software design company based in Cambridge, England.

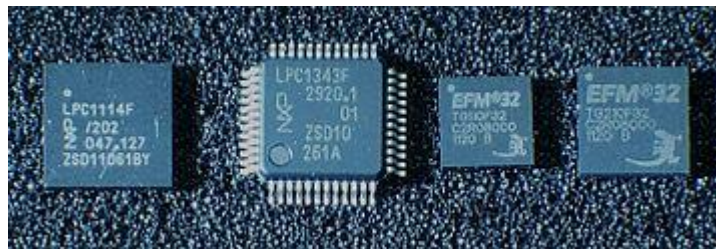
ARM Cortex A

- Characteristics
 - High frequency up to 2GHz
 - Multi-core capabilities
 - Advanced memory management
 - Linux operating system
- Applications
 - Smartphones
 - Digital TV
 - Home gateways

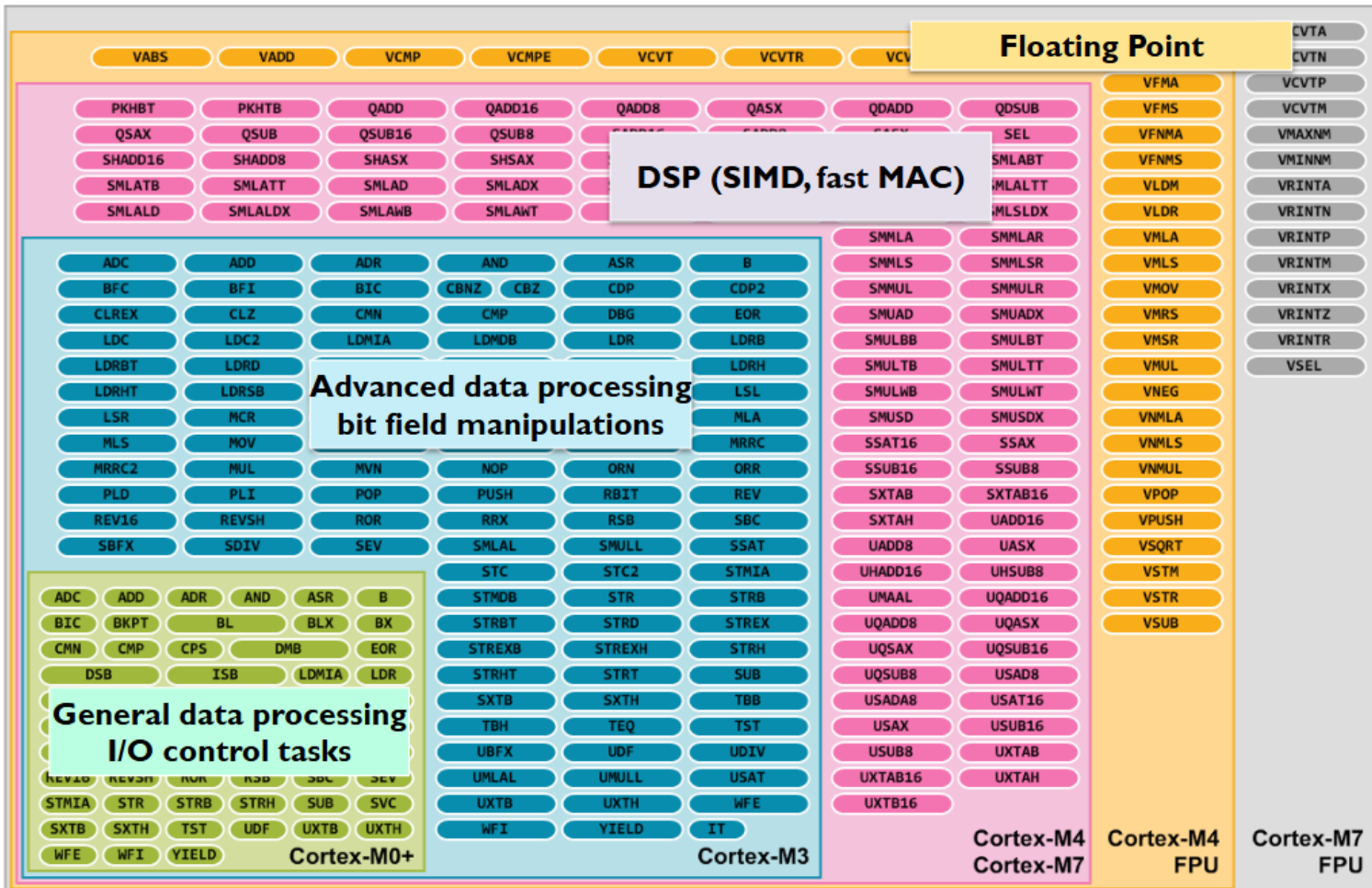


ARM Cortex M

- Characteristics
 - Cost-sensitive solutions for microcontroller applications
 - Low power consumption
 - Interrupt management
 - Low memory
- Applications
 - Microcontrollers
 - Mixed signal processing
 - Smart sensors
 - Internet of Things



ARM Cortex M



Operating Systems for IoT

- Real-Time Operating Systems
 - FreeRTOS
 - Zephyr OS
 - Mbed
- Low memory footprint (kB vs MB)
- Support for lightweight communication protocols
 - IPv4/IPv6
 - CoAP/LwM2M
 - MQTT
 - 802.15.4/Thread
 - Bluetooth Low Energy
 - CAN



Zephyr[®]

PROTOTYPING BOARDS

DIY

Communication protocols

- MQTT
- LwM2M
- XMPP
- HTTP
- CoAP
- ...

Devices

- Raspberry Pi
- Arduino
- Intel Edison
- Proton Particle
- ...



Software

- Eclipse Kura
- TensorFlow
- NodeRED
- Apache Spark
- Eclipse Edgent
- ...

Cloud platforms

- Amazon
- Google Brillo
- Apple HomeKit
- ARM mbed
- CoAP
- ...

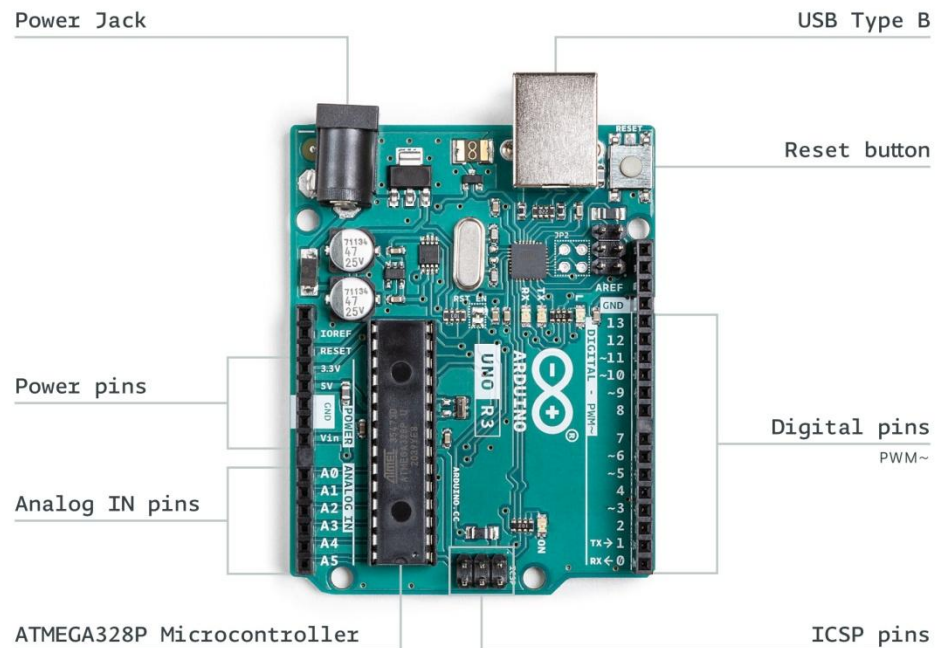
Communication technologies

- Ethernet
- 2G/LTE/5G
- LoRA
- NB-IoT
- WiFi
- Bluetooth LE
- ...

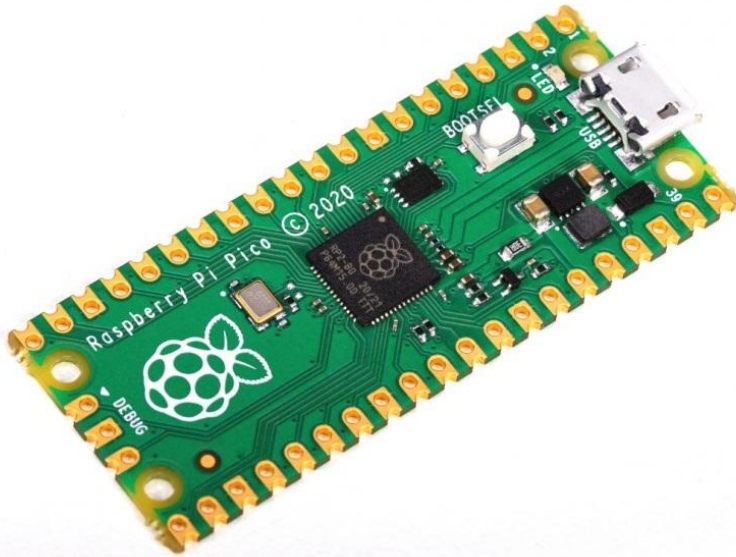
Arduino

- Open source hardware
 - Processor ATmega328
 - Clock Speed 16 MHz
 - Digital I/O Pins 14
 - Analog Input Pins 6
 - Flash Memory 32 KB
 - SRAM 2 KB
 - EEPROM 1 KB
 - Bare-metal coding

2005



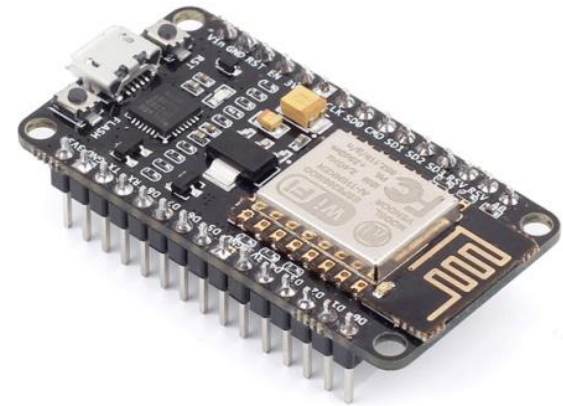
Raspberry Pi Pico



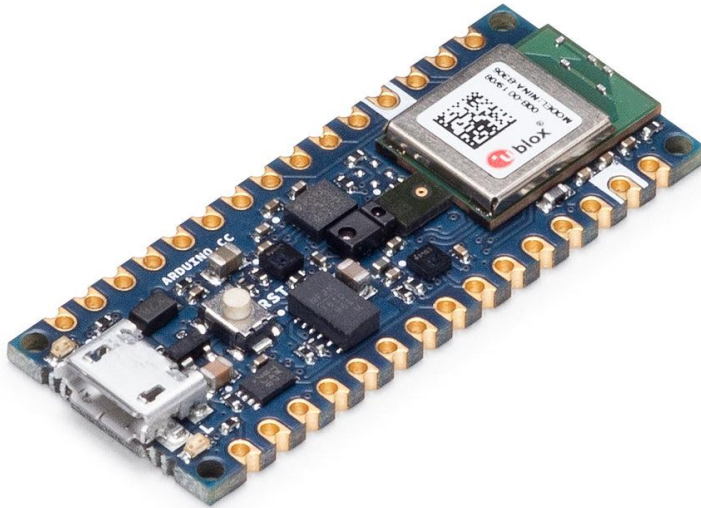
- 21 mm × 51 mm form factor
- RP2040 microcontroller chip designed by Raspberry Pi in the UK
- Dual-core Arm Cortex-M0+ processor
- flexible clock running up to 133 MHz
- 264KB on-chip SRAM
- 2MB on-board QSPI Flash
- 26 multifunction GPIO pins
 - 3 analogue inputs
 - UART, SPI, I2C, PWM, USB

ESP32

- Processor
 - Xtensa dual-core 32-bit
 - 160 or 240 MHz
- Memory
 - 520 KiB RAM
 - 448 KiB ROM
- Wireless connectivity
 - Wi-Fi 802.11 b/g/n
 - Bluetooth BLE
- 34 × programmable GPIO



Arduino BLE Sense 33

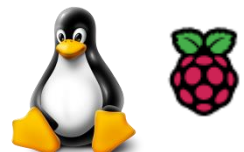


- Processor
 - 64 MHz Arm® Cortex-M4F (with FPU)
- 1 MB Flash + 256 KB RAM
- Connectivity
 - Bluetooth® 5 multiprotocol radio
 - 802.15.4 transceiver
- Sensors
 - LSM9DS1 (9 axis IMU)
 - LPS22HB (Barometer and temperature sensor)
 - HTS221 (relative humidity sensor)
 - APDS-9960 (Digital proximity, Ambient light, RGB and Gesture Sensor)
 - MP34DT05 (Digital Microphone)
 - ATECC608A (Crypto Chip)

Raspberry Pi



- Processor (Pi 5)
 - Broadcom BCM2712 @2.4GHz
 - quad-core 64-bit Arm Cortex-A76
- Memory
 - RAM 4/8GB
 - microSD card slot
- Connectivity
 - Gigabit Ethernet
 - Dual-band 802.11ac Wi-Fi
 - Bluetooth 5.0 / Bluetooth Low Energy (BLE)



Nvidia Jetson Nano

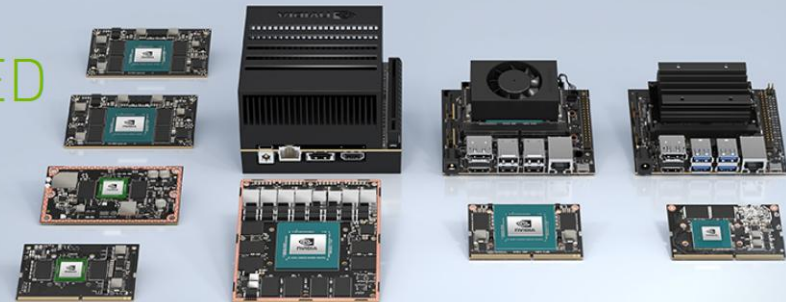
- GPU cores as in the datacenter
- NVIDIA Jetson is the most popular edge computing platform

TECHNICAL SPECIFICATIONS

GPU	NVIDIA Maxwell architecture with 128 NVIDIA CUDA® cores
CPU	Quad-core ARM Cortex-A57 MPCore processor
Memory	4 GB 64-bit LPDDR4, 1600MHz 25.6 GB/s
Storage	16 GB eMMC 5.1
Video Encode	250MP/sec 1x 4K @ 30 (HEVC) 2x 1080p @ 60 (HEVC) 4x 1080p @ 30 (HEVC) 4x 720p @ 60 (HEVC) 9x 720p @ 30 (HEVC)
Video Decode	500MP/sec 1x 4K @ 60 (HEVC) 2x 4K @ 30 (HEVC) 4x 1080p @ 60 (HEVC) 8x 1080p @ 30 (HEVC) 9x 720p @ 60 (HEVC)

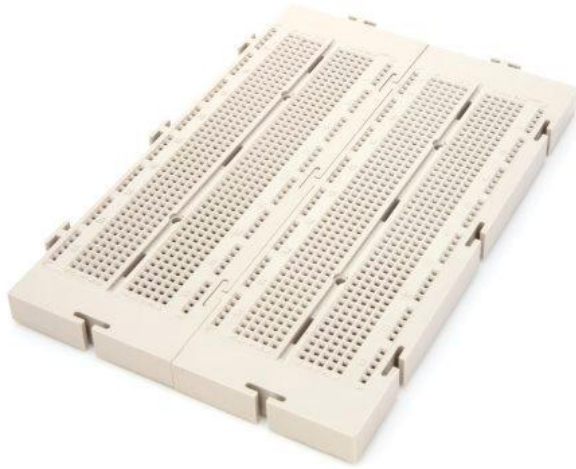
ADVANCED EMBEDDED
SYSTEMS FOR EDGE
COMPUTING

NVIDIA Jetson: The AI platform for edge computing

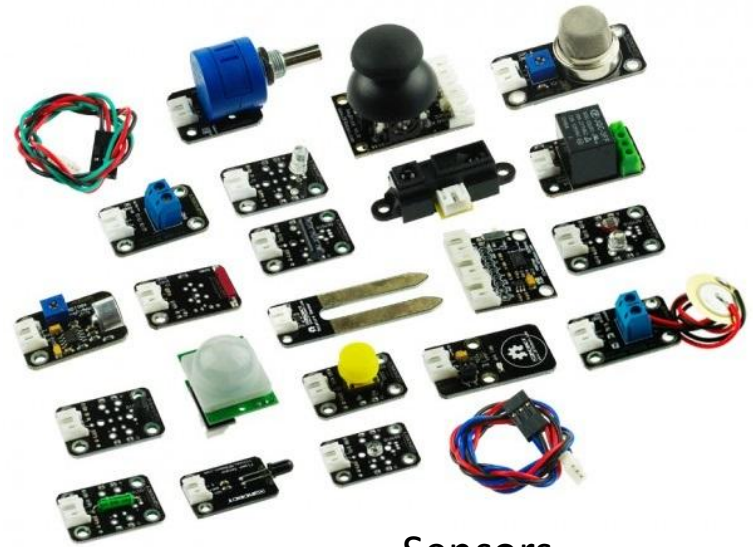


SENSORS

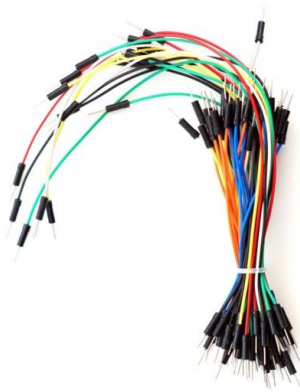
Generic Sensors



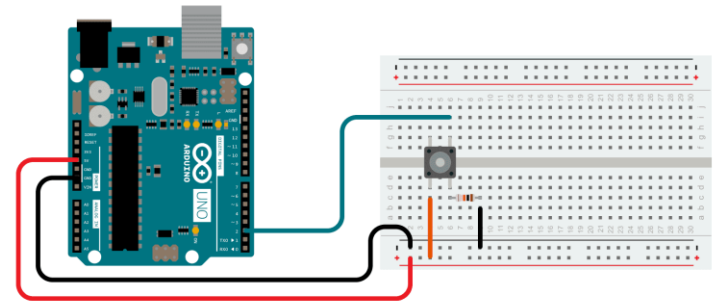
Breadboard



Sensors



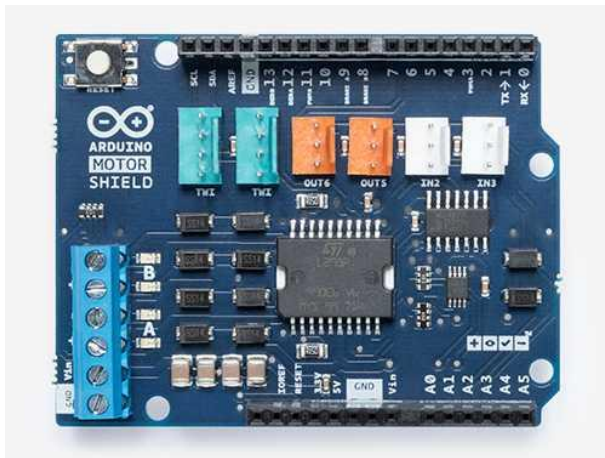
Wires



Wiring

Arduino Shields

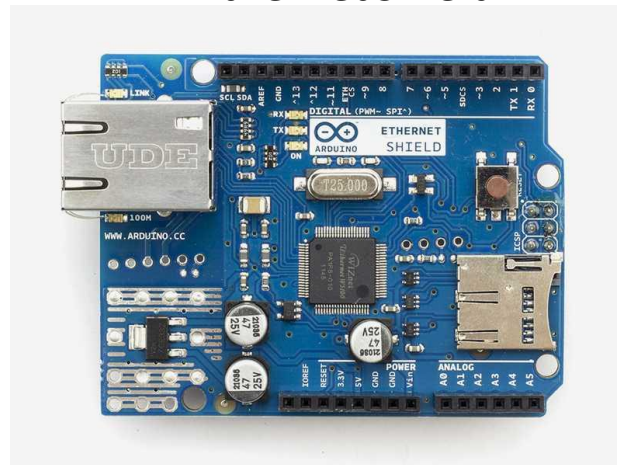
Motor Shield



Relay Shield



Ethernet Shield



RPI HATs

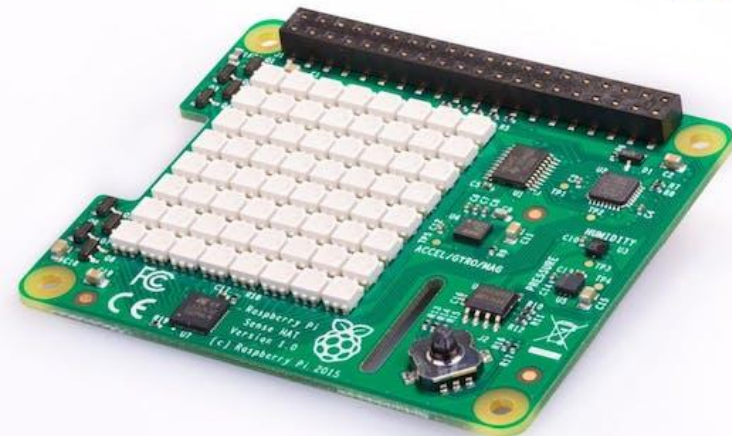
PoE Hat



Lora Hat



Sense HAT



LEGO Build HAT



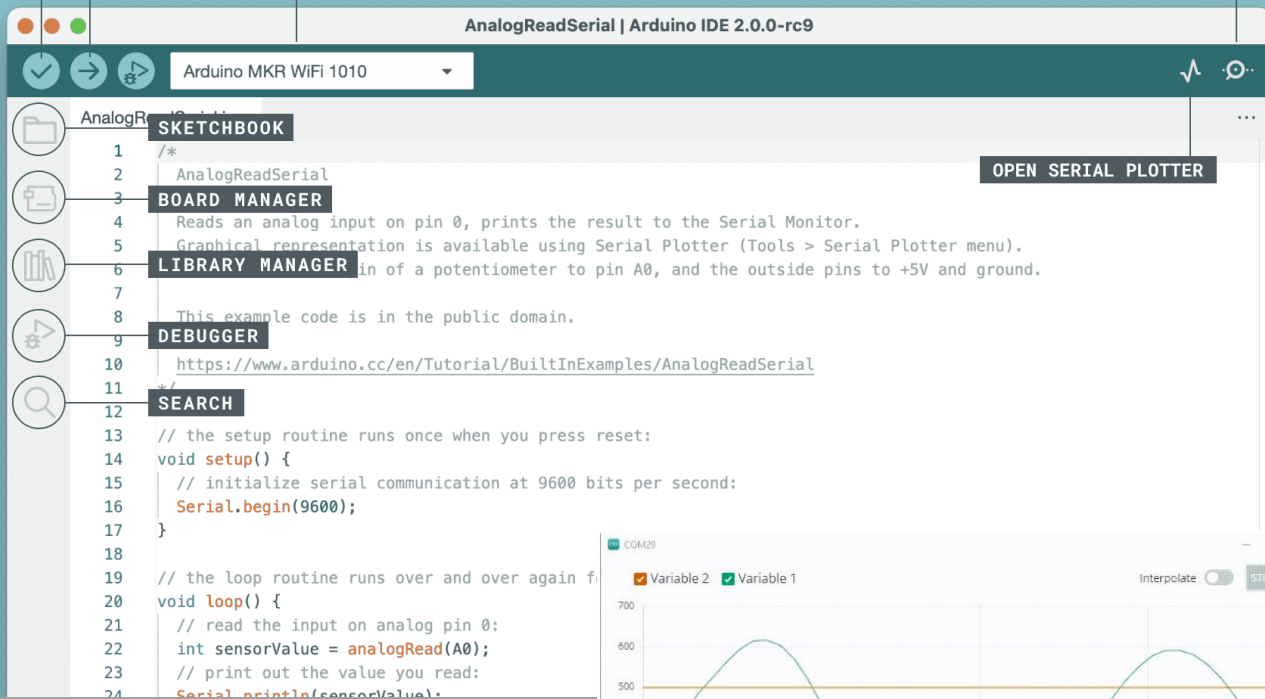
PLATFORMS

Arduino IDE

VERIFY/UPLOAD

SELECT BOARD & PORT

OPEN SERIAL MONITOR



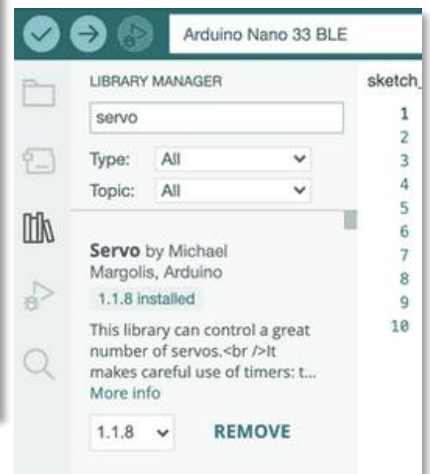
OPEN SERIAL PLOTTER



Output Serial Monitor X

Message (% + Enter to send message to 'Arduino MKR

Hello World!
Hello World!
Hello World!
Hello World!



PlatformIO

```
uint8_t WiFiClass::startProvision(const char *ssid,
{
    tstrM2MAPConfig strM2MAPConfig;

    if (!_init) {
        _init();
    }

    // Enter Provision mode:
    memset(&strM2MAPConfig, 0x00, sizeof(tstrM2MAPConfig));
    strcpy((char *)&strM2MAPConfig.au8SSID, ssid);
    strM2MAPConfig.u8ListenChannel = channel;
    strM2MAPConfig.u8SecType = M2M_WIFI_SEC_OPEN;
    strM2MAPConfig.u8SsidHide = SSID_MODE_VISIBLE;
    strM2MAPConfig.au8DHCPStaticIP[0] = 192;
    strM2MAPConfig.au8DHCPStaticIP[1] = 168;
    strM2MAPConfig.au8DHCPStaticIP[2] = 1;
    strM2MAPConfig.au8DHCPStaticIP[3] = 1;

    if (m2m_wifi_start_provision_mode((tstrM2MAPConfig)
        _status = WL_PROVISIONING_FAILED;
        return _status;
    }

    _status = WL_PROVISIONING;
    _mode = WL_PROV_MODE;

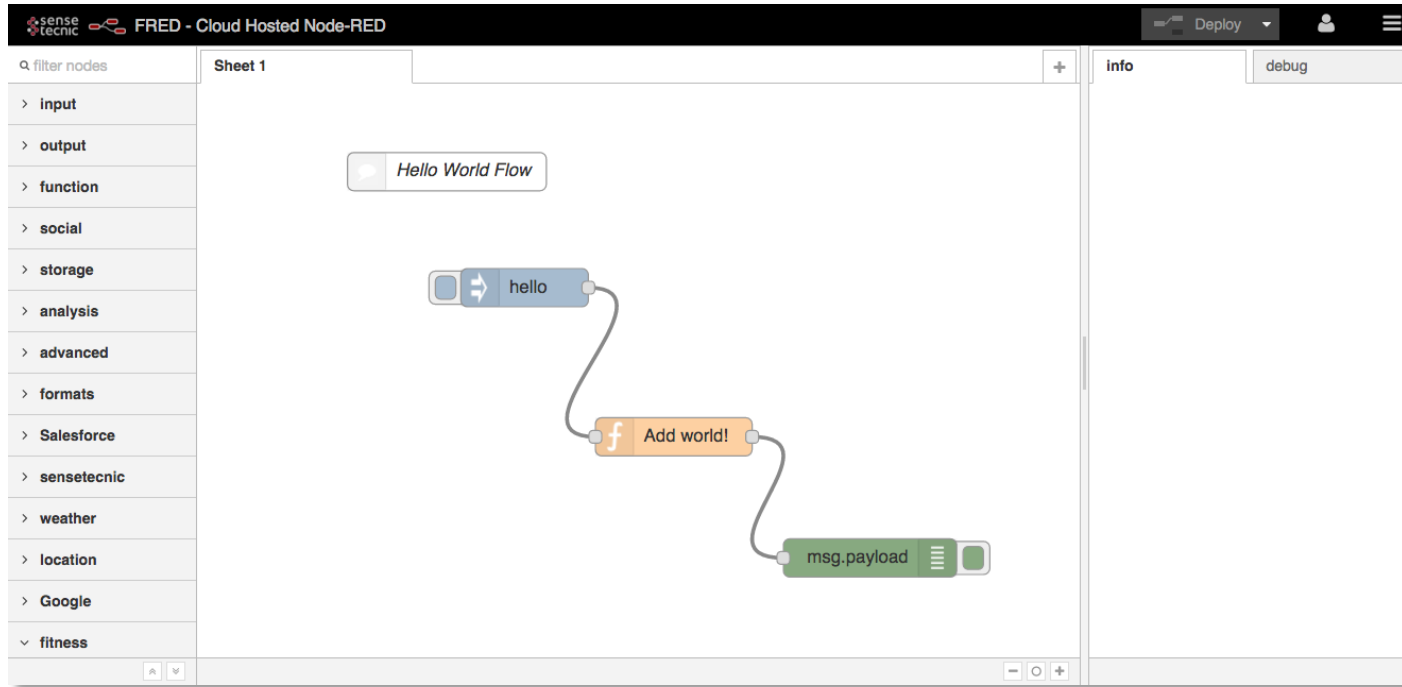
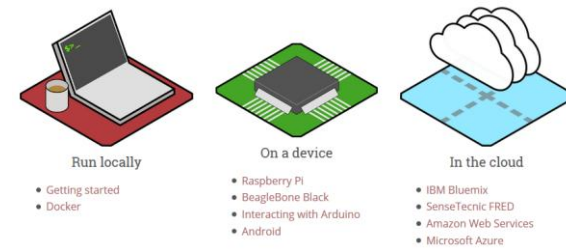
    memset(_ssid, 0, M2M_MAX_SSID_LEN);
    memcpy(_ssid, ssid, strlen(ssid));
    m2m_memcpy((uint8 *)&_localip, (uint8 *)&strM2MAPConfig.au8DHCPStaticIP, 4);
}
```

Frameworks

- [Arduino](#)
- [CMSIS](#)
- [Energia](#)
- [ESP8266 Non-OS SDK](#)
- [ESP8266 RTOS SDK](#)
- [Espressif IoT Development Framework](#)
- [Freedom E SDK](#)
- [FreeRTOS](#)
- [Renesas Flexible Software Package](#)
- [libopencm3](#)
- [Mbed OS](#)
- [PULP OS](#)
- [PULP Runtime Environment](#)
- [PULP SDK](#)
- [Shakti SDK](#)
- [Standard Peripheral Library](#)
- [STM32Cube](#)
- [WD-Firmware](#)
- [WiringPi](#)
- [Zephyr](#)

- Built on top of Microsoft's Visual Studio Code

NodeRED



- Messages

```
msg = {  
  payload:"message payload",  
  topic:"error",  
  location:"somewhere"  
};
```

- Nodes

- Input Nodes (e.g. inject)
- Output Nodes (e.g. debug)
- Processing Nodes (e.g. function)

