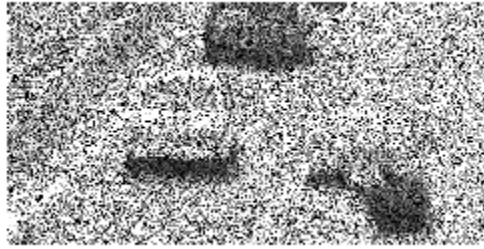


$T = 3$

Coded Snapshots Sum with Gaussian Noise



Snapshot



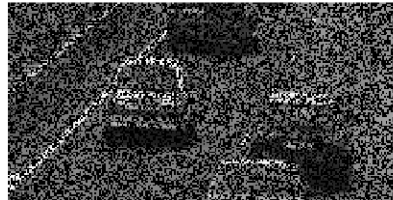
Coded SnapshotCoded Snapshot after Reconstruction



Snapshot



Coded Snapshot



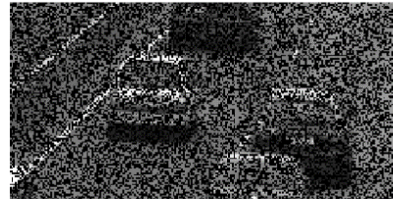
Coded Snapshot after Reconstruction



Snapshot



Coded Snapshot

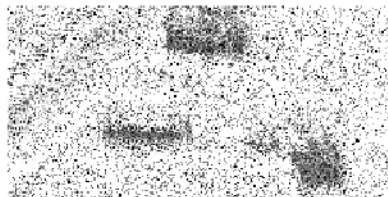


Coded Snapshot after Re



$T = 5$

With Gaussian Noise



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



$T = 7$

With Gaussian Noise



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



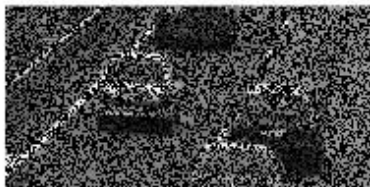
After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot

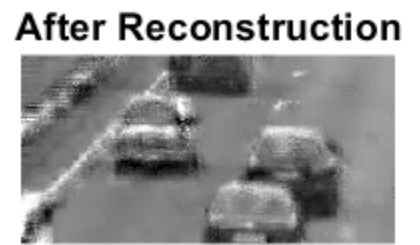
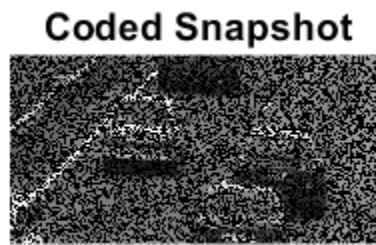


Coded Snapshot



After Reconstruction





Explanation for $\mathbf{Ax} = \mathbf{b}$:

$$E = \sum_1^T F \cdot C_t$$

E is the obtained image. We divide it into patches of 8×8 . Let E^{ij} (and similarly for other matrices) be the patch with left corner at (i,j) coordinate.

Then $E^{ij} = \sum_1^T F^{ij} \cdot C_t^{ij}$.

So, $b = E^{ij}$. Also $F^{ij} = (\psi_{8 \times 8} \otimes \psi_{8 \times 8}) * \theta$, with θ being sparse.
 x (to be recovered) is, therefore, equal to $[\theta_1 \ \theta_2 \ \theta_3]$ (for $T = 3$).

Converting all products to matrix products :

$$A = ([diag(C_1^{ij}) \ diag(C_2^{ij}) \ diag(C_3^{ij})]) * (I_{3 \times 3} \otimes \psi_{8 \times 8} \otimes \psi_{8 \times 8})$$

Where Kronecker products are taken for forming 2-D DCT matrix $diag(M)$ means putting all elements of the matrix along the diagonal row-first wise.

Explanation for error Term:

Consider $\mathbf{y} = \Phi * \mathbf{f} + \boldsymbol{\eta} = \Phi * \Psi * \boldsymbol{\theta} + \boldsymbol{\eta}$. If for each $i = 1$ to m , $\boldsymbol{\eta}_i \sim N(0, \sigma^2)$, with known σ then the squared magnitude of the vector $\boldsymbol{\eta}$ is a chi-square random variable. Hence with very high probability, the magnitude of $\boldsymbol{\eta}$ will lie within 3 standard deviations from the mean, i.e. set $\epsilon \geq 3 * \sigma * \sqrt{m}$.

Therefore, set $\epsilon = 3 * 2 * 8 = 48$.

$$RMSE = ||Reconstructed - Original||_2 / ||Original||_2$$

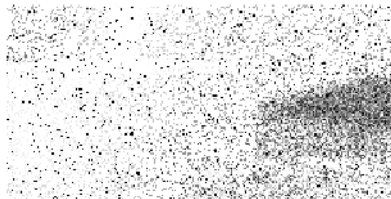
T=3 - 0.1043

T=5 - 0.1371

T=7 - 0.1759

FLAMES

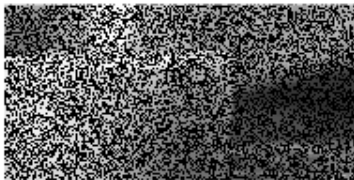
With Gaussian Noise



Snapshot



Coded Snapshot



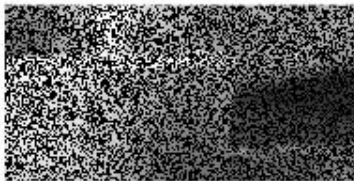
After Reconstruction



Snapshot



Coded Snapshot



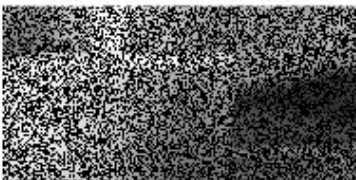
After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction



Snapshot



Coded Snapshot



After Reconstruction

