# Assignment - 8

Title: Bellman-Ford Algorithm

# Problem Statement:

Write a program to implement Bellaman.
- Ford Algorithm using Dynamic Programming and verify the time complexity.

#### Objective :

- Need and significance of Dynamic programming.
   General method of dynamic programming
   Bellman-Ford algorithm to and its analysis.

# Theory:

Dynamic Programming Strategy:

Suppose you have problem which can be divided into independent sub problem to find sol' Divide and conquer is the most strategy to deal with that kind of problem Dynamic Programming is an algorithm design technique for optimization problems: often minimizing or maximing.

Principle of Optimality:

The Principle of optimality states that an optimal sequence of decision has the property that whatever the initial state and decision sequences with regards to the stage resulting from the First decision.

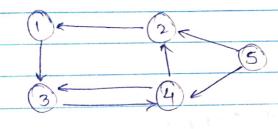


Shortest Path Problem:

Find the shortest paths from a directed acyclic weighted graph G(V, E) starting source to all reachable vertices. Bellman Ford works with negative weighted edges and gives error if negative cycle is found in graph.

Bellman-Ford Algorithm example.

Given the following directed graph.

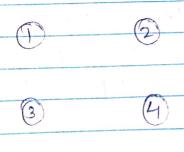


$$(1,3)=6$$

$$(2,1) = 3$$

$$(5,4) = 2$$

cising vertex 5 as the source, we initialize all the other distances to as



| (113)=6 | 1    |    |
|---------|------|----|
| (1,4)=3 | 1    | 3  |
| (211)=3 | V 0> | 0) |
| (3,4)=2 | 1    | 1  |

$$(5,12) = 4$$

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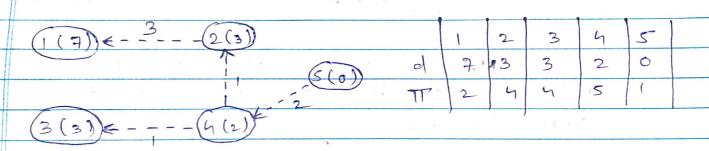
### Iteration 1:-

Edges (Us. 42) and (Us. Un) relax updating the distances to 2 and 4!

|                | 1  | 2 | 3       | 4 | 5 |  |
|----------------|----|---|---------|---|---|--|
| (1) (2(4)) d   | 0) | 4 | 05      | 2 | 0 |  |
| (5(0) -11      |    | 5 | - 1 / - | S | } |  |
| (3) (4(2)) = 2 |    | , |         |   | , |  |

# Iteration 2:

Edges (U2,U1), (U4,U2) and (U4,U3) relax updating the distances to 1,2 f 4 resp. Note edge (U4,U2). Finds a shorter path to Nertex 2 by going through verfex 4.



### Iteration 3:

Edge (112, 11.) relaxes (since a shorter path to Vertex 2 locus found in previous iteration) updating the distance to 1

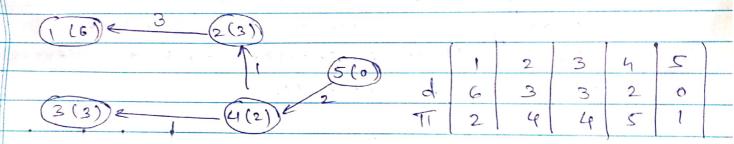
| (1(6))(2(3))    | , 1 | Ť | 2    | 3    | 4 | 5  |   |
|-----------------|-----|---|------|------|---|--|---|
| (5(0))          | d   | 6 | 3    | 3    | 2 | 0  | - |
|                 | T   | 2 | 4    | 4    | 5 | 1  |   |
| (3(3)) = (4(1)) |     |   | 1 19 | 17 % |   | ACTION COMMISSION OF COMMISSIO |   |

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Iteration H: No edge relax

|                 |   |   |   | Angle by deeper property between | calanged being contaminated | and the state of the state of the state of   | Sepport Control |
|-----------------|---|---|---|----------------------------------|-----------------------------|--|-----------------|
| (1(6)) = (2(3)) |   |   |   | - 4 i I                          |                             | and the state of t | •               |
| E(D)            |   | 1 | 2 | 3                                | 4                           | 5  |                 |
|                 | d | 6 | 3 | 3                                | 2                           | 0  |                 |
| (3(3)) =(4(2))  | T | 2 | 4 | 4                                | 5                           | )  |                 |
|                 |   |   |   |                                  |                             | ,  |                 |

The final shortest paths from vertex 5 with corresponding distance is



Magatire cycle checks we now check the relaxation condition one additional time for each edge. If any of the checks pass then there exists a negative.

weight cycle in the graph  $V_3 \cdot d > U_1 d + w(1,3) \Rightarrow 4D6 + 6 = 12$   $V_4 \cdot d > U_1 d + w(1,1) \Rightarrow 2D6 + 3 = 9$   $V_1 d > U_2 d + w(2,1) \Rightarrow 6D3 + 3 = 6$   $V_4 d > U_3 \cdot d + w(3,1) \Rightarrow 2D3 + 2 = 5$   $V_2 d > U_4 \cdot d + w(4,2) \Rightarrow 3D2 + 1 = 3$   $V_3 d > U_4 \cdot d + w(4,3) \Rightarrow 3D2 + 1 = 3$   $V_2 d > U_4 \cdot d + w(5,2) \Rightarrow 3D0 + 4 = 4$   $V_4 d > U_5 \cdot d + w(5,2) \Rightarrow 2D0 + 2 = 2$ 

Vualt. 11

The path to any reachable vertex can be found by starting at the vertex and foll. the TI's back to source.

# Algorithm:

Bellman - Ford (G, W,S)

- 1. Initialize Single Source
- 2. For i=1 to 1G.VI-1
- 3. For each edge (UIV) & G. E
- h. Relax (U,V,W)
- 5. For each edge (UIV) & G.E
- 6. if v.d > u.d + w (u,v)
- 7. return Follse
- 8. return true

# Initialize - Single - Source (G,S)

- 1. For each vertex VEG, V
- 2. vid = 0)
- 3. V. pi = NIL
- 4. S.d = 0

## Relax (U.V.W)

- 1. if v.d > 4.d + w(u,v)
- 2. V.d = u.d + W(4,V)
- 3. V-Pi = U

complexity :-

Basically the algorithm works as follows:

- 1. Initialize ds, Ti's, and set sid = 0 => 0 (v)
- 2. Loop IVI-1 times through all edges cenecking the relaxation condition to compute minimum
  - distances  $\Rightarrow$  (IVI-1) O(E) = O(VE)
- 3. Loop through all edges checking for negative weight cycles which occurs if any of the relaxa. -tion conditions fail -> 0 (E)

The run time of the Bellman-Ford algorithm is 0 (V+VE+E) = 0 (VE)

Conclusion: Bellman Ford algo to find single source shortest path is studied and impleme-nted using Dynamic Programming method.