

# CS20006: Software Engineering

## Module 05: Software Testing & Maintenance

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# Why Test?

- **Ariane 5 Flight 501**



- Un-manned satellite-launching rocket in 1996
- Self-destructed 37 seconds after launch
- Conversion from 64-bit floating point to 16-bit signed integer value had caused an exception (re-used from Ariane 4)
  - The floating point number was larger than 32767
  - Efficiency considerations had led to the disabling of the exception handler

Source: [11 of the most costly software errors in history](#)

# Why Test?

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- **NASA's Mars Climate Orbiter**

- Mission to Mars in 1998, \$125 Million
- Lost in space
- Simple conversion from English units to metric failed

- **EDS Child Support System in 2004**

- Overpay 1.9 million people
- Underpay another 700,000
- US \$7 billion in uncollected child support payments
- Backlog of 239,000 cases
- 36,000 new cases "stuck" in the system
- Cost the UK taxpayers over US \$1 billion
- Incompatible software integration

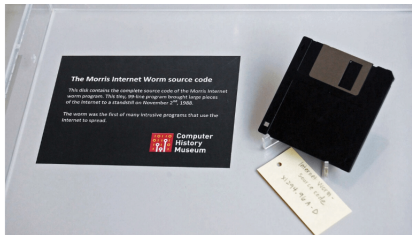
- **Heathrow Terminal 5 Opening**

- Baggage handling tested for 12,000 test pieces of luggage
- Missed to test for *removal of baggage*
- In 10 days some 42,000 bags failed to travel with their owners, and over 500 flights were cancelled

# Why Test?

## • The Morris Worm

- Developed by a Cornell University student for a harmless experiment
- Spread wildly and crashing thousands of computers in 1988 because of a coding error
- It was the first widespread worm attack on the fledgling Internet
- The graduate student, Robert Tappan Morris, was convicted of a criminal hacking offense and fined \$10,000
- Costs for cleaning up the mess may have gone as high as \$100 Million
- Morris, who co-founded the startup incubator Y Combinator, is now a professor at the Massachusetts Institute of Technology
- A disk with the worm's source code is now housed at the University of Boston



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## ● Boeing Crash

- On March 10, 2019, Ethiopian Airlines Flight 302 crashed just minutes after takeoff. All 157 people on board the flight died
- On October of 2018, Lion Air Flight 610 also crashed minutes after taking off
- Both flights involved Boeing's 737 MAX jet
- The software overpowered all other flight functions trying to mediate the nose lift
- Many pilots did not know this system existed - they were not re-trained on 737 MAX Jet

Source: [Boeing Software Scandal Highlights Need for Full Lifecycle Testing](#)

## ● Airbus Crash

- On May 9, 2015, the Airbus A400M crashed near Seville after a failed emergency landing during its first flight
- Electronic Control Units (ECU) on board malfunctioned

Source: [Airbus A400M plane crash linked to software fault](#)

# Testing a Program

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- Input test data to the program
- Observe the output
- Check if the program behaved as expected
- If the program does not behave as expected:
  - Note the conditions under which it failed
  - Debug and correct

# What's So Hard About Testing?

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- Consider `int proc1(int x, int y)`
- Assuming a 64 bit computer
  - Input space =  $2^{128}$
- Assuming it takes 10secs to key-in an integer pair
  - It would take about a billion years to enter all possible values!
  - Automatic testing has its own problems!



# Testing Facts

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- Consumes largest effort among all phases
  - Largest manpower among all other development roles
  - Implies more job opportunities
- About 50% development effort
  - But 10% of development time?
  - How?
- Testing is getting more complex and sophisticated every year
  - Larger and more complex programs
  - Newer programming paradigms

# Overview of Testing

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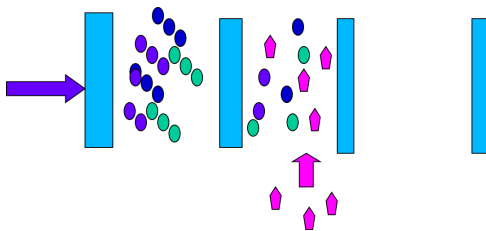
Black Box Testing

White Box Testing

- Testing Activities
  - Test Suite Design
  - Run test cases and observe results to detect failures.
  - Debug to locate errors
  - Correct errors
- Error, Faults, and Failures
  - A failure is a manifestation of an error (also defect or bug)
  - Mere presence of an error may not lead to a failure

# Pesticide Effect

- Errors that escape a fault detection technique:
  - Can not be detected by further applications of that technique



- Assume we use 4 fault detection techniques and 1000 bugs:
  - Each detects only 70% bugs
  - How many bugs would remain?
  - $1000 * (0.3)^4 = 81$  bugs

# Fault Model

- Types of faults possible in a program
- Some types can be ruled out
  - Concurrency related-problems in a sequential program
  - Consider a singleton in multi-thread

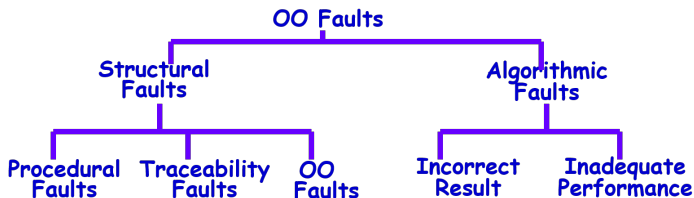
```
#include <iostream>
using namespace std;
class Printer { /* THIS IS A SINGLETON PRINTER -- ONLY ONE INSTANCE */
    bool blackAndWhite_, bothSided_;
    Printer(bool bw = false, bool bs = false) : blackAndWhite_(bw), bothSided_(bs)
    { cout << "Printer constructed" << endl; }
    static Printer *myPrinter_; // Pointer to the Singleton Printer
public:
    ~Printer() { cout << "Printer destructed" << endl; }
    static const Printer& printer(bool bw = false, bool bs = false) {
        if (!myPrinter_) // What happens on multi-thread?
            myPrinter_ = new Printer(bw, bs);
        return *myPrinter_;
    }
    void print(int nP) const { cout << "Printing " << nP << " pages" << endl; }
};
Printer *Printer::myPrinter_ = 0;

int main() {
    Printer::printer().print(10);
    Printer::printer().print(20);
    delete &Printer::printer();
    return 0;
}
```

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# Fault Model

- Fault Model of an OO Program



- Hardware Fault-Model

- Simple:
  - Stuck-at 0
  - Stuck-at 1
  - Open circuit
  - Short circuit
- Simple ways to test the presence of each
- Hardware testing is fault-based testing

# Test Cases and Test Suites

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- Each test case typically tries to establish correct working of some functionality:
  - Executes (covers) some program elements
  - For restricted types of faults, fault-based testing exists
- Test a software using a set of carefully designed test cases:
  - The set of all test cases is called the test suite
- A test case is a triplet  $[I, S, O]$ 
  - I is the data to be input to the system
  - S is the state of the system at which the data will be input
  - O is the expected output of the system (called *Golden*)

# Verification versus Validation

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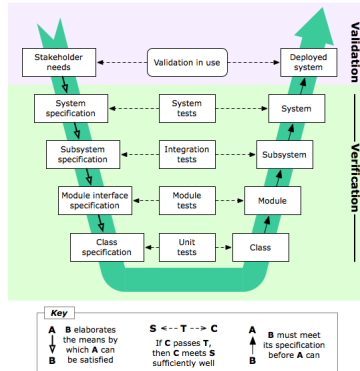
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- **Verification** is the process of determining
  - Whether output of one phase conforms to its previous phase
  - If we are building the system correctly
  - *Verification is concerned with phase containment of errors*
- **Validation** is the process of determining
  - Whether a fully developed system conforms to its SRS document
  - If we are building the correct system
  - *Whereas the aim of validation is that the final product be error free*



# Design of Test Cases

- Exhaustive testing of any non-trivial system is impractical
  - Input data domain is extremely large
- Design an optimal test suite
  - Of reasonable size and
  - Uncovers as many errors as possible
- If test cases are selected randomly
  - Many test cases would not contribute to the significance of the test suite
  - Would not detect errors not already being detected by other test cases in the suite
- Number of test cases in a randomly selected test suite
  - Not an indication of effectiveness of testing
- Testing a system using a large number of randomly selected test cases
  - Does not mean that many errors in the system will be uncovered



# Design of Test Cases

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White Box Testing

- Consider following example
  - Find the maximum of two integers  $x$  and  $y$
- The code has a simple programming error

```
if (x>y)
    max = x;
else
    max = x;
```

- Test suite  $\{(x=3,y=2); (x=2,y=3)\}$  can detect the error
- A larger test suite  $\{(x=3,y=2); (x=4,y=3); (x=5,y=1)\}$  does not detect the error

# Design of Test Cases

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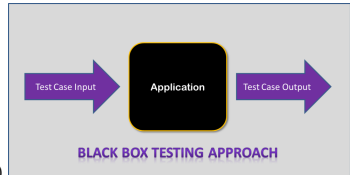
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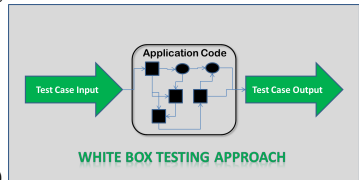
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- Systematic approaches are required to design an optimal test suite
  - Each test case in the suite should detect different errors
- There are essentially three main approaches to design test cases



- **Black-box testing** (*Zero Knowledge*)



- **White-box testing** (*Full Knowledge*)



ZERO KNOWLEDGE



SOME KNOWLEDGE



FULL KNOWLEDGE

- **Grey-box testing** (*Some Knowledge*)

# Why Both BB and WB Testing?

## Black Box Testing

- Impossible to write a test case for every possible set of inputs and outputs
- Some code parts may not be reachable
- Does not tell if extra functionality has been implemented.

## White Box Testing

- Does not address the question of whether or not a program matches the specification
- Does not tell you if all of the functionality has been implemented
- Does not discover missing program logic

# Black-Box Testing

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Black Box Testing

White Box Testing

- Black-box testing is a method of software testing that examines the functionality of an application without peering into its internal structures or workings
- This method of test can be applied virtually to every level of software testing
  - unit
  - integration
  - system and
  - acceptance
- Test cases are designed using only *functional specification* of the software
  - Without any knowledge of the internal structure of the software
- For this reason, black-box testing is also known as *functional testing* or *specification-based testing*

# White-Box Testing

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White Box Testing

- White-box testing is a method of software testing that tests internal structures or workings of an application, as opposed to its functionality
- In white-box testing an internal perspective of the system, as well as programming skills, are used to design test cases
- Designing white-box test cases
  - Requires knowledge about the *internal structure* of software
- White-box testing is also called *structural testing*

# Grey-Box Testing

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White Box Testing

- Grey-box testing is a combination of white-box testing and black-box testing
- The aim of this testing is to search for the defects if any due to improper structure or improper usage of applications

# Black-Box Testing

There are essentially two main approaches to design black box test cases

- Equivalence class partitioning
  - Input values to a program are partitioned into equivalence classes
  - Partitioning is done such that
    - Program behaves in similar ways to every input value belonging to an equivalence class
    - Test the code with just one representative value from each equivalence class – As good as testing using any other values from the equivalence classes
- Boundary value analysis
  - Some typical programming errors occur
    - At boundaries of equivalence classes
    - Might be purely due to psychological factors
  - Programmers often fail to see
    - Special processing required at the boundaries of equivalence classes

# Equivalence Class Partitioning

How do you determine the equivalence classes?

- Examine the input data – Few general guidelines for determining the equivalence classes can be given
  - If the input data is specified by a range of values
    - For example, numbers between 1 to 5000
    - One valid and two invalid equivalence classes are defined
  - If input is an enumerated set of values
    - For example, { a, b, c }
    - One equivalence class for valid input values
    - Another equivalence class for invalid input values should be defined
- A program reads an input value in the range of 1 and 5000
  - Computes the square root of the input number
  - One valid and two invalid equivalence classes are defined
    - The set of negative integers, Set of integers in the range of 1 and 5000, and Integers larger than 5000
  - A possible test suite can be: { -5, 500, 6000 }



# Equivalence Class Partitioning

- Max program reads two non-negative integers and spits the larger one

Equivalence Class	Condition	Test Case
EC 1 (Greater)	$x > y$	(5, 2)
EC 2 (Smaller)	$x < y$	(3, 7)
EC 3 (Equal)	$x = y$	(4, 4)

- QES program reads  $(a, b, c)$  and solves:  $ax^2 + bx + c = 0$

Equivalence Class	Condition	Test Case
Infinite roots	$a = b = c = 0$	(0,0,0)
No root	$a = b = 0; c \neq 0$	(0,0,2)
Single root	$a = 0, b \neq 0$	(0,2,-4)
Repeated roots	$a \neq 0; b * b - 4 * a * c = 0$	(4,4,1)
Distinct roots	$a \neq 0; b * b - 4 * a * c > 0$	(1,-5,6)
Complex roots	$a \neq 0; b * b - 4 * a * c < 0$	(2,3,4)

# Boundary Value Analysis

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- Some typical programming errors occur
  - At boundaries of equivalence classes
  - Might be purely due to psychological factors
- Programmers often fail to see
  - Special processing required at the boundaries of equivalence classes
- Programmers may improperly use  $<$  instead of  $\leq$
- Boundary value analysis
  - Select test cases at the boundaries of equivalence classes
- For a function that computes the square root of an integer in the range of 1 and 5000
  - Test cases must include the values:  $\{ 0, 1, 5000, 5001 \}$
- QES program reads  $(a, b, c)$  and solves:  $ax^2 + bx + c = 0$ 
  - $a = 0$  is a boundary. Check if this test works well
  - $b^2 - 4 * a * c = 0$  is a boundary. Check for the test

# White-Box Testing Strategies

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White Box Testing

- Coverage-based
  - Design test cases to cover certain program elements
- Fault-based
  - Design test cases to expose some category of faults
- There exist several popular white-box testing methodologies
  - Statement coverage
  - Branch coverage
  - Condition coverage
  - Path coverage
  - MC/DC coverage
  - Mutation testing
  - Data flow-based testing

# Coverage-Based Testing Versus Fault-Based Testing

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White Box Testing

- Idea behind coverage-based testing
  - Design test cases so that certain program elements are executed (or covered)
  - Example: statement coverage, path coverage, etc.
- Idea behind fault-based testing
  - Design test cases that focus on discovering certain types of faults
  - Example: Mutation testing

# Stronger, Weaker, and Complementary Testing

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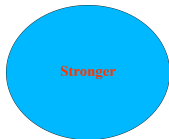
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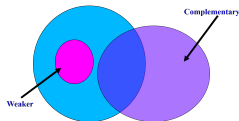
- Stronger and Weaker Testing: Test cases are a super-set of a weaker testing
  - A stronger testing covers at least all the elements of the elements covered by a weaker testing



- Complimentary Testing



- Stronger, Weaker & Complimentary Testing



# Statement Coverage

- Statement coverage methodology
  - Design test cases so that every statement in the program is executed at least once
- The principal idea
  - Unless a statement is executed
  - We do not know if an error exists in that statement
- Observe that a statement behaves properly for one i/p
  - No guarantee that it will behave correctly for all i/p values
- Coverage measurement
  - $\frac{\text{\#executed statements}}{\text{\#statements}}$
  - Rationale: a fault in a statement can only be revealed by executing the faulty statement.  
Consider Euclid's GCD algorithm:

```
int f1(int x, int y) {  
    while (x != y) {  
        if (x>y)  
            x = x - y;  
        else y = y - x;  
    }  
    return x;  
}
```
  - By choosing the test set  $\{ (x=3,y=3), (x=4,y=3), (x=3,y=4) \}$ , all statements are executed at least once

# Branch Coverage

- Test cases are designed such that
  - Different branch conditions – are given true and false values in turn
- Branch testing guarantees statement coverage
  - A stronger testing compared to the statement coverage-based testing
  - Why?

```
1: cin >> x;  
2: if (0 == x)  
3:     x = x + 1;  
4: y = 5;
```

Note that,  $\{(x = 0)\}$  covers lines  $\{1, 2, 3, 4\}$  while  $\{(x = 1)\}$  covers only lines  $\{1, 2, 4\}$ . So with  $\{(x = 0)\}$ , we get 100% statement coverage. But then, did we check for the jump from line 2 to 4 for the false condition? This condition did not get tested. So we need  $\{(x = 0), (x = 1)\}$  for 100% branch coverage and it obviously leads to 100% statement coverage.

How do we get 100% branch coverage for:

```
1: if (true)  
2:     x = x + 1;  
3: y = 5;
```

# Branch Coverage

- Example:

```
0: int f1(int x, int y) {  
1:     while (x != y) {  
2:         if (x > y)  
3:             x = x - y;  
4:             else y = y - x;  
5:     }  
6:     return x;  
7: }
```

Branches: {1-2, 1-6, 2-3, 2-4, 3-5, 4-5, 5-1}

- Test cases for branch coverage can be

- (x=3,y=3): {1-6}: {1, 6}
- (x=4,y=3): {1-2, 2-3, 3-5, 5-1}: {1, 2, 3, 5}
- (x=3,y=4): {1-2, 2-4, 4-5, 5-1}: {1, 2, 4, 5}

- *Adequacy criterion*: Each branch (in CFG) must be executed at least once

- Coverage =  $\frac{\text{\#executed branches}}{\text{\#branches}}$

- Traversing all edges of a graph causes all nodes to be visited

- So test suites that satisfy the branch adequacy criterion for a program also satisfy the statement adequacy criterion for the same program

- The converse is not true

- A statement-adequate (or node-adequate) test suite may not be branch-adequate (edge-adequate)



# All Branches can still miss conditions

- Sample fault: missing operator (negation)

```
digit_high == 1 || digit_low == -1
```

- Branch adequacy criterion can be satisfied by varying only `digit_low`
  - The faulty sub-expression might not be tested
  - Even though we test both outcomes of the branch

# Condition Coverage

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- Test cases are designed such that
  - Each component of a composite conditional expression
    - Given both true and false values
  - Consider the conditional expression
    - $((c1.and.c2).or.c3)$
  - Each of  $c1$ ,  $c2$ , and  $c3$  are exercised at least once
    - That is, given true and false values
- Basic condition testing
  - Adequacy criterion: each basic condition must be executed at least once
- Coverage
  - $$\frac{\#truth\ values\ taken\ by\ all\ basic\ conditions}{2*\#basic\ conditions}$$

# Branch Testing

- Branch testing is the simplest condition testing strategy
  - Compound conditions appearing in different branch statements
    - Are given true and false values
  - Condition testing
    - Stronger testing than branch testing
  - Branch testing
    - Stronger than statement coverage testing

# Condition Coverage

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- Consider a boolean expression having  $n$  components
  - For condition coverage we require  $2^n$  test cases
- Condition coverage-based testing technique
  - Practical only if  $n$  (the number of component conditions) is small
- Commonly known as **Multiple Condition Coverage (MCC)**, **Multicondition Coverage** and **Condition Combination Coverage**

# Modified Condition / Decision (MC/DC)

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- **Motivation**

- Effectively test important combinations of conditions, without exponential blowup in test suite size
- *Important* combinations means: Each basic condition shown to independently affect the outcome of each decision

- **Requires**

- For each basic condition C, two test cases obtained
- Values of all evaluated conditions except C are the same
- Compound condition as a whole evaluates to true for one and false for the other

- **MC/DC** stands for Modified Condition / Decision Coverage

- A kind of **Predicate Coverage** technique

- Condition: Leaf level Boolean expression.
- Decision: Controls the program flow

- **Main Idea**

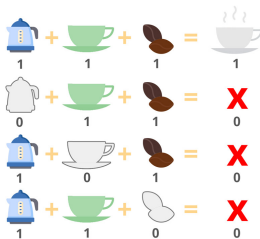
- Each condition must be shown to independently affect the outcome of a decision, that is, the outcome of a decision changes as a result of changing a single condition

# MC/DC in action: The Cup of Coffee Example

To make a cup of coffee, we would need ALL of the following: a kettle, a cup and coffee. If any of the components were missing, we would not be able to make our coffee. Or, to express this another way:

```
if (kettle && cup && coffee)
    return cup_of_coffee;
else
    return false;
```

Or to illustrate it visually:



Test	Inputs			Outputs
	Kettle	Mug	Coffee	Result
1	0	0	0	0
2	0	0	1	0
3	0	1	0	0
4	0	1	1	0
5	1	0	0	0
6	1	0	1	0
7	1	1	0	0
8	1	1	1	1

- Tests 4 & 8 demonstrate that 'kettle' can independently affect the outcome
- Tests 6 & 8 demonstrate that 'mug' can independently affect the outcome
- Tests 7 & 8 demonstrate that 'coffee' can independently affect the outcome

Source: [What is MC/DC?](#)

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# MC/DC in action: Flow Check

A sample C/C++ function with a decision composed of OR and AND expressions illustrates the difference between Modified Condition/Decision Coverage and a coverage of all possible combinations as required by MCC:

```
bool isSilent(int *line1, int *line2)
{
    if ((!line1 || *line1 <= 0) && (!line2 || *line2 <= 0))
        return true;
    else
        return false;
}
```

Or to illustrate it visually:

**Source:** [Modified Condition/Decision Coverage \(MC/DC\)](#)

# Modified Condition / Decision (MC/DC)

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$$\text{Cond} = (((a \parallel b) \&\& c) \parallel d) \&\& e$$

## Condition Coverage Test Cases

*Every condition in the decision has taken all possible outcomes at least once*

#	a	b	c	d	e	Cond
0:	F	F	F	F	F	F
1:	F	F	F	F	T	F
2:	F	F	F	T	F	F
3:	F	F	F	T	T	T
4:	F	F	T	F	F	F
5:	F	F	T	F	T	F
6:	F	F	T	T	F	F
7:	F	F	T	T	T	T
8:	F	T	F	F	F	F
9:	F	T	F	F	T	F
10:	F	T	F	T	F	F
11:	F	T	F	T	T	T
12:	F	T	T	F	F	F
13:	F	T	T	F	T	T
14:	F	T	T	T	F	F
15:	F	T	T	T	T	T

#	a	b	c	d	e	Cond
16:	T	F	F	F	F	F
17:	T	F	F	F	T	F
18:	T	F	F	T	F	F
19:	T	F	F	T	T	T
20:	T	F	T	F	F	F
21:	T	F	T	F	T	T
22:	T	F	T	T	F	F
23:	T	F	T	T	T	T
24:	T	T	F	F	F	F
25:	T	T	F	F	T	F
26:	T	T	F	T	F	F
27:	T	T	F	T	T	T
28:	T	T	T	F	F	F
29:	T	T	T	F	T	T
30:	T	T	T	T	F	F
31:	T	T	T	T	T	T

## MC/DC Coverage Test Cases

*Every condition in the decision independently affects the decision's outcome*

#	a	b	c	d	e	Cond	Cases
1:	T	X	T	X	T	T	21, 23, 29, 31
2:	F	T	T	X	T	T	13, 15
3:	T	X	F	T	T	T	19, 27
4:	T	X	T	X	F	F	20, 22, 28, 30
5:	T	X	F	F	X	F	16, 17, 24, 25
6:	F	F	X	F	X	F	0, 1, 4, 5



# Modified Condition / Decision (MC/DC)

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- **MC/DC is**
  - basic condition coverage (C)
  - branch coverage (DC)
  - plus one additional condition (M): every condition must independently affect the decision's output
- It is subsumed by compound conditions and subsumes all other criteria discussed so far
  - stronger than statement and branch coverage
- A good balance of thoroughness and test size (and therefore widely used)
- MC/DC code coverage criterion is commonly used software testing. For example, [DO-178C software development guidance](#) in the aerospace industry requires MC/DC for the most critical software level (DAL A).
- **MC/DC vs. MCC**
  - MCC testing is characterized as number of tests =  $2^C$ . In coffee example we have 3 conditions (kettle, cup and coffee) therefore tests =  $2^3 = 8$
  - MC/DC requires significantly fewer tests ( $C + 1$ ). In coffee example we have 3 conditions, therefore  $3 + 1 = 4$
  - In a real-world setting, most aerospace projects would include some decisions with 16 conditions or more. So the reduction would be from  $2^{16} = 65,536$  to  $16 + 1 = 17$ . That is,  $65,519/65,536 = 99.97\%$

Source: [What is MC/DC?](#)

# Different Types of Code Coverage

Coverage Criteria	SC	DC	MC/DC	MCC
Every statement in the program has been invoked at least once	X			
Every point of entry and exit in the program has been invoked at least once		X	X	X
Every control statement (that is, branch-point) in the program has taken all possible outcomes (that is, branches) at least once		X	X	X
Every non-constant Boolean expression in the program has evaluated to both a True and False result		X	X	X
Every non-constant condition in a Boolean expression in the program has evaluated to both a True and False result			X	X
Every non-constant condition in a Boolean expression in the program has been shown to independently affect that expression's outcome			X	X
Every combination of condition outcomes within a decision has been invoked at least once				X

- **SC**: Statement Coverage
- **DC**: Decision Coverage
- **MC/DC**: Modified Condition / Decision Coverage
- **MCC**: Multiple Condition Coverage

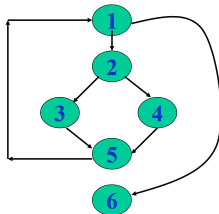
Source: [What is MC/DC?](#)

# Path Coverage

- Design test cases such that
  - All linearly independent paths in the program are executed at least once
- Defined in terms of
  - Control flow graph (CFG) of a program
- To understand the path coverage-based testing
  - we need to learn how to draw control flow graph of a program
- A control flow graph (CFG) describes
  - The sequence in which different instructions of a program get executed
  - The way control flows through the program
- Number all statements of a program
- Numbered statements
  - Represent nodes of control flow graph
- An edge from one node to another node exists
  - If execution of the statement representing the first node – Can result in transfer of control to the other node

# Path Coverage: CFG

```
int f1(int x,int y) {  
1 while (x != y){  
2   if (x>y) then  
3     x=x-y;  
4   else y=y-x;  
5 }  
6 return x;      }
```



- A path through a program:
  - A node and edge sequence from the starting node to a terminal node of the control flow graph
  - There may be several terminal nodes for program
- Any path through the program that introduces at least one new edge (not included in any other independent path) is a *Linearly Independent Path* (LIP).
- A set of paths are linearly independent if none of them can be created by combining the others in some way.
  - It is straight forward to identify linearly independent paths of simple programs; but not so for complicated programs
- LIP in the above example:
  - 1,6
  - 1,2,3,5,1,6
  - 1,2,4,5,1,6

# Path Coverage: LIP

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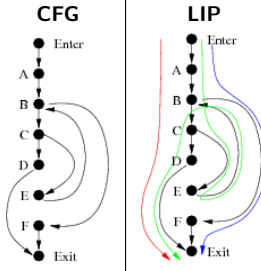
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```
public static boolean isPrime(int n) {  
  A   int i = 2;  
  B   while (i < n) {  
  C     if (n % i == 0) {  
  D       return false  
        }  
  E     i++;  
  F   }  
      return true;  
}
```



Source: [The 'Linearly Independent Paths' Metric for Java](#)

# Path Coverage: McCabe's Cyclomatic Metric

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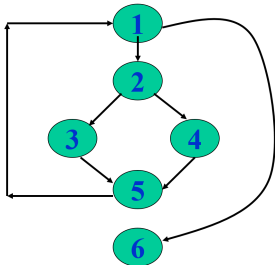
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- An upper bound for the number of linearly independent paths of a program – a practical way of determining the maximum number of LIP
- Given a control flow graph  $G$ , cyclomatic complexity  $V(G)$ :
  - $V(G) = E - N + 2$
  - $N$  is the number of nodes in  $G$
  - $E$  is the number of edges in  $G$
- Alternately, inspect control flow graph to determine number of bounded areas (any region enclosed by a nodes and edge sequence) in the graph  
 $V(G) = \text{Total number of bounded areas} + 1$
- Example: Cyclomatic complexity =  $7 - 6 + 2 = 3 = 2 + 1$



# Path Coverage: McCabe's Cyclomatic Metric

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- McCabe's metric provides a quantitative measure of testing difficulty and the ultimate reliability
- Intuitively, number of bounded areas increases with the number of decision nodes and loops
- The first method of computing  $V(G)$  is amenable to automation:
  - You can write a program which determines the number of nodes and edges of a graph
  - Applies the formula to find  $V(G)$
- The cyclomatic complexity of a program provides:
  - A lower bound on the number of test cases to be designed
  - To guarantee coverage of all linearly independent paths
- A measure of the number of independent paths in a program
- Provides a lower bound
  - for the number of test cases for path coverage
- Knowing the number of test cases required
  - Does not make it any easier to derive the test cases
  - Only gives an indication of the minimum number of test cases required

# Path Coverage: Practical Path Testing

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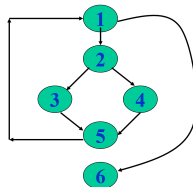
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- Tester proposes initial set of test data using her experience & judgement
- A dynamic program analyzer is used to measure which parts of the program have been tested
- Result used to determine when to stop testing
- Derivation of Test Cases
  - Draw control flow graph.
  - Determine  $V(G)$ .
  - Determine the set of linearly independent paths.
  - Prepare test cases to force execution along each path
- Example: Number of independent paths: 3

```
int f1(int x,int y) {  
1 while (x != y){  
2   if (x>y) then  
3     x=x-y;  
4   else y=y-x;  
5 }  
6 return x;      }
```



- 1,6: test case ( $x=1, y=1$ )
- 1,2,3,5,1,6: test case ( $x=1, y=2$ )
- 1,2,4,5,1,6: test case ( $x=2, y=1$ )



# Path Coverage: An Interesting Application of Cyclomatic Complexity

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- Relationship exists between:
  - McCabe's metric
  - The number of errors existing in the code,
  - The time required to find and correct the errors.
- Cyclomatic complexity of a program:
  - Also indicates the psychological complexity of a program
  - Difficulty level of understanding the program
- From maintenance perspective,
  - Limit cyclomatic complexity of modules To some reasonable value.
- Good software development organizations:
  - Restrict cyclomatic complexity of functions to a maximum of ten or so

# White-Box Testing : Summary

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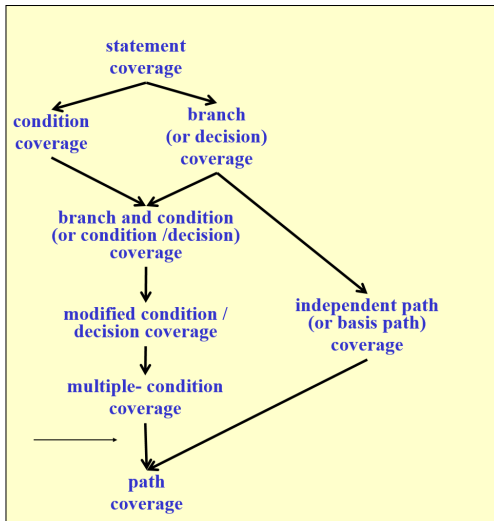
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# Mutation Testing

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- The software is first tested:
  - Using an initial testing method based on white-box strategies we already discussed
- After the initial testing is complete
  - mutation testing is taken up
- The idea behind mutation testing
  - Make a few arbitrary small changes to a program at a time
- Good software development organizations:
  - Restrict cyclomatic complexity of functions to a maximum of ten or so
- Insert faults into a program:
  - Check whether the tests pick them up
  - Either validate or invalidate the tests
  - Example:

```
1: cin >> x;
2: if (0 == x)
3:     x = x + 1;
4: y = 5;
```

Note that,  $\{(x = 0)\}$  covers lines  $\{1, 2, 3, 4\}$  while  $\{(x = 1)\}$  covers only lines  $\{1, 2, 4\}$ . So with  $\{(x = 0)\}$ , we get 100% statement coverage. But then, did we check for the jump from line 2 to 4 for the false condition? This condition did not get tested. So we need  $\{(x = 0), (x = 1)\}$  for 100% branch coverage and it obviously leads to 100% statement coverage.

How do we get 100% branch coverage for:

```
1: if (true)
2:     x = x + 1;
3: y = 5;
```

# Mutation Testing

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White Box Testing

- Insert faults into a program:
  - Check whether the tests pick them up
  - Either validate or invalidate the tests
- Each time the program is changed
  - it is called a **mutated program**
  - the change is called a **mutant**
- A mutated program:
  - Tested against the full test suite of the program
- If there exists at least one test case in the test suite for which:
  - A mutant gives an incorrect result, then the mutant is said to be **dead**
- If a mutant remains **alive**:
  - even after all test cases have been exhausted, the test suite is enhanced to kill the mutant
- The process of generation and killing of mutants
  - can be automated by pre-defining a set of primitive changes that can be applied to the program
- The primitive changes can be
  - Deleting a statement
  - Altering an arithmetic operator
  - Changing the value of a constant
  - Changing a data type, etc.

# Data Flow-Based Testing

**Data Flow Testing** is a type of structural testing. It is a method that is used to find the test paths of a program according to the locations of definitions and uses of variables in the program

- It is concerned with:
  - Statements where variables receive values
  - Statements where these values are used or referenced
- To illustrate the approach of data flow testing, assume that each statement in the program assigned a unique statement number. For a statement number  $S$ :
  - $DEF(S) = \{X \mid \text{statement } S \text{ contains a definition of } X\}$
  - $USE(S) = \{X \mid \text{statement } S \text{ contains a use of } X\}$
  - Example: 1:  $a = b$ ;  $DEF(1) = \{a\}$ ,  $USE(1) = \{b\}$
  - Example: 2:  $a = a + b$ ;  $DEF(2) = \{a\}$ ,  $USE(2) = \{a, b\}$
- If a statement is a loop or if condition then its DEF set is empty and USE set is based on the condition of statement  $s$ .
- Data Flow Testing uses the control flow graph to find the situations that can interrupt the flow of the program.
- Reference or define anomalies in the flow of the data are detected at the time of associations between values and variables. These anomalies are:
  - A variable is defined but not used or referenced
  - A variable is used but never defined
  - A variable is defined twice before it is used

# Data Flow-Based Testing

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White Box Testing

- **Advantages** of Data Flow Testing

- To find a variable that is used but never defined
- To find a variable that is defined but never used
- To find a variable that is defined multiple times before it is use
- Deallocating a variable before it is used

- **Disadvantages** of Data Flow Testing

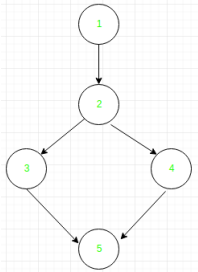
- Time consuming and costly process
- Requires knowledge of programming languages

# Data Flow-Based Testing

- Example:

```
1. read x, y;  
2. if (x > y)  
3. a = x + 1  
   else  
4. a = y - 1  
5. print a;
```

- CFG



- Define/use of variables

Variable	Defined at node	Used at node
x	1	2, 3
y	1	2, 4
a	3, 4	5

# Data Object Categories

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- (d) Defined, Created, Initialized. An object (like variable) is defined when it:
  - appears in a data declaration
  - is assigned a new value
  - is a file that has been opened
  - is dynamically allocated
  - ...
- (k) Killed, Undefined, Released
- (u) Used:
  - (c) Used in a calculation
  - (p) Used in a predicate
  - An object is used when it is part of a computation or a predicate
    - A variable is used for a computation (c) when it appears on the RHS (sometimes even the LHS in case of array indices) of an assignment statement
    - A variable is used in a predicate (p) when it appears directly in that predicate

**Source:** [Topics in Software Dynamic White-box Testing: Part 2: Data-flow Testing](#)



# Data Flow-Based Testing: Definition and Use

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```
1. read (x, y);
2.  z = x + 2;
3.  if (z < y)
4.      w = x + 1;
   else
5.      y = y + 1;
6.  print (x, y, w, z);
```

<i>Def</i>	<i>C-use</i>	<i>P-use</i>
x, y		
z	x	
		z, y
w	x	
y	y	
	x, y, w, z	

- To find a variable that is used but never defined
- To find a variable that is defined but never used
- To find a variable that is defined multiple times before it is use
- Deallocating a variable before it is used