CS 577- Intro to Algorithms

Dynamic Programming

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Divide and Conquer

Recursive approach such that subproblems decrease significantly in size.

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Dynamic Programming

Recursive approach such that:

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- Iteration: build up table of solved instances from easier to harder bottom-up, ad hoc



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Recursive algorithm

```
Input: n \in \mathbb{N}

Output: F_n

1: procedure FIB-REC(n)

2: if n \le 1 then

3: return n

4: else

5: return FIB-REC(n-1) + FIB-REC(n-2)
```

Recursion Tree

Memoization

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Iteration

Memoization

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Iteration

```
1: procedure FIB-IT(n)

2: Fib[0 \cdots n] \leftarrow a new array of size n+1

3: for i=0 to n do

4: if i \leq 1 then

5: Fib[i] \leftarrow i

6: else

7: Fib[i] \leftarrow Fib[i-1] + Fib[i-2]

8: return Fib[n]
```

▶ time: O(n), space: $O(n) \rightarrow O(1)$

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Weighted interval scheduling

Input: meetings $i \in [n]$ specified by start time $s_i \in \mathbb{R}$, end time $e_i \in \mathbb{R}$, and importance $w_i \in \mathbb{R}$.

Ouput: $S \subseteq [n]$ such that no distinct intervals $[s_i, e_i)$ for $i \in S$ overlap and $\sum_{i \in S} w_i$ is maximized.

Principle of Optimality

Subproblem specification

For $J \subseteq [n]$, let $\mathsf{OPT}(J)$ denote the maximum total importance achievable for the subproblem defined by the meetings in J

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▶ For $J \neq \emptyset$, let j^* denote the first meeting in J and $C(j^*)$ the meetings that overlap with j^* .

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- **▶** OPT(*J*) =

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► State reduction: compression of decision history

Bounding the Number of Distinct Subproblems

- State reduction: compression of decision history
- Explicit description of subproblems: few parameters with small ranges

Improved Algorithm

Idea

Sort the meetings earliest start time first, then run prior algorithm.

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- $ightharpoonup OPT(k) = \max(OPT(k+1), w_k + OPT(next(k)))$

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Memory space

▶ *O*(*n*)

Retrieving the Solution

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Recursively

Return both the value and a solution achieving it.

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Iteratively

```
1: procedure Retrieve-Solution
2: S \leftarrow \emptyset
i \leftarrow 1
4: while i \leq n do
            if OPT(i) = OPT(i+1) then
5:
                 i \leftarrow i + 1
6:
7:
            else
                 S \leftarrow S \cup \{i\}
8:
                 i \leftarrow \text{next}(i)
9:
        return S
10:
```