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For X to be a random variable

$$\{\omega \in \Omega : X(\omega) \in B\} \in \mathcal{F}, \ \forall B \in \mathcal{B}$$



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- ► The distribution function satisfies
 - 1. $0 \le F_X(x) \le 1, \ \forall x$
 - 2. $F_X(-\infty) = 0$; $F_X(\infty) = 1$
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- ► We also have

$$F_X(x^+) - F_X(x^-) = F_X(x) - F_X(x^-) = P[X = x]$$

 $P[a < X \le b] = F_X(b) - F_X(a).$

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- Its distribution function, F_X is a stair-case function with jump discontinuities at each x_i and the magnitude of the jump at x_i is equal to $P[X=x_i]$

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We can calculate the probability of any event as

$$P[X \in B] = \sum_{\substack{i: \\ x: \in B}} f_X(x_i)$$



▶ X is said to be a continuous random variable if there exists a function $f_X: \Re \to \Re$ satisfying

$$F_X(x) = \int_{-\infty}^x f_X(x) \ dx$$

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► A continuous rv takes uncountably many distinct values. However, not every rv that takes uncountably many values is a continuous rv

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In particular,

$$P[a \le X \le b] = \int_a^b f_X(t) dt$$



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▶ Binomial: $X \in \{0, 1, \dots, n\}$; Parameters: n, p

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▶ Geometric: $X \in \{1, 2, \dots\}$; Parameter: p, 0 .

$$f_X(x) = p(1-p)^{x-1}, x = 1, 2, \cdots$$



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▶ Gaussian (Normal): Parameters: $\sigma > 0, \mu$.

$$f_X(x) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}, -\infty < x < \infty$$



Functions of a random variable

We next look at random variables defined in terms of other random variables. ▶ Let X be a rv on some probability space (Ω, \mathcal{F}, P) .

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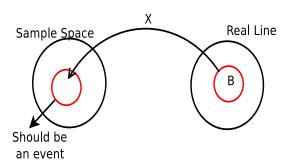
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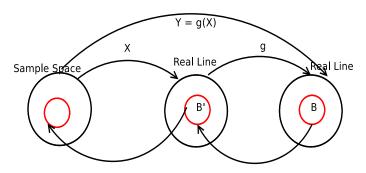
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- ► Thus, in principle, we can find the distribution of *Y* if we know that of *X*

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- ► This tells us how to find df of Y when it is an affine function of X.
- ▶ If X is continuous rv, then, $f_Y(y) = \frac{1}{a} f_X\left(\frac{y-b}{a}\right)$

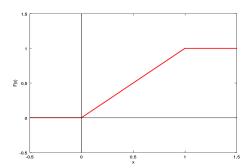


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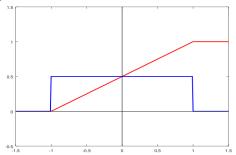


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- ► These are plotted below



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- ▶ Hence $f_Y(y) = \frac{1}{a}$, $y \in [b, a+b]$ and $Y \sim U[b, a+b]$.
- ▶ If $X \sim U[0, 1]$ then Y = aX + b, (a > 0), is uniform over [b, a + b].

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▶ This shows that $Y \sim \mathcal{N}(b, a^2)$



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$$= \sum_{\substack{i: \ g(x_i) = y}} f_X(x_i)$$

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$$f_Y(b+ka) = f_X(k) = \frac{1}{N}, \ 1 \le k \le N$$



► Suppose *X* is geometric:

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▶ This is written as $Y = X^+$ to indicate the function only keeps the positive part.

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- ► Thus, the df of *Y* is

$$F_Y(y) = \begin{cases} 0 & \text{if } y < 0\\ 0.5 & \text{if } y = 0\\ \frac{1+y}{2} & \text{if } 0 < y < 1\\ 1 & \text{if } y > 1 \end{cases}$$

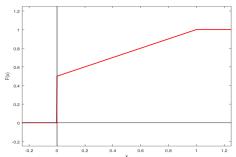
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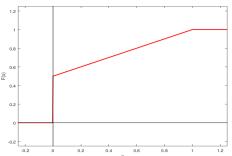
► This is plotted below



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▶ This is neither a continuous rv nor a discrete rv.

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- ightharpoonup Let $Y=X^2$.
- ► For y < 0, $F_Y(y) = P[Y \le y] = 0$ (since $Y \ge 0$)
- ▶ For $y \ge 0$, we can get $F_Y(y)$ as

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▶ This is the general formula for density of X^2 when X is continuous rv.

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► This is an example of gamma density.

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- ▶ Here $\alpha, \lambda > 0$ are parameters.
- ▶ The earlier density we saw corresponds to $\alpha = \lambda = 0.5$:

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- ▶ If $\alpha = 1$, gamma density becomes exponential density.

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$$= 1 - e^{-\lambda y}, y > 0 \text{ (since } X \sim U(0, 1))$$

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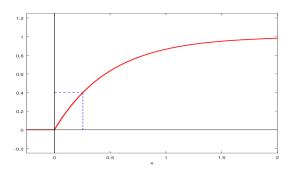
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- ► Thus, the inverse of F is $F^{-1}(z) = \frac{-1}{\lambda} \ln(1-z)$
- ▶ So, we had $Y = F^{-1}(X)$ and the df of Y was F

► We can visualize this as shown below



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- ► Thus, starting with uniform rv, we can generate a rv with a desired distribution.
- Very useful in random number generation. Known as the inverse function method.
- ► Can be generalized to handle discrete rv also. It only involves defining an 'inverse' when F is a stair-case function. (Left as an exercise!)

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- ▶ For 0 < y < 1 we can obtain $F_V(y)$ as

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- Has interesting applications.
 E.g., histogram equalization in image processing

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- ▶ If $X \sim U[0, 1]$ and $Y = F^{-1}(X)$, then Y has df F.
- ▶ If df of X is F and Y = F(X) then Y is uniform over [0, 1].

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- ▶ We have seen a number of examples.
- ► Finally, we look at a theorem that gives a formula for pdf of *Y* in certain special cases

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▶ **Proof**: Since g'(x) > 0, g is strictly monotonically increasing and hence is invertible and g^{-1} would also be monotone and differentiable.

- ▶ Let $g: \Re \to \Re$ be differentiable with $g'(x) > 0, \forall x$.
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 - ► This completes the proof. 🔹 🗸 🔍 🤈 P S Sastry, IISc, E1 222, Aug 2021 36/50

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$$f_Y(y) = f_X(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right|, \ a \le y \le b$$

where
$$a = \min(g(\infty), g(-\infty))$$
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- Essentially, what we need is that for a any y, the equation g(x) = y would have finite solutions and the derivative of g is not zero at any of these points.
- ▶ There are multiple ' $g^{-1}(y)$ ' and we can get density of Y by summing all the terms.

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▶ If g(x) = y has no solution (or no solution satisfying $g'(x) \neq 0$), then at that y, $f_Y(y) = 0$.

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► This is same as what we derived from first principles earlier.

Expectation and Moments of a random variable

We next consider the important notion of expectation of a random variable

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- ➤ To make the above finite and well defined, we can stipulate the following as condition for existence of expectation

$$\sum_{i} |x_i| f_X(x_i) < \infty$$



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► Though we consider only discrete or continuous rv's, expectation is defined for all random variables.

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▶ When an rv takes only finitely many values or when the pdf is non-zero only on a bounded set, the expectation is always finite.

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$$EX = EX^+ - EX^-$$
, if at least one of them is finite

Otherwise EX does not exist.

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$$X^+ = \left\{ \begin{array}{ll} X & \text{if} \;\; X > 0 \\ 0 & \text{otherwise} \end{array} \right.$$

$$X^{-} = \begin{cases} -X & \text{if } X < 0\\ 0 & \text{otherwise} \end{cases}$$

Note that both X^+ and X^- are non-negative. Hence their expectations exist.

(Also,
$$X(\omega) = X^+(\omega) - X^-(\omega), \ \forall \omega$$
).

ightharpoonup Now we define expectation of X by

$$EX = EX^{+} - EX^{-}$$
, if at least one of them is finite

Otherwise EX does not exist.

Now, expectation does not exist only when $EX^+ = EX^- = \infty$

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- ▶ But to get a feel for the more formal definition, we look at a couple of examples.