Recap: Brownian Motion

- ▶ $\{X(t), t \ge 0\}$ is called a Brownian motion if
 - 1. X(0) = 0
 - 2. The process has stationary and independent increments
 - 3. For every t>0, X(t) is Gaussian with mean 0 and variance $\sigma^2 t$
- ▶ If $\sigma^2 = 1$, it is called standard Brownian Motion
- $Y(t) = X(t) + \mu$ is called Brownian motion with a drift

Recap: Some properties

- An important result is that Brownian motion paths are continuous
- ▶ The autocorrelation and autocovariance of the process is

$$R(t_1,t_2) = \sigma^2 \min(t_1,t_2) \ = \mathsf{Cov}(X(t_1),X(t_2))$$

All n^{th} order distributions are Gaussian: $X(t_1), \dots, X(t_n)$ are jointly Gaussian.

Recap: Gaussian Processes

- A continuous-time continuous-state process $\{X(t),\ t\geq 0\}$ is said to be a Gaussian process if for all n and all t_1,t_2,\cdots,t_n , we have that $X(t_1),\cdots,X(t_n)$ are jointly Gaussian.
- ► A general Gaussian process is specified by the mean function and the variance and covariance functions
- ▶ The Brownian motion is an example of a Gaussian Process
- ▶ The Brwonian motion is a Gaussian process with

$$E[X(t)] = 0, \quad \mathsf{Var}(X(t)) = \sigma^2 t, \quad \mathsf{Cov}(X(s), X(t)) = \sigma^2 \min(s, t)$$

Recap: Conditional Densities

▶ For s < t, $f_{X(s)|X(t)}$ is Gaussian and

$$E[X(s)|X(t)] = \frac{s}{t} X(t); \quad \operatorname{Var}(X(s)|X(t)) = \frac{s}{t} (t-s)$$

▶ For s < t, we also showed $f_{X(t)|X(s)}$ is Gaussian with

$$E[X(t) | X(s)] = X(s); Var(X(t)|X(s)) = (t - s)$$

Recap: Hitting Times

ightharpoonup Let T_a denote the first time Brownian motion hits a.

$$Pr[T_a \le t] = \frac{2}{\sqrt{2\pi}} \int_{|a|/\sqrt{t}}^{\infty} e^{-\frac{y^2}{2}} dy$$

▶ By continuity of sample paths,

$$Pr[\max_{0 \le s \le t} X(s) \ge a] = Pr[T_a \le t] = 2Pr[X(t) \ge a]$$

Recap: Geometric Brownian Motion

Let $\{Y(t), t \ge 0\}$ be a Brownian motion with drift. Define

$$X(t) = e^{Y(t)}$$

▶ Then, $\{X(t), t \ge 0\}$ is called geometric Brownian motion. It is useful in mathematial finance

- We have considered three random processes
- ► (discrete-time) Markov Chain
 - Example of Discrete-time discrete-state process
- ► Continuous time Markov Chains (e.g., Poisson Process)
 - Example of continuous-time discrete-state process
- Brownian Motion
 - Example of continuous-time continuous-state process
- We need an example of discrete-time continuous-state process!
- ► Any sequence of continuous random variables would be a discrete-time continuous-state process

- ► In general, any 'stochastic' algorithm would generate discrete-state continuous time process.
- ► If an algorithm uses a random step, then the algorithm would be like

$$X(n+1) = X(n) + \eta_n G(X(n), \xi(n))$$

where $\xi(n)$ would be some random variable which may be dependent on X(n).

- Many algorithms can be written in this general form.
- ▶ The $X(n), n = 0, 1, \cdots$ would be a discrete-time continuous-state stocahstic process
- ▶ We consider an important class of such processes

- ▶ Let $\{X_n, n = 0, 1, \dots\}$ be a discrete-time continuous-state process.
- ▶ It is called a martingale if $E|X_n| < \infty$, $\forall n$ and

$$E[X_{n+1} \mid X_n, \cdots, X_0] = X_n, \ \forall n$$

- One can think of Martingale as a general fair gambling game.
- \blacktriangleright When X_n is a martingale, we have

$$E[X_{n+1}] = E[X_n], \ \forall n$$

Example

- Sequence of sums of independent random variables forms a Martingale
- ightharpoonup Suppose Z_i are iid with $Pr[Z_i = +1] = Pr[Z_i = -1] = 0.5$. Let

$$X_n = \sum_{i=1}^{n} Z_i \quad \Rightarrow \quad X_{n+1} = X_n + Z_{n+1}$$

 $E[X_{n+1} \mid X_n, \cdots] = E[X_n + Z_{n+1} \mid X_n, \cdots] = X_n + E[Z_{n+1} \mid X_n, \cdots] = X_n$

- ightharpoonup Since $EZ_i = 0, \ \forall i$.

ightharpoonup Hence, X_n is a martingale.

Example

- ▶ Suppose X_1, X_2, \cdots are iid with $E[X_i] = 1$.
- \blacktriangleright Let $Z_n = \prod_{i=1}^n X_i$.
- ▶ Since $Z_{n+1} = Z_n X_{n+1}$,

$$E[Z_{n+1}|Z_n, \dots, Z_1] = E[Z_n X_{n+1}|Z_n, \dots, Z_1]$$

$$= Z_n E[X_{n+1}|Z_n, \dots, Z_1]$$

$$= Z_n, \text{ since } X_i i i d, E[X_i] = 1$$

ightharpoonup Thus, Z_n is a martingale

▶ Given $\{X_n, n=1,2,\cdots\}$ and $E|X_n|<\infty, \forall n$, It is called a martingale if

$$E[X_{n+1} \mid X_n, \cdots, X_1] = X_n, \ \forall n$$

► We may often actually show

$$E[X_{n+1} \mid Y_n, \cdots, Y_1] = X_n, \ \forall n$$

Where Y_1, \dots, Y_n determine X_1, \dots, X_n for all n.

► This is justified by the following two identities

$$E[E[X_{n+1} \mid X_n, \dots, X_1, Y_n, \dots, Y_1] \mid X_1, \dots, X_n]$$

= $E[X_{n+1} \mid X_n, \dots, X_1]$

for any X_i, Y_i by properties of conditional expectation

$$E[X_{n+1} \mid X_n, \dots, X_1, Y_n, \dots, Y_1] = E[X_{n+1} \mid Y_n, \dots, Y_1]$$

when Y_1, \dots, Y_n determine X_1, \dots, X_n for all n

A property of Conditional Expectation

► Conditional expectation satisfies

$$E[E[h(X)|Y,Z] | Y] = E[h(X)|Y]$$

Note that all these can be random vectors.

▶ Let

$$g_1(Y,Z) = E[h(X)|Y,Z]$$

$$g_2(Y) = E[g_1(Y,Z)|Y]$$

We want to show $q_2(Y) = E[h(X)|Y]$

• Recall: $g_1(Y, Z) = E[h(X)|Y, Z], g_2(Y) = E[g_1(Y, Z)|Y]$

$$g_2(y) = \int g_1(y, z) f_{Z|Y}(z|y) dz$$

$$= \int \left[\int h(x) f_{X|YZ}(x|y, z) dx \right] f_{Z|Y}(z|y) dz$$

$$= \int h(x) \left[\int f_{X|YZ}(x|y, z) f_{Z|Y}(z|y) dz \right] dx$$

$$= \int h(x) \left[\int f_{XZ|Y}(x, z|y) dz \right] dx$$

$$= \int h(x) f_{X|Y}(x|y) dx$$

Thus we get

$$E[E[h(X)|Y,Z] \mid Y] = E[h(X)|Y]$$

Example

- We saw that partial sums of iid X_i with $E[X_i] = 0$ is a martingale.
- ▶ We can generalize this.
- Let X_1, X_2, \cdots any sequence of random variables.
- ▶ Let $W_i = X_i E[X_i \mid X_1, \dots, X_{i-1}].$
- Now $E[W_i] = 0, \forall i$ though W_i may not be independent.
- ightharpoonup Let $Z_n = \sum_{i=1}^n W_i$.
- We can show that $Z_n, n = 1, 2, \cdots$ is a martingale, assuming that $E[|Z_n|] < \infty$.

► We have

$$Z_n = \sum_{i=1}^n W_i = \sum_{i=1}^n X_i - E[X_i \mid X_1, \dots, X_{i-1}]$$

Note that X_1, \dots, X_n determine $Z_1, \dots, Z_n, \forall n$

▶ We have, $Z_{n+1} = Z_n + X_{n+1} - E[X_{n+1}|X_1, \dots, X_n]$.

$$E[Z_{n+1}|X_1, \cdots, X_n] = E[Z_n + W_{n+1}|X_1, \cdots, X_n]$$

$$= Z_n + E[X_{n+1}|X_1, \cdots, X_n] - E[X_{n+1}|X_1, \cdots, X_n]$$

$$= Z_n$$

ightharpoonup This shows that Z_n is a martingale

- Let N be a positive integer valued random variable with $P[N < \infty] = 1$.
- ▶ N is said to be a stopping time for the process Z_1, Z_2, \cdots if the event [N=n] is determined by the random variable
- If we know the values of Z_1, \dots, Z_n , then we can say whether or not N = n.

 Z_1, \cdots, Z_n

► The idea is that we can decide to stop the process at *N* and the decision to stop cannot anticipate the future

- ▶ Let N be a stopping time for the process $\{Z_n, n \ge 1\}$.
- Define

$$\bar{Z}_n = \left\{ \begin{array}{ll} Z_n & \text{if } n \le N \\ Z_N & \text{if } n > N \end{array} \right.$$

▶ We call $\{\bar{Z}_n, n \geq 1\}$ the stopped process

- ▶ Let $\{Z_n, n \ge 1\}$ be a martingale and let N a stopping time for it.
- ► **Theorem**: The stopped Process is a martingale That is, a stopped martingale is a martingale
- Note that, by definition, $\bar{Z}_1 = Z_1$.
- ▶ So, if the stopped process is a martingale, then,

$$E[\bar{Z}_n] = E[\bar{Z}_1] = E[Z_1], \forall n$$

- ▶ Recall that for a martingale, $E[Z_n] = E[Z_1], \forall n$
- ► The theorem essentially says there is no strategy to have a positive expectation from a fair gambling game.

▶ $\{X_n, n = 0, 1, \cdots\}$ and $E|X_n| < \infty, \forall n$ is called a martingale if

$$E[X_{n+1} \mid X_n, \cdots, X_0] = X_n, \ \forall n$$

▶ It is called a supermartingale if

$$E[X_{n+1} \mid X_n, \cdots, X_0] \le X_n, \ \forall n$$

▶ It is called a submartingale if

$$E[X_{n+1} \mid X_n, \cdots, X_0] \ge X_n, \ \forall n$$

- Note that $E[X_{n+1}] \leq E[X_n]$ for supermartingales and $E[X_{n+1}] > E[X_n]$ for submartingales.
- ▶ In the above, the conditioning random variables can be another sequence Y_i if Y_1, \dots, Y_n determine X_1, \dots, X_n

- ▶ A useful result is the martingale convergence theorem.
 - Martingale convergence theorem: If X_n is a martingale with $\sup_n E|X_n| < \infty$ then X_n converges almost surely to a rv X which will have finite expectation. A positive supermartingale also converges almost surely
- ▶ If X_n are bounded, then the condition is always true and the almost sure convergence implies convergence in the mean.
- ► This is often useful in dealing with many sequences of random variables such as a stochastic algorithm.

Example

- We consider a simple algorithm for a two armed bandit problem.
- 2 arms. Response is binary (1 for reward).
- lacktriangledown d_i prob of reward for arm-i. Do not know d_i
- need to play and find which is better arm.
- We choose arm-1 with prob p(k) (and hence arm-2 with prob (1-p(k)) at iteration k and update p(k) based on the outcome.

- ightharpoonup p(k) denotes probability of choosing arm-1 at k and b(k) denotes the response.
- ▶ Our algorithm for the 2-armed bandit problem is

$$\begin{array}{lll} p(k+1) &=& p(k)+\lambda(1-p(k)) & \text{if arm 1 chosen, } b(k)=1\\ &=& p(k)-\lambda p(k) & \text{if arm 2 is chosen and } b(k)=1\\ &=& p(k) & \text{if } b(k)=0 \end{array}$$

▶ We want to know whether the algorithm converges.

► The algorithm is

$$\begin{array}{lcl} p(k+1) & = & p(k) + \lambda(1-p(k)) & \text{if arm 1 chosen, } b(k) = 1 \\ & = & p(k) - \lambda p(k) & \text{if arm 2 is chosen and } b(k) = 1 \\ & = & p(k) & \text{if } b(k) = 0 \end{array}$$

► We get

$$\begin{split} E[p(k+1) - p(k)|p(k)] \\ &= \lambda(1-p(k)) \; Pr[b(k) = 1, \text{arm 1} \mid p(k)] \\ &- \lambda p(k) \; Pr[b(k) = 1, \text{arm 2} \mid p(k)] \\ &= \lambda(1-p(k)) \; Pr[b(k) = 1 \mid \text{arm 1}, p(k)] \; Pr[\text{arm 1} \mid p(k)] \\ &- \lambda p(k) \; Pr[b(k) = 1 \mid \text{arm 2}, p(k)] \; Pr[\text{arm 2} \mid p(k)] \end{split}$$

► This gives us

$$\begin{split} E[p(k+1) - p(k)|p(k)] &= \lambda (1 - p(k)) \; d_1 \; p(k) \\ &- \lambda p(k) \; d_2 \; (1 - p(k)) \\ &= \; \lambda \; p(k) (1 - p(k)) \; (d_1 - d_2) \\ &\geq \; 0, \quad \text{if} \quad d_1 > d_2 \end{split}$$

$$\Rightarrow E[p(k+1) \mid p(k)] \ge p(k) \Rightarrow E[p(k+1)] \ge E[p(k)], \forall k$$

- ightharpoonup This also shows p(k) is a submartingale.
- ▶ Here, p(k) is bounded and 1 p(k) is a supermartingale.
- ► So, we can conclude, the algorithm converges almost surely

- We considered martingales as an example of discrete-time continuous-state processes
- ▶ Stochastic iterative algorithms generate such processes.
- Martingales can be useful in analyzing convergence of many stochastic algorithms
- ► While we mentioned only discrete-time martingales, one can similarly have continuous-time martingales that satisfy

$$E[X(t)|(X(s'), 0 < s' < s < t] = X(s)$$