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- ► The index need not necessarily represent time. It can represent, for example, space coordinates.

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- ▶ We will denote the random variables as X_t or X(t)

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- As we saw, for a Markov chain, π_0 and P together specify all such joint distributions

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If all X_t are continuous random variables and if all distributions have density functions, then we denote joint density of X_{t_1}, \dots, X_{t_n} by $f_X(x_1, \dots, x_n; t_1, \dots t_n)$

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- One example is the Markovian assumption.
- As we saw, in a Markov chain, the transition probabilities and initial state probabilities would determine all the distributions
- Another such useful assumption is what is called a process with independent increments

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- Now suppose this is a discrete-state process.
- ▶ Then we can write n^{th} order pmf's as

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▶ We only need up to second order distributions

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► Another example of how all finite dimensional distributions of a process can be specified.

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- ▶ Given a random process $\{X(t), t \in T\}$
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$$\eta_X(t) = E[X(t)], \ t \in T$$

▶ We define the autocorrelation of the process by

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)]$$

▶ We define the autocovariance of the process by

$$C_X(t_1, t_2) = E[(X(t_1) - E[X(t_1)])(X(t_2) - E[X(t_2)])]$$

= $R_X(t_1, t_2) - \eta_X(t_1)\eta_X(t_2)$

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- ► This is a rather stringent condition and is often referred to as strict-sense stationarity

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- ▶ This is the definition normally used in mathematics books.

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- ► In this course we take the above as the definition of wide-sense stationary process
- ► When the process is wide-sense stationary, we write autocorrelation as

$$R_X(\tau) = E[X(t)X(t+\tau)]$$

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The autocorrelation function of a wide-sense stationary process is a symmetric function of (single) time variable.

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This gives: $R_X(0) > R_X(\tau)$.

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- ► It plays an important role in analysis of linear systems with random inputs

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- ▶ But, thus is not implied by law of large numbers; X(i) need not be uncorrelated (e.g., Markov chain)

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- ► Such Markov chains are called ergodic chains.

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- One sufficient condition could be that covariance between X(t) and $X(t+\tau)$ decreases fast with increasing τ .

Define

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- ► Hence it is enough if we show

$$\sigma_{\tau}^2 \triangleq E\left[(\eta_{\tau} - \eta)^2 \right] \rightarrow 0$$
, as $\tau \rightarrow \infty$

$$C_X(t_1, t_2) = E[(X(t_1) - \eta)(X(t_2) - \eta)]$$

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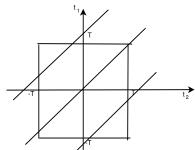
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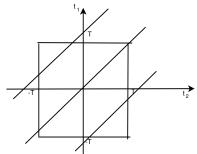
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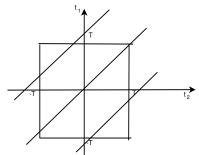


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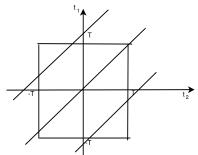
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► This is a sufficient condition for the process being mean-ergodic

► The process is mean-ergodic if

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► Similar relation holds for discrete time processes also.