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$$P[X_n \rightarrow X] = 1 \quad \text{or} \quad P[\limsup |X_n - X| > \epsilon] = 0$$

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- ▶ All the implications are one-way and we have seen counter examples
- ▶ In general, almost sure convergence does not imply convergence in  $r^{th}$  mean and vice versa

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# Recap: Central Limit Theorem

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- ▶ **(Lindberg-Levy) Central Limit Theorem**

$$\lim_{n \rightarrow \infty} P \left[ \tilde{S}_n \leq x \right] = \lim_{n \rightarrow \infty} P \left[ \frac{S_n - n\mu}{\sigma\sqrt{n}} \leq x \right] = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-\frac{t^2}{2}} dt, \quad \forall x$$

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- ▶ For example, binomial rv is well approximated by normal for large  $n$

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 &= 2 \left( 1 - \Phi \left( \frac{n\epsilon}{\sigma\sqrt{n}} \right) \right)
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(because  $\Phi(-x) = (1 - \Phi(x))$  )

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- ▶ This interval is called the  $100(1 - \delta)\%$  confidence interval.

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- ▶ One generally uses an estimate for  $\sigma$  obtained from  $X_i$
- ▶ In analyzing any experimental data the confidence intervals or the variance term is important

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- ▶ While independence is important, all rv need not have the same distribution.
- ▶ Essentially, the variances should not die out.

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- ▶ How do we specify or characterize an infinite collection of random variables?
- ▶ We need the joint distribution of every finite subcollection of them.





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- ▶ For a Markov chain, given the current state, the future evolution is independent of the history of how you reached the current state

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$$P[Y_{n+1} = y | Y_n = x, Y_{n-1}, \dots] = P[X_{n+1} = y - x]$$

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- ▶ Note that  $Y_{n+1} = Y_n + X_{n+1}$  and  $X_{n+1}$  is independent of  $Y_0, \dots, Y_n$ .

$$P[Y_{n+1} = y | Y_n = x, Y_{n-1}, \dots] = P[X_{n+1} = y - x]$$

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# Example

- ▶ Let  $X_i$  be iid discrete rv taking integer values.
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In such applications, it is called a queuing chain.
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$$P = \begin{bmatrix} P(0,0) & P(0,1) \\ P(1,0) & P(1,1) \end{bmatrix} = \begin{bmatrix} 1-p & p \\ q & 1-q \end{bmatrix}$$

- ▶ Now we can calculate the joint distribution, e.g., of  $X_1, X_2$  as

$$\begin{aligned} Pr[X_1 = 0, X_2 = 1] &= \sum_{x=0}^1 Pr[X_0 = x, X_1 = 0, X_2 = 1] \\ &= \sum_{x=0}^1 \pi_0(x) P(x, 0) P(0, 1) \\ &= \pi_0(0)(1-p)p + \pi_0(1)qp \end{aligned}$$



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- ▶ This can easily be seen through a graphical notation.

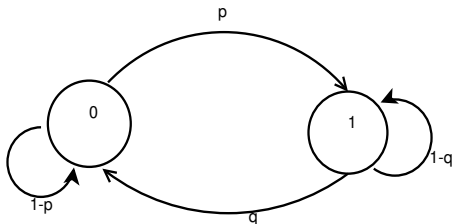
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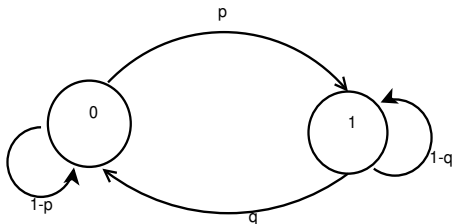




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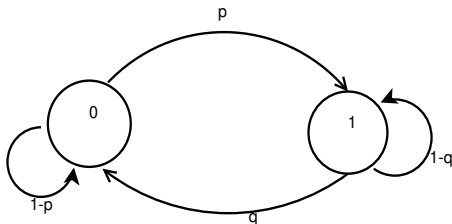


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$$Pr[X_0 = 0, X_1 = 1, X_2 = 1, X_3 = 0] = \pi_0(0)p(1-q)q$$

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- ▶ We may want to know about  $\lim_{n \rightarrow \infty} Pr[X_n = 1]$



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- ▶ A man has 4 umbrellas. carries them from home to office and back when needed. Probability of rain in the morning and evening is same, namely,  $p$ .

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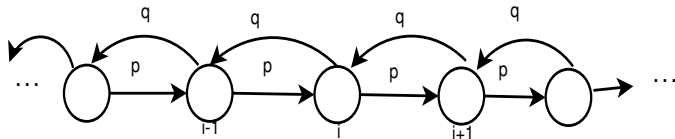
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- ▶  $S = \{0, 1, \dots, 5\}$ . The transition probabilities are

$$P = \left[ \begin{array}{c|ccccc} & 0 & 1 & 2 & 3 & 4 \\ \hline 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1-p & p \\ 2 & 0 & 0 & 1-p & p & 0 \\ 3 & 0 & 1-p & p & 0 & 0 \\ 4 & 1-p & p & 0 & 0 & 0 \end{array} \right]$$

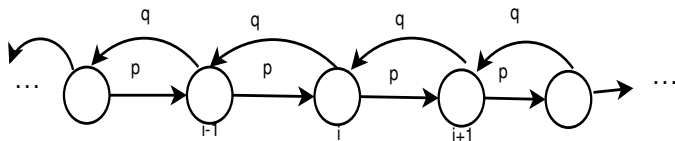
# Birth-Death chain

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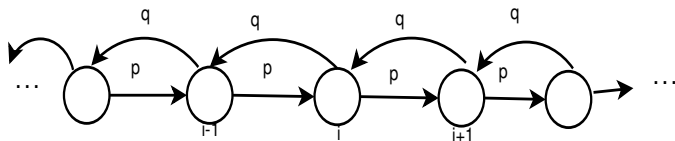
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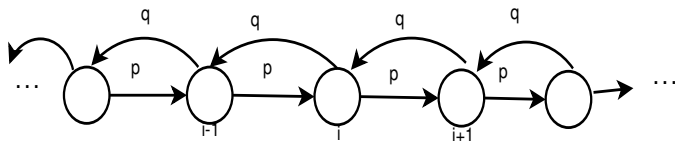


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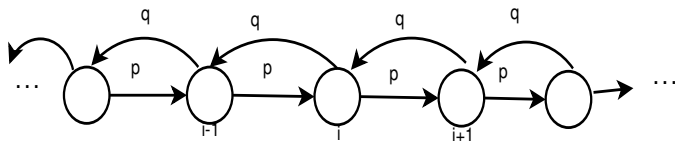
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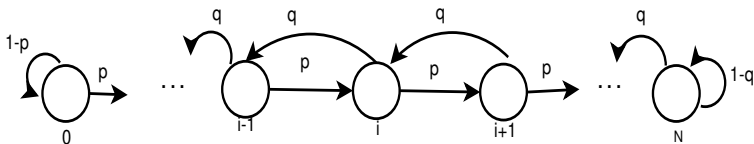
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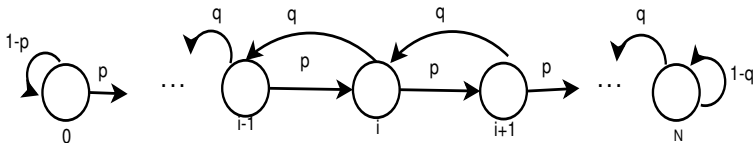


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- ▶ Birth-death chains can also have self-loops on states

- We can have birth-death chains with finite state space also

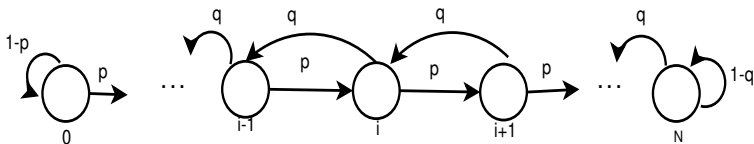


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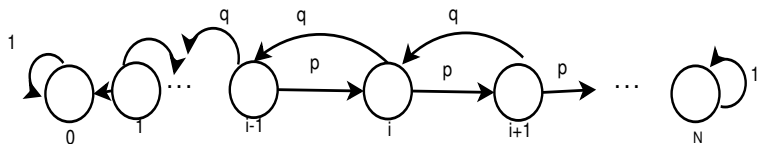
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- ▶ We can say it has 'reflecting boundaries'
- ▶ This chain keeps visiting all the states again and again.

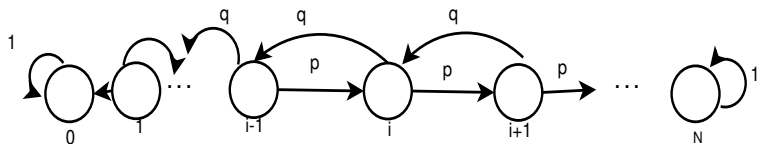
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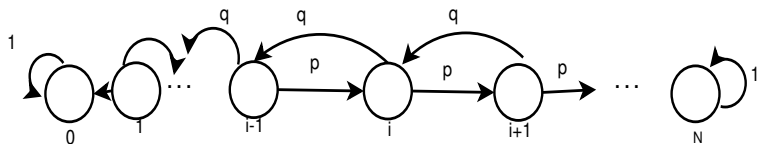
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