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 $\label{eq:when X,Y} \mbox{ are jointly Gaussian, the joint density is given by}$ 

$$f_{XY}(x,y) = \frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-\rho^2}} e^{-\frac{1}{2(1-\rho^2)} \left(\frac{(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} - \frac{2\rho(x-\mu_x)(y-\mu_y)}{\sigma_x\sigma_y}\right)}$$

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- ▶  $X_1, \dots, X_n$  are jointly Gaussian if and only if  $\mathbf{t}^T \mathbf{X}$  is Gaussian for for all non-zero  $\mathbf{t} \in \Re^n$ .

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▶ Shows density of  $X_i$  is Gaussian for each i. For example, if we take  $\mathbf{t} = (1, 0, 0, \dots, 0)^T$  then  $\mathbf{t}^T \mathbf{X}$  would be  $X_1$ .

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► This is a defining property of multidimensional Gaussian density

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▶ Why did we assume A has rank k?

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- ▶ For example, if you take A to be

$$A = \left[ \begin{array}{cccc} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \end{array} \right]$$

then 
$$\mathbf{Y} = (X_1, X_2)^T$$

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- ▶ t<sup>T</sup>X being Gaussian for every non-zero t is a defining property of Gaussian vectors.

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▶ This method is useful for finding distribution of  $S_N$  when we can recognize the distribution from its mgf

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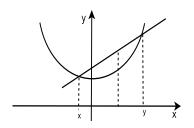
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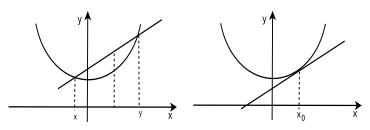
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$$\begin{array}{rcl} g(X) & \geq & g(EX) + \lambda(EX)(X - EX) \\ \Rightarrow & E[g(X)] & \geq & g(EX) + \lambda(EX) \; E[X - EX] = g(EX) \end{array}$$

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► This completes the proof

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- A generalization of Cauchy-Schwartz inequality is Holder inequality

 $\blacktriangleright$  For all p,q with p,q>1 and  $\frac{1}{p}+\frac{1}{q}=1$ 

$$E[|XY|] \le (E|X|^p)^{\frac{1}{p}} (E|Y|^q)^{\frac{1}{q}}$$

(We assume all the expectations are finite)

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▶ First we will show, for p, q > 1 and  $\frac{1}{p} + \frac{1}{q} = 1$ 

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- ▶ Hence, for all  $x_1, x_2 > 0$  and  $0 \le t \le 1$ ,

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lacktriangle Note we do not need knowledge of any moments of  $X_i$  to calculate the bound

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Known as weak law of large numbers

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- ▶ In general one can get an approximate value of expectation of *X* through simulations/experiments

- X is a random variable and we want to find EX.
- ▶ Make multiple independent observations of X. Call them  $X_1, \dots, X_n$ .
- ▶ These are called samples of X.  $S_n = \sum_{i=1}^n X_i$
- $\triangleright \frac{S_n}{n}$  is the sample mean average of all samples.
- ▶  $\frac{S_n}{n}$  has the same expectation as X but has much smaller variance.
- ► Sample mean 'converges' to expectation ('population mean')
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- ▶ In general one can get an approximate value of expectation of *X* through simulations/experiments
- Known as Monte Carlo simulations

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► There are other ways of defining convergence of random variables

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- ► There are different notions of convergence of a sequence of functions to a function.

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- ▶ Or we can ask for  $\int |g_n(x) g_0(x)|^2 dx \to 0$ .
- ► There are multiple notions of convergence that are reasonable for a sequence of functions.
- ► Thus there would be multiple ways to define convergence of sequence of random variables.

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• We only need marginal distributions of individual  $X_n$  to decide whether a sequence converges to a constant in probability

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- ▶ Hence we have  $\frac{S_n}{n} \stackrel{P}{\to} \mu$
- ► Weak law of large numbers says that sample mean converges in probability to the expectation