

On The Bayesian Characterization of Diffusivity Through Linear Heat Losses

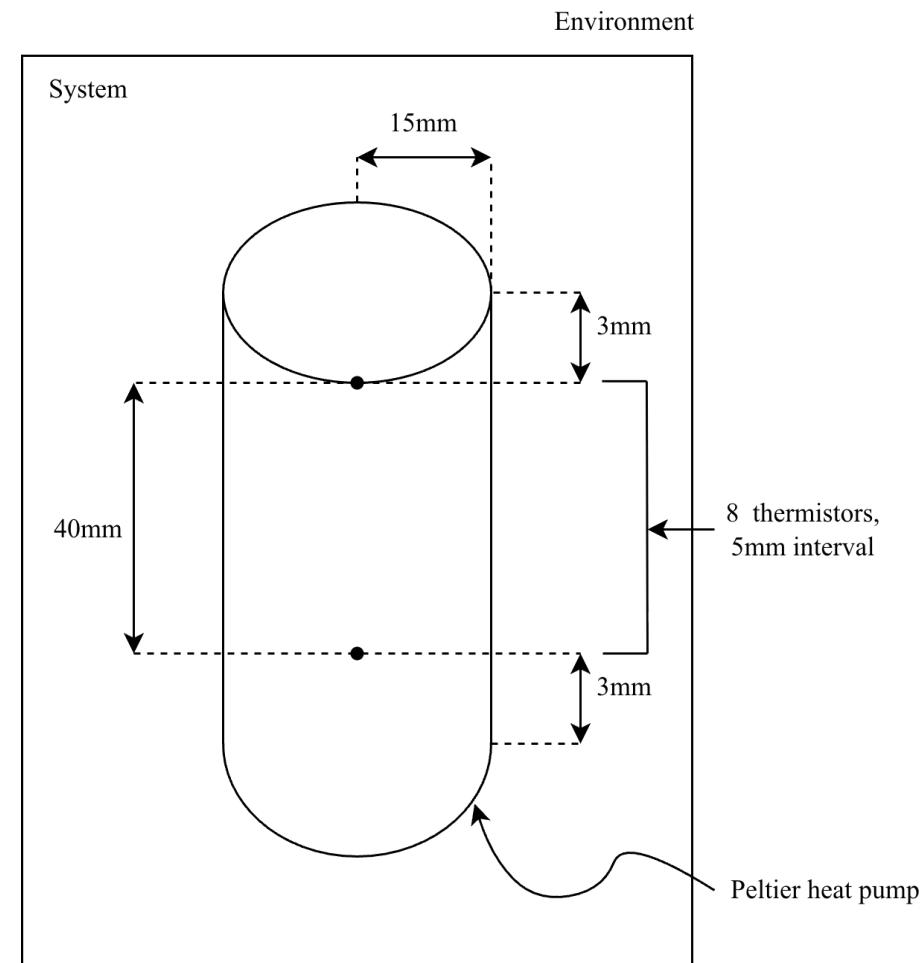
Introduction and Aims

The system is governed by the **1-dimensional heat equation** with a periodic source at the origin, to which we append **Newton's cooling term**.

We perform **Bayesian inference** on four candidate models derived from physical motivations of this experiment.

We use **Hamiltonian Monte Carlo** methods, testing on the **leave-one-out predictive power** of our models.

Does the inclusion of linear heat loss terms **statistically improve** the predictive accuracy of diffusivity measurements in Aluminium?



Experimental Methods

Peltier pump outputting sinusoidal voltage of amplitude 7V. We varied the periods, using 5, 10, 15, 20, 25, 35, 40, 50, 60, and 70s.

Linearity check revealed higher-order harmonics; mitigated by filtering data to the fundamental frequency.

Once some sense of **equilibrium** was observed at each period, we took data over 800s.

Every signal was trimmed to a window with minimal **transient power**.

We choose to explore aluminium since we expected it would have the least ambiguous existing data.

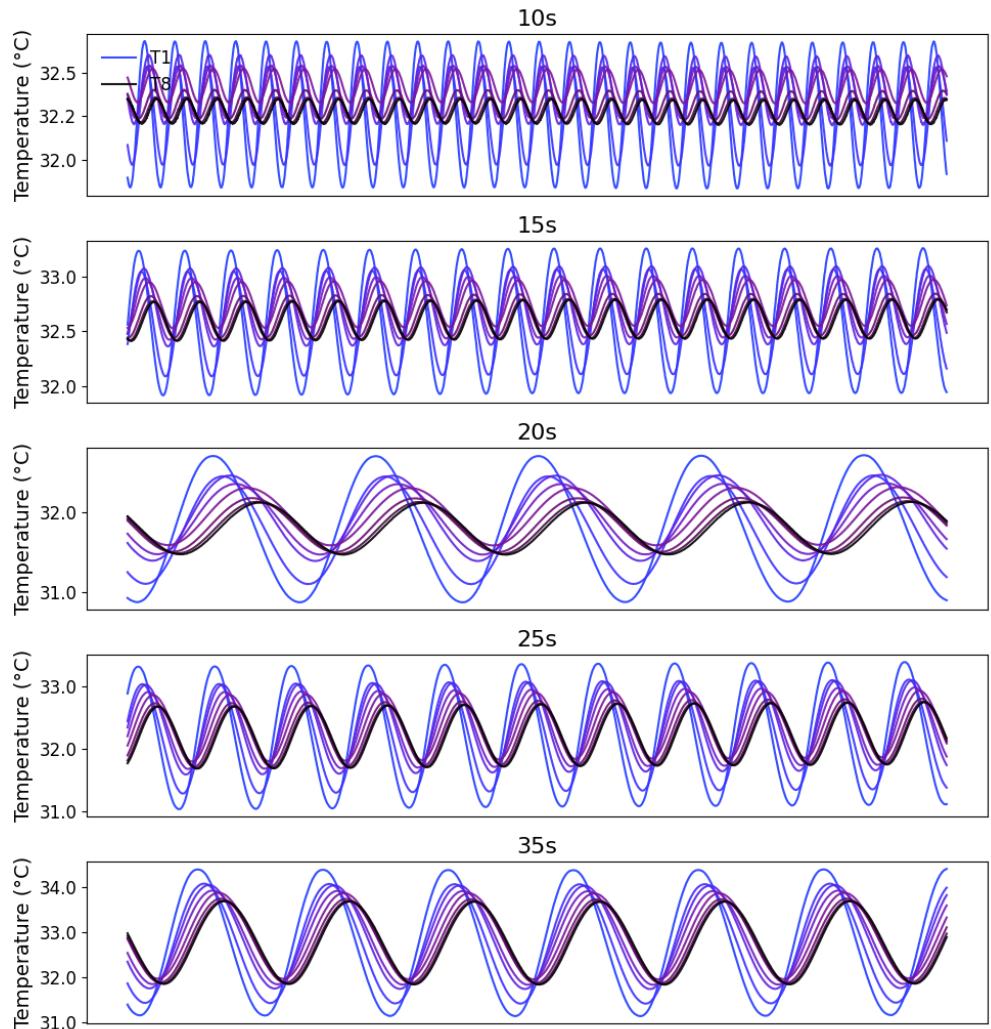


Figure 1, demonstrating clipping of data to minimal transients across the first five periods collected.

Heat Losses

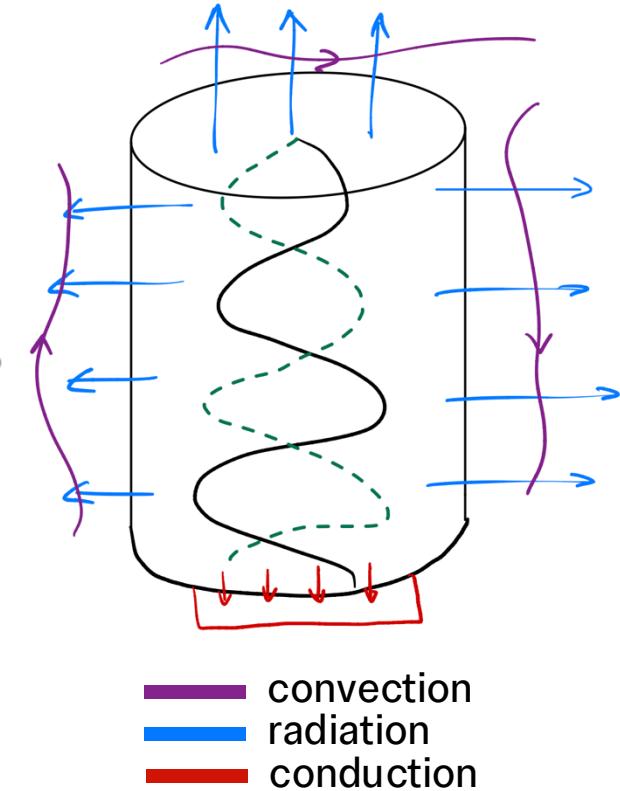
Convection. Heat is transferred to the air surrounding the cylinder. Even in a stagnant box, natural convection occurs as heated air rises due to buoyancy. For small temperature fluctuations, this is laminar.

Radiation. The rod emits infrared energy to the surrounding walls of the box, following from the Stefan-Boltzmann law. We linearized this by a Taylor expansion about the ambient temperature.

$$q_{\text{rad}} = \epsilon\sigma(T^4 - T_{\text{env}}^4)$$

$$\begin{aligned} q_{\text{rad}} &\approx \epsilon\sigma(T_{\text{env}}^4 + 4T_{\text{env}}^3(T - T_{\text{env}}) - T_{\text{env}}^4) \\ &\implies \approx [4\epsilon\sigma T_{\text{env}}^3](T - T_{\text{env}}) \end{aligned}$$

Conduction. Heat "leaks" through the base or mechanical supports holding the cylinder. Since conduction follows Fourier's Law, it is naturally linear.



Candidate Models

General boundary conditions

unless specified otherwise, the conditions are:

$$\begin{aligned}x &= 0, \quad \partial_t Q = \dot{Q}_0 e^{-i\omega t} \\x &= L, \quad \partial_t Q = 0\end{aligned}$$

SimpleForward

basic unbounded 1-dimensional diffusion

$$D\partial_{xx}T = \partial_t T, \iff L\sqrt{\frac{2\omega}{D}} \gg 1$$

FullSolutionNewton

includes convective transfer, linearized Stefan-Boltzmann radiation, conduction as a consequence of Fourier's law

$$D\partial_{xx}T = \partial_t T + \eta(T - T_{\text{env}})$$

FullSolution

Adds the effect of a finite length cylinder with reflection

$$D\partial_{xx}T = \partial_t T, \quad \forall L\sqrt{\frac{2\omega}{D}}$$

FullSolutionRobin

Diffusion equation with heat losses + convective heat loss at the boundary. Measures leakiness.

$$\begin{aligned}D\partial_{xx}T &= \partial_t T + \eta(T - T_{\text{env}}) \\ \text{b.c. } -\kappa\partial_x T &= h(T(L, t) - T_{\text{env}})\end{aligned}$$

Processing and the Hierarchy

To obtain informed priors, we seeded with least-squares minimized a sinusoid to our data → helped solve identifiability issues between phase and diffusivity

We used the No-U-Turn Sampler [1] to adaptively explore the target distribution space, sampling with 4 chains, 1500 draws and 500 tuning steps per frequency model.

Verified convergence of the posterior via the Gelman-Reuben statistic.

To account for potential variations in heat injection, local parameters (amplitude, phase, mean temperature) were allowed to vary per frequency and sensor; the physical constants D and η and were constrained as global parameters shared across the hierarchy.

Models were then ranked by expected log predictive density using leave-one-out cross validation.

This approach provides a rigorous statistical penalty for model complexity, ensuring that the selected model is the one that best captures the underlying physics without overfitting the thermistor noise. ELPD is defined below.

$$\text{ELPD}_{\text{LOO}} = \sum_{i=1}^n \log p(\mathbf{T}_i | \mathbf{T}_{-i})$$

Results and Discussion

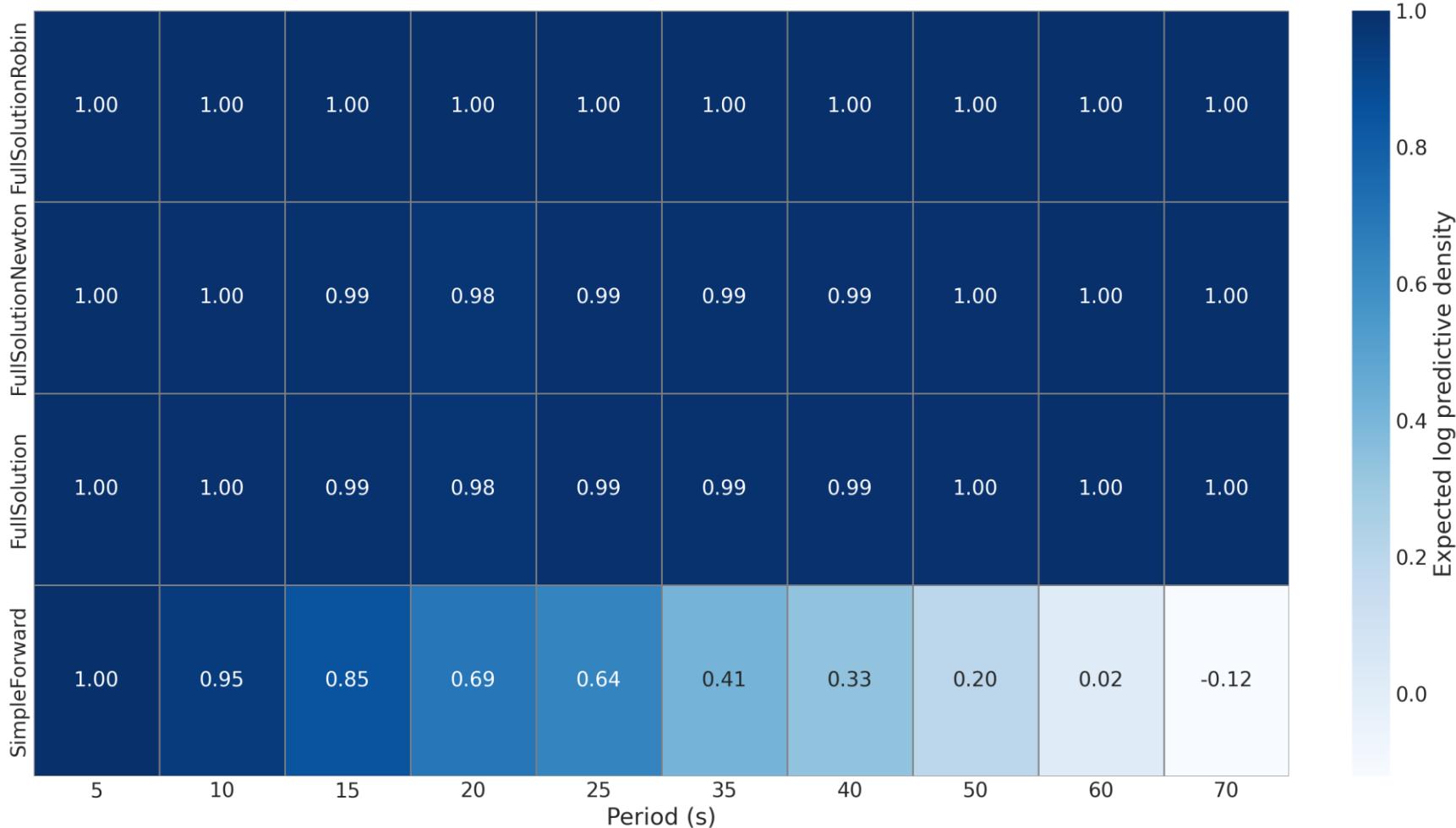


Figure 3. Above is a plot with ELPD score normalized by column for each model across every frequency. All FullSolution candidates perform **comparingly across all frequencies**. SimpleForward sees a **consistently decreasing power** in predictive capacity as expected.

Validating an Isolated System

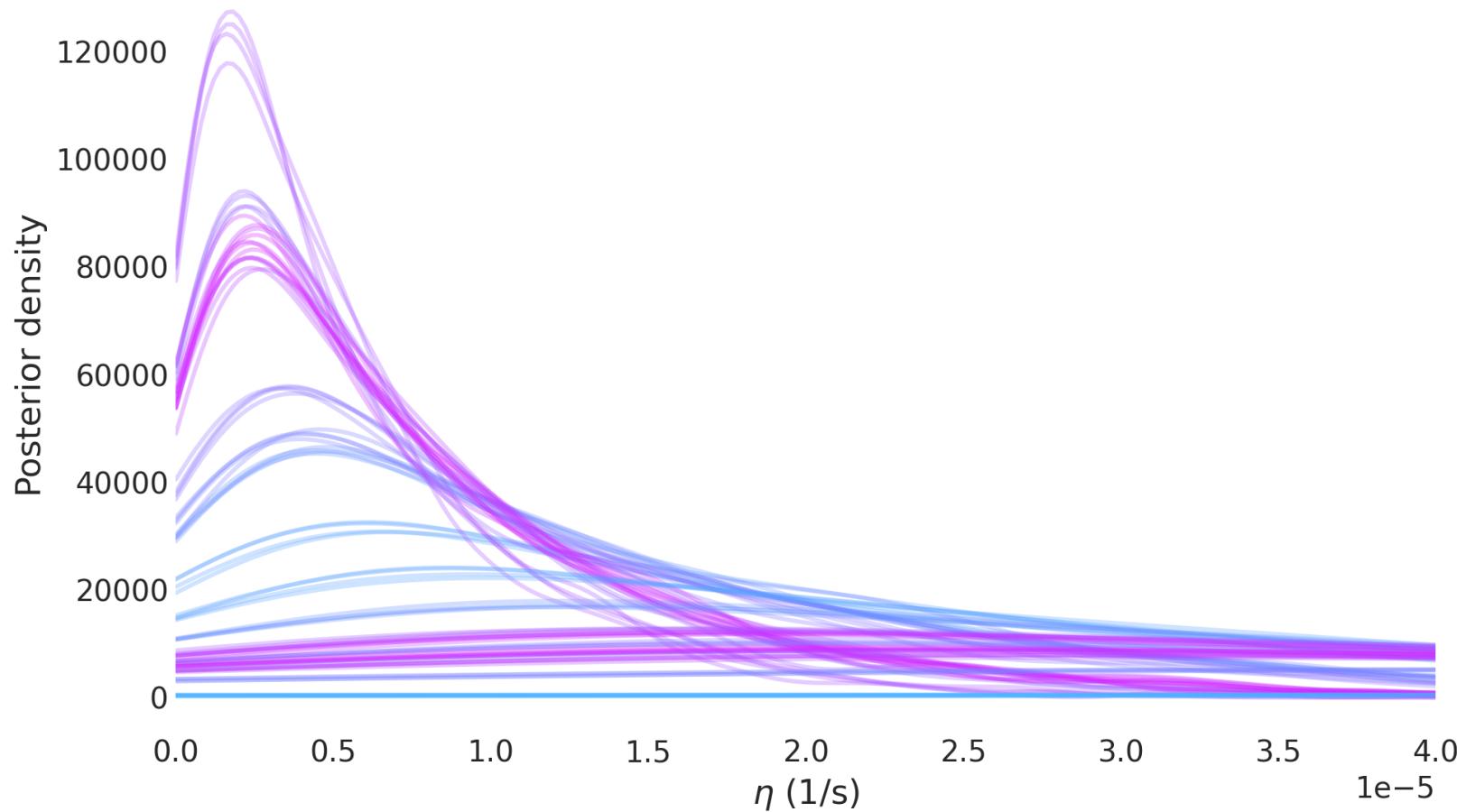


Figure 3. above is a plot of the posteriors across all chains, all frequencies for the FullSolutionNewton and FullSolutionRobin models. The **effective loss coefficient is consistently infinitesimal frequencies → cylinder is thermally isolated during the wave's propagation.**

Results and Discussion

Since both models in Figure 4. agree that η is close to zero, the Bayesian evidence will likely favor the simpler FullSolution or SimpleForward models.

The tight grouping of the lines indicates that chains have converged to a single, consistent physical reality across 10 different frequencies.

The null hypothesis is now that the mean diffusivity for each pairwise model is the same.

On performing Welch's t-tests (since the samples have unequal variances and sizes), we reveal that there is no statistically significantly different results across the models.

Below is a summary of diffusivity statistics for each model, across all frequencies. Percent error is computed relative to the literature value of $D = 9.7 \text{ m}^2/\text{s}$ [3].

Model	\bar{D}	σ_D	$D_{\text{HDI low}}$	$D_{\text{HDI high}}$	$\Delta\%$
FullSolution	9.6×10^{-5}	7.0×10^{-6}	9.5×10^{-5}	9.6×10^{-5}	-1.30
FullSolutionNewton	9.6×10^{-5}	7.0×10^{-6}	9.5×10^{-5}	9.6×10^{-5}	-1.30
FullSolutionRobin	9.7×10^{-5}	8.0×10^{-6}	9.6×10^{-5}	9.7×10^{-5}	-0.43
SimpleForward	1.19×10^{-4}	7.1×10^{-5}	1.17×10^{-4}	1.21×10^{-4}	22.54

References

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