```
class MultistageGraph:
  def __init__(self):
    self.graph = {}
  def add_edge(self, u, v, cost):
    if u not in self.graph:
      self.graph[u] = []
    self.graph[u].append((v, cost))
  def find_shortest_path(self, start, end):
    # Initialize the distance dictionary
    dist = {node: float('inf') for node in self.graph}
    dist[start] = 0
    # Using dynamic programming to find the shortest path
    for i in range(len(self.graph)):
      for u in self.graph:
         if dist[u] != float('inf'):
           for v, cost in self.graph[u]:
             if dist.get(v, float('inf')) > dist[u] + cost:
                dist[v] = dist[u] + cost
    # Check if the end vertex is reachable
    return dist.get(end, float('inf'))
def main():
  graph = MultistageGraph()
  print("Enter edges in the format 'start_vertex end_vertex cost'. Type 'done' to finish:")
  while True:
    user_input = input()
    if user_input.lower() == 'done':
       break
    try:
       u, v, cost = user_input.split()
       cost = int(cost)
       graph.add_edge(u, v, cost)
    except ValueError:
       print("Invalid input. Please enter in the correct format.")
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start = input("Enter the start vertex: ")
end = input("Enter the end vertex: ")

shortest_path_cost = graph.find_shortest_path(start, end)

if shortest_path_cost == float('inf'):
    print(f"No path found from {start} to {end}.")
else:
    print(f"The shortest path cost from {start} to {end} is: {shortest_path_cost}")

if __name__ == "__main__":
    main()

E:\Sthsem\DAA\practicals>forward.py
Enter edges in the format 'start_vertex end_vertex cost'. Type 'done' to finite to the start of th
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```
Enter edges in the format 'start_vertex end_vertex cost'. Type 'done' to finish:
1 2 5
132
2 4 3
2 6 3
3 4 6
3 5 5
3 6 8
471
484
5 7 6
5 8 2
6 7 6
6 8 2
797
8 9 3
done
Enter the start vertex: 1
Enter the end vertex: 9
The shortest path cost from 1 to 9 is: 12
```

```
class MultistageGraph:
  def __init__(self):
    self.graph = {}
  def add_edge(self, u, v, cost):
    if v not in self.graph:
      self.graph[v] = []
    self.graph[v].append((u, cost)) # Reverse the direction for backward approach
  def find_shortest_path(self, start, end):
    # Initialize the distance dictionary
    dist = {node: float('inf') for node in self.graph}
    dist[end] = 0 # Start from the end vertex
    # Using dynamic programming to find the shortest path
    for i in range(len(self.graph)):
      for u in self.graph:
         if dist[u] != float('inf'):
           for v, cost in self.graph[u]:
             if dist.get(v, float('inf')) > dist[u] + cost:
                dist[v] = dist[u] + cost
    # Check if the start vertex is reachable
    return dist.get(start, float('inf'))
def main():
  graph = MultistageGraph()
  print("Enter edges in the format 'start_vertex end_vertex cost'. Type 'done' to finish:")
  while True:
    user_input = input()
    if user_input.lower() == 'done':
      break
    try:
      u, v, cost = user_input.split()
      cost = int(cost)
      graph.add_edge(u, v, cost)
    except ValueError:
      print("Invalid input. Please enter in the correct format.")
```

```
start = input("Enter the start vertex: ")
  end = input("Enter the end vertex: ")
  shortest_path_cost = graph.find_shortest_path(start, end)
  if shortest_path_cost == float('inf'):
    print(f"No path found from {start} to {end}.")
  else:
    print(f"The shortest path cost from {start} to {end} is: {shortest_path_cost}")
if __name__ == "__main__":
  main()
E:\5thsem\DAA\practicals>backward.py
Enter edges in the format 'start_vertex end_vertex cost'. Type 'done' to finish:
2 1 5
3 1 2
4 2 3
6 2 3
4 3 6
5 3 5
6 3 8
7 4 1
8 4 4
7 5 6
8 5 2
7 6 6
8 6 2
9 7 7
9 8 3
Enter the start vertex: 9
Enter the end vertex: 1
The shortest path cost from 9 to 1 is: 12
```

```
import sys
def tsp(graph, start_vertex):
  n = len(graph)
  memo = {}
  def dp(mask, pos):
    if mask == (1 << n) - 1:
       return graph[pos][start_vertex] # Return to starting point
    if (mask, pos) in memo:
       return memo[(mask, pos)]
    ans = sys.maxsize
    for city in range(n):
      if mask & (1 << city) == 0: # If city is not visited
         new_ans = graph[pos][city] + dp(mask | (1 << city), city)</pre>
         ans = min(ans, new_ans)
    memo[(mask, pos)] = ans
    return ans
  return dp(1 << start_vertex, start_vertex)</pre>
def main():
  print("Enter the distance matrix row by row (type 'done' when finished):")
  graph = []
  while True:
    line = input().strip()
    if line.lower() == "done":
       break
    # Convert the input line into a list of integers and append to the graph
    row = list(map(int, line.split()))
    graph.append(row)
  print("Enter the start vertex (0 to {}):".format(len(graph) - 1))
  start_vertex = int(input().strip())
```

```
result = tsp(graph, start_vertex)

print(f"The minimum cost of visiting all cities starting from vertex {start_vertex} is: {result}")

if __name__ == "__main__":

main()

E:\5thsem\DAA\practicals>tsp.py
Enter the distance matrix row by row (type 'done' when finished):
0 10 15 20
5 0 9 10
6 13 0 12
8 8 9 0
done
Enter the start vertex (0 to 3):
```

The minimum cost of visiting all cities starting from vertex 0 is: 35

```
def matrix_chain_order(p):
  n = len(p) - 1 # Number of matrices
  m = [[0] * n for _ in range(n)]
  s = [[0] * n for _ in range(n)] # s[i][j] stores the index of the split
  for length in range(2, n + 1): # Length of the chain
    for i in range(n - length + 1):
      j = i + length - 1
      m[i][j] = float('inf')
      for k in range(i, j):
         q = m[i][k] + m[k+1][j] + p[i] * p[k+1] * p[j+1]
         if q < m[i][j]:
           m[i][j] = q
           s[i][j] = k # Record the index of the split
  return m, s
def print_optimal_parens(s, i, j):
  if i == j:
    print(f"A{i + 1}", end="")
  else:
    print("(", end="")
    print_optimal_parens(s, i, s[i][j])
    print_optimal_parens(s, s[i][j] + 1, j)
    print(")", end="")
def main():
  print("Enter the number of matrices:")
  n = int(input().strip())
  print("Enter the dimensions of matrices (as a space-separated list):")
  dimensions = list(map(int, input().strip().split()))
  if len(dimensions) != n + 1:
    print("Error: Number of dimensions should be one more than the number of matrices.")
    return
  m, s = matrix_chain_order(dimensions)
  print(f"The minimum number of multiplications is: {m[0][n - 1]}")
```

```
print("Optimal parenthesization is: ", end="")
print_optimal_parens(s, 0, n - 1)
print() # For a new line

if __name__ == "__main__":
    main()

E:\Sthsem\DAA\practicals>matrix.py
Enter the number of matrices:
4
Enter the dimensions of matrices (as a space-separated list):
12 5 45 11 10
The minimum number of multiplications is: 3625
Optimal parenthesization is: (A1((A2A3)A4))
```

```
def print_board(board):
  for row in board:
    print(" ".join(row))
  print()
def is_safe(board, row, col, n):
  # Check this column on upper side
  for i in range(row):
    if board[i][col] == 'Q':
       return False
  # Check upper diagonal on left side
  for i, j in zip(range(row, -1, -1), range(col, -1, -1)):
    if j < 0:
       break
    if board[i][j] == 'Q':
       return False
  # Check upper diagonal on right side
  for i, j in zip(range(row, -1, -1), range(col, n)):
    if j \ge n:
      break
    if board[i][j] == 'Q':
       return False
  return True
def solve_n_queens_util(board, row, n):
  if row >= n:
    print_board(board) # Print the board configuration
    return True
  res = False
  for col in range(n):
    if is_safe(board, row, col, n):
       board[row][col] = 'Q' # Place the queen
       res = solve_n_queens_util(board, row + 1, n) or res
       board[row][col] = '.' # Backtrack
```

```
def solve_n_queens(n):
    board = [['.' for _ in range(n)] for _ in range(n)] # Create an empty board
    if not solve_n_queens_util(board, 0, n):
        print("No solution exists")

def main():
    n = int(input("Enter the number of queens (N): "))
    solve_n_queens(n)

if __name__ == "__main__":
    main()

E:\Sthsem\DAA\practicals>n_queen.py
Enter the number of queens (N): 4
    . Q .
    . . Q
    . . .
    . Q .
    . . Q .
    . . Q .
    . . . Q
    . . .
    . . Q .
    . . . Q
```

```
def is_safe(graph, color, vertex, c):
  # Check if the current color assignment is safe for vertex
  for neighbor in graph[vertex]:
    if color[neighbor] == c:
      return False
  return True
def graph_coloring_util(graph, m, color, vertex):
  # If all vertices are assigned a color then return true
  if vertex == len(graph):
    return True
  # Try different colors for vertex
  for c in range(1, m + 1):
    if is_safe(graph, color, vertex, c):
      color[vertex] = c # Assign color c to vertex
      if graph_coloring_util(graph, m, color, vertex + 1):
         return True
      color[vertex] = 0 # Backtrack
  return False
def graph_coloring(graph, m):
  color = [0] * len(graph) # Initialize color assignments
  if not graph_coloring_util(graph, m, color, 0):
    print("Solution does not exist")
    return False
  print("Solution exists: Following are the assigned colors:")
  for vertex in range(len(graph)):
    print(f"Vertex {vertex}: Color {color[vertex]}")
  return True
def main():
  n = int(input("Enter the number of vertices: "))
  graph = [[] for _ in range(n)]
  print("Enter the edges in the format 'u v' (one edge per line). Type 'done' to finish:")
  while True:
    edge = input()
```

```
if edge.lower() == 'done':
      break
    u, v = map(int, edge.split())
    graph[u].append(v)
    graph[v].append(u) # Undirected graph
  m = int(input("Enter the number of colors: "))
  graph_coloring(graph, m)
if __name__ == "__main__":
  main()
E:\5thsem\DAA\practicals>coloring.py
Enter the number of vertices: 4
Enter the edges in the format 'u v' (one edge per line). Type 'done' to finish:
0 1
0 3
1 2
2 3
done
Enter the number of colors: 3
Solution exists: Following are the assigned colors:
Vertex 0: Color 1
Vertex 1: Color 2
Vertex 2: Color 1
Vertex 3: Color 2
```