

## Differential Equation II

### 1. Partial Differentiation

In engineering problems, many quantities depend on more than one variable. Partial differentiation is the process of finding the rate of change of a function with respect to one variable while keeping the other variables constant.

**Definition:** If  $z = f(x, y)$ , then  $\partial z/\partial x$  and  $\partial z/\partial y$  are called partial derivatives.

**Notation:**

$\partial z/\partial x \rightarrow$  Partial derivative of  $z$  with respect to  $x$  ( $y$  constant)

$\partial z/\partial y \rightarrow$  Partial derivative of  $z$  with respect to  $y$  ( $x$  constant)

**Example:**

Let  $z = x^2y + 3xy^2$ .

$\partial z/\partial x = 2xy + 3y^2$

$\partial z/\partial y = x^2 + 6xy$

**Higher Order Partial Derivatives:**

Second and higher order partial derivatives are obtained by differentiating the first order derivatives again with respect to  $x$  or  $y$ . Example:  $\partial^2 z/\partial x^2$ ,  $\partial^2 z/\partial y^2$ ,  $\partial^2 z/\partial x \partial y$ .

### 2. Euler's Theorem on Homogeneous Functions

A function is said to be homogeneous if all its terms are of the same degree. Euler's theorem provides a simple relation between a homogeneous function and its partial derivatives.

**Homogeneous Function:**

A function  $f(x, y)$  is homogeneous of degree  $n$  if  $f(tx, ty) = t^n f(x, y)$ .

**Euler's Theorem Statement:**

If  $z = f(x, y)$  is a homogeneous function of degree  $n$ , then:

$$x(\partial z/\partial x) + y(\partial z/\partial y) = nz$$

**Illustrative Example:**

Let  $z = x^2y + xy^2$ . This is homogeneous of degree 3. By calculating  $\partial z/\partial x$  and  $\partial z/\partial y$  and substituting in Euler's formula, the theorem is verified.

### 3. Maxima and Minima of Functions of Two Variables

In engineering applications, it is often required to find the maximum or minimum value of a function of two variables such as cost, efficiency, stress, or temperature.

**Stationary Points:**

Points where both first order partial derivatives vanish are called stationary or critical points.

**Procedure:**

1. Find  $\partial z/\partial x$  and  $\partial z/\partial y$ .
2. Equate them to zero to find stationary points.
3. Find second order derivatives  $\partial^2 z/\partial x^2$ ,  $\partial^2 z/\partial y^2$  and  $\partial^2 z/\partial x \partial y$ .

**Second Derivative Test:**

Let  $D = f_{xx} f_{yy} - (f_{xy})^2$ .

If  $D > 0$  and  $f_{xx} > 0 \rightarrow$  Minimum

If  $D > 0$  and  $f_{xx} < 0 \rightarrow$  Maximum

If  $D < 0 \rightarrow$  Saddle Point

If  $D = 0 \rightarrow$  Test fails

## 4. Lagrange's Method of Multipliers

Lagrange's method is used when we need to optimize a function subject to a constraint. This method avoids direct substitution and uses an auxiliary variable called a Lagrange multiplier.

### Given:

Objective function:  $f(x, y)$

Constraint:  $g(x, y) = 0$

### Lagrange's Conditions:

$$\frac{\partial f}{\partial x} = \lambda \frac{\partial g}{\partial x}$$

$$\frac{\partial f}{\partial y} = \lambda \frac{\partial g}{\partial y}$$

$$g(x, y) = 0$$

### Steps:

1. Form equations using Lagrange's condition.
2. Solve for  $x$ ,  $y$ , and  $\lambda$ .
3. Substitute values in  $f(x, y)$  to obtain maximum or minimum value.