

Yash Varshney

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GITHUB | LINKEDIN | HACKERRANK | CODECHEF | PORTFOLIO

EDUCATION

ACHARYA NARENDRA DEV COLLEGE
BSc(HONS) ELECTRONICS
GPA: 8.568

August 2018 - June 2021
New Delhi, India

EXPERIENCE

ZEEVE DEEP TECH | SOFTWARE ENGINEER

Noida, India | 29/09/2021 - Currently

EDYST | SOFTWARE INTERN

Remote | June 2021 - August 2021

- Drafting problem statements regarding topics of algorithms, data structures and competitive coding. And Answering queries on Edyst chat and forums.

ACHARYA NARENDRA DEV COLLEGE | STUDENT RESEARCHER

Delhi | June 2019 - July 2019

- Developed a embedded electronic passenger counting system for DTC Bus using Arduino and LDR sensor. It works with the accuracy of 0.85. Developed an API using PHP to receive data from Bus to server.

SKILLS

PROGRAMMING LANGUAGES	Python(4.5/5), JavaScript(4/5), Html, Css, C++(3.5/5)
LIBRARIES/FRAWORKS	Django(3/5), Flask, NodeJs(3.5/5), ReactJs
TOOLS / PLATFORMS	Git(3/5), ROS, Coppeliasim, Linux(4/5)
DATABASES	MySQL, SQLite

PROJECTS / OPEN-SOURCE

FILE SHARING APP | LINK

Django, Html, CSS, SQLite

With this project I tried to create a platform where user can share the file with password protection. Build a security middleware to prevent illegal access.

2048 GAME | LINK

HTML, CSS, JavaScript

Built 2048 game from scratch using HTML, CSS and JavaScript.

R.T.P.C.S | LINK

Arduino, PHP, C++, MySQL

With this project I made a attempt to create full stack IOT product using which passenger of DTC bus can know the number of passenger in incoming DTC bus and location of all incoming DTC bus in real time.

BALL BALANCING PLATORM | LINK

Coppeliasim, Lua, Python, OpenCV

This is simulation based project which built during EyrC 2020-2021. We got 6th rank(AIR) in our assigned theme(Nirakshak Bot). Developed ball balancing model in Coppeliasim from scratch. Applied Image processing to identify ball color, to get ball location on table. Used BFS to make path in maze and PID script to traverse ball on table

RESCUER | LINK

ROS, Python, OpenCV

This is a robotics project which built during EyrC 2019-2020. We got 35th rank(AIR) in our assigned theme(Survey and Rescue). We programmed the drone to work according to the situation.

HONORS & AWARDS

- 3* Coder on CodeChef
- Global 318 rank in March Lunchtime 2021 on CodeChef