**Programming language used :** Python 3.6

**Required Libraries**

* Pip install keras\_facenet
* Pip install mtcnn
* Pip install cv2
* Pip install numpy
* Pip install pickle
* Pip install os
* Pip install import distance
* Pip install math
* Pip install time
* Pip install pyttsx3
* Pip install gtts
* Pip install tempfile
* Pip install playsound

After getting the required libraries for python

**Code operation via:**

Jupyter notebook:

* You can open the code file using pre install jupyter notebook in anaconda service
* Or by getting jupyter notebook separately

**Run the code:**

After installing the jupyter notebook just open the code file in it and the Code will run.

**Final\_Code.ipynb** is the final code which will run the hardware.

**stereo caliberation.ipynb** is for checking the alignment of the camera.