

# Yashveer Jain

[yashveerjain.github.io](https://github.com/yashveerjain) | E-mail: yashveer@terpmail.umd.edu

## EDUCATION

<b>Master of Engineering (Robotics) (GPA:3.97/4)</b> University of Maryland College Park, USA Semester 1: Control System, Robot Modelling, Software Development for Robotics Semester 2: Robot Planning, Robot Perception, Cognitive Robotics, Becoming a Design Thinker Semester 3: NLP (Natural Language Programming), Visual Learning & Recognition, Deep Learning (ongoing)	Expected - July 2024
<b>Bachelor of Engineering (Mechatronics) (GPA:9.44/10)</b> Manipal University Jaipur, Rajasthan, India	July 2016- July 2020

## PROFESSIONAL EXPERIENCE

<b>University of Maryland, College Park, USA</b> <ul style="list-style-type: none"><li><b>Graduate Teaching Assistant (Fall 2023):</b> ENPM667 - Control of Robotic Systems, part of master's program at UMD.</li><li><b>Research Assistant (Spring 2023):</b> At the Perception and Robotics Group, I am engaged in scaling autonomous robots to dimensions smaller than 6 cm, under the guidance of Professor Yiannis Aloimonos.</li></ul>	Aug 2022 - ongoing
<b>Renesas Electronics, USA</b> (Embedded AI Intern) <ul style="list-style-type: none"><li>I work with various sensors and embedded devices such as Renesas RA6 Series and RL78, to train and deploy AI models, enabling them to operate effectively in real-world scenarios.</li></ul>	May 2023 – Aug 2023
<b>AIMonk Labs, Bengaluru, India</b> (Machine learning Engineer) <ul style="list-style-type: none"><li>Worked on a math mojo project, where the task was to use OCR to detect the text and decode the math equation to latex symbols, where I created synthetic latex OCR data that increased the accuracy of the transformer OCR model to 60%.</li><li>Developed an AI solution for a client to detect the cars occupying the parking spots and improvised it by segmentation to detect whether the cars are covered by trees or not, and added additional features to enhance the detection matching, overall resulting in an increase in the accuracy by 20%, on hard positive cases.</li><li>Headed the project for developing a testing environment for AI models, resulting in efficient testing and development of the AI project, by the QA and the dev team.</li></ul>	Aug 2020 - Aug 2022
<b>Swaayatt Robotics, India</b> (Research Intern) <ul style="list-style-type: none"><li>Worked on the tracking algorithm like the Kalman filter, and particle filter with the optical flow, to identify the sustainability of these algorithms on the ADAS system for tracking vehicles and pedestrians.</li></ul>	Jan 2020 – May 2020
<b>Omax Auto, India</b> (Research Intern) <ul style="list-style-type: none"><li>Developed a program for automatic inspection of the part holes using a Machine Vision algorithm, resulting in an increase in the company's production, for higher and faster quality inspection.</li></ul>	May 2019 – July 2019

## PROJECTS

<b>Autonomous Aerial Filming - <a href="#">GitHub</a></b> <ul style="list-style-type: none"><li>In a team of three, I contributed to an architecture for realistic aerial filming using YouTube data and autonomous drone movement, specializing in deep learning for camera pose prediction.</li></ul>	Jan 2023 - May 2023
<b>Leader Follower - <a href="#">GitHub</a></b> <ul style="list-style-type: none"><li>Collaborated with a 5-member team on leader-follower tracking with automatic obstacle detection and coordination for seamless platoon movement, where I worked on computer vision task for tracking.</li></ul>	Jan 2023 - May 2023
<b>UnDeepVO (Unsupervised Deep Learning Visual Odometry) - <a href="#">GitHub</a></b> <ul style="list-style-type: none"><li>Implemented visual odometry using deep learning to handle depth estimation and rotation using a monocular camera.</li></ul>	Jan 2020 - May 2020
<b>Third eye - <a href="#">GitHub</a></b> <ul style="list-style-type: none"><li>A device created for blind people to navigate around the world, using computer vision, and Text2speech.</li></ul>	Oct 2019 - Dec 2019
<b>Search and Rescue Drone – <a href="#">GitHub</a></b> <ul style="list-style-type: none"><li>Developed an AI Drone to detect human beings in hazardous areas and send their locations to the Rescue team.</li></ul>	Jul 2019 - Oct 2019
<b>Industrial Manipulator (2-axis cartesian manipulator) – <a href="#">GitHub</a></b> <ul style="list-style-type: none"><li>Made a cartesian robot for detecting objects and grabbing them if an object is a metal and placing it in a different bin.</li></ul>	Jan 2019 - Apr 2019

## AWARDS AND ACTIVITIES

Secured 1st Runner up in Infosys Competition Techazooka	Dec 2019
Best project award with a cash prize of INR 15K in Manipal Navonmesh 2019	Nov 2019
Achieved runner-up position with INR 25K cash prize in Secure Vikram Award for best project innovation	Nov 2019

## SKILLS AND LANGUAGES

**Production Skills:** Microsoft Office, Linux, Git, Docker, Microsoft10, AWS - Lambda, S3, SQS, EC2; Azure - devops, VM, google Suits.  
**Machine Learning:** Computer Vision, Machine Learning, Deep Learning, NLP, machine learning algorithms (linear regression, SVM, logistic regression), Artificial intelligence Applications and Genetic Algorithms, TensorFlow, PyTorch, Pandas, matplotlib.  
**Programming Languages:** Python, C, C++, Ladder programming, Embedded C, MATLAB Simulink, Flutter & Dart.  
**Others:** ROS(Robot Operating System), ROS2 Humble, SLAM, Heuristic and Graph-based search algorithms, FastApi, Mqtt, Path planning, OpenCV, LQR & LQG Control system, Nexus Vicon, PLC.