FNU YASHWANTH GOWDA

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Aspiring Robotics Engineer with a strong foundation in mechanical engineering and hands-on experience in cybersecurity and compliance. Proficient in CAD/CAM, automation, control systems, and a range of programming languages, including MATLAB, C, Java, and Python. Currently upgrading with a Master's in Robotics and Autonomous Systems, seeking summer internships and full-time roles in industrial robotics, automated vehicles, controls engineering, and automation.

EDUCATION

Master of Science in Robotics and Autonomous Systems (Mechanical and Aerospace Engineering)
 Arizona State University, Tempe, AZ, USA

May 2026

 Bachelor of Engineering in Mechanical Engineering Bangalore Institute of Technology, Bengaluru, India

September 2023

TECHNICAL SKILLS

- CAD Software: Solid Edge, CATIA, Solid Works, CNC Train, and Simulation Tools: Ansys, MATLAB
- Programming Languages: C, Java, Python, Robotic Operating Systems, Arduino, and Microsoft Office
- Cybersecurity Skills: Risk assessment, incident management, security auditing, Patch Management, Cybersecurity Frameworks (ISO 27001, HIPAA, NIST CSF, CCPA), Phishing Attack Monitoring and Security Tools: Microsoft Defender 365, SAFEScore.ai, KDMARC, Infosec IQ (for cybersecurity-focused tasks)

PROFESSIONAL EXPERIENCE

Cybersecurity GRC Intern at CyRAACS

March 2022 - January 2023

- Implemented InfoSec protocols, reducing threat exposure by 50% and ensuring full compliance with ISO, NIST, GDPR.
- Conducted information security audits and collaborated with cross-functional teams to enhance system resilience, contributing to risk mitigation across multiple environments, and demonstrating strong communication and analytical skills.
- Assisted in **risk assessments and incident management**, proactively strengthening cybersecurity frameworks to protect critical infrastructure. Worked closely with clients to tailor security strategies

CATIA Intern at **GTTC**

September 2021 - September 2021

- Designed and optimized 3D models using CATIA V5, improving product development efficiency and precision.
- Performed **Finite Element Analysis (FEA)** and structural simulations, reducing design flaws by **30%** and improving overall product reliability, worked in a **collaborative environment**, and independently handling complex design tasks.

Java with OOPs Intern at IC Solutions

August 2020 - August 2020

- Developed and deployed **data-driven tools**, including Instagram Profile Growth Rate and YouTube Subscriber Growth Calculators, enhancing social media analytics.
- Created **problem-solving applications** such as the Feedback Rating Calculator and Fortune Cookie Simulator, improving software functionality and user engagement.
- Optimized code efficiency, reducing execution time by **15**%, enhancing overall **application performance and scalability**, while collaborating with a **team of developers**, showcasing adaptability, problem-solving, and **time management skills**.

Office Assistant at Sapthagiri Group, Bengaluru, India (Part-Time)

January 2019 – August 2024

- Streamlined daily administrative tasks by scheduling meetings, managing documents, and supporting efficient communication across teams, ensuring seamless office operations.
- Enhanced office processes through data entry, inventory tracking, and vendor coordination, improving efficiency.

ACADEMIC PROJECTS

Effect of Inclination on Natural Convection in Porous Enclosures

February 2021 to August 2021

Performed thermal analysis with ANSYS to investigate heat transfer in porous enclosures, designing thermal management systems for robotics enclosures.

Microcontroller-Based Line Follower Automated Guided Vehicle

August 2021 to August 2022

Created an automated guided vehicle (AGV) using Arduino, incorporating sensors for transporting materials within a factory, aimed at enhancing automation in manufacturing industries, showcasing skills in automation and real-time control systems, logistics and industrial automation.

Debris Detection using Swarm Robots

August 2024 to December 2024

Designed and simulated a decentralized swarm robotics system using MATLAB, implemented SLAM algorithms to facilitate efficient navigation & debris detection & confirmed the swarm's capability to work together autonomously in mapping debris

Autonomous Warehouse Patrolling Robot

January 2025 to May 2025

This project demonstrates a scalable and low-cost robotic solution for structured warehouse environments. It uses multi-sensor fusion (LiDAR, IMU, Depth) and layered ROS 2 control architecture to enable fully autonomous patrols.

COMMUNITY ENGAGEMENT/EXTRACURRICULAR ACTIVITIES

Ira A Fulton Schools of Engineering – Arizona State University

October - November 2024

Volunteer for Southwest Robotics Symposium (SWRS) 2024, Assisted in event organization.

• Cognition, Bengaluru

Participated in humanitarian initiatives, including food donation drives and COVID-19 awareness campaigns.