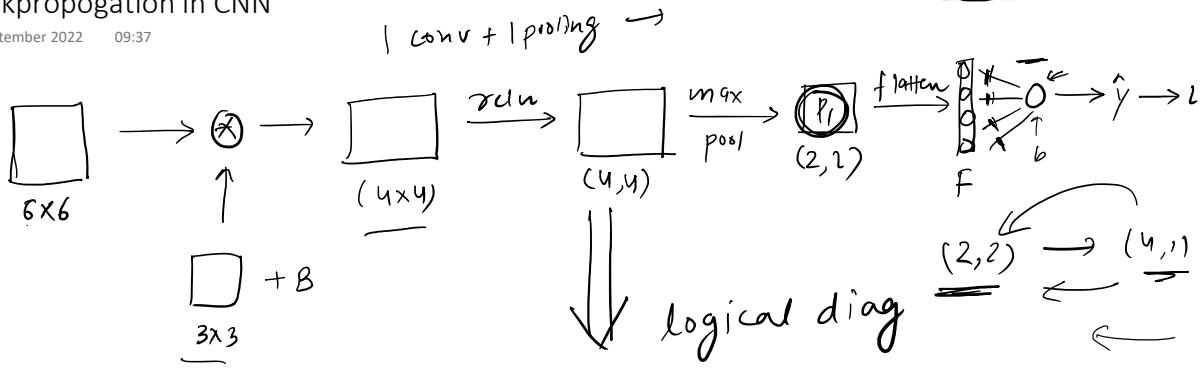


## Lee-48 Backpropagation-II

### Backpropagation in CNN

15 September 2022 09:37



### Forward Prop

$$z_1 = \text{conv}(x, w_1) + b_1$$

$$A_1 = \text{relu}(z_1)$$

$$P_1 = \text{maxpool}(A_1)$$

$$F = \text{flatten}(P_1)$$

$$z_2 = w_2 F + b_2$$

$$A_2 = \sigma(z_2)$$

$$L = \frac{1}{m} \sum_{i=1}^m [-y_i \log(A_2) - (1-y_i) \log(1-A_2)]$$

### 6 derivatives

$$\left[ \frac{\partial z_2}{\partial F} \right] = w_2 \rightarrow$$

Shape?  $\rightarrow (F)$

$$\frac{\partial F}{\partial P_1}$$

no trainable parameters

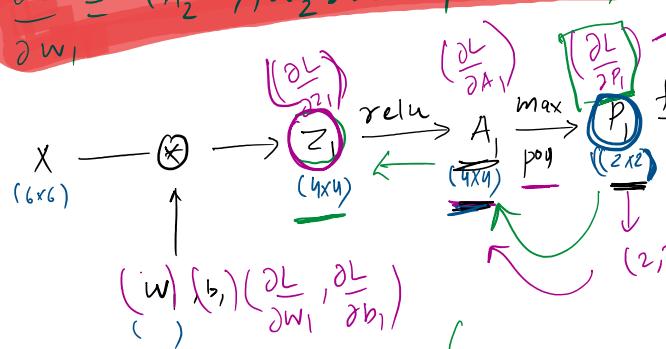
$$\text{conv}(x, \frac{\partial L}{\partial z_1})$$

$$\frac{\partial L}{\partial w_1} = \left[ \frac{\partial L}{\partial A_2} \times \frac{\partial A_2}{\partial z_2} \frac{\partial z_2}{\partial F} \frac{\partial F}{\partial P_1} \frac{\partial P_1}{\partial A_1} \frac{\partial A_1}{\partial z_1} \frac{\partial z_1}{\partial w_1} \right] \frac{1}{5}$$

$$\frac{\partial L}{\partial b_1} = \left[ \frac{\partial L}{\partial A_2} \frac{\partial A_2}{\partial z_2} \frac{\partial z_2}{\partial F} \frac{\partial F}{\partial P_1} \frac{\partial P_1}{\partial A_1} \frac{\partial A_1}{\partial z_1} \frac{\partial z_1}{\partial b_1} \right]$$

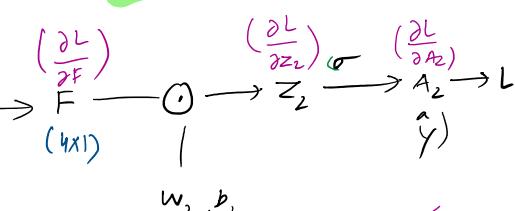
reshape( $P_1$ .shape)

$$\frac{\partial L}{\partial w_1} = (A_2 - y) w_2 \cdot \text{reshape}(P_1, \text{shape})$$



$$\begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix}$$

→  $P_1$  কে flatten করে  $F$  প্রস্তুতি নাম, back-prop এর জন্য  $P_1$  এর শালনা derivative করলে,  $F$  কে  $P_2$  এর জন্য আমলা।  $(2,2) \rightarrow (4,4)$

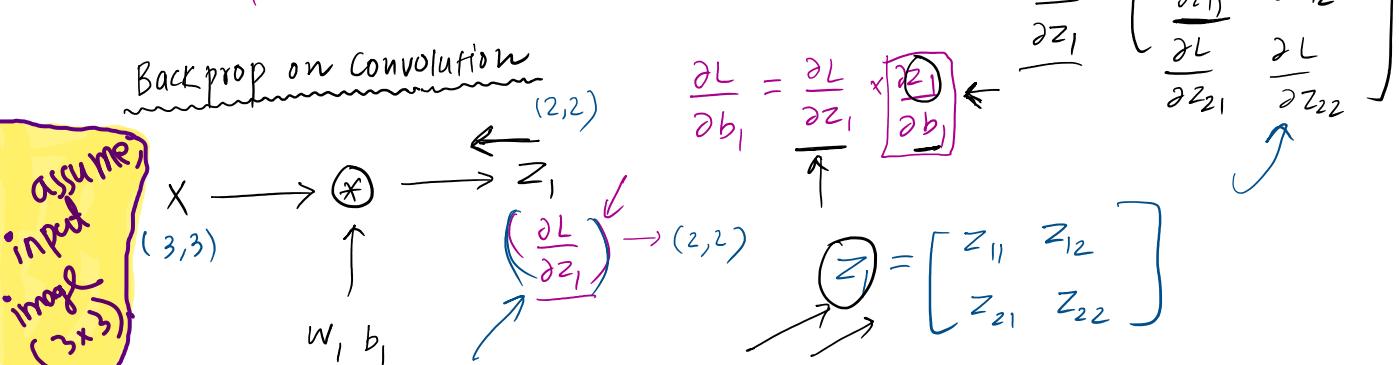
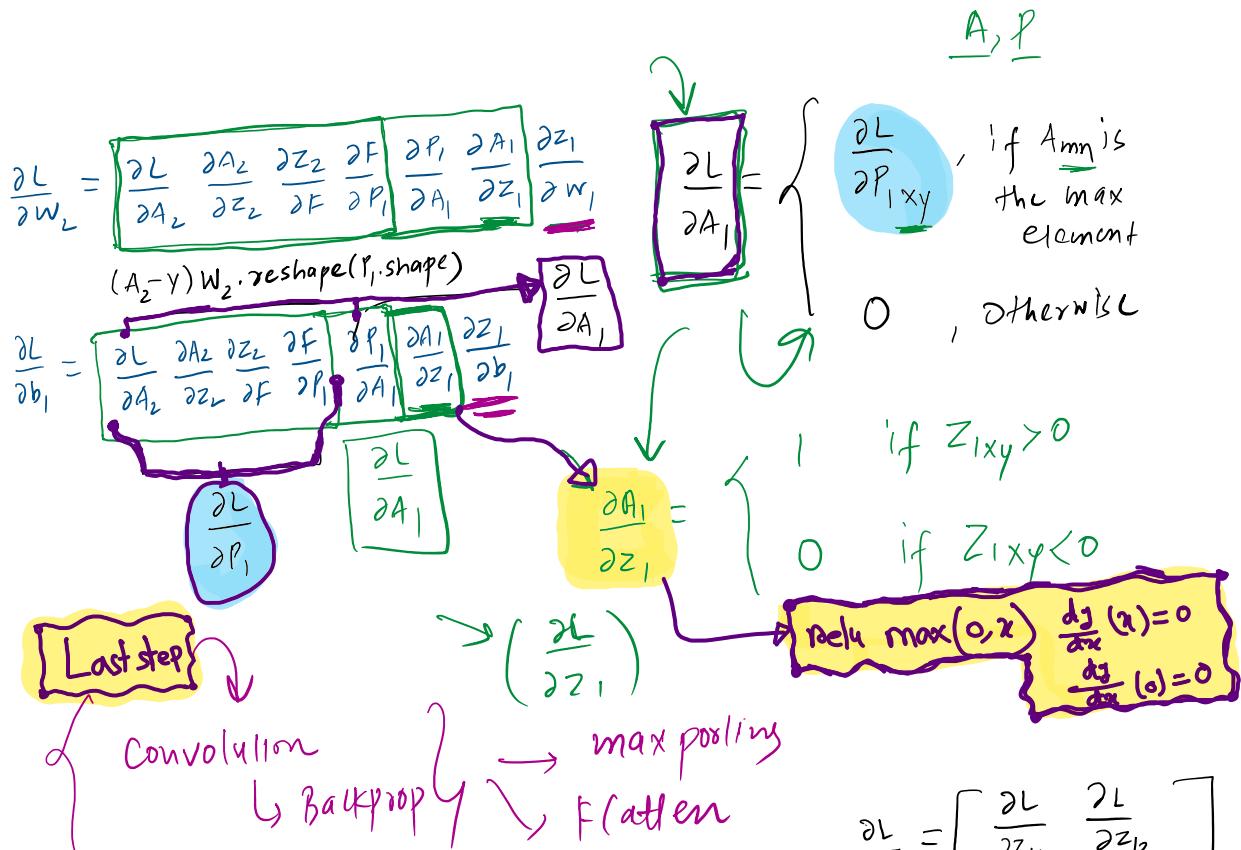
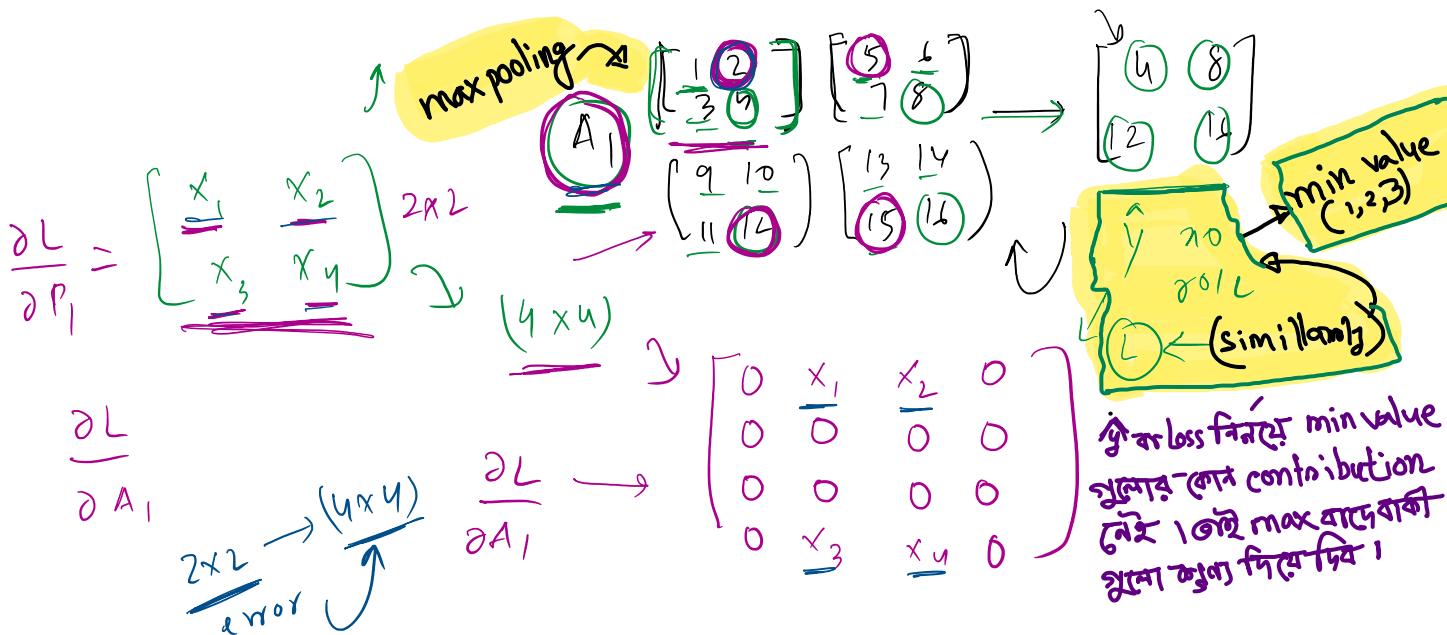


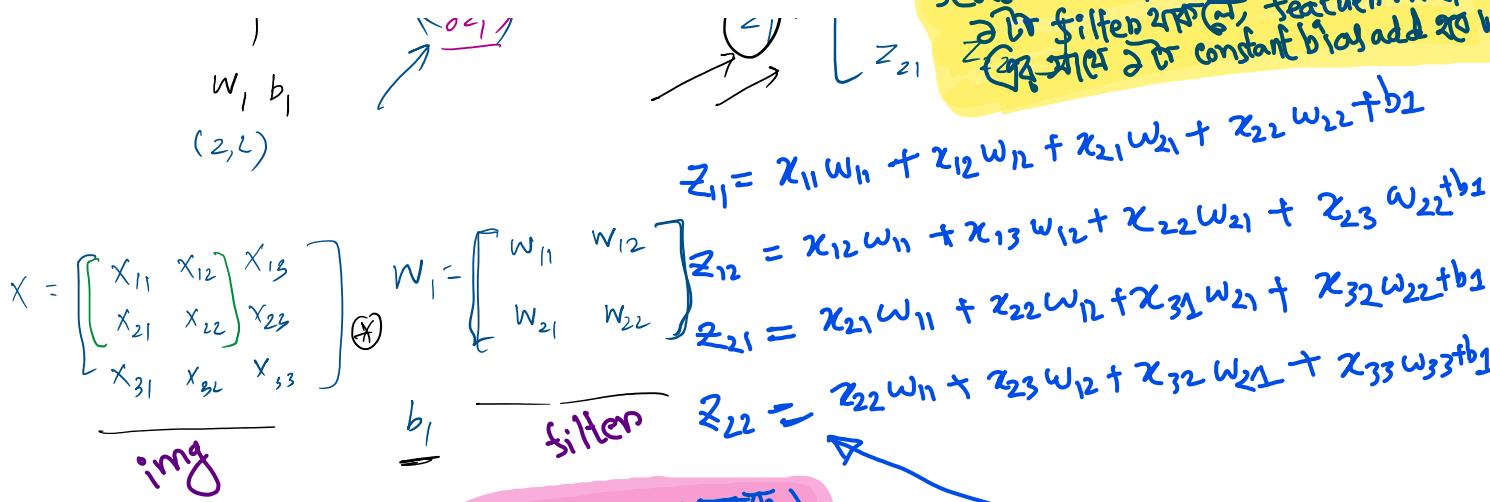
$$\begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix}$$

$$\frac{\partial L}{\partial A_1} = (4,4)$$

$$\frac{\partial L}{\partial A_1} = (4, 4)$$

In pooling like, flatten  $\rightarrow$  no trainable parameters





$$\frac{\partial L}{\partial b_1} = \frac{\partial L}{\partial z_1} \times \frac{\partial z_1}{\partial b_1} = \left[ \frac{\partial L}{\partial z_{11}} \times \frac{\partial z_{11}}{\partial b_1} + \frac{\partial L}{\partial z_{12}} \times \frac{\partial z_{12}}{\partial b_1} + \frac{\partial L}{\partial z_{21}} \times \frac{\partial z_{21}}{\partial b_1} + \frac{\partial L}{\partial z_{22}} \times \frac{\partial z_{22}}{\partial b_1} \right]$$

↑                      ↑                      ↑                      ↑

$$= \left( \frac{\partial L}{\partial z_{11}} + \frac{\partial L}{\partial z_{12}} + \frac{\partial L}{\partial z_{21}} + \frac{\partial L}{\partial z_{22}} \right) = \text{sum} \left( \frac{\partial L}{\partial z_i} \right)$$

$$\boxed{\frac{\partial L}{\partial b_1}} = \text{sum} \left( \frac{\partial L}{\partial z_1} \right) \rightarrow \text{scalar}$$

bias

A diagram illustrating a neural network layer. It starts with an input  $X$  (labeled  $(3 \times 3)$ ) which is multiplied by weight matrix  $W_1$  (labeled  $(2 \times 2)$ ). The result is then added to bias vector  $b_1$ . The final output is  $Z_1$ , which is the derivative of the loss function  $\frac{\partial L}{\partial z_1}$ .

$$\underline{x} = \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix} \quad \underline{w}_1 = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{bmatrix} + \underline{\epsilon}_1$$

$$\frac{\partial L}{\partial w_1} = \begin{bmatrix} \frac{\partial L}{\partial w_{11}} & \frac{\partial L}{\partial w_{12}} \\ \frac{\partial L}{\partial w_{21}} & \frac{\partial L}{\partial w_{22}} \end{bmatrix} \quad \frac{\partial L}{\partial z_1} = \begin{bmatrix} \frac{\partial L}{\partial z_{11}} & \frac{\partial L}{\partial z_{12}} \\ \frac{\partial L}{\partial z_{21}} & \frac{\partial L}{\partial z_{22}} \end{bmatrix}$$

$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial z_1} \times \frac{\partial z_1}{\partial w_1}$$

$$\frac{\partial L}{\partial w_{11}} = \frac{\partial L}{\partial z_{11}} \times \left| \frac{\partial z_{11}}{\partial w_{11}} \right| + \frac{\partial L}{\partial z_{12}} \times \underbrace{\left| \frac{\partial z_{12}}{\partial w_{11}} \right|}_{\text{green bracket}} + \frac{\partial L}{\partial z_{21}} \times \underbrace{\left| \frac{\partial z_{21}}{\partial w_{11}} \right|}_{\text{green bracket}} + \frac{\partial L}{\partial z_{22}} \times \underbrace{\left| \frac{\partial z_{22}}{\partial w_{11}} \right|}_{\text{green bracket}}$$

$$\frac{\partial L}{\partial w_{12}} = \underbrace{\frac{\partial L}{\partial z_{11}} \times \frac{\partial z_{11}}{\partial w_{12}}}_{\text{Term 1}} + \underbrace{\frac{\partial L}{\partial z_{12}} \times \frac{\partial z_{12}}{\partial w_{12}}}_{\text{Term 2}} + \underbrace{\frac{\partial L}{\partial z_{21}} \times \frac{\partial z_{21}}{\partial w_{12}}}_{\text{Term 3}} + \underbrace{\frac{\partial L}{\partial z_{22}} \times \frac{\partial z_{22}}{\partial w_{12}}}_{\text{Term 4}}$$

feature map  $\oplus$  माझे bias घाटा  
उत्तर filter घाटा, feature map  
ऐसे माझे उत्तर constant bias add घेऊ

$$\frac{\partial L}{\partial w_{21}} = \underbrace{\frac{\partial L}{\partial z_{11}} \times \frac{\partial z_{11}}{\partial w_{21}}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{12}} \times \frac{\partial z_{12}}{\partial w_{21}}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{21}} \times \frac{\partial z_{21}}{\partial w_{21}}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{22}} \times \frac{\partial z_{22}}{\partial w_{21}}}_{\text{green bracket}}$$

$$\frac{\partial L}{\partial w_{22}} = \underbrace{\frac{\partial L}{\partial z_{11}} \times \frac{\partial z_{11}}{\partial w_{22}}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{12}} \times \frac{\partial z_{12}}{\partial w_{22}}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{21}} \times \frac{\partial z_{21}}{\partial w_{22}}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{22}} \times \frac{\partial z_{22}}{\partial w_{22}}}_{\text{green bracket}}$$

$$\left\{ \begin{array}{l} \frac{\partial L}{\partial w_{11}} = \underbrace{\frac{\partial L}{\partial z_{11}} x_{11}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{12}} x_{12}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{21}} x_{21}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{22}} x_{22}}_{\text{green bracket}} \\ \frac{\partial L}{\partial w_{12}} = \underbrace{\frac{\partial L}{\partial z_{11}} x_{12}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{12}} x_{13}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{21}} x_{22}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{22}} x_{23}}_{\text{green bracket}} \\ \frac{\partial L}{\partial w_{21}} = \underbrace{\frac{\partial L}{\partial z_{11}} x_{21}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{12}} x_{22}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{21}} x_{31}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{22}} x_{32}}_{\text{green bracket}} \\ \frac{\partial L}{\partial w_{22}} = \underbrace{\frac{\partial L}{\partial z_{11}} x_{22}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{12}} x_{23}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{21}} x_{32}}_{\text{green bracket}} + \underbrace{\frac{\partial L}{\partial z_{22}} x_{33}}_{\text{green bracket}} \end{array} \right\}$$

$X = \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ x_{31} & x_{32} & x_{33} \end{bmatrix}$     $\frac{\partial L}{\partial z_1} = \begin{bmatrix} \frac{\partial L}{\partial z_{11}} & \frac{\partial L}{\partial z_{12}} \\ \frac{\partial L}{\partial z_{21}} & \frac{\partial L}{\partial z_{22}} \end{bmatrix}$

$\frac{\partial L}{\partial w_1} = \text{conv}(X, \frac{\partial L}{\partial z_1})$

$$\frac{\partial L}{\partial w_1} = \text{conv}(X, \frac{\partial L}{\partial z_1})$$

$$\frac{\partial L}{\partial z_1} = \text{sum}(\frac{\partial L}{\partial z_1})$$

## Why use Pretrained models?

03 October 2022 12:52

