

"A programming language is low level when its programs require attention to the irrelevant."
- Alan J. Perlis.

CSE341

Programming Languages

Lecture 8 – November 26, 2015

ADT

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Slides are taken from C. Li & W. He

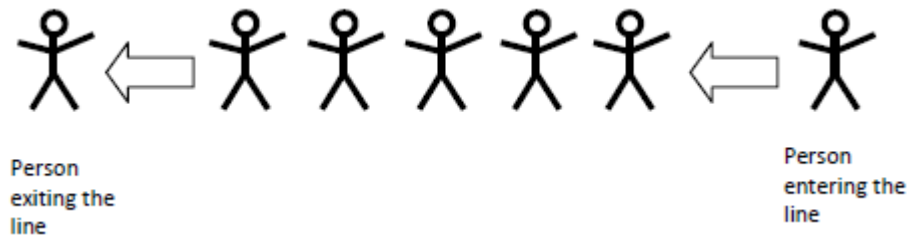
Abstract Data Types

Data Types

- Predefined
- Type constructors: build new data types
- How to provide “queue”?
 - What should be the data values?
 - What should be the operations?
 - How to implement (data representation, operations)?

Queue

- A common abstract data type is a queue.



- A queue is a first in, first out (FIFO) structure or in the other sense, a last in, last out (LIFO) structure. A queue is sometimes generalized as a structure where insertion (enqueue) occur at one end and removal (dequeue) occurs at the other end.

Queue Implementation

What are inadequate here?

- **The operations are not associated with the data type**
 - You can use the operation on an invalid value
- **Users see all the details: direct access to data elements, implementations**
 - Implementation dependent
 - Users can even mess up with things

What do we want?

- For basic types:
 - 4 bytes or 2 bytes, users don't need to know.
 - Can only use predefined operations.
- Similarly, for the “Queue” data type:
?

Abstract Data Types

- Built-in types have important properties that "abstract" away the implementation: use of int and its operations (+, *, etc.) normally do not require knowledge of bit patterns (2's complement? 4 bytes?)
- User-defined types do not in general have this property: internal structure is visible to all code
- Use of internal structure makes it difficult to change later
- Operations on data (except the most basic) not specified and often hard to find

Kenneth C. Loudon, 2005

Abstract Data Types

- A mechanism of a programming language designed to imitate the abstract properties of a built-in type as much as possible
- Must include a specification of the operations that can be applied to the data
- Must hide the implementation details from client code
- These properties are sometimes called encapsulation & information hiding (with different emphases)

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Abstract Data Type

- **Encapsulation:**

All definitions of allowed operations for a data type in one place.

- **Information Hiding:**

Separation of implementation details from definitions. Hide the details .

Algebraic Specification of ADT

- **Syntactic specification (signature, interface):**
the name of the type, the prototype of the operations
- **Semantic specification (axioms, implementation):**
guide for required properties in implementation
mathematical properties of the operations

They don't specify:

- data representation
- implementation details

Syntactic Specification

type queue(element) **imports** boolean

operations:

createq: queue

enqueue: queue × element → queue

dequeue: queue → queue

frontq: queue → element

emptyq: queue → boolean

- **imports**: the definition queue needs boolean
- Parameterized data type (element)
- createq: not a function, or viewed as a function with no parameter

Algebraic Specification

variables: q : queue; x : element

axioms:

<code>emptyq(createq)</code>	<code>= true</code>
<code>emptyq(enqueue(q, x))</code>	<code>= false</code>
<code>frontq(createq)</code>	<code>= error</code>
<code>frontq(enqueue(q, x))</code>	<code>= if emptyq(q) then x else frontq(q)</code>
<code>dequeue(createq)</code>	<code>= error</code>
<code>dequeue(enqueue(q, x))</code>	<code>= if emptyq(q) then q else enqueue(dequeue(q), x)</code>

- `error` axiom (exceptions)

Stack

```
type stack(element) imports boolean
```

```
operations:
```

```
  createstk : stack  
  push      : stack × element → stack  
  pop       : stack → stack  
  top       : stack → element  
  emptystk  : stack → boolean
```

```
variables: s: stack; x: element
```

```
axioms:
```

```
  emptystk(createstk)      = true  
  emptystk(push(s,x))      = false  
  top(createstk)           = error  
  top(push(s,x))           = x  
  pop(createstk)           = error  
  pop(push(s,x))           = s
```

Axioms

- How many axioms are sufficient for proving all necessary properties?

Some Heuristics

type stack(element) **imports** boolean

operations:

createstk : stack
push : stack × element → stack
pop : stack → stack
top : stack → element
emptystk : stack → boolean

variables: s: stack; x: element

axioms:

emptystk(createstk) = true
emptystk(push(s,x)) = false
top(createstk) = error
top(push(s,x)) = x
pop(createstk) = error
pop(push(s,x)) = s

Constructor:

createstk
push

Inspector:

pop
top
emptystk

2 * 3 = 6 rules

Binary Search Tree

```
type BST(element) imports boolean, int
operations:
  createbst    : BST
  emptybst     : BST → boolean
  insert       : BST × element → BST
  delete       : BST × element → BST
  getRoot      : BST → element
  getHeight    : BST → int
  max          : BST → element
  search       : BST × element → boolean
```

```
variables: t: bst; x: element
```

```
axioms:
```

```
  emptystk(createbst)      = true
```

```
  ...
```

Other Examples of ADT

- Stack
- Queue
- Tree
- Set
- Map
- Vector
- List
- Priority Queue
- Graph
- ...

Algebraic Specification Notes

- Specifications are usually written in functional form with no side effects or assignment. So no "void" functions
- Specifications are often simplified to make axiom writing easier
 - E.g., in the stack example, pop does not return the top, only the (previously created) stack below the current top.
 - We could have written pop as $\text{pop: stack} \rightarrow \text{element} \times \text{stack}$, but the axioms are more complex

ADT Language Mechanisms

- Most languages do not have a specific ADT mechanism – instead they have a more general module mechanism
- Specific ADT mechanisms
 - ML abstype – but newer module mechanism is more useful...
- General module mechanism: not just about a single data type and its operations
 - Separate compilation and name control: C, C++, Java
 - Ada, ML
- Class in OO languages (which has many of the properties needed by an ADT mechanism)

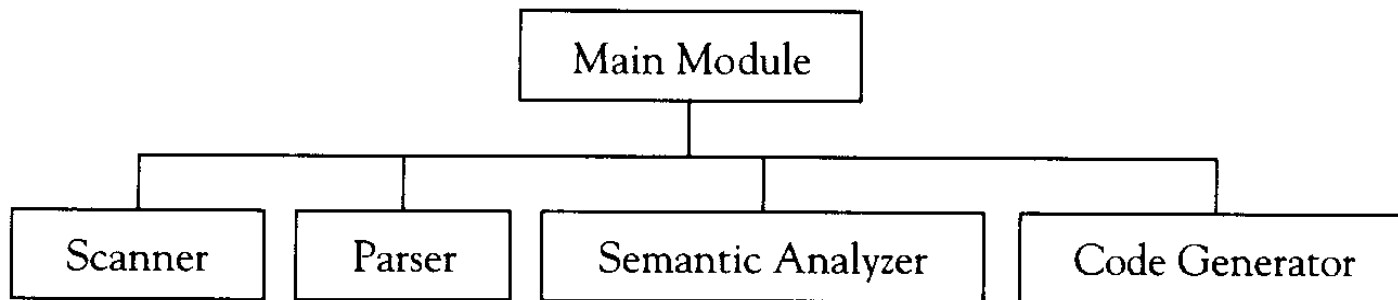
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Modules

- **Module:** A program unit with a public interface and a private implementation; all services that are available from a module are described in its public interface and are exported to other modules, and all services that are needed by a module must be imported from other modules.
- A module offers general services, which may include types and operations on those types, but are not restricted to these.
- Modules have nice properties:
 - A module can be (re)used in any way that its public interface allows.
 - A module implementation can change without affecting the behavior of other modules.
- In addition to ADT, module supports structuring of large programs:
Separate compilation and name control

Modules

- Modules are the principle mechanism used to decompose large programs
- Example – a compiler:



- Modules usually offer an additional benefit: names within one module do not clash with names in other modules
- Modules usually have a close relationship to separate compilation (though this is often hard to make precise in a specification)

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Modules

- Languages that have comprehensive module mechanisms:
 - Ada, where they are called packages (not to be confused with Java packages)
 - ML, where they are called structures
- Languages that have weak mechanisms with some module-like properties:
 - C++, where they are called namespaces
 - Java, where they are called packages
- Languages with no module mechanism:
 - C (but modules can be imitated using separate compilation)
 - Pascal

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C++ Namespaces & Java Packages

- C++ and Java do not have modules in the sense of Ada and ML: classes are used instead
- C++ and Java do have mechanisms for controlling name clashes and organizing code into groups: namespaces in C++, packages in Java.
- Clients must use similar dot notation as in Ada and ML to reference names in namespaces/packages.
- Each of these languages has a mechanism for automatically dereferencing names:
 - Ada: use
 - ML: open
 - C++: using [namespace]
 - Java: import
- Only Ada has explicit dependency syntax (keyword with). Java class loader automatically searches for code. C++ requires textual inclusions for declarations, linker must search for code. ML "compilation manager" does this too (not in ML specification).

C: Separate Compilation

- queue.h : header file

```
#ifndef QUEUE_H  
#define QUEUE_H
```

```
struct Queuerep;  
typedef struct Queuerep * Queue;  
Queue createq(void);  
Queue enqueue(Queue q, void* elem);  
void* frontq(Queue q);  
Queue dequeue(Queue q);  
int emptyq(Queue q);
```

```
#endif
```

Incomplete type:
Separate implementation

Simulate
Parameteric polymorphism

C: Separate Compilation

- `queue.c`: queue implementation

```
#include "queue.h"
```

```
struct Queuerep  
{ void* data;  
  Queue next;  
};
```

```
Queue createq(void)  
{ return 0;  
}
```

```
void* frontq(Queue q)  
{ return q->next->data;  
}
```

```
...
```

C: Separate Compilation

- `q_user.C`: client code

```
#include "queue.h"
```

```
int *x = malloc(sizeof(int));
```

```
int *y = malloc(sizeof(int));
```

```
int *z;
```

```
*x = 2;
```

```
*y = 3;
```

```
Queue q = createq();
```

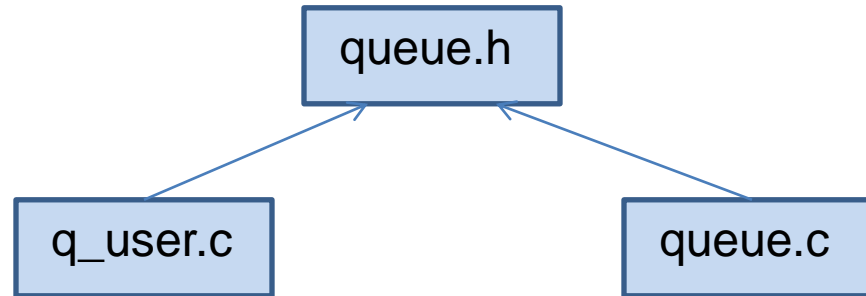
```
q = enqueue(q, x);
```

```
q = enqueue(q, y);
```

```
q = dequeue(q);
```

```
z = (int*) frontq(q);
```

C: Separate Compilation



- Not real ADT
 - casting, allocation: for parametric polymorphism
 - header file directly incorporated into `q_user.c`: definition / usage consistent
 - data not protected: user may manipulate the type value in arbitrary ways
 - The language itself doesn't help in tracking changes and managing compilation/linking: thus tools like `make`

C++: Namespaces

- **queue.h:**

```
#ifndef QUEUE_H
#define QUEUE_H
namespace MyQueue
{
    struct Queuerep;
    typedef struct Queuerep * Queue;
    Queue createq(void);
    ...
}
#endif
```

- **queue.c:**

```
#include "queue.h"

struct MyQueue::Queuerep
{ void* data;
  Queue next;
};
...
```

C++: Namespaces

- q_user.cpp:

```
#include "queue.h"

using std::endl;
using namespace MyQueue;
main() {
    int *x = malloc(sizeof(int));
    int *y = malloc(sizeof(int));
    int *z;
    *x = 2;
    *y = 3;
    Queue q = MyQueue::createq();
    q = enqueue(q, x);
    q = enqueue(q, y);
    q = dequeue(q);
    z = (int*) frontq(q);
    ...
}
```

Java: Packages

Queue.java:

```
package queues.myqueue;  
...
```

PQueue.java:

```
package queues.myqueue;  
...
```

Q_user.java:

```
import queues.myqueue.Queue;  
import queues.myqueue.*;  
queues.myqueue.Queue;
```

directory:
queues/myqueue

class files:
Queue.class, PQueue.class

queues/myqueue in
CLASSPATH

Example

- Package java.util
<http://java.sun.com/j2se/1.5.0/docs/api/java/util/package-summary.html>
- Interface Collection
<http://java.sun.com/j2se/1.5.0/docs/api/java/util/Collection.html>
- Class PriorityQueue
<http://java.sun.com/j2se/1.5.0/docs/api/java/util/PriorityQueue.html>
- boost: providing free peer-reviewed portable C++ source libraries
<http://www.boost.org/>

boost

```
#include <boost/lambda/lambda.hpp>
#include <iostream>
#include <iterator>
#include <algorithm>

int main() {
    using namespace boost::lambda;
    typedef std::istream_iterator<int> in;

    std::for_each(
        in(std::cin), in(), std::cout << (_1 * 3) << " " );
}
```

boost lambda

The Boost Lambda Library (BLL) is a C++ template library, which implements a form of lambda abstractions for C++. The term originates from functional programming and lambda calculus, where a lambda abstraction defines an unnamed function. The primary motivation for the BLL is to provide flexible and convenient means to define unnamed function objects for STL algorithms.

Example:

```
for_each(a.begin(), a.end(), std::cout << _1 << ' ');
```

boost queue

```
// In header: <boost/lockfree/queue.hpp>

template<typename T, ... Options>
class queue {
public:
    // types
    typedef T value_type;
    typedef implementation_defined::allocator allocator;
    typedef implementation_defined::size_type size_type;

    // construct/copy/destruct
    queue(void);
    template<typename U>
        explicit queue(typename node_allocator::template rebind< U >::other const &);
    explicit queue(allocator const &);
    explicit queue(size_type);
    template<typename U>
        queue(size_type,
            typename node_allocator::template rebind< U >::other const &);
    ~queue(void);

    // public member functions
    bool is_lock_free(void) const;
    void reserve(size_type);
    void reserve_unsafe(size_type);
    bool empty(void);
    bool push(T const &);
    bool bounded_push(T const &);
    bool unsynchronized_push(T const &);
    bool pop(T &);
    template<typename U> bool pop(U &);
    bool unsynchronized_pop(T &);
    template<typename U> bool unsynchronized_pop(U &);
};
```

Problems with Modules

- Modules are not types
 - Modules sometimes used to imitate OO classes
 - Module interface usually contains types, whose representations may be exposed
- Modules are static
 - Modules are primarily compile-time artifacts
 - Use of a module to imitate a class (without exporting a type) results in only one available object
- Modules do not control values of exported types
 - Assignment can cause undesirable aliasing
 - Equality tests may not be appropriate
 - ML and Ada have some ability to control these (with effort)

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Problems with Modules

- These problems can be (mostly) overcome by using OO classes, with modules relegated to code organization status (C++, Java)
- Significant problems still exist, even with OO :
 - Modules do not expose dependencies
 - Only Ada documents compilation dependencies in code (keyword with)
 - Hidden implementation dependencies can be worse: order relation is a common one
 - C++ does a particularly good job of hiding these
 - Ada uses constrained polymorphism
 - Java uses interfaces such as Comparable, Comparator
 - Modules do not express semantics
 - Universally ignored in today's languages
 - Useful for proving code correctness

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