

Building a Bridge: Close the Domain Gap in CT Metal Artifact Reduction

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Abstract. Metal artifacts in computed tomography (CT) degrade the imaging quality, leading to a negative impact on the clinical diagnosis. Empowered by medical big data, many DL-based approaches have been proposed for metal artifact reduction (MAR). In supervised MAR methods, models are usually trained on simulated data and then applied to the clinical data. However, inferior MAR performance on clinical data is usually observed due to the domain gap between simulated and clinical data. Existing unsupervised MAR methods usually use clinical unpaired data for training, which often distort the anatomical structure due to the absence of supervision information. To address these problems, we propose a novel semi-supervised MAR framework. The clean image is employed as the bridge between the synthetic and clinical metalaffected image domains to close the domain gap. We also break the cycleconsistency loss, which is often utilized for domain transformation, since the bijective assumption is too harsh to accurately respond to the facts of real situations. To further improve the MAR performance, we propose a new Artifact Filtering Module (AFM) to eliminate features helpless in recovering clean images. Experiments demonstrate that the performance of the proposed method is competitive with several state-of-theart unsupervised and semi-supervised MAR methods in both qualitative and quantitative aspects.

Keywords: Computed Tomography \cdot Metal Artifact Reduction \cdot Deep Learning \cdot Domain Gap

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1 Introduction

Metal implants can heavily attenuate X-rays in computed tomography (CT) scans, leading to severe artifacts in reconstructed images. It is essential to remove metal artifacts in CT images for subsequent diagnosis.

Recently, with the emergence of deep learning (DL) [21,22], many DLbased approaches have been proposed for metal artifact reduction (MAR) and achieved encouraging results. These methods can be roughly classified into three groups: supervised, unsupervised, and semi-supervised MAR methods. Supervised MAR methods [2,8,10,12,19,20,23,24] directly learn the mapping from synthetic metal-affected data to metal-free one under the guidance of the desired data. Then the learned models are applied to the clinical data. Unfortunately, due to the domain gap between synthetic and clinical data, poor generalization performance usually occurs, leading to unexpected results. Unsupervised MAR methods [5,9,27] can avoid the problem since their training and application are both on the clinical data. Nonetheless, the absence of supervision information makes it easy to distort the anatomical structure in the corrected results. Recently, several semi-supervised MAR methods have been proposed. SFL-CNN [17] and a variant of ADN [9] denoted as SemiADN [14] are two representative works, which utilize the same network to deal with synthetic and clinical data simultaneously. These methods inherit the advantages of both supervised and unsupervised MAR methods, but the mentioned-above domain gap problem remains. In these works, the network attempts to find a balance between the synthetic and clinical data but ultimately results in an unsatisfactory outcome in both domains, leaving room for further improvement.

In this work, our goal is to explicitly reduce the domain gap between synthetic and clinical metal-corrupted CT images for improved clinical MAR performance. Some domain adaptation-based networks [7,16,18,25] are designed to close the domain gap and they usually assume that there is a one-to-one correspondence between two domains, i.e. bijection, which is implemented via the constraint of cycle consistency loss. However, this assumption is too harsh to accurately respond to the facts of real situations. Furthermore, when the model learns an identical transformation, this assumption is still met. Hence, maintaining the diversity of image generation is another challenge.

To close the domain gap, we propose a novel semi-supervised MAR framework. In this work, the clean image domain acts as the bridge, where the bijection is substituted with two simple mappings and the strict assumption introduced by the cycle-consistency loss is relaxed. Our goal is to convert simulated and clinical metal-corrupted data back and forth. As an intermediate product, clean images are our target. To improve the transformations of two metal-corrupted images into metal-free ones, we propose a feature selection mechanism, denoted as Artifact Filtering Module (AFM), where AFM acts as a filter to eliminate features helpless in recovering clean images.

2 Method

2.1 Problem Formulation

The metal corruption process can be formulated as a linear superposition model as [10,11]:

$$X_{ma} = X_{free} + A, (1)$$

where X_{ma} , X_{free} , and A represent metal-affected CT images, metal-free CT images, and metal artifacts, respectively. X_{ma} is the observation signal and X_{free} is the target signal to be reconstructed.

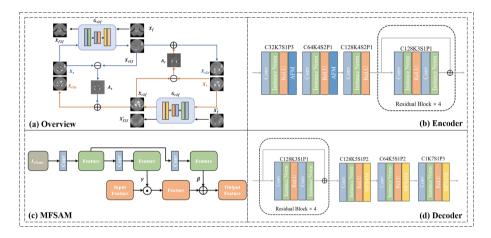


Fig. 1. Overview of the proposed method. C: channel number, K: kernel size, S: stride, and P: padding size. More details on AFM are in Sect. 2.3.

2.2 Overview

Figure 1 presents the overall architecture of our proposed method. Let I_s be the domain of all synthetic metal-corrupted CT images and I_c be the domain of all clinical metal-corrupted CT images. The generators aim to convert them to clean CT image domain I_f , where different generators take metal-corrupted CT images from different domains. I_f takes the role of a bridge to close the domain gap. The following subsections present the details of these image translation branches.

2.3 Image Translation

According to Eq. 1, if two metal artifact reduction translations are completed, the subsequent two transformations can be obtained by subtracting the output of the network from the original input. Therefore, only two translators are needed. The first translator is used to convert I_s into I_f , denoted as G_{s2f} and the second

translator is used to convert I_c into I_f , denoted as G_{c2f} . In this work, two translators, G_{s2f} and G_{c2f} , share the same network architecture, consisting of one encoder and one decoder, as shown in Fig. 1 (b) and (d).

Encoding Stage. In most DL-based MAR methods, the networks take a metal-corrupted CT image as input and map it to a metal-free CT image domain. Noise-related features are involved in the entire process, which negatively affects the restoration of clean images. In the principal component analysis (PCA)-based image denoising method [1], by retaining only the most important features, noise and irrelevant information are eliminated. In this work, we propose an artifact filtering module (AFM) for feature selection. At the encoding step, feature maps that contribute little to the reconstruction are also considered to be related to noise, where the encoder acts as a filter and only allows useful information to pass through. Specifically, there are two criteria for feature selection: 1) the selected feature maps contain as much information as possible, which is assessed by Variance (Var), and 2) the correlation between the selected feature maps should be as small as possible, which is measured by covariance (Cov). Finally, each feature map gets a score as:

$$score = \frac{Var}{Cov + \lambda},\tag{2}$$

where λ is a small constant to prevent division by zero and we set $\lambda = 1e - 7$ in this paper. Feature maps with high scores will be selected. Therefore, we can dynamically select different feature maps according to the inputs.

Decoding Stage. At the encoding stage, features that are helpless to reconstruct the clean image are filtered out. Decoder then maps the remaining features, which contain useful information, back into the image domain. To push the generated image to fall into the clean image domain, we employ conditional normalization layers [4,15] and propose a metal-free spatially aware module (MFSAM). The mean and variance of the features are modulated to match those of the metal-free image style by the MFSAM. The details of MFSAM are illustrated in Fig. 1 (c).

Metal Artifacts Reduction and Generation Stage. The framework consists of four image translation branches: two metal artifacts reduction branches $I_s \leftarrow I_f$ and $I_c \leftarrow I_f$, and two metal artifact generation branches $I_f \leftarrow I_c$ and $I_f \leftarrow I_c$.

(1) $I_s \leftarrow I_f$: In this transformation, we employ G_{s2f} to learn the mapping from the synthetic metal-affected image domain to the metal-free image domain, which is denoted as:

$$X_{s2f} = G_{s2f}(X_s), \tag{3}$$

where X_s is synthetic metal-affected CT image in I_s and X_{s2f} is the corrected result of X_s . According to Eq. 1, the metal artifacts A_s can be obtained as follows:

$$A_s = X_s - X_{s2f}. (4)$$

(2) $I_c \leftarrow I_f$: In this transformation, we use G_{c2f} to learn the mapping from the clinical metal-affected image domain to the metal-free image domain, resulting

in metal-corrected CT image X_{c2f} and the metal artifacts A_c . This process is the same as the transformation of $I_s \leftarrow I_f$ and can be formulated as follows:

$$X_{c2f} = G_{c2f}(X_c), \tag{5}$$

$$A_c = X_c - X_{c2f}, (6)$$

where X_c is clinical metal-affected CT image in I_c .

(3): $I_f \leftarrow I_s$: We use the artifacts of X_s to obtain a synthetic domain metal-corrupted image X_{c2s} by adding A_s to the learned metal-free CT image X_{c2f} :

$$X_{c2s} = X_{c2f} + A_s. (7)$$

(4): $I_f \leftarrow I_c$: Synthesizing clinical domain metal-corrupted image X_{s2c} can be achieved by adding A_c to the learned metal-free CT image X_{s2f} :

$$X_{s2c} = X_{s2f} + A_c. (8)$$

2.4 Loss Function

In our framework, the loss function contains two parts: adversarial loss and reconstruction loss.

Adversarial Loss. Due to the lack of paired clinical metal-corrupted and metal-free CT images, as well as paired clinical and synthetic metal-corrupted CT images, we use PatchGAN-based discriminators, D_f , D_s , and D_c , and introduce an adversarial loss for weak supervision. D_f learns to distinguish whether an image is a metal-free image, D_s learns to determine whether an image is a synthetic metal-affected CT image, and D_c learns to determine whether an image is a clinical metal-affected CT image. The total adversarial loss \mathcal{L}_{adv} is written as:

$$\mathcal{L}_{adv} = \mathbb{E}[logD_f(X_f)] + \mathbb{E}[1 - logD_f(X_{c2f})] + \mathbb{E}[logD_s(X_s)] + \mathbb{E}[1 - logD_s(X_{c2s})] + \mathbb{E}[logD_c(X_c)] + \mathbb{E}[1 - logD_c(X_{s2c})].$$

$$(9)$$

Reconstruction Loss. The label X_{gt} of X_s is employed to guide the G_{s2f} to reduce the metal artifacts. The reconstruction loss \mathcal{L}_{s2f} on X_{x2f} can be formulated as:

$$\mathcal{L}_{s2f} = ||(X_{s2f} - X_{qt})||_1. \tag{10}$$

When X_{syn} is transformed into the clinical domain, G_{c2f} can also reduce the metal artifacts with the help of X_{gt} . The reconstruction loss \mathcal{L}_{sc2f} on X_{sc2f} can be formulated as:

$$\mathcal{L}_{sc2f} = ||(X_{sc2f} - X_{gt})||_1, \tag{11}$$

where X_{sc2f} is the MAR results of X_{s2c} .

To obtain optimal MAR results, it is necessary to remove any noise-related features while preserving as much of the content information as possible. When

the input image is already metal-free, the input image has no noise-related features, and the reconstructed image should not suffer from any information loss. Here, we employed the model error loss to realize this constrain:

$$\mathcal{L}_{model_error} = ||(X_{f2f} - X_f)||_1 + ||(X'_{f2f} - X'_f)||_1, \tag{12}$$

where X_{f2f} is a reconstructed image from X_f using G_{s2f} and X'_{f2f} is a reconstructed image from X'_f using G_{c2f} .

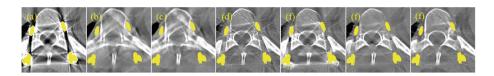


Fig. 2. Visual comparisons with the SOTA MAR methods on simulated data. (a): Uncorrected, (b): LI,(c): NMAR,(d): ADN, (e): β -cycleGAN, (f): SemiADN, (e): Ours. Display window: [-375,560] HU.

PSNR(dB)/SSIM Small Middle Large Average Params(M) Uncorrected 16.23/0.7092 16.16/0.651316.19 /0.6594 | 16.14/0.6443 16.12/0.6288 16.18/0.6684 LI 28.68/0.8095 26.84/0.7549 25.37/0.7347 26.07/0.7309 26.06/0.7296 27.19/0.7664 NMAR 29.41/0.8294 28.19/0.7913 27.24/0.7752 27.80/0.7743 27.62/0.7711 28.43/0.7987 31.32/ 0.8425 30.28/0.8043 ADN 30.50/0.808929.98/0.7908 29.69/0.7806 30.54/0.812732 43 $27.\overline{99/0.7961}$ β-cycleGAN 30.34/0.8365 28.17/0.7811 27.18/0.7710 26.45/0.7502 28.53/0.7958 5.48 SemiADN 31.07/0.8636 30.99/0.8393 31.68/0.850030.23/0.8322 29.37/0.8144 30.66/0.843532.43 32.57/0.8789 31.28/0.854131.29/**0.8562** 30.83/0.8472 30.38/0.8402 31.54/0.8606

Table 1. Quantitative results of SOTA MAR methods on the simulated dataset.

Overall Loss. The overall loss function is defined as follows:

$$\mathcal{L} = \mathcal{L}_{adv} + \lambda_{recon}(\mathcal{L}_{s2f} + \mathcal{L}_{sc2f} + \mathcal{L}_{model_error}), \tag{13}$$

where λ_{recon} is the weighting parameter and as suggested by [9,14], it was set as 20.0 in our work.

3 Experiments

3.1 Dataset and Implementation Details

In this work, we used one synthesized dataset and two clinical datasets, denoted as SY, CL1 and CL2, respectively. The proposed method was trained on SY and CL1. For data simulation, we followed the procedure of [26] and used the metal-free CT images of the Spineweb dataset [3]. We set the threshold to 2,000 HU [20,24] to obtain 116 metal masks from metal-affected CT images of the

Spineweb dataset, where 100 masks are for training and the remaining 16 masks are for testing. We used 6,000 synthesized pairs for training and 2,000 pairs for evaluation. For CL1, we randomly chose 6,000 metal-corrupted CT images and 6,000 metal-free CT images from Spineweb for training and another 224 metal-corrupted CT images for testing. For CL2, clinical metal-corrupted CT images were collected from our local hospital to investigate the generalization performance. The model was implemented with the PyTorch framework and optimized by the Adam optimizer with the parameters $(\beta_1, \beta_2) = (0.5, 0.999)$. The learning rate was initialized to 0.0001 and halved every 20 epochs. The network was trained with 60 epochs on one NVIDIA 1080Ti GPU with 11 GB memory, and the batch size was 2.

3.2 Comparison with State-of-the-Art Methods

The proposed method was compared with several classic and state-of-the-art (SOTA) MAR methods: LI [6], NMAR [13], ADN [9], β -cycleGAN [5] and SemiADN [14]. LI and NMAR are traditional MAR methods. ADN and β -cycleGAN are SOTA unsupervised MAR methods. SemiADN is a SOTA semi-supervised MAR method. Structural similarity (SSIM) and peak signal-to-noise ratio (PSNR) were adopted as quantitative metrics. Our intuition for determining the number of feature maps selected in AFM is based on the observation that the majority of information in an image is typically related to its content, while noise-related features are few. Therefore, in our work, during the encoding stage, we discarded 2 out of 32 and 4 out of 64 feature maps at the first and second down-sampling stages, respectively.

MAR Performance on SY: The quantitative scores are presented in Table 1. The sizes of the 16 metal implants in the testing dataset are: [254, 274, 270, 262, 267, 363, 414, 441, 438, 445, 527, 732, 845, 889, 837, 735] in pixels. They are divided into five groups according to their sizes. It is observed that all methods significantly improve both SSIM and PSNR scores compared with uncorrected CT images. Aided by supervision, SemiADN obtains higher quantitative scores than ADN. Compared with these SOTA unsupervised and semi-supervised MAR methods, our method achieves the best quantitative performance. Figure 2 shows the visual comparisons on SY. The proposed method outperforms all other methods in artifact suppression and effectively preserves anatomical structures around metallic implants, thereby demonstrating its effectiveness.

MAR Performance on CL1: Figure 3 presents three representative clinical metal-affected CT images with different metallic implant sizes from small to large. When the metal is small, all methods can achieve good MAR performance but there are differences in tissue detail preservation. ADN and β -cycleGAN are more prone to lose details around the metal. In SemiADN, the missing details are recovered with the help of the supervision signal. However, in the second case, more artifacts are retained in SemiADN than ADN and β -cycleGAN. Compared with these MAR methods, our method is well-balanced between detail preservation and artifact reduction. When the metallic implant gets larger, as shown in

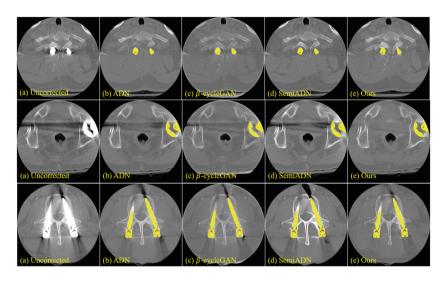


Fig. 3. Visual comparisons on CL1 dataset. Display window: [-1000,1000] HU.

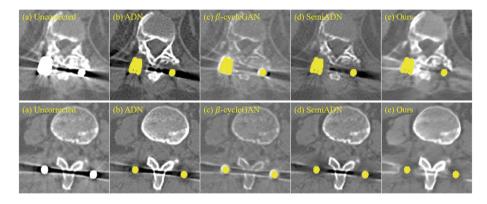


Fig. 4. Visual comparisons on CL2 dataset. Display window: [-375,560] HU.

the third case, other methods are limited to reduce artifacts, and SemiADN even aggravates the impact of artifacts. Fortunately, our method is able to effectively suppress metal artifacts, thus demonstrating its potential for practical clinical use.

MAR Performance on CL2: To assess the generalization capability of our method, we further evaluated MAR performance on CL2 with the model trained on SYN and CL1. Two practical cases are presented in Fig. 4. ADN and Semi-ADN fail to deal with severe artifacts and even introduce a deviation of HU value, while β -cycleGAN shows a certain ability to suppress these artifacts. Nonetheless, our proposed method outperforms β -cycleGAN in terms of artifact suppression and detail preservation. It can be seen that our method exhibits good

generalization ability, which means it can effectively address metal artifacts even in scenarios where the simulated data and clinical metal-corrected data have different clean image domains. It shows the robustness of our proposed method across different imaging configurations.

3.3 Ablation Study

In this section, we investigate the effectiveness of the proposed AFM. Table 2 shows the results of our ablation models, where M1 refers to the model without AFM, and M2 replaces the AFM with channel attention. Table 2 shows that AFM can improve the scores of M1. Although M2 integrates a channel attention mechanism to dynamically adjust the weight of different feature maps, our proposed AFM method achieves higher quantitative scores, which indicates its superior performance.

	M1	M2	Ours
PSNR(dB)	28.99	29.37	31.54
SSIM	0.8025	0.8353	0.860

Table 2. Quantitative comparison of different variants of our method.

4 Conclusion

In this paper, we explicitly bridge the domain gap between synthetic and clinical metal-corrupted CT images. We employ the clean image domain as the bridge and break the cycle-consistency loss, thereby eliminating the necessity for strict bijection assumption. At the encoding step, feature maps with limited influence will be eliminated, where the encoder acts as a bottleneck only allowing useful information to pass through. Experiments demonstrate that the performance of the proposed method is competitive with several SOTA MAR methods in both qualitative and quantitative aspects. In particular, our method exhibits good generalization ability on clinical data.

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