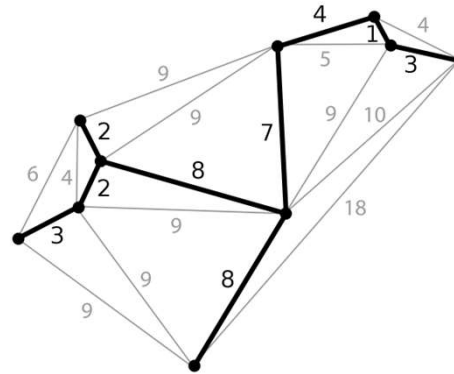




# Algorithms Analysis and Design

## Chapter 5

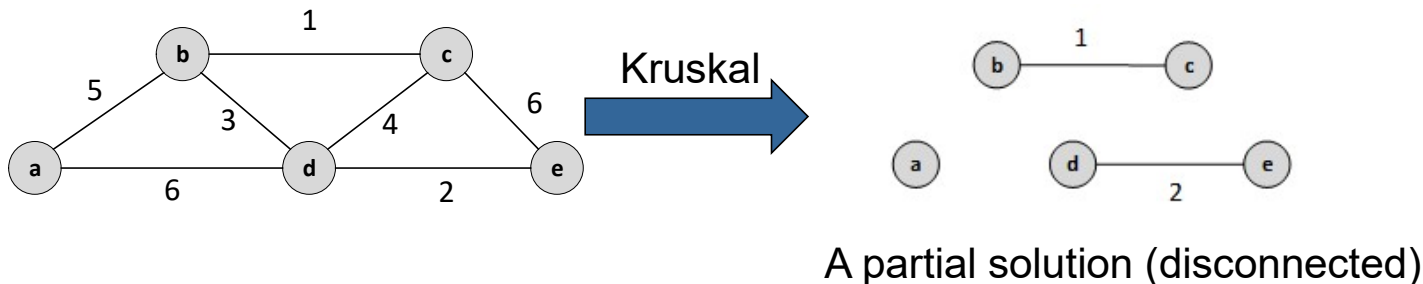
### Greedy Technique Part 2



# Prim's Algorithm

# Prim's algorithm

- Prim's algorithm constructs a minimum spanning tree through a sequence of expanding subtrees.
- Unlike Kruskal's whose partial solutions are not necessarily connected, a **partial solution in prim's algorithm is a tree** (of course, trees are always connected).



# Prim's algorithm

- Begin with a start vertex and no edges
  - Initial subtree consists of a single vertex selected arbitrarily from the set  $V$  of the graph's vertices.
- Apply the greedy rule at each iteration to expands the current tree
  - Add an edge of min weight that has one vertex in the current tree and the other not in the current tree
- Continue until you get a single tree  $T$ 
  - The algorithm stops after all the graph's vertices have been included in the tree being constructed.

Since the algorithm expands a tree by exactly one vertex on each of its iterations, the total number of such iterations is  $n - 1$ , where  $n$  is the number of vertices in the graph

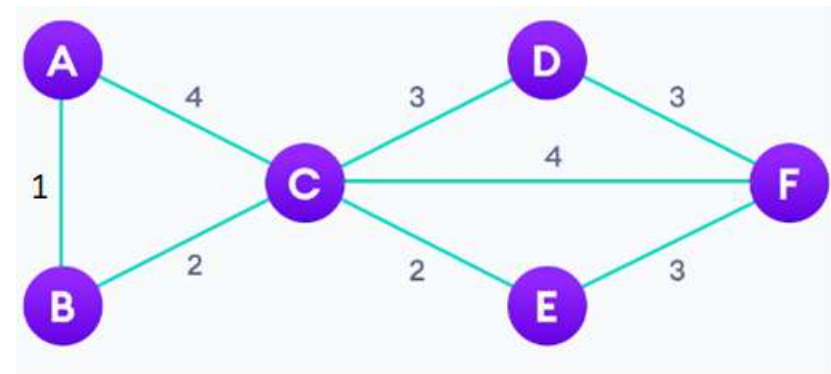
# Application of Prim's algorithm

**Example:** Apply Kruskal's algorithm to find the MST of the following graph. Start with vertex **A**

vertex	known	cost	previous
A	0	0	-
B	0	$\infty$	-
C	0	$\infty$	-
D	0	$\infty$	-
E	0	$\infty$	-
F	0	$\infty$	-

0: False  
1: True

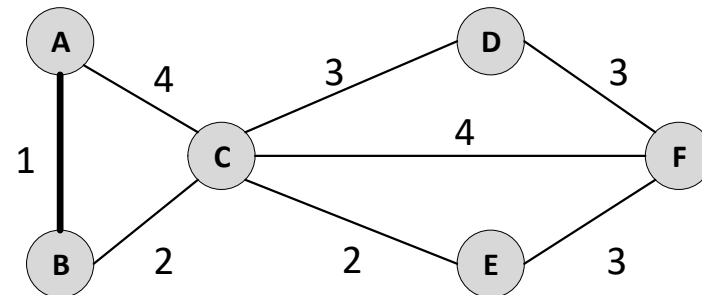
Initially, the cheapest unknown vertex is (**A**)



# Application of Prim's algorithm

vertex	known	cost	previous
A	1	0	-
B	1	1	A
C	0	4	-
D	0	$\infty$	-
E	0	$\infty$	-
F	0	$\infty$	-

$1 < \infty$   
 $4 < \infty$



Update cost of neighbors of vertex A

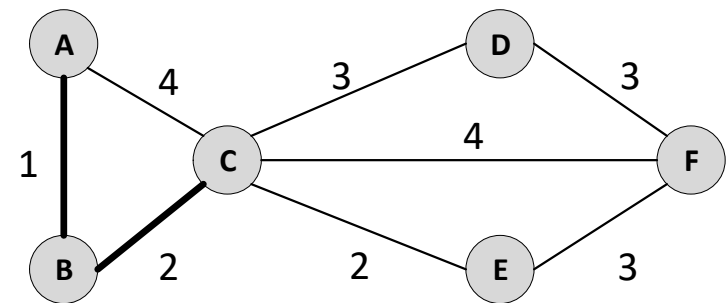
Find the cheapest unknown vertex (**B**)

Set known field of **B** to True

# Application of Prim's algorithm

vertex	known	cost	previous
A	1	0	-
B	1	1	A
C	1	<del>4</del> 2	B
D	0	$\infty$	-
E	0	$\infty$	-
F	0	$\infty$	-

2 < 4



Update cost of neighbors of vertex B

Find cheapest unknown vertex (C)

Set known field of c to True

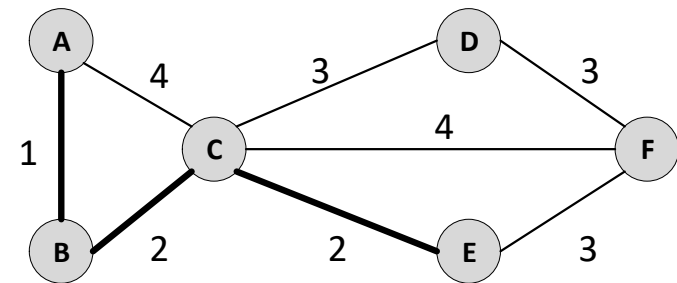
# Application of Prim's algorithm

vertex	known	cost	previous
A	1	0	-
B	1	1	A
C	1	<del>4</del> 2	B
D	0	3	-
E	1	2	C
F	0	4	-

$3 < \infty$

$2 < \infty$

$4 < \infty$



Update cost of neighbors of vertex C

Find cheapest unknown vertex (**E**)

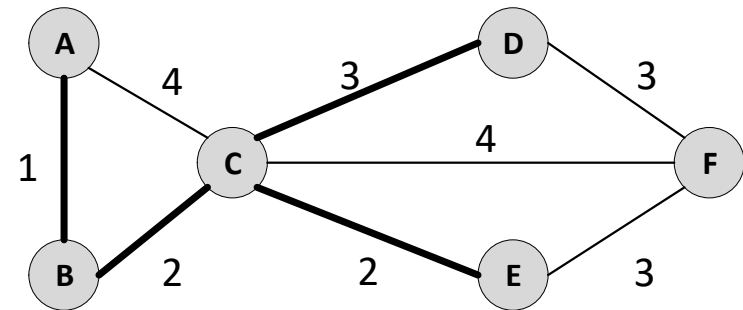
Set known field of **E** to True



# Application of Prim's algorithm

vertex	known	cost	previous
A	1	0	-
B	1	1	A
C	1	<del>4</del> 2	B
D	1	<span style="border: 1px solid black; padding: 2px;">3</span>	C
E	1	2	C
F	0	<span style="border: 1px solid black; padding: 2px;"><del>4</del> 3</span>	-

3 < 4



Update cost of neighbors of vertex E

Find cheapest unknown vertex (**D**)

Set known field of **D** to True

**Note:** a tie can be resolved arbitrarily

# Application of Prim's algorithm

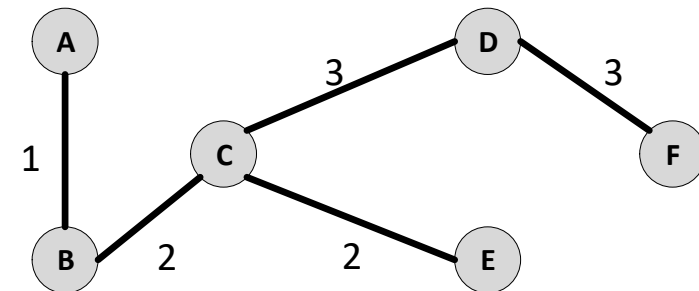
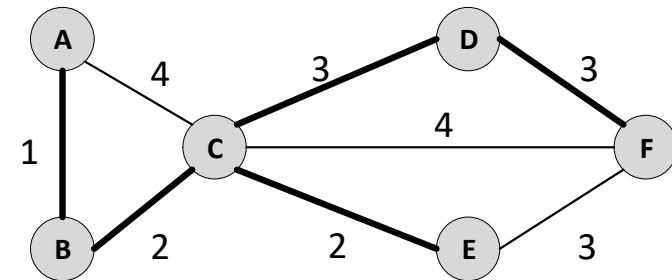
vertex	known	cost	previous
A	1	0	-
B	1	1	A
C	1	<del>4</del> 2	B
D	1	3	C
E	1	2	C
F	1	<del>4</del> 3	D

Update cost of neighbors of vertex D

Find cheapest unknown vertex (**F**)

Set known field of **F** to True

**Stop:** All vertices are known



MST cost = 11

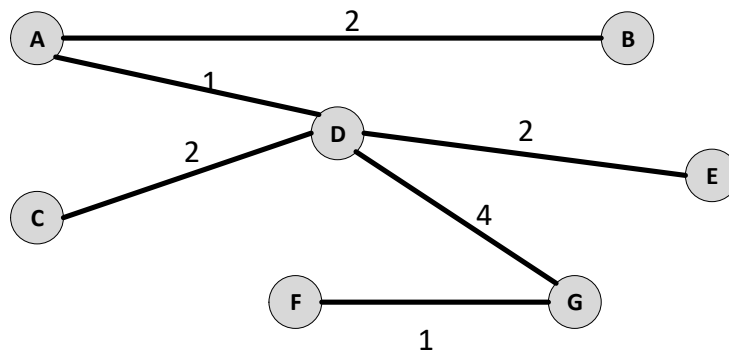
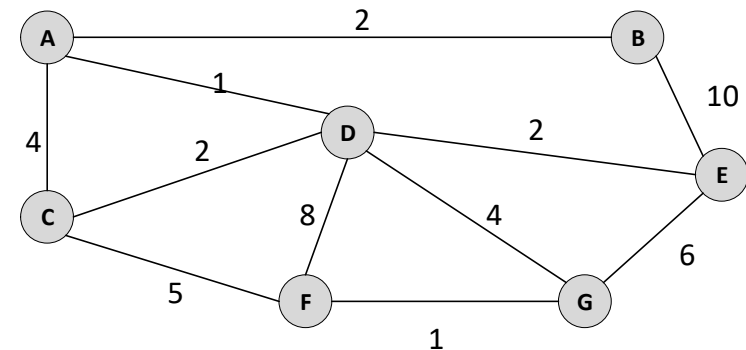
# Application of Prim's algorithm

vertex	known	cost	previous
A	1	0	-
B	1	1	A
C	1	<del>4</del> 2	B
D	1	3	C
E	1	2	C
F	1	<del>4</del> 3	D

We can create the tree from the table as the cost and path are known

# Application of Prim's algorithm

**Example:** Apply Prim's algorithm to the following graph:



MST cost = 12

# Prim's algorithm

## ○ Implementation:

- It necessary to provide each vertex not in the current tree with the **information about the shortest edge connecting the vertex to a tree vertex**.
- We can provide such information by **attaching two labels to a vertex**: the name of the nearest tree vertex and the length (the weight) of the corresponding edge.
- Vertices that are not adjacent to any of the tree vertices can be given the  $\infty$  label indicating their “infinite” distance to the tree vertices and a null label for the name of the nearest tree vertex.
- With such labels, finding the next vertex to be added to the current tree  $T = \langle V_T, E_T \rangle$  becomes a simple task of **finding a vertex with the smallest distance label** in the set  $V - VT$ .

# Pseudocode of Prim's algorithm

## **ALGORITHM** *Prim*( $G$ )

//Prim's algorithm for constructing a minimum spanning tree

//Input: A weighted connected graph  $G = \langle V, E \rangle$

//Output:  $E_T$ , the set of edges composing a minimum spanning tree of  $G$

$V_T \leftarrow \{v_0\}$  //the set of tree vertices can be initialized with any vertex

$E_T \leftarrow \emptyset$

**for**  $i \leftarrow 1$  **to**  $|V| - 1$  **do**

    find a minimum-weight edge  $e^* = (v^*, u^*)$  among all the edges  $(v, u)$   
    such that  $v$  is in  $V_T$  and  $u$  is in  $V - V_T$

$V_T \leftarrow V_T \cup \{u^*\}$

$E_T \leftarrow E_T \cup \{e^*\}$

**return**  $E_T$

# Time Complexity of Prim's algorithms

## ○ How efficient is Prim's algorithm?

- The answer **depends on the data structures chosen for the graph itself and for the priority queue of the set  $V - V_T$**  whose vertex priorities are the distances to the nearest tree vertices

If a graph is represented by its **adjacency lists** and the **priority queue is implemented as a min-heap**, the running time of the algorithm is in  **$O(|E| \log |V|)$** .

Search



A min-heap is a complete binary tree in which every element is less than or equal to its children. **Deletion** of the smallest element from and **insertion** of a new element into a min-heap of size  $n$  are  **$O(\log n)$**

# Animations of MST algorithms

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For a better understanding of Kruskal's, Prim's algorithms and visualizing its operation through animation:

<https://visualgo.net/en/mst?slide=1>

<https://www.cs.usfca.edu/~galles/visualization/Kruskal.html>

<https://www.cs.usfca.edu/~galles/visualization/Prim.html>



# Exercise

Indicate whether the following statements are true or false. **Justify your answer with examples.**

1. If edge weights of a connected weighted graph are all distinct, the graph must have exactly one minimum spanning tree.
2. If  $e$  is a minimum-weight edge in a connected weighted graph, it must be among edges of at least one minimum spanning tree of the graph.
3. If  $e$  is a minimum-weight edge in a connected weighted graph, it must be among edges of each minimum spanning tree of the graph.
4. If edge weights of a connected weighted graph are not all distinct, the graph must have more than one minimum spanning tree.