A Sublinear-Time Quantum Algorithm for Approximating Partition Functions

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Abstract

We present a novel quantum algorithm for estimating Gibbs partition functions in *sublinear time* with respect to the logarithm of the size of the state space. This is the first speed-up of this type to be obtained over the seminal nearly-linear time algorithm of Štefankovič, Vempala and Vigoda [ŠVV09]. Our result also preserves the quadratic speed-up in precision and spectral gap achieved in previous work by exploiting the properties of quantum Markov chains. As an application, we obtain new polynomial improvements over the best-known algorithms for computing the partition function of the Ising model, and counting the number of k-colorings, matchings or independent sets of a graph.

Our approach relies on developing new variants of the quantum phase and amplitude estimation algorithms that return nearly *unbiased* estimates with *low variance* and *without destroying* their initial quantum state. We extend these subroutines into a nearly unbiased quantum mean estimator that reduces the variance quadratically faster than the classical empirical mean. No such estimator was known to exist prior to our work. These properties, which are of general interest, lead to better convergence guarantees within the paradigm of simulated annealing for computing partition functions.

1 Introduction

The Boltzmann–Gibbs distribution is a paradigmatic tool for modeling systems that obey the principle of maximum entropy. It arises in several fields of research such as statistical mechanics [Geo11; FV17; Sin82], economic modeling [DY00], image processing [GG84; Bes86], statistical learning theory [Cat04], etc. The probability assigned by the Gibbs distribution to each possible configuration of a system is inversely proportional to the exponential of its energy multiplied by the inverse temperature. Mathematically, for a classical Hamiltonian $H:\Omega\to\{0,\ldots,n\}$ specifying the energy level of each configuration x, the Gibbs distribution at inverse temperature β is given by $\pi_{\beta}(x)=\frac{1}{Z(\beta)}e^{-\beta H(x)}$ where the normalization factor

$$Z(\beta) = \sum_{x \in \Omega} e^{-\beta H(x)} \tag{1}$$

is called the partition function. While it is often straightforward to evaluate the partition function at high temperature (when $\beta=0$, it is just the number of possible configurations), the low-temperature regime captures ground state properties that are challenging to compute. For instance, $Z(\infty)$ can represent the cardinalities of exponentially large combinatorial structures (such as the number of colorings of a graph [Jer95; ŠVV09], the volume of convex bodies [DFK91; DF91] or the permanent of non-negative matrices [JSV04]) which are generally #P-hard to compute exactly [Val79; DF88; JS93].

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The standard approach for evaluating partition functions at low-temperature is to resort to Markov chain Monte Carlo methods [JS96]. A celebrated line of works [VC72; JVV86; DF91; BŠVV08; ŠVV09] has shown how to turn the ability to efficiently sample from the Gibbs distribution into that to efficiently approximate the partition function. At a high level, these works rely on the same two-stage simulated annealing algorithm. First, they compute a short cooling schedule, which is an increasing sequence of inverse temperature $0 = \beta_1 < \cdots < \beta_\ell = \infty$ with limited fluctuations in Gibbs distributions between two consecutive values. Next, the partition function is expressed as a telescoping product

$$Z(\infty) = Z(0) \prod_{i=0}^{\ell-1} \frac{Z(\beta_{i+1})}{Z(\beta_i)}$$
(2)

which is approximated by using a suitable product estimator. As an example, the seminal algorithm of Štefankovič, Vempala and Vigoda [ŠVV09] generates a so-called "Chebyshev cooling schedule" of length $\ell = O(\sqrt{\log |\Omega|})$ (ignoring logarithmic dependences on the degree n, which is often on the order of $n \sim \log |\Omega|$) where each ratio $Z(\beta_{i+1})/Z(\beta_i)$ is expressed as the expectation value of a random variable X_i with bounded relative second moment $\mathbb{E}[X_i^2] \leq O(\mathbb{E}[X_i]^2)$. Such schedules are known to admit a product estimator that requires $O(\ell^2/\epsilon^2)$ classical Gibbs samples to estimate $Z(\infty) = Z(0) \cdot \mathbb{E}[X_1] \cdots \mathbb{E}[X_\ell]$ with relative error ϵ . Thus, if we let δ denote the spectral gap of a Markov chain generating samples from the considered Gibbs distributions, the overall cost of this classical algorithm is $O(\log |\Omega|/(\epsilon^2 \delta))$.

The theory of quantum algorithms provides several directions for accelerating the computation of partition functions. Quantum Markov chains [Sze04; MNRS11] can prepare coherent "qsample" encodings $|\pi_{\beta}\rangle = \sum_{x} \sqrt{\pi_{\beta}(x)} |x\rangle$ of the Gibbs distribution with a quadratic improvement in spectral gap for the rate of convergence (but an increase dependence on other parameters). Quantum phase estimation [Kit95] and amplitude estimation [BHMT02] lead to quadratically better convergence rates for estimating expectation values [Ter99; AW99; Hei02; BDGT11; Mon15; HM19; Ham21]. Yet, while this may hint at the existence of an $O(\sqrt{\log |\Omega|}/(\epsilon\sqrt{\delta}))$ quantum algorithm for estimating partition functions, the best known algorithms [HW20; AHN+21] still require a linear scaling $O(\log |\Omega|/(\epsilon \sqrt{\delta}))$ with the logarithm of the size of the state space. This bottleneck is due to additional challenges posed by current quantum algorithmic techniques. It is for instance significantly harder to prepare the qsample $|\pi_{\beta}\rangle$ (at low temperature) than to implement the reflection $\mathbb{I} - 2|\pi_{\beta}\rangle\langle\pi_{\beta}|$ through it. This obstacle requires using nondestructive procedures [MW05; WA08; WCNA09; TOV+11; ORR13; HW20] to recycle the same qsamples all along the algorithm, and to rely mostly on the reflection operator. Another fundamental limitation faced by current best quantum mean estimators [Mon15; HM19; Ham21] is the presence of biases in the estimates that degrade the convergence guarantee of the product estimators.

1.1 Contributions

Our main contribution is to develop the first quantum algorithm for approximating Gibbs partition functions with a complexity scaling sublinearly with respect to the logarithm of the size of the state space. Formally, we prove the next theorem in Section 4.

Theorem 4.1 (Informal). There is a quantum algorithm such that, given a Gibbs distribution generated by a Markov chain with spectral gap δ , it computes an estimate \widetilde{Z} of the partition function at zero temperature satisfying $|\widetilde{Z} - Z(\infty)| \le \epsilon Z(\infty)$ by using $\widetilde{O}(\log^{3/4} |\Omega| \log^{3/4}(n)/\epsilon + \sqrt{\log |\Omega|} \log(n))$ steps of the quantum walk operator.

Our result achieves state-of-the-art dependence on the other parameters (spectral gap δ , accuracy ϵ , degree n of the partition function) up to logarithmic factors. We provide a comparison with prior work in Table 1.

¹We use the notation $\widetilde{O}(.)$ to hide polylogarithmic factors in the argument.

	Schedule generation	Mean-value estimation	Total cost
[DF91; BŠVV08]	0 (non-adaptive)	$\widetilde{O}ig(\log^2 \lvert \Omega \rvert / (\epsilon^2 \delta)ig)$	$\widetilde{O}\left(\log^2 \Omega /(\epsilon^2\delta)\right)$
[ŠVV09; Hub15; Kol18]	$\widetilde{O}ig(\log \Omega /\deltaig)$	$\widetilde{O}ig(\log \lvert \Omega \rvert / (\epsilon^2 \delta)ig)$	$\widetilde{O}ig(\log \Omega /(\epsilon^2\delta)ig)$
[WCNA09]	Use [BŠVV08]	$\widetilde{O}(\log^2 \Omega /(\epsilon\sqrt{\delta}))$	$\widetilde{O}\left(\log^2 \Omega /(\epsilon\sqrt{\delta})\right)$
[Mon15]	Use [ŠVV09]	$\widetilde{O}ig(\log \Omega /(\epsilon\sqrt{\delta})ig)$	$\widetilde{O}(\log \Omega (1/\delta + 1/\epsilon\sqrt{\delta}))$
[HW20; AHN+21]	$\widetilde{O}ig(\sqrt{\log \lvert \Omega vert / \delta}ig)$	Use [Mon15]	$\widetilde{O}(\log \Omega /(\epsilon \sqrt{\delta}))$
Our work	Use [HW20; AHN+21]	$\widetilde{O}(\log^{3/4} \Omega /(\epsilon\sqrt{\delta}))$	$\widetilde{O}\left(\log^{3/4} \Omega /(\epsilon\sqrt{\delta})\right)$

Table 1: Comparison of the complexity (in terms of Markov chain steps) needed to compute partition functions over a state space Ω , where δ is the spectral gap of the Markov chain and ϵ is the accuracy parameter. Here, we omit the polylogarithmic dependencies on the degree n of the partition function, which is typically on the order of $n \sim \log |\Omega|$, $poly(1/\delta)$. The first two rows are classical algorithms only.

The main technical ingredients of our work are new variants of the quantum phase and amplitude estimation algorithms (Theorems 2.2 and 2.4) that return (nearly) unbiased estimates and restore the quantum set used in the process with high probability. We extend these properties into new quantum mean estimators described in Section 3. In particular, the next result is crucial in the development of our improved product estimator (Theorem 3.3), and may be of independent interest. It shows that the relative error ϵ in bias can be decreased exponentially quickly, whereas previous works [Mon15; HM19; Ham21] incurred an inverse linear dependence on ϵ .

Proposition 3.1 (Informal). For any parameters $t, \epsilon, \widetilde{\sigma}$ there is a quantum algorithm such that, given a random variable X with variance at most $\widetilde{\sigma}$, it computes a mean estimate $\widetilde{\mu}$ with bias $|\mathbb{E}[\widetilde{\mu}] - \mu| \le \epsilon \widetilde{\sigma}$ and variance $\operatorname{Var}[\widetilde{\mu}] \le \left(\frac{\widetilde{\sigma}}{t}\right)^2$ by using one copy of a qsample $|\pi_X\rangle$ (restored at the end of the computation) and $\widetilde{O}(t \log(1/\epsilon)^2)$ applications of the reflection $\mathbb{I} - 2|\pi_X\rangle\langle\pi_X|$.

Finally, we provide applications of our work in Section 4.2, where we improved upon the best known algorithms for several approximate counting problems that can be phrased as partition functions. These results are described succinctly in Table 2.

	Colorings, Ising model, Independent sets	Matchings
[ŠVV09]	$\widetilde{O}(V ^2/\epsilon^2)$	$\widetilde{O}(V ^2 E /\epsilon^2)$
[HW20; AHN+21]	$\widetilde{O}(V ^{1.5}/\epsilon)$	$\widetilde{O}(V ^{1.5} E ^{0.5}/\epsilon)$
Our work	$\widetilde{O}(V ^{1.25}/\epsilon)$	$\widetilde{O}(V ^{1.25} E ^{0.5}/\epsilon)$

Table 2: Comparison of the best known classical (row 1) and quantum (rows 2–3) algorithms for approximate counting problems. Here, ϵ is the accuracy parameter, V is the vertex set, and E is the edge set.

1.2 Proof overview

We give a high-level description of the algorithms developed in this paper. We first explain the main differences with previous works [WCNA09; Mon15; HW20; AHN+21] that allow us to obtain a sublinear algorithm for estimating partition functions. Next, we present new variants of phase estimation, amplitude estimation and quantum mean estimation that are needed for implementing our approach.

Estimating partition functions (Section 4). The current bottleneck in quantizations of the classical simulated annealing algorithm of Štefankovič, Vempala and Vigoda [ŠVV09] lies in estimating the expectation of a Chebyshev cooling schedule for the telescoping product displayed in Equation (2). Abstractly, this problem amounts to estimating with relative error ϵ

the expectation of the product $X = X_1 \cdots X_\ell$ of ℓ independent random variables with bounded relative variance $\operatorname{Var}[X_i] \leq O(\mathbb{E}[X_i]^2)$. By Bernoulli's inequality, one can show that estimating the expectation of each inner random variable X_i with relative error $O(\epsilon/\ell)$ and taking the product of the estimates is sufficient for that purpose. Montanaro [Mon15] developed a quantum algorithm for computing each such inner estimate in time $O(\ell/\epsilon)$, quadratically faster than it is possible classically, leading to an overall complexity of $O(\ell^2/\epsilon)$. Nevertheless, a different classical estimator from Dyer and Frieze [DF91] provides the same quadratic complexity with respect to the schedule length: replace the ϵ/ℓ -error inner estimates with unbiased estimates of variance $O((\epsilon^2/\ell) \cdot \mathbb{E}[X_i]^2)$. The latter estimates can simply be obtained by averaging $O(\ell/\epsilon^2)$ samples due to the bounded variance property. The overall variance of this new product estimator is shown to be $O((\epsilon \mathbb{E}[X])^2)$ which, by Chebyshev's inequality and the fact that it is unbiased. implies that the overall relative error is ϵ . We follow a similar approach in our work to speed up the estimation of $\mathbb{E}[X]$. Our main contribution is a new quantum estimator that reduces the variance quadratically faster than classically, while keeping the estimates (nearly) unbiased. This allows us to compute each inner estimate in time $\widetilde{O}(\sqrt{\ell}/\epsilon)$, leading to an overall complexity of $\widetilde{O}(\ell^{3/2}/\epsilon)$. Our estimator requires new unbiased variants of the phase and amplitude estimation algorithms, which are sketched in the next paragraphs. Additionally, these algorithms are made nondestructive (i.e. they restore a copy of their starting state) to ensure the reusability of the gsamples which are an expensive resource in our applications.

Unbiased phase estimation (Section 2.1). The phase estimation problem asks the question of estimating the eigenphase $\theta \in [0,1)$ of a quantum state $|\psi\rangle$ satisfying $U|\psi\rangle = e^{2\pi i\theta}|\psi\rangle$ for a given unitary operator U. Kitaev's algorithm [Kit95] returns an estimate $\widetilde{\theta}$ within distance 1/tfrom θ with constant success probability by using O(t) controlled-U operations. By standard success amplification techniques, the variance of this estimate can be guaranteed to be of the order of $1/t^2 + \epsilon$ at the cost of an $O(\log 1/\epsilon)$ overhead in complexity. One simple idea² to make this estimator unbiased is to consider the phase-shifted unitary $U_{\varphi}|\psi\rangle = e^{2\pi i(\theta+\varphi)}|\psi\rangle$ for a random φ , run phase estimation on it and subtract the shift φ from the estimate. Although it provides an unbiased estimate of $e^{2\pi i\theta}$ (and, therefore, of $\sin^2(\theta)$), we do not know how to reduce its variance without introducing a new bias. We overcome this difficulty by exploiting more properties of the output distribution of phase estimation and looking for an unbiased estimate of θ directly. First, we show that it is possible to compute with high probability the exact value of the first $\log t$ bits of $\theta + \varphi = 0.b_1b_2...$ for a well-chosen phase shift φ (steps 1–5 in Algorithm 1). This relies on the ability to pinpoint exactly the interval $\left[\frac{k}{t}, \frac{k+1}{t}\right]$ for $k \in \{0, \dots, t-1\}$ containing the phase $\theta + \varphi$, as long as the latter is not too close to an interval endpoint (which is avoided by the choice of φ). Secondly, we look for a low-variance unbiased estimate of the remaining bits $0.0^{\log t}b_{\log t+1}b_{\log t+2}\dots$ (steps 6–7 in Algorithm 1). For that, we consider the exponentiated unitary U_{φ}^t which amplifies the eigenphase to $\lambda = 0.b_{\log t + 1}b_{\log t + 2}\dots$ Using phase-to-amplitude conversion techniques, we transform it into a new unitary V that encodes λ into the amplitude of a new auxiliary quantum register. This register can simply be measured to obtain an unbiased binary estimate $\lambda \in \{-1,1\}$ of λ . The variance of the correction term λ/t added to the previously computed bits $0.b_1b_2...b_{\log t}$ is thus of order $O(1/t^2)$. We also have to be careful that λ is bounded away from 0 and 1 in order for the conversion techniques to succeed. This is again guaranteed by carefully choosing the phase shift. The final algorithm is summarized in Theorem 2.2.

Nondestructive amplitude estimation (Appendix B). The amplitude estimation algorithm [BHMT02] approximates the measurement probability $p = ||\Pi|\psi\rangle||^2$ for a state $|\psi\rangle$ and a projector Π , given access to the reflection operators $R_{\psi} = \mathbb{I} - 2|\psi\rangle\langle\psi|$ and $R_{\Pi} = \mathbb{I} - 2\Pi$. This algorithm relies on the observation that the Grover operator $G = -R_{\psi}R_{\Pi}$ has two conjugate

²This was communicated to us by András Gilyén.

eigenvalues $e^{\pm 2i \arcsin(\sqrt{p})}$ with $|\psi\rangle$ being a superposition over the two corresponding eigenvectors. In its original form [BHMT02], the algorithm consists of running phase estimation on the latter state and applying the function $x \mapsto \sin^2(\pi x)$ on the measured register. Although the post-measurement state is still a superposition over the two above eigenvectors, this process can introduce a relative phase that makes it far from the initial state $|\psi\rangle$. Harrow and Wei [HW20] argued that amplitude estimation can be made nondestructive (i.e. it restores the state $|\psi\rangle$) by using an uncomputation trick inspired by the Marriott-Watrous rewinding technique [MW05]. We discuss this result in Appendix B, where we provide a new proof of it that avoids some complications in the analysis.

Nondestructive unbiased amplitude estimation (Section 2.2). We aim at combining the above two properties in order to obtain a variant of amplitude estimation that is both nondestructive and unbiased. Unfortunately, the properties of the Grover operator do not allow us to simply use the unbiased phase estimation on it. Indeed, it would require the ability to shift its two eigenphases by opposite values simultaneously. Moreover, it would provide an unbiased estimate of $\arcsin(\sqrt{p})$ instead of p. We overcome these two obstacles by first applying the function $x \mapsto \sin^2(\pi x)$ on the eigenphases of the Grover operator (via amplitudeto-phase conversion techniques [GAW17]), which produces a new unitary G' with "merged" eigenvalue $e^{2\pi ip}$ and eigenvector $|\psi\rangle$. We next apply the unbiased phase estimation on G'and $|\psi\rangle$, which is inherently nondestructive since the latter state is now an eigenvector. Yet, this unbiased estimator poses a new problem: its variance is worse than that of the original amplitude estimation algorithm (roughly, $1/t^2$ vs. $p/t^2 + 1/t^4$), which is due to encoding p instead of $\arcsin(\sqrt{p})$ into the phase. Our solution to this problem is to first compute a rough biased amplitude estimate $q = \Theta(\max(p, 1/t^2))$ (via standard nondestructive amplitude estimation) and to apply the new function $x \mapsto \sin^2(\pi x)/q$ on the eigenphases of the Grover operator (via linear amplitude amplification [Low17]). Since the obtained operator will require time $O(1/\sqrt{q})$ to be simulated, we are left with $O(\sqrt{qt})$ steps available to perform unbiased phase estimation on it. The variance is then shown to be of the order of p/t^2 when $p = O(1/t^2)$ and q/t^2 otherwise. A side tool of independent interest (needed when p is smaller than $O(1/t^2)$) is a nondestructive coin flipping algorithm (Proposition 2.3) for sampling from the Bernoulli variable of parameter $\|\Pi|\psi\rangle\|^2$.

Nondestructive unbiased mean estimator (Section 3). Our final step is to generalize the amplitude estimation algorithm to estimate the expectation of an arbitrary random variable Xwhose distribution is encoded into a quample $|\pi_X\rangle = \sum_x \sqrt{\Pr[X=x]} |x\rangle$ (amplitude estimation handles the case of Bernoulli distributions). The estimator shall meet the three requirements of being unbiased, nondestructive and low-variance in order to be applied efficiently to the partition function problems. We build upon the quantum estimators from [Hei02; Mon15; HM19; Ham21] that already satisfy the low-variance property. In the latter works, the estimation of $\mathbb{E}[X]$ is reduced to estimating the means of a series of Bernoulli distributions whose parameters are determined by certain quantiles of the input distribution. We follow the same approach, by instead using the nondestructive unbiased amplitude estimation algorithm in the reduction. This is not enough yet to make the estimator nondestructive and unbiased. First, we modify a recentering step in [Mon15; Ham21] that computed a rough mean estimate by averaging classical samples (obtained from destructive measurements of copies of $|\pi_X\rangle$). We develop a new median estimator for this purpose that needs not destroy any copy of $|\pi_{\chi}\rangle$ (Proposition 3.2). Secondly, the existing estimators require truncating the random variable X by replacing its outcomes larger than a certain threshold value with zero. We suppress most of the truncation-induced bias by adding extra Bernoulli distributions to the reduction. The sum of these added estimates has low variance and is equal (in expectation) to most of the previously truncated tail of X. The final estimator is summarized in Proposition 3.1.

2 Unbiased and nondestructive quantum subroutines

2.1 Phase estimation

In this section, we describe a variant of phase estimation that returns a (nearly) unbiased estimate. We use the next notation for separating the most and least significant bits of a phase $\theta \in [0, 1]$.

Definition 2.1. Let $\theta \in [0,1]$ be a real number with binary expansion $\theta = 0.\theta_1\theta_2\theta_3...$ where $\theta_j \in \{0,1\}$. Then, for any integer $\tau \geq 0$, we denote $\theta_{\leq \tau} = 0.\theta_1\theta_2...\theta_{\tau}$ and $\theta_{>\tau} = 0.\theta_{\tau+1}\theta_{\tau+2}...$ such that $\theta = \theta_{<\tau} + 2^{-\tau}\theta_{>\tau}$.

Suppose that we can call a controlled unitary U, and that we have a copy of an eigenstate $|\psi\rangle$, satisfying $U|\psi\rangle = e^{2\pi i\theta}|\psi\rangle$. Then, we can implement the *phase-shift* operation $e^{2\pi i\varphi}U|\psi\rangle = e^{2\pi i(\theta+\varphi)}|\psi\rangle$ for any φ with one call to U, and the *bit-shift* operation $U^{2^{\tau}}|\psi\rangle = e^{2\pi i\theta>\tau}|\psi\rangle$ with 2^{τ} calls to U. We make use of these two operations to design the following unbiased, nondestructive, low-variance phase estimation algorithm.

Algorithm 1. Unbiased low-variance phase estimation, Ub-Phase $(U, |\psi\rangle, t, \epsilon)$.

- 1: **for** k = 0, ..., 8 **do**
- 2: Set $\varphi = k/(16t')$ where t' = 8t.
- 3: Run phase estimation $\lceil 200 \log(72t'/\epsilon) \rceil$ times on the phase-shifted unitary $e^{2\pi i \varphi} U$ with initial state $|\psi\rangle$ and time t'. Compute the frequencies $(\widetilde{p}(i))_{i\in\{0,\dots,t'-1\}}$ of the obtained values.
- 4: if there is an index i such that $\widetilde{p}(i)$, $\widetilde{p}(i+1) \ge 0.17$ and $(i/t')_{>\tau} \in (4/7, 5/7)$ then
- 5: Stop the for loop and set $\tilde{\theta}_{\varphi} = (i/t')_{\leq \tau}$.
- 6: Let $U_{\varphi} = e^{2\pi i \varphi} U$. Apply phase-to-amplitude conversion on the exponentiated unitary U_{φ}^t with precision $\epsilon/4$ to obtain a unitary V such that

$$V(|\psi\rangle|0\rangle^{\otimes a}) = |\psi\rangle(\sqrt{1-p'}|0\rangle^{\otimes a} + \sqrt{p'}|\Phi^{\perp}\rangle).$$

- 7: Compute the state $V(|\psi\rangle|0\rangle^{\otimes a})$ and measure its last a qubits in the standard basis. If the result is the all-zero string then set b=0 else set $b=1/(2\pi)$.
- 8: Output $\widetilde{\theta} = \widetilde{\theta}_{\varphi} + b/t \varphi$.

Theorem 2.2 (Unbiased low-variance phase estimation). Let U be a unitary operator with an eigenvector $|\psi\rangle$ such that $U|\psi\rangle = e^{2\pi i\theta}|\psi\rangle$ where $\theta \in [0,1/2]$. Given $t=2^{\tau} \geq 1$ and $\epsilon \in (0,1)$, the unbiased low-variance phase estimation algorithm Ub-Phase $(U,|\psi\rangle,t,\epsilon)$ (Algorithm 1) outputs an estimate $\widetilde{\theta} \in [-1,1]$ such that

$$\left| \mathbb{E} \left[\widetilde{\theta} \right] - \theta \right| \le \epsilon \quad and \quad \operatorname{Var} \left[\widetilde{\theta} \right] \le \frac{1}{t^2} + \epsilon.$$

The algorithm needs one copy of $|\psi\rangle$, which is restored at the end of the computation with probability at least $1 - \epsilon$, and $O(t \log(t/\epsilon))$ controlled-U operations.

Proof. We decompose the analysis of Algorithm 1 into three parts. First, we show that the two phases $\varphi \in (0, 1/t)$ and $\widetilde{\theta}_{\varphi} \in (0, 1)$ obtained at the end of steps 1–5 satisfy the equations

$$\widetilde{\theta}_{\varphi} = (\theta + \varphi)_{\leq \tau} \quad \text{and} \quad (\theta + \varphi)_{>\tau} \in (1/2, 3/4)$$
 (3)

with probability at least $1 - \epsilon/8$. We refer to this part as exact phase estimation since $\widetilde{\theta}_{\varphi}$ is exactly equal to the first τ bits of the shifted phase $\theta + \varphi$. Next, conditioned on any pair $(\varphi, \widetilde{\theta}_{\varphi})$ satisfying the above equation, we prove that the estimate b obtained at the end of steps 6–7 satisfies

$$|\mathbb{E}[b \mid (\varphi, \widetilde{\theta}_{\varphi})] - (\theta + \varphi)_{>\tau}| \le \epsilon/2 \quad \text{and} \quad \operatorname{Var}[b \mid (\varphi, \widetilde{\theta}_{\varphi})] \le 1.$$
 (4)

We refer to this part as *unbiased phase estimation*. Finally, we analyze the expectation and variance of the final estimate constructed at step 8.

Exact phase estimation (steps 1-5). For each phase shift φ and integer $i \in \{0, \dots, t'-1\}$, let ϵ_i^{φ} denote the distance between the angles $\theta + \varphi$ and i/t' along the unit circle. The two smallest distances are achieved by $\epsilon_{i^*}^{\varphi}$, $\epsilon_{i^*+1}^{\varphi} \leq 1/t'$ where $i^* = t'(\theta + \varphi)_{\leq 3\tau}$, whereas the other indices $j \notin \{i^*, i^* + 1\}$ are at distance at least $\epsilon_j^{\varphi} > 1/t'$. By Hoeffding's inequality and a union bound over the t' possible indices, at each round of step 3 the empirical frequency vector \widetilde{p} is at distance $\|p - \widetilde{p}\|_{\infty} \leq 0.05$ from the probability vector p with probability at least $1 - \epsilon/72$. Since step 3 is executed at most 9 times, all of the frequency vectors computed by the algorithm satisfy this bound with probability at least $1 - \epsilon/8$. On the other hand, there is at least one value of φ (among the 9 possible ones) such that $\epsilon_{i^*}^{\varphi}$, $\epsilon_{i^*+1}^{\varphi} \leq 5/(8t')$ and $(\theta + \varphi)_{>\tau} \in (1/2, 3/4)$. The algorithm will correctly detect such a value because of the gaps proved in Corollary A.2 between the probabilities $p(i^*)$, $p(i^*+1)$ and the probabilities p(j) for $j \notin \{i^*, i^*+1\}$. This proves Equation (3).

Unbiased phase estimation (steps 6-7). The state $|\psi\rangle$ is an eigenvector of U_{φ}^t such that $U_{\varphi}^t|\psi\rangle = e^{2\pi i(\theta+\varphi)>\tau}|\psi\rangle$. If the pair $(\varphi,\widetilde{\theta}_{\varphi})$ obtained at the end of steps 1-6 satisfies Equation (3) then, by Lemma A.5, the amplitude $\sqrt{p'}$ obtained at step 6 is at distance at most $|\sqrt{p'} - \sqrt{2\pi(\theta+\varphi)_{>\tau}}| \le \epsilon/4$ from the shifted phase. Thus, conditioned on any fixed correct pair $(\varphi,\widetilde{\theta}_{\varphi})$, we get $|\mathbb{E}[b|(\varphi,\widetilde{\theta}_{\varphi})] - (\theta+\varphi)_{>\tau}| = |p'-(\theta+\varphi)_{>\tau}| \le \epsilon/2$ and $\mathrm{Var}[b|(\varphi,\widetilde{\theta}_{\varphi})] \le 1$ for the estimate b computed at step 7. This proves Equation (4).

Low-variance (step 8). The expectation and variance of the final estimate $\widetilde{\theta}$ are $|\mathbb{E}[\widetilde{\theta}|(\varphi,\widetilde{\theta}_{\varphi})] - \theta| \leq \epsilon/2$ and $\operatorname{Var}[\widetilde{\theta}|(\varphi,\widetilde{\theta}_{\varphi})] \leq 1/t^2$ conditioned on any pair $(\varphi,\widetilde{\theta}_{\varphi})$ satisfying Equation (3). Since $|\theta| \leq 1$ and Equation (3) holds with probability at least $1 - \epsilon/8$, we obtain by the law of total expectation that $|\mathbb{E}[\widetilde{\theta}] - \theta| \leq \epsilon/2 + \max|\widetilde{\theta} - \theta| \cdot \epsilon/8 \leq 3\epsilon/4$ and by the law of total variance that $\operatorname{Var}[\widetilde{\theta}] = \mathbb{E}[\operatorname{Var}[\widetilde{\theta}|(\varphi,\widetilde{\theta}_{\varphi})]] + \operatorname{Var}[\mathbb{E}[\widetilde{\theta}|(\varphi,\widetilde{\theta}_{\varphi})]] \leq 1/t^2 + \epsilon/8 + \mathbb{E}[|\mathbb{E}[\widetilde{\theta}|(\varphi,\widetilde{\theta}_{\varphi})] - \theta|^2] \leq 1/t^2 + \epsilon/8 + (\epsilon/2)^2 + 4 \cdot \epsilon/8 \leq 1/t^2 + 7\epsilon/8$. The number of controlled-U operations used by the algorithm is $O(t \log(t/\epsilon))$ at steps 1–5 and $O(t \log(1/\epsilon))$ at steps 6–7. Moreover, the state $|\psi\rangle$ is preserved by the phase estimation and the phase-to-amplitude conversion algorithms.

2.2 Amplitude estimation

In this section, we describe a variant of amplitude estimation that returns a (nearly) unbiased estimate and restores the initial state with high probability. We start with a simple procedure, adapted from the Marriott-Watrous scheme [MW05], to sample nondestructively from a Bernoulli variable of parameter $\|\Pi|\psi\rangle\|^2$ given a projector Π and a single copy of a state $|\psi\rangle$.

Algorithm 2. Nondestructive coin flip

- 1: Measure the state $|\psi\rangle$ according to the projectors $\{\Pi, \mathbb{I} \Pi\}$. Set b = 1 if the result is $\Pi|\psi\rangle$ and b = 0 if it is $(\mathbb{I} \Pi)|\psi\rangle$.
- 2: Measure the residual state according to the projectors $\{|\psi\rangle\langle\psi|, \mathbb{I}-|\psi\rangle\langle\psi|\}$.
- 3: **while** the residual state is not $|\psi\rangle$ **do**
- 4: Measure the residual state according to the projectors $\{\Pi, \mathbb{I} \Pi\}$.
- 5: Measure the residual state according to the projectors $\{|\psi\rangle\langle\psi|, \mathbb{I}-|\psi\rangle\langle\psi|\}$.
- 6: Output b and $|\psi\rangle$.

Proposition 2.3 (Nondestructive coin flip). Let $|\psi\rangle$ be a quantum state and Π be a projection operator. The nondestructive coin flip algorithm (Algorithm 2) outputs a Boolean value $b \in \{0,1\}$ such that $\mathbb{E}[b] = ||\Pi|\psi\rangle||^2$. The algorithm needs one copy of $|\psi\rangle$, which is restored at the end of the computation, and O(1) applications in expectation of the reflection operators $\mathbb{I} - 2|\psi\rangle\langle\psi|$ and $\mathbb{I} - 2\Pi$.

Proof. Let $p = \|\Pi|\psi\rangle\|^2$ denote the probability to be estimated and define r = 2p(1-p). By the standard Marriott-Watrous analysis [MW05], the residual state at the end of step 2 is $|\psi\rangle$ with probability 1-r (in which case steps 3–5 need not be executed) and the probability that one iteration of steps 4–5 succeeds in restoring $|\psi\rangle$ is r. Thus, the expected number of iterations needed to restore $|\psi\rangle$ is $r^2\sum_{i=0}^{\infty}(i+1)(1-r)^i=1$.

We now extend the above algorithm to a low-variance unbiased estimator.

Algorithm 3. Nondestructive unbiased amplitude estimation, NdUb-Amplitude $(|\psi\rangle, \Pi, t, \epsilon)$.

- 1: Run nondestructive amplitude estimation Nd-Amplitude($|\psi\rangle, \Pi, 2t, \epsilon/8$) on $|\psi\rangle$ with projector Π to obtain a (biased) amplitude estimate q of $p = ||\Pi|\psi\rangle||^2$.
- 2: Let $\tau = \frac{1}{4} \min\{t, 1/\sqrt{q}\}$. Run linear amplitude amplification on $|\psi\rangle$ with projector Π , time τ and precision $\epsilon/40$ to obtain a unitary $V_{\tau,\epsilon/40}$ preparing a state $|\psi'\rangle = V_{\tau,\epsilon/40}|\psi\rangle$ such that

$$\left| \|\Pi|\psi'\rangle\| - \tau \|\Pi|\psi\rangle\| \right| \le \epsilon/40.$$

- 3: **if** $q \le 1/t^2$ **then**
- 4: Measure the state $|\psi'\rangle$ according to the projectors $\{\Pi, \mathbb{I}-\Pi\}$ by using the nondestructive coin flip algorithm. Let $b \in \{0,1\}$ denote the Boolean value it returns.
- 5: Output $\widetilde{p} = b/\tau^2$.
- 6: **else**
- 7: Run amplitude-to-phase conversion on the unitary $V_{\tau,\epsilon/40}$ with precision $\epsilon' = \Omega\left(\frac{\tau^2}{t^2 \log(t/(\epsilon\tau))}\right)$ to obtain a unitary $U_{\epsilon'}$ such that

$$||U_{\epsilon'}(|\psi'\rangle|0\rangle^{\otimes a}) - e^{i||\Pi|\psi'\rangle||^2} |\psi'\rangle|0\rangle^{\otimes a}|| \le \epsilon'.$$

- 8: Run the unbiased phase estimation algorithm Ub-Phase $(U_{\epsilon'}, |\psi'\rangle|0\rangle^{\otimes a}, 7t/\tau, \epsilon/90)$ on $U_{\epsilon'}$ with (approximate) eigenstate $|\psi'\rangle|0\rangle^{\otimes a}$ to compute an eigenphase estimate \tilde{p}' .
- 9: Output $\widetilde{p} = 2\pi \widetilde{p}'/\tau^2$.

Theorem 2.4 (Nondestructive unbiased amplitude estimation). Let $|\psi\rangle$ be a quantum state and Π be a projection operator with $p = ||\Pi|\psi\rangle||^2$. Given $t \geq 1$ and $\epsilon \in (0,1)$, the nondestructive unbiased amplitude estimation algorithm NdUb-Amplitude $(|\psi\rangle, \Pi, t, \epsilon)$ (Algorithm 3) outputs an estimate $\widetilde{p} \in [-1, 1]$ such that

$$|\mathbb{E}[\widetilde{p}] - p| \le \epsilon \quad and \quad \operatorname{Var}[\widetilde{p}] \le \frac{91p}{t^2} + \epsilon.$$

The algorithm needs one copy of $|\psi\rangle$, which is restored at the end of the computation with probability at least $1 - \epsilon$, and $O(t \log \log(t) \log(t/\epsilon))$ applications in expectation of the reflection operators $\mathbb{I} - 2|\psi\rangle\langle\psi|$ and $\mathbb{I} - 2\Pi$.

Proof. By a simple application of Proposition B.2, with probability at least $1 - \epsilon/8$, the amplitude estimate q computed at step 1 satisfies

$$\tilde{q} = 0 \text{ if } p \le 1/(4t^2), \qquad q \le 7p \text{ if } p \ge 1/(4t^2), \qquad q \ge p/4 \text{ if } q > 1/t^2.$$

We analyze the rest of the algorithm conditioned on the above inequalities being true. Similarly to the proof of Theorem 2.2, by the laws of total expectation and total variance, when removing the condition the expectation and variance of the estimate \tilde{p} will differ respectively by at most $\epsilon/4$ and $7\epsilon/8$ from the values computed below.

The amplification parameter τ at step 2 satisfies $\tau \|\Pi|\psi\rangle\| = \tau \sqrt{p} \le 1/2$ as required by Lemma A.3. Thus, the norm of the post-amplification state $|\psi'\rangle$ projected along Π is

$$\left| \|\Pi|\psi'\rangle\|^2 - \tau^2 p \right| = \left| \|\Pi|\psi'\rangle\| + \tau \|\Pi|\psi\rangle\| \cdot \left| \|\Pi|\psi'\rangle\| - \tau \|\Pi|\psi\rangle\| \right| \le \epsilon/20. \tag{5}$$

We split the analysis of the subsequent steps of Algorithm 3 into two cases depending on whether the biased estimate q is smaller or larger than $1/t^2$.

If $q \leq 1/t^2$ (steps 3–5). We have $\tau = t/4$ and, by Proposition 2.3, the Boolean value b at step 4 is sampled from a Bernoulli distribution of parameter $\mathbb{E}[b] = \|\Pi|\psi'\rangle\|^2$. Thus, the expectation of the output estimate satisfies $|\mathbb{E}[\widetilde{p}] - p| = |(\|\Pi|\psi'\rangle\|/\tau)^2 - p| \leq \epsilon/(20\tau^2) \leq \epsilon/2$ and its variance is $\operatorname{Var}[\widetilde{p}] \leq \mathbb{E}[\widetilde{p}^2] = \|\Pi|\psi'\rangle\|^2/\tau^4 \leq (\tau^2 p + \epsilon/20)/\tau^4 \leq p/\tau^2 + \epsilon/(20\tau^4) \leq 16p/t^2 + \epsilon/8$.

If $q > 1/t^2$ (steps 6–9). We have $\tau = 1/(4\sqrt{q})$. We start by analysing the estimate obtained when the unitary $U_{\epsilon'}$ used in phase estimation (step 8) is replaced with a unitary U that perfectly satisfies

$$U(|\psi'\rangle|0\rangle^{\otimes a}) = e^{i\|\Pi|\psi'\rangle\|^2}|\psi'\rangle|0\rangle^{\otimes a}$$

and is at distance at most $||U - U_{\epsilon'}|| \le \epsilon'$ from $U_{\epsilon'}$ (such a unitary exists since $||U_{\epsilon'}(|\psi'\rangle|0\rangle^{\otimes a}) - e^{i||\Pi|\psi'\rangle||^2}|\psi'\rangle|0\rangle^{\otimes a}|| \le \epsilon'$ by Lemma A.4). We rename the phase and output estimates computed at steps 8 and 9 to \hat{p}' and \hat{p} respectively in this case. Observe that the eigenphase $||\Pi|\psi'\rangle||^2/(2\pi)$ satisfies the boundedness requirement of Theorem 2.2 since it is at most $(\tau^2 p + \epsilon/20)/(2\pi) \le 1/2$ by Equation (5) and $\tau = 1/(4\sqrt{q}) \le 1/(2\sqrt{p})$. Thus, the expectation of the estimate \hat{p}' computed at step 8 satisfies $|\mathbb{E}[2\pi\hat{p}'] - \tau^2 p| \le |\mathbb{E}[2\pi\hat{p}'] - ||\Pi|\psi'\rangle||^2 + ||\Pi|\psi'\rangle||^2 - \tau^2 p| \le 2\pi\epsilon/90 + \epsilon/20$, where the first step is by the triangle inequality and the second step is by Theorem 2.2 and Equation (5). The variance is at most $\operatorname{Var}[\hat{p}'] \le \tau^2/(7t)^2 + \epsilon/90$ by Theorem 2.2. Since the final estimate is the scalar multiple $\hat{p} = 2\pi\hat{p}'/\tau^2$ of \hat{p}' , its expectation and variance are $|\mathbb{E}[\hat{p}] - p| \le 2\pi(2\pi\epsilon/90 + \epsilon/20)/\tau^2 \le \epsilon/4$ and $\operatorname{Var}[\hat{p}] \le 4\pi^2/(7t\tau)^2 + 4\pi^2\epsilon/(90\tau^4) \le 91p/t^2 + \epsilon/9$.

Consider now the case where U is replaced with the actual unitary U_{ϵ} . Let T denote the number of times the operator U_{ϵ} is used by the unbiased phase estimation procedure at step 8. By Theorem 2.2, we have $T = O((t/\tau)\log(t/(\epsilon\tau)))$. By standard approximation arguments (see [NC11, p.194] for instance), the distribution of the actual estimate \tilde{p} is at distance at most $2T\|U - U_{\epsilon'}\|$ (in ℓ_{∞} -norm) from that of \hat{p} . Moreover, by a simple analysis of Algorithm 1, both estimates are distributed in [-1,1] and can take at most $36\pi t/\tau$ different values. We conclude that $|\mathbb{E}[\tilde{p}] - p| \leq |\mathbb{E}[\tilde{p}] - p| + 2T\|U - U_{\epsilon'}\| \cdot 36\pi t/\tau \leq \epsilon/4 + 2T\epsilon' \cdot 36\pi t/\tau \leq \epsilon/2$ and $\mathrm{Var}[\tilde{p}] \leq \mathrm{Var}[\tilde{p}] + 8T\|U - U_{\epsilon'}\| \cdot 36\pi t/\tau \leq 91p/t^2 + \epsilon/9 + 8T\epsilon' \cdot 36\pi t/\tau \leq 91p/t^2 + \epsilon/8$ by choosing a value $\epsilon' = \Theta(\frac{\tau^2}{t^2 \log(t/(\epsilon\tau))})$.

3 Mean estimation

We construct first a quantum estimator that decreases the variance quadratically faster than classically while keeping the estimate (nearly) unbiased. Moreover, it requires a single qsample, which is not destroyed with high probability. The main ingredient is the nondestructive amplitude estimation algorithm constructed in the previous section. The estimator is based on expressing the mean as a linear combination of carefully chosen Bernoulli random variables (with parameters $\widetilde{\mu}_j^+$ and $\widetilde{\mu}_j^-$ defined at steps 4 and 7 of Algorithm 4) which are related to different truncations of the input random variable. We use a more sophisticated truncation pattern than in previous work [Hei02; Mon15; Ham21; CHJ22] to ensure that the estimate is nearly unbiased. Our estimator requires knowing a rough estimate \widetilde{m} of the mean and an upper-bound $\widetilde{\sigma}$ on the variance of the random variable. We explain how to find \widetilde{m} nondestructively in Proposition 3.2, whereas $\widetilde{\sigma}$ will be provided directly by our applications.

Algorithm 4. Unbiased mean estimator, Unbiased $(X, t, \widetilde{m}, \widetilde{\sigma}, \epsilon)$.

- 1: Define the shifted random variable $\bar{X} = X \tilde{m}$.
- 2: Set $a_{-1} = 0$ and $a_j = 2^j \widetilde{\sigma}$ for $j \in \{0, \dots, k\}$, where $k = \lceil \log(580/\epsilon) \rceil$.
- 3: for j = 0 to k do
- 4: Use a controlled rotation to transform $|\pi_X\rangle$ into the state

$$|\pi_j^+\rangle = \sum_{x \notin (a_{j-1}, a_j]} \sqrt{\pi_{\bar{X}}(x)} |x\rangle |0\rangle + \sum_{x \in (a_{j-1}, a_j]} \sqrt{\pi_{\bar{X}}(x)} |x\rangle \left(\sqrt{1 - \frac{x}{a_j}} |0\rangle + \sqrt{\frac{x}{a_j}} |1\rangle\right)$$

and denote $\mu_j^+ = \mathbb{E}\left[\frac{\bar{X}}{a_j}\mathbbm{1}_{\bar{X}\in(a_{j-1},a_j]}\right] = \|(\mathbb{I}\otimes|1\rangle\langle1|)|\pi_j^+\rangle\|^2$.

- 5: Compute an estimate $\widetilde{\mu}_{j}^{+}$ of μ_{j}^{+} by using the nondestructive unbiased amplitude estimation algorithm NdUb-Amplitude($|\pi_{j}^{+}\rangle, \mathbb{I}\otimes |1\rangle\langle 1|, 300t, \epsilon'$) where $\epsilon' = \left(\frac{\epsilon}{2320t}\right)^{2}$.
- 6: Restore $|\pi_i^+\rangle$ to $|\pi_X\rangle$ by undoing the controlled rotation.
- 7: Repeat steps 4–6 with the state

$$|\pi_{j}^{-}\rangle = \sum_{x \notin [-a_{j}, -a_{j-1})} \sqrt{\pi_{\bar{X}}(x)} |x\rangle |0\rangle + \sum_{x \in [-a_{j}, -a_{j-1})} \sqrt{\pi_{\bar{X}}(x)} |x\rangle \left(\sqrt{1 - \frac{|x|}{a_{j}}} |0\rangle + \sqrt{\frac{|x|}{a_{j}}} |1\rangle \right)$$

to obtain an estimate $\widetilde{\mu}_j^-$ of $\mu_j^- = \mathbb{E}\Big[\frac{|\bar{X}|}{a_j}\mathbbm{1}_{\bar{X} \in [-a_j, -a_{j-1})}\Big]$.

8: Output $\widetilde{\mu} = \widetilde{m} + \sum_{j=0}^{k} a_j (\widetilde{\mu}_j^+ - \widetilde{\mu}_j^-).$

Proposition 3.1 (Unbiased mean estimator). Let X be a finite random variable with mean μ and variance σ^2 encoded as a qsample $|\pi_X\rangle$. Given two reals $\epsilon \in (0,1)$ and $t \geq 1$ and two estimates $\widetilde{m}, \widetilde{\sigma}$ such that $|\mu - \widetilde{m}| \leq 17\sigma$ and $\widetilde{\sigma} \geq \sigma$, the unbiased mean estimator Unbiased $(X, t, \widetilde{m}, \widetilde{\sigma}, \epsilon)$ (Algorithm 4) outputs a mean estimate $\widetilde{\mu}$ such that

$$|\mathbb{E}[\widetilde{\mu}] - \mu| \le \epsilon \widetilde{\sigma} \quad and \quad \operatorname{Var}[\widetilde{\mu}] \le \left(\frac{\widetilde{\sigma}}{t}\right)^2.$$

The algorithm needs one copy of $|\pi_X\rangle$, which is restored at the end of the computation with probability at least $1 - \epsilon$, and $\widetilde{O}(t \log(1/\epsilon)^2)$ applications of the reflection $\mathbb{I} - 2|\pi_X\rangle\langle\pi_X|$ in expectation.

Proof. We start by giving several properties of the shifted random variable $\bar{X} = X - \tilde{m}$. First, its second moment is at most

$$\mathbb{E}[\bar{X}^2] = \mathbb{E}[(X - \mu)^2] + (\mu - \tilde{m})^2 \le 290\sigma^2 \tag{6}$$

since, by assumption, the approximate median \widetilde{m} satisfies $|\mu - \widetilde{m}| \leq 17\sigma$. Next, the expected value of $|\bar{X}|$ over any interval $(a_{j-1}, a_j]$ is at most $\mathbb{E}[|\bar{X}|\mathbb{1}_{|\bar{X}| \in (a_{j-1}, a_j]}] \leq \mathbb{E}[\bar{X}^2\mathbb{1}_{|\bar{X}| \in (a_{j-1}, a_j]}]/a_{j-1}$. Hence, the normalized means μ_j^+ and μ_j^- satisfy

$$\mu_j^+ + \mu_j^- \le \frac{2}{a_j^2} \mathbb{E}\left[\bar{X}^2 \mathbb{1}_{|\bar{X}| \in (a_{j-1}, a_j]}\right] \quad \text{when } j > 0.$$
 (7)

Lastly, the expectation of $|\bar{X}|$ over the interval $[a_k, +\infty)$ is at most

$$\mathbb{E}[|\bar{X}|\mathbb{1}_{|\bar{X}|} \ge a_k] \le \frac{\mathbb{E}[\bar{X}^2]}{a_k} \le \frac{290\sigma}{2^k} \tag{8}$$

where we used Equation (6) and the assumption that $\tilde{\sigma} \geq \sigma$.

We now analyze the expectation and variance of the final estimate $\widetilde{\mu}$. Each of the $\widetilde{\mu}_j^+$ and $\widetilde{\mu}_j^-$ estimates introduces a bias of at most ϵ' by Theorem 2.4 and there is another bias due to the truncated part $\mathbb{E}[\bar{X}\mathbbm{1}_{|\bar{X}|} \geq a_k]$ analyzed in Equation (8). Overall, we have $|\mathbb{E}[\widetilde{\mu}] - \mu| \leq \sum_{j=0}^k a_j \epsilon' + \frac{290\sigma}{2^k} \leq (2^{k+1}\epsilon' + \frac{290}{2^k})\widetilde{\sigma} \leq \epsilon \widetilde{\sigma}$. Since the estimates $\widetilde{\mu}_j$ are independent random variables, the variance is $\mathrm{Var}[\widetilde{\mu}] = \sum_{j=0}^k a_j^2 \mathrm{Var}[\widetilde{\mu}_j]$. Thus, by Theorem 2.4 and Equation (7), $\mathrm{Var}[\widetilde{\mu}] \leq \sum_{j=0}^k a_j^2 \left(\frac{\mu_j^+ + \mu_j^-}{(30t)^2} + \epsilon'\right) \leq a_0^2 \left(\frac{2}{(30t)^2} + \epsilon'\right) + \sum_{j=1}^k \left(\frac{2\mathbb{E}\left[\bar{X}^2\mathbbm{1}_{|\bar{X}| \in (a_{j-1}, a_{j})}\right]}{(30t)^2} + a_j^2 \epsilon'\right) \leq \frac{2\widetilde{\sigma}^2 + 2\mathbb{E}\left[\bar{X}^2\right]}{(30t)^2} + 2^{2k+1}\widetilde{\sigma}^2 \epsilon' \leq \left(\frac{582}{(30t)^2} + 2^{2k+1}\epsilon'\right)\widetilde{\sigma}^2 \leq \left(\frac{\widetilde{\sigma}}{t}\right)^2$.

By Theorem 2.4, the algorithm uses $\widetilde{O}(kT\log(1/\epsilon')) = \widetilde{O}(t\log(1/\epsilon)^2)$ reflections through $|\pi_X\rangle$ and it preserves the copy of $|\pi_X\rangle$ with probability at least $1 - 2(k+1)\epsilon' \geq 1 - \epsilon$.

We now explain how to find an estimate \widetilde{m} that satisfies the first requirement $|\mu - \widetilde{m}| \leq 17\sigma$ needed to apply the above estimator. If we had access to classical samples then it would suffice to compute the average of $O(\log 1/\eta)$ samples to get the above inequality with probability $1 - \eta$. Nevertheless, we do not know how to extract a classical sample from a qsample $|\pi_X\rangle$ without destroying it. Since the mean is always within one standard deviation of the median, we can instead attempt to estimate the median. There exist quantum algorithms [NW99; Nay99; Ham21] for computing the quantiles of a distribution, however they also require measuring qsamples. We follow a new approach that incurs a logarithmic overhead in the size of the support but is nondestructive. Our algorithm consists of performing a binary search over the support of the random variable, where we test if a value x is close to the median by estimating the probability $\Pr[X \geq x]$ with the nondestructive amplitude estimation algorithm.

Algorithm 5. Nondestructive median estimator, $\mathsf{Median}(X, \eta)$.

- 1: Let $x_1 < \cdots < x_n$ denote the values in the support of X.
- 2: Set a = 1 and b = n + 1. Run the following binary search until a = b:
- 3: Set $k = \lfloor \frac{a+b}{2} \rfloor$.
- 4: Compute an estimate \widetilde{p}_k of $p_k = \Pr[X \ge x_k]$ by running the nondestructive amplitude estimation algorithm Nd-Amplitude($|\pi_k\rangle, \mathbb{I} \otimes |1\rangle\langle 1|, 3\sqrt{2}, \eta/\log(m)$) where

$$|\pi_k\rangle = \left(\sum_{x < x_k} \sqrt{\pi_X(x)} |x\rangle\right) |0\rangle + \left(\sum_{x \ge x_k} \sqrt{\pi_X(x)} |x\rangle\right) |1\rangle.$$

- 5: If $\widetilde{p}_k \leq 1/6$ then set b = k else set a = k + 1.
- 6: Output $\widetilde{m} = x_{a-1}$.

Proposition 3.2 (NONDESTRUCTIVE MEDIAN ESTIMATOR). Let X be a finite random variable with support size n, mean μ and variance σ^2 . Given a real $\eta \in (0,1)$, the nondestructive median estimator Median (X, η) (Algorithm 5) outputs an approximate median \widetilde{m} such that

$$|\mu - \widetilde{m}| \le 17\sigma$$

with probability at least $1-\eta$. The algorithm needs one copy of $|\pi_X\rangle$, which is restored at the end of the computation with probability at least $1-\eta$, and $O(\log(n)\log(\log(n)/\eta))$ applications of the reflection $\mathbb{I}-2|\pi_X\rangle\langle\pi_X|$.

Proof. By Theorem B.2 and a union-bound argument, all the estimates \widetilde{p}_k computed by Algorithm 5 satisfy $|\widetilde{p}_k - p_k| \leq \sqrt{p_k}/(3\sqrt{2}) + 1/18$ with probability at least $1 - \eta$. In particular, if $p_k \geq 1/2$ then $\widetilde{p}_k \geq p_k - \sqrt{p_k}/(3\sqrt{2}) - 1/18 \geq 5/18$ and if $p_k \leq 1/18$ then $\widetilde{p}_k \leq p_k + \sqrt{p_k}/(3\sqrt{2}) + 1/18 \leq 1/6$. Thus, the binary search stops with a = b satisfying

 $p_a < 1/2 \le 9p_{a-1}$ with probability at least $1 - \eta$ (note that $a \ge 2$ since $p_1 = 1$). Consequently, if we define the quantile function $Q_X(p) = \sup\{x \in \mathbb{R} : \Pr[X \geq x] \geq p\}$ for all $p \in [0,1]$, we have $Q_X(1/2) \leq \widetilde{m} \leq Q_X(1/18)$. Finally, the result $|\mu - \widetilde{m}| \leq 17\sigma$ follows from the quantile inequality $\mu - \sigma \sqrt{\frac{p}{1-p}} \le Q_X(p) \le \mu + \sigma \sqrt{\frac{1-p}{p}}$ proved in [BB04, Section 3.1].

We describe our final estimator for estimating the mean of a product of ℓ independent random variables X_1, \ldots, X_ℓ with relative error ϵ . We make the standard assumptions that the relative second moment $\frac{\mathbb{E}[X_i^2]}{\mathbb{E}[X_i]^2}$ and the inverse fidelity $1/|\langle \pi_{X_i}|\pi_{X_{i+1}}\rangle|^2$ are upper-bounded by some known value B, which is a constant in our applications (Section 4). Our estimator uses a similar approach to that of Dyer and Frieze [DF91], by taking the product of ℓ (nearly) unbiased estimates $\widetilde{\mu}_1, \dots, \widetilde{\mu}_\ell$ of $\mathbb{E}[X_1], \dots, \mathbb{E}[X_\ell]$ respectively, each with variance $O(\epsilon^2/\ell)$. We obtain a quantum speed-up by using the quantum unbiased estimator of Proposition 3.1 to reduce the variances quadratically faster than classically.

Algorithm 6. Product estimator, $Product(X_1, ..., X_{\ell}, B, \epsilon)$.

- 1: for i = 1 to ℓ do
- Define \widehat{X}_i to be the average of $K = \max\{1, 1156(B-1)\}$ independent samples from X_i .
- Compute an estimate \widetilde{m}_i of the median of X_i by using the nondestructive median 3: estimator Median $(X_i, 1/(11\ell))$. Set $\widetilde{\sigma}_i = \widetilde{m}_i B$.
- Compute an estimate $\widetilde{\mu}_i$ of the expectation $\mathbb{E}[\widehat{X}_i]$ by using the unbiased mean estimator 4: Unbiased $(\widehat{X}_i, \frac{96B\sqrt{\ell}}{\epsilon}, \widetilde{m}_i, \widetilde{\sigma}_i, \frac{\epsilon}{6\ell B})$. Anneal the qsample $|\pi_{\widehat{X}_i}\rangle$ to $|\pi_{\widehat{X}_{i+1}}\rangle$ with probabilistic annealing.
- 6: Output $\widetilde{\mu} = \widetilde{\mu}_1 \cdots \widetilde{\mu}_\ell$.

Theorem 3.3 (Product estimator). Let B > 1 and $\epsilon \in (0,1)$. Consider a sequence X_1, \ldots, X_ℓ of ℓ independent random variables with support size n, bounded relative second moment $\frac{\mathbb{E}[X_i^2]}{\mathbb{E}[X_i]^2} \leq B$ and bounded fidelity $|\langle \pi_{X_i} | \pi_{X_{i+1}} \rangle|^2 \geq 1/B$ for all i. Denote their product as $X = X_1 \cdots X_\ell$. Then, the product estimator $\mathsf{Product}(X_1, \ldots, X_\ell, B, \epsilon)$ (Algorithm 6) outputs a multiplicative-error estimate $\widetilde{\mu}$ such that

$$\left|\widetilde{\mu} - \mathbb{E}\left[\prod_{i=1}^{\ell} X_i\right]\right| \le \epsilon \mathbb{E}\left[\prod_{i=1}^{\ell} X_i\right]$$

with probability at least 2/3. It uses O(B) copies of $|\pi_{X_1}\rangle$ and $\widetilde{O}(B^2\ell^{3/2}/\epsilon + \ell(B\log(n) + B^{1156B}))$ reflections through the states $|\pi_{X_1}\rangle, \ldots, |\pi_{X_\ell}\rangle$ in expectation.

Proof. By a union-bound argument, with probability at least 10/11, all the median estimates \tilde{m}_i computed at step 3 are within distance $17\sqrt{\mathrm{Var}[\hat{X}_i]}$ of the means $\mathbb{E}[\hat{X}_i]$. We condition on this event happening for the rest of the proof.

We start by analysing steps 2–5 for a given random variable X_i . First, notice that we can construct a quample for \widehat{X}_i by taking $|\pi_{\widehat{X}_i}\rangle = U_{\text{average}}(|\pi_{X_i}\rangle^{\otimes K}\otimes |0\rangle)$ where U_{average} is a unitary computing the average of the first K registers in the last register. The expectation is unchanged $\mathbb{E}[X_i] = \mathbb{E}[X_i]$, whereas the relative second moment and the fidelity are

$$\frac{\mathbb{E}[\widehat{X}_i^2]}{\mathbb{E}[X_i]^2} \le 1 + \frac{B-1}{K} \quad \text{and} \quad |\langle \pi_{\widehat{X}_i} | \pi_{\widehat{X}_{i+1}} \rangle|^2 \ge \frac{1}{B^K}$$
 (9)

since $|\langle \pi_{\widehat{X}_i} | \pi_{\widehat{X}_{i+1}} \rangle|^2 = |\langle \pi_{X_i} | \pi_{X_{i+1}} \rangle|^{2K}$ by properties of the fidelity. The next equation shows that the distance between the rough estimate \tilde{m}_i computed at step 3 and the expectation is bounded by a multiple of the standard deviation (by Proposition 3.2), which in turn is a small multiple of the expectation (since the relative variance is small by Equation (9)).

$$|\widetilde{m}_i - \mathbb{E}[X_i]| \le 17\sqrt{\operatorname{Var}[\widehat{X}_i]} \le 17\sqrt{\frac{B-1}{K}}\mathbb{E}[X_i] = \frac{\mathbb{E}[X_i]}{2}$$
(10)

Finally, the expectation of each estimate $\widetilde{\mu}_i$ computed at step 4 is bounded as

$$|\mathbb{E}[\widetilde{\mu}_i] - \mathbb{E}[X_i]| \le \frac{\epsilon}{6\ell B} \widetilde{\sigma}_i \le \frac{\epsilon}{4\ell} \mathbb{E}[X_i]$$
(11)

where the first inequality is by Theorem 2.4 and the second is by $\widetilde{\sigma}_i = B\widetilde{m}_i$ and Equation (10). Consider now the product random variable $X = X_1 \cdots X_\ell$. The expectation of the final estimate $\widetilde{\mu}$ is at most $\mathbb{E}[\widetilde{\mu}] \leq (1 + \frac{\epsilon}{4\ell})^\ell \prod_{i=1}^\ell \mathbb{E}[\mu_i] \leq (\epsilon/2)\mathbb{E}[X]$ and at least $\mathbb{E}[\widetilde{\mu}] \geq (1 - \frac{\epsilon}{4\ell})^\ell \prod_{i=1}^\ell \mathbb{E}[\mu_i] \geq (\epsilon/4)\mathbb{E}[X]$ by Equation (11). Thus, $|\mathbb{E}[\widetilde{\mu}] - \mathbb{E}[X]| \leq (\epsilon/2)\mathbb{E}[X]$. The relative variance of $\widetilde{\mu}$ is at most $\frac{\mathrm{Var}[\widetilde{\mu}]}{\mathbb{E}[\widetilde{\mu}]^2} = \prod_{i=1}^\ell \left(1 + \frac{\mathrm{Var}[\widetilde{\mu}_i]}{\mathbb{E}[\widetilde{\mu}_i]^2}\right) - 1 \leq \prod_{i=1}^\ell \left(1 + \frac{\epsilon^2}{(t\mathbb{E}[\widetilde{\mu}_i])^2}\right) - 1 = \prod_{i=1}^\ell \left(1 + \frac{\epsilon^2}{32\ell}\right)^\ell - 1 \leq \epsilon^2/16$ where the second step is by Proposition 3.1 and the fourth step uses that $\widetilde{m}_i/\mathbb{E}[\widetilde{\mu}_i] \leq 3$ by Equations (10) and (11). We conclude by using the triangle and Chebyshev inequalities that $|\widetilde{\mu} - \mathbb{E}[X]| \leq |\widetilde{\mu} - \mathbb{E}[\widetilde{\mu}]| + |\mathbb{E}[\widetilde{\mu}] - \mathbb{E}[X]| \leq (\epsilon/2 + \epsilon/2)\mathbb{E}[X]$ with

probability at least $1 - 4\frac{\operatorname{Var}[\tilde{\mu}]}{(\epsilon \mathbb{E}[\tilde{\mu}])^2} \geq 3/4$.

The algorithm needs K copies of the initial qsample $|\pi_{X_1}\rangle$ to anneal into K copies of $|\pi_{X_i}\rangle$ at the i-th stage of steps 2–5. Each transition from $|\pi_{X_i}\rangle^{\otimes K}$ to $|\pi_{X_{i+1}}\rangle^{\otimes K}$ requires $O(B^K)$ measurements in expectation by Lemma A.6. Furthermore, at each stage, step 3 uses $O(\log(n)\log(\ell))$ reflections through $|\pi_{\widehat{X}_i}\rangle$ by Proposition 3.2 and step 4 uses $O(B\sqrt{\ell}/\epsilon)$ reflections by Proposition 3.1. Overall, the number of reflections through $|\pi_{X_1}\rangle, \ldots, |\pi_{X_\ell}\rangle$ is $O(\ell K(B^K + \log(n) + B\sqrt{\ell}/\epsilon))$.

4 Partition function estimation

In this section, we showcase an application of our newly-constructed quantum mean estimation algorithm. Specifically, we show how it can be used to speed up existing quantum algorithms for estimating partition functions. In Section 4.1, we elaborate on the generic algorithm for partition function estimation and how our results provide a speed up and, in Section 4.2, we discuss how this gives rise to more efficient quantum algorithms for several applications.

4.1 General algorithm for partition function estimation

In this subsection, we first describe our partition function estimation algorithm in high level, and define the required notation along the way. We follow the exposition in [HW20], but use slightly different notation to match the rest of this document more closely.

Let Ω be a state space, and let $H:\Omega\to\{0,\ldots,n\}$ be a Hamiltonian, i.e., a function associating a numerical value to each of the states. Our goal will be to compute the number of states whose value is 0, i.e., $|H^{-1}(0)|$. To that end, we define the partition function $Z:[0,\infty]\to\mathbb{R}$ as

$$Z(\beta) = \sum_{x \in \Omega} e^{-\beta H(x)},$$

and we observe that $Z(0) = |\Omega|$, and $Z(\infty) = |H^{(-1)}(0)|$. The partition function arises frequently in statistical physics, where β is referred to as the inverse temperature.

Next, we define a sequence of inverse temperatures $0 = \beta_0 < \beta_1 < \cdots < \beta_\ell = \infty$, and express $Z(\infty)$ as the product

$$Z(\infty) = Z(0) \cdot \frac{Z(\beta_1)}{Z(0)} \cdot \frac{Z(\beta_2)}{Z(\beta_1)} \cdot \dots \cdot \frac{Z(\infty)}{Z(\beta_\ell)} = Z(0) \prod_{i=0}^{\ell-1} \frac{Z(\beta_{i+1})}{Z(\beta_i)}.$$
 (12)

Since throughout the sequence of β_i 's, we are increasing the inverse temperature, and hence decreasing the temperature, this sequence is referred to as the *cooling schedule*. Its length ℓ is called the *schedule length*. The core idea for estimating $Z(\infty)$ is to evaluate each of the factors in the product on the right-hand side of Equation (12) individually.

Thus, let $i \in [\ell]$. We endow Ω with a probability distribution π_i , called the Gibbs distribution in statistical physics, and define a random variable $X_i : \Omega \to \mathbb{R}$ on it, with

$$\pi_i(x) = \frac{e^{-\beta_i H(x)}}{Z(\beta_i)}, \quad \text{and} \quad X_i(x) = e^{-(\beta_i - \beta_{i-1})H(x)}.$$

It follows immediately that

$$\mu_i = \mathbb{E}[X_i] = \sum_{x \in \Omega} \frac{e^{-\beta_i H(x)}}{Z(\beta_i)} \cdot e^{-(\beta_{i+1} - \beta_i)H(x)} = \sum_{x \in \Omega} \frac{e^{-\beta_{i+1} H(x)}}{Z(\beta_i)} = \frac{Z(\beta_{i+1})}{Z(\beta_i)}.$$

The idea is now to devise a procedure that samples from the Gibbs distribution and obtains an estimator $\widetilde{\mu}_i$ of $\mathbb{E}[X_i]$.

In order to be able to sample from the Gibbs distribution, we encode it in a quantum state. To that end, we define the Gibbs state $|\pi_i\rangle \in \mathbb{C}^{\Omega}$ at inverse temperature β_i , defined as

$$|\pi_i\rangle = \frac{1}{\sqrt{Z(\beta_i)}} \sum_{x \in \Omega} \sqrt{e^{-\beta_i H(x)}} |x\rangle.$$

In typical applications (see the next subsection), it can be much easier to reflect through the Gibbs state than to prepare it. Therefore, we estimate $\mathbb{E}[X_i]$ using a nondestructive mean estimation algorithm, which we constructed in the previous sections. This has the benefit of having access to the Gibbs state even after the computation of $\widetilde{\mu}_i$, which makes it possible to reuse it for computing the next factor in the product on the right-hand side of Equation (12).

It remains to choose the cooling schedule, i.e., the inverse temperatures $\beta_1, \ldots, \beta_{\ell-1}$. For reasons that are sketched on high level, we want our cooling schedule to have the following two properties.

1. B-Chebyshev. For any $B \ge 1$, a cooling schedule is called B-Chebyshev, if for any two subsequent β_{i-1} and β_i , we have

$$\frac{\mathbb{E}[X_i^2]}{\mathbb{E}[X_i]^2} = \frac{Z(2\beta_{i+1} - \beta_i)Z(\beta_i)}{Z(\beta_{i+1})^2} \le B.$$

This requirement can be viewed as a tail bound – it tells us that X_i cannot have too much weight above $\mathbb{E}[X_i]$. Indeed, by Markov's inequality, $\Pr[X_i \geq t\mathbb{E}[X_i]] = \Pr[X_i^2 \geq t^2\mathbb{E}[X_i]^2] \leq \mathbb{E}[X_i^2]/(t\mathbb{E}[X_i])^2 \leq B/t^2$. It ensures that we can not only give a good additive estimate of $\mathbb{E}[X_i]$, but also a good multiplicative one.

2. B-slowly varying. For any $B \geq 1$, a cooling schedule is called B-slowly varying if

$$\left| \langle \pi_i | \pi_{i+1} \rangle \right|^2 = \frac{Z\left(\frac{\beta_i + \beta_{i+1}}{2}\right)^2}{Z(\beta_i)Z(\beta_{i+1})} \le 1/B.$$

This requirement can be seen as a proximity requirement – it tells us that the Gibbs states $|\pi_i\rangle$ and $|\pi_{i+1}\rangle$ have some non-negligible overlap. It ensures that we can *anneal*, i.e., transform, $|\pi_i\rangle$ into $|\pi_{i+1}\rangle$ without having to do too much work, and hence circumvents having to prepare $|\pi_{i+1}\rangle$ from scratch for each of the factors on the right-hand side of Equation (12).

When we set $B=e^2$, it is shown in [ŠVV09] that there exists a cooling schedule of length $\ell=\widetilde{\mathcal{O}}(\sqrt{\log|\Omega|\log(n)})$, which is *B*-Chebyshev. Subsequently, it was shown [HW20] that one can modify the construction so that the resulting cooling schedule is not only *B*-Chebyshev, but also slowly varying. Moreover, computing this cooling schedule can be done on the fly, with associated cost scaling approximately linearly in the schedule length.

Combining previous work with our product estimator, Theorem 3.3, gives rise to the following result.

Theorem 4.1 (Partition function estimator). Let $H: \Omega \to \{0, ..., n\}$ be a Hamiltonian, and let Z be the corresponding partition function defined as above. Then, we can estimate $|H^{(-1)}(0)| = Z(\infty)$ up to multiplicative error ϵ , with probability at least 2/3, using $\widetilde{O}(\log^{3/4} |\Omega| \log^{3/4}(n)/\epsilon + \sqrt{\log |\Omega|} \log(n))$ Gibbs state reflections in expectation.

Proof. We run the algorithm from [HW20] to compute the cooling schedule on the fly. The total number of Gibbs state reflections used in this step is $\widetilde{O}(\sqrt{\log |\Omega| \log(n)})$ [HW20, Theorem 13], and the resulting cooling schedule is both e^2 -slowly varying and e^2 -Chebyshev, and of length $\widetilde{O}(\sqrt{\log |\Omega| \log(n)})$. For computing the product in Equation (12), we use the product estimator, Theorem 3.3. The total number of Gibbs state reflections used in this algorithm is $\widetilde{O}(\log^{3/4} |\Omega| \log^{3/4}(n)/\epsilon + \sqrt{\log |\Omega|} \log(n))$. With standard failure probability reduction techniques, we obtain that the number of Gibbs state reflections performed by the resulting algorithm scales as the sum of the two complexities, which yields the desired result.

The core of our improvement lies in our product estimator – the one used in [HW20] is quadratic in the schedule length, whereas ours is subquadratic. Thus, more generally, if we are in a setting where a cooling schedule that is shorter than $O(\sqrt{\log |\Omega| \log(n)})$ suffices, then our resulting algorithm scales with the schedule length to the power of 3/2. A typical setting where this is the case is when we a priori know a lower bound on $|H^{(-1)}(0)|$ – then we can terminate the annealing at a lower inverse temperature, and hence obtain a shorter cooling schedule. We leave working out the details in this setting for future work.

4.2 Applications

The quantum partition function estimator can be applied to several counting problems. See [HW20] for more possible applications. In all applications we list in this section, n scales at most polylogarithmically in $|\Omega|$, so we can hide any dependence on $\log(n)$ in the tilde of the big-O notation.

Counting k-colorings Let G = (V, E) be an undirected simple graph with degree at most Δ , and suppose we have k colors. We would like to count the number of ways we can color the vertices such that no two adjacent ones have the same color. We let Ω be all the possible colorings, which means $Z(0) = |\Omega| = k^{|V|}$. We define H(x) to be the number of monochromatic edges in G. Then, $Z(\infty) = |H^{(-1)}(0)|$ is exactly the number of k-colorings. Jerrum [Jer95] constructed a Markov chain whose stationary distribution is the Gibbs state at infinite temperature, and analyzed that its mixing time is $O(|V|\log|V|)$. With a metropolis sampling correction this can be turned into Gibbs states at arbitrary temperatures, and thus performing approximate Gibbs state reflections takes time $\widetilde{O}(1/\sqrt{|V|})$. Multiplying by the complexity in Theorem 4.1, we can obtain an ϵ -multiplicative approximation to $Z(\infty)$ in time $\widetilde{O}(\log |\Omega|^{3/4}\sqrt{|V|}/\epsilon) = \widetilde{O}(|V|^{5/4}/\epsilon)$.

Ising model Let G = (V, E) be an undirected simple graph of maximum degree Δ , and assign a sign ± 1 to each of the vertices. We let Ω be the set of all assignments of signs to the vertices, which readily implies that $|\Omega| = 2^{|V|}$. We let H(x) be the number of edges whose endpoints have the same sign. Then, Mossel and Sly [MS13] construct a Markov chain whose stationary

distribution is the Gibbs state at arbitrary temperature. They also show that it mixes in time $O(n \log(n))$ as long as $(\Delta - 1) \tanh(\beta) < 1$. Thus, for any of these inverse temperatures β , we can evaluate $Z(\beta)$ up to relative error ϵ in time $\widetilde{O}(|V|^{5/4}/\epsilon)$.

Counting matchings Let G=(V,E) be an undirected simple graph. A matching M is a subset of edges such that every vertex $v\in V$ is incident to at most edge in M. We let Ω be the set of all matchings, and H(M)=|M|, i.e., the number of edges in the matching. Then $Z(0)=|\Omega|$ is the number of matchings, and $Z(\infty)=1$. Now, the setting is slightly different than before, since the partition function is easy to calculate at zero temperature, rather than at infinite temperature. The core idea is to run the same algorithm as outlined before, but anneal in the opposite direction. Previous works [HW20; Mon15] justify this idea in more detail. Jerrum and Sinclair [JS89] constructed a Markov chain whose stationary distribution is the Gibbs state at zero temperature, and analyzed that the mixing time of this Markov chain is O(|V||E|). Similarly as before, the Markov chain can be easily adapted by a metropolis sampling correction so that its stationary distribution is a Gibbs state at arbitrary temperature, and so we can perform Gibbs state reflections in time $\widetilde{O}(\sqrt{|V||E|})$. The state space of this random walk is of size $|\Omega| = O(|V|!2^{|V|})$, which implies that $\log |\Omega| = O(|V|\log |V|)$. Thus, combining with the complexity in Theorem 4.1, we can find a ϵ -multiplicative estimate of the number of matchings in time $\widetilde{O}(|V|^{5/4}|E|^{1/2}/\epsilon)$.

Counting independent sets Let G = (V, E) be an undirected simple graph, with degree at most Δ . An independent set is a subset of vertices $I \subseteq V$ such that none of the edges has both endpoints in I. Similarly as before, we let Ω be the set of all independent sets, and we let H(I) = |I|. Then, as in the setting where we were counting matchings, we know $Z(\infty) = 1$, and we want to compute $Z(0) = |\Omega|$. Vigoda [Vig01] constructed a Markov chain whose stationary distribution is the Gibbs state at arbitrary temperature, and analyzes the mixing time to be $O(|V| \log |V|)$. Furthermore, $|\Omega| \leq 2^{|V|}$, and hence our algorithm runs in time $\widetilde{O}(|V|^{5/4}/\epsilon)$.

Computing the volume of a convex body We can also use our techniques to speed up one of the costly subroutines in the volume estimation algorithm of convex bodies from [CCH+19]. To that end, let r, R > 0, and let $K \subseteq \mathbb{R}^d$ be a convex set with $B(0, r) \subseteq K \subseteq B(0, R)$. Let D = R/r, and without loss of generality assume that $B(0, 1) \subseteq K \subseteq B(0, D)$. Define $K' = ([0, 2D] \times K) \cap C$, where $C = \{(t, x) \in \mathbb{R}_{\geq 0} \times \mathbb{R}^d : t \geq ||x||\}$. The algorithm from [CCH+19] first estimates the volume of K' with $\widetilde{O}(d^3 + d^{2.5}/\epsilon)$ queries to O_K , and then estimates the ratio between the volume of K' and K with another $\widetilde{O}(d^{2.5}/\epsilon)$ queries. The first part can be sped up with our methods to $\widetilde{O}(d^3 + d^2/\epsilon)$, but it's unclear if our techniques help to improve the second part. We leave this for further research.

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Appendix A Algorithmic primitives

We use the next properties that characterize the output distribution of the quantum phase estimation algorithm.

Lemma A.1 (Phase estimation [Kit95; BHMT02]). Let U be a unitary operator with an eigenvector $|\psi\rangle$ such that $U|\psi\rangle = e^{2\pi i\theta}|\psi\rangle$ where $\theta \in [0,1)$. Given an integer $t=2^{\tau}$, the phase estimation algorithm outputs an estimate $\tilde{\theta} = i/t$ where the number $i \in \{0,\ldots,t-1\}$ is chosen with probability

$$p(i) = \frac{\sin^2(t\Delta_i\pi)}{t^2\sin^2(\Delta_i\pi)}$$
(13)

and $\Delta_i = \min\{|\theta - i/t|, |1 + \theta - i/t|, |1 - \theta + i/t|\}$ is the distance between θ and i/t along the unit circle. The algorithm needs one copy of $|\psi\rangle$, which is restored at the end of the computation, and O(t) controlled-U operations.

Corollary A.2. If $t \geq 8$ then the probability distribution $(p(i))_i$ defined in Equation (13) satisfies $p(i) \geq 0.22$ when $\Delta_i \leq 5/(8t)$ and $p(i) \leq 0.11$ when $\Delta_i \geq 1/t$.

Proof. Suppose first that $\Delta_i \leq 5/(8t)$. Using the inequality $\sin(x) \leq x$ when $0 \leq x \leq \pi/2$ and the fact that $y \mapsto (\sin(y)/y)^2$ is non-increasing on $[0, 5\pi/8]$, we have $p(i) \geq (\sin(t\Delta_i\pi)/(t\Delta_i\pi))^2 \geq (\sin(5\pi/8)/(5\pi/8))^2 \geq 0.22$. Suppose now that $\Delta_i \geq 1/t$. Using that $\Delta_i \leq 1/2$ and $t \geq 8$, we have $p(i) \leq 1/(t\sin(\pi/t))^2 \leq 1/(8\sin(\pi/8))^2 \leq 0.11$.

We consider a variant of quantum amplitude amplification [BHMT02] that provides a precise linear amplification of the amplitude.

Lemma A.3 (LINEAR AMPLITUDE AMPLIFICATION, Theorem 6.10 in [Low17]). Consider two reals $t \ge 1$ and $\epsilon \in (0,1)$. Let $|\psi\rangle$ be a quantum state and Π be a projection operator such that $\|\Pi|\psi\rangle\| \le 1/(2t)$. Then, there is a unitary operator $V_{t,\epsilon}$ such that

$$\left| \|\Pi V_{t,\epsilon} |\psi\rangle\| - t \|\Pi |\psi\rangle\| \right| \le \epsilon$$

which can be implemented with $O(t \log(1/\epsilon))$ applications of the reflection operators $\mathbb{I} - 2|\psi\rangle\langle\psi|$ and $\mathbb{I} - 2\Pi$.

The next two results provide efficient quantum algorithms for converting between phase and amplitude encodings of a real parameter.

Lemma A.4 (AMPLITUDE-TO-PHASE CONVERSION, Theorem 14 in [GAW17]). Let $|\psi\rangle$ be a quantum state and Π be a projection operator with $p = ||\Pi|\psi\rangle||^2$. Then, given a real $\epsilon \in (0,1)$, there is a unitary operator U_{ϵ} and an integer $a = O(\log \log 1/\epsilon)$ such that

$$U_{\epsilon}(|\psi\rangle|0\rangle^{\otimes a}) = |\psi\rangle|\varphi_p\rangle \quad where \quad |||\varphi_p\rangle - e^{ip}|0\rangle^{\otimes a}|| \le \epsilon$$

and U_{ϵ} can be implemented with $O(\log(1/\epsilon))$ applications of the reflection operators $\mathbb{I} - 2|\psi\rangle\langle\psi|$ and $\mathbb{I} - 2\Pi$.

Lemma A.5 (Phase-to-Amplitude conversion, Lemma 16 in [GAW17]). Let U be a unitary operator with an eigenvector $|\psi\rangle$ such that $U|\psi\rangle = e^{i\theta}|\psi\rangle$ where $\theta \in [1/4, 3/4]$. Then, given a real $\epsilon \in (0, 1)$, there is a unitary operator V_{ϵ} and an integer $a = O(\log 1/\epsilon)$ such that

$$V_{\epsilon}\big(|\psi\rangle|0\rangle^{\otimes a}\big) = |\psi\rangle\big(\sqrt{1-p'}|0\rangle^{\otimes a} + \sqrt{p'}|\Phi^{\perp}\rangle\big) \quad where \quad |\sqrt{p'} - \sqrt{p}| \leq \epsilon \ and \ \langle 0|\Phi^{\perp}\rangle = 0$$

and V_{ϵ} can be implemented with $O(\log(1/\epsilon))$ applications of the (controlled) U and U^{\dagger} operators.

Finally, we explain how to anneal from one state to the next, given that there is a non-negligible overlap between the two. The idea is due to Marriott and Watrous [MW05] and is similar to the coin flipping algorithm (Proposition 2.3).

Algorithm 7. Annealing from $|\psi\rangle$ to $|\phi\rangle$, Anneal $(|\psi\rangle, |\phi\rangle)$

- 1: Start with the state $|\psi\rangle$.
- 2: repeat
- 3: Measure in the $\{|\psi\rangle\langle\psi|, \mathbb{I} |\psi\rangle\langle\psi|\}$ basis.
- 4: Measure in the $\{|\phi\rangle\langle\phi|, \mathbb{I} |\phi\rangle\langle\phi|\}$ basis.
- 5: **until** the final measurement outcome is $|\phi\rangle$.

Lemma A.6 (PROBABILISTIC ANNEALING). Let $|\psi\rangle$ and $|\phi\rangle$ be two linearly independent quantum states of equal dimension. Then the expected number of reflections through $|\psi\rangle$ and $|\phi\rangle$ performed by Algorithm 7 is $1 + 1/(2|\langle\psi|\phi\rangle|^2)$.

Proof. Let $p = |\langle \psi | \phi \rangle|^2$. Since the first iteration starts in state $|\psi\rangle$, the outcome of the first measurement is deterministic, and hence we will terminate with probability p. Afterward, every iteration starts in a state $|\psi^{\perp}\rangle$, which is orthogonal to $|\phi\rangle$ and in the 2D-subspace spanned by $|\psi\rangle$ and $|\phi\rangle$. Thus, the algorithm terminates with probability f = 2p(1-p), in this iteration. Putting everything together, let T be the number of iterations the algorithm uses. Then, $\mathbb{E}[T-1|T\geq 2] = \sum_{t=2}^{\infty} (t-1)f(1-f)^{t-2} = 1/f$, and so $\mathbb{E}[T] = 1 + (1-p)/f = 1 + 1/(2p)$. \square

Appendix B Nondestructive amplitude estimation

The nondestructive amplitude estimation algorithm is a variant of amplitude estimation introduced by Harrow and Wei [HW20] for restoring the initial quantum state with high probability. This is a crucial ingredient in their work for computing a cooling schedule faster than classically. In Section 2.2, we further extend the properties of amplitude estimation by making the output nearly unbiased. Our algorithm requires a rough amplitude estimate to start with, which can be obtained from the (biased) procedure of [HW20].

Below, we recall the statement of the nondestructive amplitude estimation theorem of Harrow and Wei [HW20] and we suggest a new (still biased) construction achieving this result. While the original algorithm of Harrow and Wei may be correct, its analysis seems to use two properties of amplitude estimation [BHMT02] that do not hold in general: the collapsing of the post-measurement state to an eigenvector of the Grover operator (it can be a superposition of two eigenvectors when the amplitude p is close to 0), and the output distribution giving overwhelming probability to a single amplitude estimate (there are two high-probability estimates when the underlying phase $\frac{1}{\pi} \arcsin(\sqrt{p})$ is at equal distance from the two nearest phase estimates on the unit circle). We avoid such complications by describing a new nondestructive amplitude estimation algorithm based on the next "uncomputation trick" with boosted success probability.

Lemma B.1 (AMPLIFIED UNCOMPUTATION). Consider a quantum algorithm that consists of applying a unitary U on a state $|\psi\rangle|0\rangle^{\otimes k}$ and measuring the last k qubits in the standard basis. Let $\pi(1), \ldots, \pi(2^k)$ denotes the probabilities of measuring the outcomes $1, \ldots, 2^k$ respectively. Then, given a lower bound $\lambda \leq \sum_{i=1}^{2^k} \pi(i)^2$ and a success parameter $\eta \in (0,1)$, one can sample $i \in \{1, \ldots, 2^k\}$ from the distribution

$$i \sim \frac{\pi(i)^2}{\sum_{i=1}^{2^k} \pi(i)^2}$$

and restore the state $|\psi\rangle$ with probability at least $1-\eta$ by using $O(\log(1/\eta)/\sqrt{\lambda})$ applications of U, U^{\dagger} and $\mathbb{I} - 2|\psi\rangle\langle\psi|$.

Proof. Let $U(|\psi\rangle|0\rangle^{\otimes k}) = \sum_i \alpha_i |\psi_i\rangle|i\rangle$ denote the state computed by the unitary U. Define the "uncomputation" unitary $U_{\text{uncomp}} = (U^{\dagger} \otimes \mathbb{I}_{\mathbb{C}^{2^k}})(\mathbb{I}_{\mathcal{H}} \otimes \text{CNOT})(U \otimes \mathbb{I}_{\mathbb{C}^{2^k}})$ that consists of running U, copying the output register into a new register and running the inverse U^{\dagger} . Then, the amplitude of $|\psi\rangle|0\rangle|i\rangle$ in the state obtained by applying U_{uncomp} on $|\psi\rangle|0\rangle^{\otimes k}|0\rangle^{\otimes k}$ is

$$(\langle \psi | \langle 0 | \langle i |) U_{\text{uncomp}}(|\psi\rangle | 0 \rangle | 0 \rangle) = \left(\sum_{j} \alpha_{j}^{*} \langle \psi_{j} | \langle j | \langle i | \right) \left(\sum_{j} \alpha_{j} | \psi_{j} \rangle | j \rangle | j \rangle \right) = |\alpha_{i}|^{2} = \pi(i).$$

We run fixed-point amplitude amplification [YLC14] on the projector $\Pi = |\psi\rangle\langle\psi|\otimes|0\rangle\langle0|\otimes\mathbb{I}$ and the state $U_{\rm uncomp}(|\psi\rangle|0\rangle|0\rangle)$, using the amplitude lower bound $\|\Pi U_{\rm uncomp}(|\psi\rangle|0\rangle|0\rangle)\|^2 \geq \lambda$ and

the amplification parameter η . The probability of measuring $|\psi\rangle|0\rangle$ in the first two registers of the resulting state is at least $1-\delta$, in which case the last register collapses to $\frac{1}{\sqrt{\sum_i \pi(i)^2}} \sum_i \pi(i) |i\rangle$.

Thus, we can restore $|\psi\rangle$ and sample $i \sim \frac{\pi(i)^2}{\sum_j \pi(i)^2}$ with success probability at least $1 - \delta$. The algorithm requires $O(\log(1/\eta)/\sqrt{\lambda})$ applications of (controlled) $U_{\rm uncomp}$, $U_{\rm uncomp}^{\dagger}$, $\mathbb{I} - 2\Pi$ and $\mathbb{I} - 2|\psi\rangle\langle\psi|$.

We obtain below the same statement as [HW20] for performing nondestructive amplitude estimation. Furthermore, we show that the amplitude estimate is zero with high probability when the amplitude is sufficiently small (as is the case for the regular amplitude estimation [BHMT02]).

Proposition B.2 (Nondestructive amplitude estimation). Let $|\psi\rangle$ be a quantum state and Π be a projection operator with $p = ||\Pi|\psi\rangle||^2$. Given $t \ge 1$ and $\eta \in (0, 1/2)$, the nondestructive amplitude estimation algorithm Nd-Amplitude($|\psi\rangle, \Pi, t, \eta$) outputs an estimate $\widetilde{p} \in (0, 1)$ such that

$$|\widetilde{p} - p| < \frac{\sqrt{p(1-p)}}{t} + \frac{1}{t^2}$$

with probability at least $1-\eta$. Moreover, if $p \leq 1/(4t^2)$ then it outputs $\widetilde{p}=0$ with probability at least $1-\eta$. The algorithm needs one copy of $|\psi\rangle$, which is restored at the end of the computation with probability at least $1-\eta$, and $O(t\log(1/\eta))$ applications of the reflection operators $\mathbb{I}-2|\psi\rangle\langle\psi|$ and $\mathbb{I}-2\Pi$.

Proof. The standard analysis of the amplitude estimation algorithm (Theorems 11 and 12 in [BHMT02]) shows that, after t steps, it outputs with probability at least $8/\pi^2$ one of two values $\widetilde{p} \in \{\widetilde{p}_1, \widetilde{p}_2\}$ that both satisfy $|\widetilde{p}_i - p| < 2\pi \frac{\sqrt{p(1-p)}}{t} + \frac{\pi^2}{t^2}$. Moreover, if $p \leq 1/(4t^2)$ then the probability to output $\widetilde{p} = 0$ is at least $8/\pi^2$. Thus, by taking the median of $O(\log(1/\eta))$ independent runs of amplitude estimation, we obtain $\widetilde{p} \in \{\widetilde{p}_1, \widetilde{p}_2\}$, or $\widetilde{p} = 0$ when $p \leq 1/(4t^2)$, with probability at least $1 - \eta/2$. We use amplified uncomputation (Lemma B.1) on this algorithm with amplitude lower bound $\lambda = 1/8$ and success parameter $\eta/2$. If the algorithm succeeds, the probability to sample $\widetilde{p} \in \{\widetilde{p}_1, \widetilde{p}_2\}$ is at least $\frac{2(1/2 - \eta/4)^2}{2(1/2 - \eta/4)^2 + (\eta/2)^2} \geq 1 - \eta/2$, and when $p \leq 1/(4t^2)$ the probability of $\widetilde{p} = 0$ is at least $\frac{(1 - \eta/2)^2}{(1 - \eta/2)^2 + (\eta/2)^2} \geq 1 - \eta/2$.