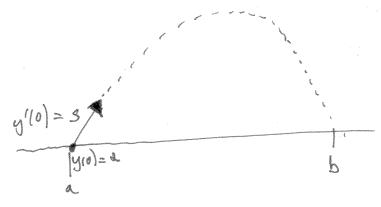
To start: consider IVP

$$y'' = 2y^3$$

$$y(a) = 2$$

$$y'(a) = 3$$

The angle of spotte your morter"



Need to consent to system, to solve numerically

Let
$$\vec{V} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$
 with $\vec{V}_1 = \vec{y}$ $\vec{V}_2 = \vec{y}$

Then
$$\frac{1}{y'} = \frac{1}{2} \frac{1}{3}$$

Now use Eder's method to solve IVP: You = Yn + (At) Yn

The solution depends on the choice of S, the slope. (2)
Let's write

y(b;s) - the solin at point b depends on S

Now consider BVP $u'' = 2u^3$ u(a) = d $u(b) = \beta$

we and solve this easily for a, but we can solve for y(b;s).

Ly if we find some s^* such that $y(b;s^*) = \beta (= a(b))$.

then we're donc!

Define $\phi(s) = y(b;s) - \beta$ 5 Need to find the root of $\phi(s)$! Define $\phi(s) = y(b;s) = \beta$! Define $\phi(s) = y(b;s) = \beta$! Use Newton's Method.

Remember:

$$S_{KH} = S_K - \frac{\phi(S_K)}{\phi(S_K)}$$

But wait... what is $\phi'(s_R)$? We don't know $\phi'(s) = \frac{d}{s} y(b_i s)$.

Define $z = \frac{\partial}{\partial s} (\phi(s)) = \phi'(s) = \frac{\partial}{\partial s} y(b;s)$

we an differentiate urt a

$$\frac{d}{dx^2} = \frac{\partial}{\partial x^2} \left(\frac{\partial}{\partial s} y(x;s) \right)$$

$$= \mathcal{F}_{S} \left(\mathcal{F}_{x^{2}} \mathcal{F}(x; S) \right)$$

Sprose y solves ODE y"= fla, y, y')

$$= \Re \left(f(x, y(x; s), y'(x; s)) \right)$$

= fy(x,y,y') &y +fy' | x,y,y' | &y'

Annanagna

$$SD \geq \left(=\phi'(SI)\right)$$

(F)

Solves

$$\begin{cases} Z'' = \int_{S} [\alpha_{i}y_{i}y']Z + \int_{Y'} [\alpha_{i}y_{i}y']Z' \\ Z[a] = 0 \\ Z'[a] = 1 \end{cases}$$

for
$$w$$
, $f = 2y^3$
 $f_y = 86y^2$
 $f_y' = 0$

Je
$$\begin{cases} 2'' = 6y^2 \\ = 6y^2 \\ = 6y^2 \end{cases}$$

 $= 6y^2 = 6y$

For every Sh of the newton Solver we need to solve ODE

$$y'' = 2y^3$$

$$z'' = 6y^2 z$$

$$y'(a) = 2$$

$$y'(a) = 5x$$

$$z(d = 0)$$

ey. We Eder for Systems.

Remember
$$z(b) = \phi'(sk)$$

So plug tais in:
 $s_{kx} = s_k - \frac{\phi(q_k)}{\phi'(s_k)}$
 $= s_k - \frac{y(b_i s_k)}{z(b)}$

