# Computer Problem set 2.

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The objective of this computer set is to implement different ways to simulate a discretization of the Brownian motion. The first question uses the forward approach by exploiting the independence of the increments of Brownian motion. The second question uses a backward approach with the conditional distribution. The third question is an application of both methods to compute the quadratic variation of the Brownian motion.

## 1

#### 1.1 Question 1-a

Let n > 0 and  $1 \le i \le 2^n$  be integers.

We define the random variable  $Z_i$  as follows:

$$Z_i = \frac{W_{t_i^n} - W_{t_{i-1}^n}}{\sqrt{\Delta T}}$$

Since  $(W_t)_{t\geq 0}$  is a Brownian motion, then by definition  $W_{t_i^n} - W_{t_{i-1}^n}$  is a  $\mathcal{N}(0, \Delta T)$  random variable and thus  $Z_i$  is a  $\mathcal{N}(0, 1)$  random variable. And again since  $(W_t)_{t\geq 0}$  is a Brownian motion the increments are independent which means that the variables  $(Z_j)_{1\leq j\leq 2^n}$  are iid  $\mathcal{N}(0, 1)$  random variables.

#### 1.2 Questions 1-b, 1-c

Simulation results for T=1 and (N=1000 number of copies): As predicted by theroy, we have:

$$Var(W_T) \simeq T$$

and

$$CovMatrix(W_T, W_{\frac{T}{2}}) \simeq \begin{bmatrix} T & \frac{T}{2} \\ \frac{T}{2} & \frac{T}{2} \end{bmatrix}$$

We observe when estimating the quantities  $Var(W_T)$  and  $CovMatrix(W_T, W_{\frac{T}{2}})$  using the N discrete trajectories the results do not vary much when n becomes bigger. This observation may seem weird at first since one would expect that the estimations will be more accurate. However, it is natural that increasing n does not affect the precision because it's only a parameter of discretization

and since we only compute  $Var(W_T)$  and  $CovMatrix(W_T, W_{\frac{T}{2}})$  it does not matter how large n is because only the number of copies N affects the estimation precision of these two quantities, while n quantifies the extent of detail to which we have information on the random trajectories.

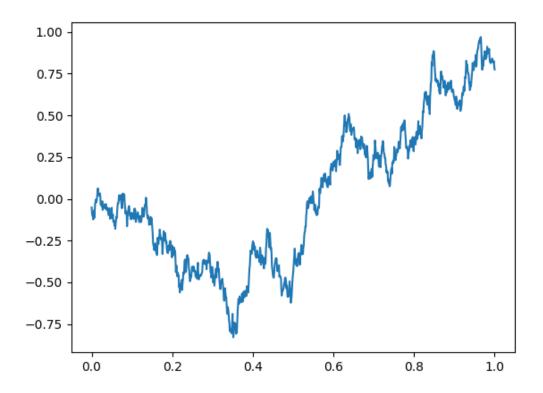


Figure 1: Trajectory simulated by forward approach

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## 2.1 Question 2.a

We have:  $W_{\bar{s}}|(W_{s_1}=x_1,W_{s_2}=x_2)=W_{s_1}+(W_{\bar{s}}-W_{s_1})|(W_{s_1}=x_1,W_{s_2}=x_2)$  Then since  $W_{s_1}$ ,  $(W_{\bar{s}}-W_{s_1})$  are independent and  $W_{s_1}$ ,  $(W_{s_2}-W_{s_1})$  we can write the following:

$$W_{\bar{s}}|(W_{s_1}=x_1,W_{s_2}=x_2)=x_1+(W_{\bar{s}}-W_{s_1})|(W_{s_2}-W_{s_1}=x_2-x_1)$$

And since  $(W_t - W_{s_1})$  is a Brownian motion, we can deduce from the information given that:  $(W_{\bar{s}} - W_{s_1})|(W_{s_2} - W_{s_1} = x_2 - x_1)$  is normally distributed with conditional mean  $\frac{\bar{s} - s_1}{s_2 - s_1}(x_2 - x_1)$  and conditional variance  $\frac{\bar{s} - s_1}{s_2 - s_1}(s_2 - \bar{s})$ .

Then the distribution of  $(W_{\bar{s}}-W_{s_1})|(W_{s_2}-W_{s_1}=x_2-x_1)$  is  $\mathcal{N}(\frac{x_2-x_1}{2},\frac{s_2-s_1}{4})$  And we can deduce that:

$$W_{\bar{s}}|(W_{s_1}=x_1,W_{s_2}=x_2) \stackrel{D}{\sim} \mathcal{N}(\frac{x_2+x_1}{2},\frac{s_2-s_1}{4})$$

### 2.2 Question 2.b

We have:

$$W_{\bar{s}}|(W_{s_1}=x_1,W_{s_2}=x_2,(W_u)_{u\not\in[s_1,s_2]})=W_{\bar{s}}|((W_u)_{u\in[0,s_1[},W_{s_1}=x_1,W_{s_2}=x_2,(W_u)_{u\in[s_2,+\infty[)})$$

And since  $(W_t)$  is a Markovian process we then have :

$$\begin{aligned} W_{\bar{s}}|(W_{s_1} = x_1, W_{s_2} = x_2, (W_u)_{u \notin [s_1, s_2]}) &= W_{\bar{s}}|(W_{s_1} = x_1, W_{s_2} = x_2, (W_u)_{u \in [s_2, +\infty[)}) \\ &= W_{\bar{s}}|(W_{s_1} = x_1, W_{s_2} = x_2, (W_u - W_{s_2})_{u \in [s_2, +\infty[)}) \\ &= W_{\bar{s}}|(W_{s_1} = x_1, W_{s_2} = x_2) \end{aligned}$$

The last equality is due to the fact that  $((W_u - W_{s_2})_{u \in [s_2, +\infty[}))$  is independent of  $W_{\bar{s}}$ . Then, using the result of question 2.b we get that

$$W_{\bar{s}}|(W_{s_1}=x_1,W_{s_2}=x_2,(W_u)_{u\not\in[s_1,s_2]})\overset{D}{\sim}\mathcal{N}(\frac{x_2+x_1}{2},\frac{s_2-s_1}{4})$$

#### 2.3 Questions 2.c and 2.d

When computing  $Var(W_T)$  and  $CovMatrix(W_T, W_{\frac{T}{2}})$  we get the same results as we did in the forward approach:

As predicted by theroy, we have:

$$Var(W_T) \simeq T$$

and

$$CovMatrix(W_T, W_{\frac{T}{2}}) \simeq \begin{bmatrix} T & \frac{T}{2} \\ \frac{T}{2} & \frac{T}{2} \end{bmatrix}$$

The remark on the effect of n on the estimations remains valid for this approach as well.

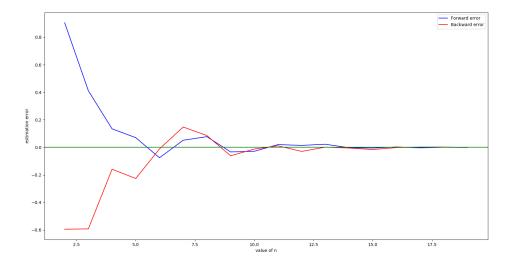


Figure 2: Quadratic Variation estimation error