Semiparametric Single Index Models

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Introduction

A semiparametric single index model is given by

$$Y = g(X^T \beta_0) + u,$$

where

 $Y \in \mathbb{R}$: a dependent variable, $X \in \mathbb{R}^q$: a $q \times 1$ explanatory vector, $\beta_0 \in \mathbb{R}^q$: a $q \times 1$ vector of unknown parameters, $u \in \mathbb{R}$: an error term which satisfies $\mathbb{E}(u \mid X) = 0$, $g(\cdot)$: an unknown distribution function.

Introduction

- Even though x is a $q \times 1$ vector, $x^T \beta_0$ is a scalar of a single linear combination, which is called a single index.
- By the form of the single index model, we obtain

$$\mathbb{E}(Y \mid X) = g(X^T \beta_0),$$

which means that the conditional expectation of Y only depends on the vector X through a single index $X^T\beta_0$.

- The model is SEMIPARAMETRIC when $\beta \in \mathbb{R}^q$ is estimated with the parametric methods and $g(\cdot)$ with the nonparametric methods.
- Some of the PARAMETRIC single index models are really familiar with us.

Examples of Parametric Single Index Model

• If $g(\cdot)$ is the identity function, then the model turns out to be a linear regression model:

$$Y = g(X^T \beta_0) + u = X^T \beta_0 + u.$$

- If $g(\cdot)$ is the CDF of Normal(0,1), then the model turns out to be a probit model.
 - See the textbook for further discussions on a probit model.
- If $g(\cdot)$ is the CDF of logistic distribution, then the model turns out to be a logistic regression model.

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Identification Conditions

Proposition 8.1 (Identification of a Single Index Model)

For the semiparametric single index model $Y = g(x^T \beta_0) + u$, identification of β_0 and $g(\cdot)$ requires that

- (i) x should not contain a constant/intercept, and must contain at least one continuous variable. Moreover, $\|\beta_0\|=1$.
- (ii) $g(\cdot)$ is differentiable and is not a constant function on the support of $x^T\beta_0$.
- (iii) For the discrete components of x, varying the values of the discrete variables will not divide the support of $x^T\beta_0$ into disjoint subsets.

Identification Condition (i)

- Note that the location and the scale of β_0 are not identified.
- The vector x cannot include an intercept because the function $g(\cdot)$ (which is to be estimated in nonparametric manners) includes any location and level shift.
 - That is, β_0 cannot contain a location parameter.
- Some normalization criterion (scale restrictions) for β_0 are needed.
 - One approach is to set $\|\beta_0\|$.
 - The second approach is to set one component of β_0 to equal one. This approach requires that the variable corresponding to the component set to equal one is continuously distributed and has a non-zero coefficient.
 - Then, x must be dimension 2 or larger. If x is one-dimensional, then $\beta_0 \in \mathbb{R}^1$ is simply normalized to 1, and the model is the one-dimensional nonparametric regression $E(Y \mid x) = g(x)$ with no semiparametric component.

Identification Conditions (ii) and (iii)

- The function $g(\cdot)$ cannot be a constant function and must be differentiable on the support of $x^T \beta_0$.
- x must contain at least one continuously distributed variable and this continuous variable must have non-zero coefficient.
 - If not, $x^T\beta_0$ only takes a discrete set of values and it would be impossible to identify a continuous function $g(\cdot)$ on this discrete support.

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- Suppose that the functional form of $g(\cdot)$ were known.
- Then we could estimate β_0 by minimizing the least-squares criterion:

$$\sum_{i=1} \left[Y_i - g(X_i^T \beta) \right]^2$$

with respect to β .

- We could think about replacing $g(\cdot)$ with a nonparametric estimator $\hat{g}(\cdot)$.
- However, since g(z) is the conditional mean of Y_i given $X_i^T\beta_0=z$, $g(\cdot)$ depends on unknown β_0 , so we cannot estimate $g(\cdot)$ here.

• Nevertheless, for a fixed value of β , we can estimate

$$G(X_i^T\beta) := \mathbb{E}(Y_i \mid X_i^T\beta) = \mathbb{E}(g(X_i^T\beta) \mid X_i^T\beta).$$

- In general $G(X_i^T \beta) \neq g(X_i^T \beta)$.
- When $\beta=\beta_0$ ¹, it holds that $G(X_i^T\beta_0)=g(X_i^T\beta_0).$

¹Recall that β_0 is the true value of β .

• First, we estimate $G(X_i^T\beta)$ with the leave-one-out NW estimator:

$$\hat{G}_{-i}(X_i^T \beta) := \hat{\mathbb{E}}_{-i}(Y_i \mid X_i^T \beta)$$

$$= \frac{\sum_{j \neq i} Y_j K\left(\frac{X_j^T \beta - X_i^T \beta}{h}\right)}{\sum_{j \neq i} K\left(\frac{X_j^T \beta - X_i^T \beta}{h}\right)}.$$

• Second, using the leave-one-out NW estimator $\hat{G}_{-i}(X_i^T\beta)$, we estimate β with

$$\hat{\beta} := \arg\min_{\beta} \sum_{i=1}^{n} \left[Y_i - \hat{G}_{-i}(X_i^T \beta) \right]^2 w(X_i) \mathbf{1}(X_i \in A_n) := S_n(\beta).$$

- $w(X_i)$ is a nonnegative weight function.
- $\mathbf{1}(X_i \in A_n)$ is a trimming function to trim out small values of $\frac{1}{nh} \sum_{j \neq i} K\left(\frac{X_j^T \beta X_i^T \beta}{h}\right)$, so that do not suffer the random dominator problem.

Asymptotic Distribution of Ichimura (1993)'s Estimator

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Useful references also include some lecture notes of the following topic courses:

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- セミノンパラメトリック計量分析(末石直也,2014年度後期,京都大学).