Semiparametric Single Index Models

Li and Racine (2007, Chapter 8)

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Introduction

A semiparametric single index model is given by

$$Y = g(X^T \beta_0) + u,$$

where

 $Y\in\mathbb{R}$: a dependent variable, $X\in\mathbb{R}^q: \text{a }q\times 1 \text{ explanatory vector,}$ $\beta_0\in\mathbb{R}^q: \text{a }q\times 1 \text{ vector of unknown parameters,}$ $u\in\mathbb{R}: \text{an error term which satisfies }\mathbb{E}(u\mid X)=0,$ $g(\cdot): \text{an unknown distribution function.}$

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Introduction

- Even though x is a $q \times 1$ vector, $x^T \beta_0$ is a scalar of a single linear combination, which is called a single index.
- By the form of the single index model, we obtain

$$\mathbb{E}(Y \mid X) = g(X^T \beta_0),$$

which means that the conditional expectation of Y only depends on the vector X through a single index $X^T\beta_0$.

• The model is semiparametric when $\beta \in \mathbb{R}^q$ is estimated with the parametric methods and $g(\cdot)$ with the nonparametric methods.

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Examples of Parametric Single Index Model

• If $g(\cdot)$ is the identity function, then the model turns out to be a linear regression model:

$$Y = g(X^T \beta_0) + u = X^T \beta_0 + u.$$

- If $g(\cdot)$ is the CDF of Normal(0,1), then the model turns out to be a probit model.
 - See the textbook for further discussions on a probit model.
- If $g(\cdot)$ is the CDF of logistic distribution, then the model turns out to be a logistic regression model.

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Identification Conditions

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Proposition 8.1 (Identification of a Single Index Model)

For the semiparametric single index model $Y=g(x^T\beta_0)+u$, identification of β_0 and $g(\cdot)$ requires that

- (i) x should not contain a constant/an intercept, and must contain at least one continuous variable. Moreover, $\|\beta_0\|=1$.
- (ii) $g(\cdot)$ is differentiable and is not a constant function on the support of $x^T\beta_0$.
- (iii) For the discrete components of x, varying the values of the discrete variables will not divide the support of $x^T\beta_0$ into disjoint subsets.

Identification Condition (i)

- Note that the location and the scale of β_0 are not identified.
- The vector x cannot include an intercept because the function $g(\cdot)$ (which is to be estimated in nonparametric manners) includes any location and level shift.
 - That is, β_0 cannot contain a location parameter.

Identification Condition (i)

- Some normalization criterion (scale restrictions) for β_0 are needed.
 - One approach is to set $\|\beta_0\| = 1$.
 - The second approach is to set one component of β_0 to equal one. This approach requires that the variable corresponding to the component set to equal one is continuously distributed and has a non-zero coefficient.
 - Then, x must be dimension 2 or larger. If x is one-dimensional, then $\beta_0 \in \mathbb{R}^1$ is simply normalized to 1, and the model is the one-dimensional nonparametric regression $E(Y \mid x) = g(x)$ with no semiparametric component.

Identification Conditions (ii) and (iii)

- The function $g(\cdot)$ cannot be a constant function and must be differentiable on the support of $x^T \beta_0$.
- x must contain at least one continuously distributed variable and this continuous variable must have non-zero coefficient.
 - If not, $x^T\beta_0$ only takes a discrete set of values and it would be impossible to identify a continuous function $g(\cdot)$ on this discrete support.

Ichimura's (1993) Method

- Textbook: Sections 8.2; 8.4.1; and 8.12.
- Suppose that the functional form of $g(\cdot)$ were known.
- ullet Then we could estimate eta_0 by minimizing the least-squares criterion:

$$\sum_{i=1} \left[Y_i - g(X_i^T \beta) \right]^2$$

with respect to β .

- We could think about replacing $g(\cdot)$ with a nonparametric estimator $\hat{g}(\cdot)$.
- However, since g(z) is the conditional mean of Y_i given $X_i^T\beta_0=z,\ g(\cdot)$ depends on unknown β_0 , so we cannot estimate $g(\cdot)$ here.

• Nevertheless, for a fixed value of β , we can estimate

$$G(X_i^T \beta) := \mathbb{E}(Y_i \mid X_i^T \beta) = \mathbb{E}(g(X_i^T \beta) \mid X_i^T \beta).$$

- In general $G(X_i^T\beta) \neq g(X_i^T\beta)$.
- When $\beta = \beta_0$, it holds that $G(X_i^T \beta_0) = g(X_i^T \beta_0)$.

• First, we estimate $G(X_i^T\beta)$ with the leave-one-out NW estimator:

$$\hat{G}_{-i}(X_i^T \beta) := \hat{\mathbb{E}}_{-i}(Y_i \mid X_i^T \beta)$$

$$= \frac{\sum_{j \neq i} Y_j K\left(\frac{X_j^T \beta - X_i^T \beta}{h}\right)}{\sum_{j \neq i} K\left(\frac{X_j^T \beta - X_i^T \beta}{h}\right)}.$$

• Second, using the leave-one-out NW estimator $\hat{G}_{-i}(X_i^T\beta)$, we estimate β with

$$\hat{\beta} := \arg\min_{\beta} \sum_{i=1}^{n} \left[Y_i - \hat{G}_{-i}(X_i^T \beta) \right]^2 w(X_i) \mathbf{1}(X_i \in A_n)$$

$$:= \arg\min_{\beta} S_n(\beta),$$

which is called Ichimura's estimator (the WSLS estimator).

- $w(X_i)$ is a nonnegative weight function.
- $\mathbf{1}(X_i \in A_n)$ is a trimming function to trim out small values of $\hat{p}(X_i^T\beta) = \frac{1}{nh} \sum_{j \neq i} K\left(\frac{X_j^T\beta X_i^T\beta}{h}\right)$, so that we do not suffer the random denominator problem.
 - $A_{\delta} = \{x : p(x^T \beta) \geq \delta, \text{ for } \forall \beta \in \mathcal{B}\}.$
 - $A_n = \{x : ||x x^*|| \le 2h, \text{ for } \exists x^* \in A_\delta\}$, which shrinks to A_δ as $n \to \infty$ and $h \to 0$.

- Let $\hat{\beta}$ denote the semiparametric estimator of β_0 obtained from minimizing $S_n(\beta)$.
- To derive the asymptotic distribution of $\hat{\beta}$, the following conditions are needed:

Assumpution 8.1

The set A_{δ} is compact, and the weight function $w(\cdot)$ is bounded and posotive on A_{δ} . Define the set

$$D_z = \{z : z = x^T \beta, \beta \in \mathcal{B}, x \in A_\delta\}.$$

Letting $p(\cdot)$ denote the PDF of $z \in D_z$, $p(\cdot)$ is bounded below by a positive constant for $\forall z \in D_z$

Assumpttion 8.2

 $g(\cdot)$ and $p(\cdot)$ are 3 times differentiable w.r.t. $z=x^{\beta}$. The third derivatives are Lipschitz continuous uniformly over \mathcal{B} for $\forall z \in D_z$.

Assumpttion 8.3

The kernel function is a bounded second order kernel, which has bounded support; is twice differentiable; and its second derivative is Lipschitz continuous.

Assumpttion 8.4

$$\begin{split} \mathbb{E}(|Y^m|) < \infty \text{ for } ^\exists m \geq 3. \text{ var}(Y \mid x) \text{ is bounded and bounded} \\ \text{away from zero for } ^\forall x \in A_\delta. \ \frac{q \ln(h)}{nh^{3+\frac{3}{m-1}}} \to 0 \text{ and } nh^8 \to 0 \text{ as } \\ n \to \infty. \end{split}$$

Theorem 8.1. Under assumptions 8.1 through 8.4,

$$\sqrt{n}(\hat{\beta} - \beta_0) \xrightarrow{d} \mathsf{Normal}(0, \Omega_I),$$

with

$$\Omega_{I} = V^{-1} \Sigma V^{-1},
V = \mathbb{E}\{w(X_{i})(g_{i}^{(1)})^{2}
\times (X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))(X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))^{T}\},
\Sigma = \mathbb{E}\{w(X_{i})\sigma^{2}(X_{i})(g_{i}^{(1)})^{2}
\times (X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))(X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))^{T}\},$$

where

- $(g_i^{(1)}) = \frac{\partial g(v)}{\partial v} \mid_{v=X_i^T \beta_0}$,
- $\mathbb{E}_A(X_i \mid v) = \mathbb{E}(X_i \mid x_A^T \beta_0 = v)$,
- x_A has the distribution of X_i conditional on $X_i \in A_{\delta}$.

- See Ichimura (1993); and Hardle, Hall and Ichimura (1993) for the proof of **Theorem 8.1**.
- Horowitz (2009) provides an excellent heuristic outline for proving **Theorem 8.1**, using only the familiar Taylor series methods, the standard LLN, and the Lindeberg-Levy CLT.

Optimal Weight under the Homoscedasticity Assumption

• We introduce the following homoscedasticity assumpution:

$$\mathbb{E}(u_i^2 \mid X_i) = \sigma^2.$$

- Under this assumptaion, the optimal choice of $w(\cdot)$ is $w(X_i)=1.$
- In this case,

$$\hat{\beta} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - \hat{G}_{-i}(X_i^T \beta)^2) \mathbf{1}(X_i \in A_n)$$

is semiparametrically efficient in the sense that Ω_I is the semiparametric variance lower bound (conditional on $X \in A_\delta$).

Optimal Weight under Heteroscedasticity

- In general, $\mathbb{E}(u_i^2 \mid X_i) = \sigma^2(X_i)$.
- An infeasible case: If one assues that $\mathbb{E}(u_i^2 \mid X_i) = \sigma^2(X_i^T \beta_0)$, that is, the conditional variance depends only on the single index $X_i^T \beta_0$, the choice of $w(X_i) = \frac{1}{\sigma^2(X_i^T \beta_0)}$ can lead to a semiparametrically efficient estimation.
- We could adopt a two-step procedure as follows.

A two-step procedure to Choose Optimal Weight

- Suppose that the conditional variance is a function of $X_i^T \beta_0$ (Let $\sigma^2(X_i^T \beta_0)$ denote it).
- The first step: Use $w(X_i)=1$ to obtain a \sqrt{n} -consistent estimator of β_0 .
- Let β_0 denote the estimator of β_0 , and $\tilde{u}_i = Y_i \hat{g}$ denote the residual obtained from $\tilde{\beta}_0$.
- We can obtain a consistent nonparametric estimator of the conditional variance: $\hat{\sigma}^2(X_i^T\beta_0)$.
- The second step: Estimate β_0 again using $w(X_i) = \frac{1}{\hat{\sigma}^2(X_i^T\beta_0)}$:

$$\hat{\beta}_0 = \arg\min_{\beta} \sum_{i=1}^{n} \left[Y_i - \hat{G}_{-i}(X_i^T \beta) \right]^2 \frac{1}{\hat{\sigma}^2(X_i^T \beta_0)} \mathbf{1}(X_i \in A_n).$$

• The estimator $\hat{\beta}_0$ is semiparametrically efficient because $\hat{\sigma}^2(v) - \sigma^2(v)$ converges to zero at a particular rate uniformly over $v \in D_v$ (D_v is the support of $X_i^T \beta_0$).

Bandwidth Selection for Ichimura's Method

• Hardle, Hall and Ichimura (1993) suggest picking β and the bandwidth h jointly by minimization of $S_n(\beta)$.

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Klein and Spady's (1993) Estimator

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Estimator

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Maximum Score Estimator

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Estimator

Multinomial Discrete Choice Models

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Maximum Likelihood Approach

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References (2)

Useful references also include some lecture notes of the following topic courses:

- ECON 718 NonParametric Econometrics (Bruce Hansen, Spring 2009, University of Wisconsin-Madison),
- セミノンパラメトリック計量分析(末石直也, 2014 年度後期, 京都大学).