Semiparametric Single Index Models

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Introduction

A semiparametric single index model is given by

$$Y = g(X^T \beta_0) + u,$$

where

 $Y\in\mathbb{R}$: a dependent variable, $X\in\mathbb{R}^q: \text{a }q\times 1 \text{ explanatory vector,}$ $\beta_0\in\mathbb{R}^q: \text{a }q\times 1 \text{ vector of unknown parameters,}$ $u\in\mathbb{R}: \text{an error term which satisfies }\mathbb{E}(u\mid X)=0,$ $g(\cdot): \text{an unknown distribution function.}$

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Introduction

- Even though x is a $q \times 1$ vector, $x^T \beta_0$ is a scalar of a single linear combination, which is called a single index.
- By the form of the single index model, we obtain

$$\mathbb{E}(Y \mid X) = g(X^T \beta_0),$$

which means that the conditional expectation of Y only depends on the vector X through a single index $X^T\beta_0$.

- The model is semiparametric when $\beta \in \mathbb{R}^q$ is estimated with the parametric methods and $g(\cdot)$ with the nonparametric methods.
- Some of the parametric single index models are really familiar with us.

Examples of Parametric Single Index Model

• If $g(\cdot)$ is the identity function, then the model turns out to be a linear regression model:

$$Y = g(X^T \beta_0) + u = X^T \beta_0 + u.$$

- If $g(\cdot)$ is the CDF of Normal(0,1), then the model turns out to be a probit model.
 - See the textbook for further discussions on a probit model.
- If $g(\cdot)$ is the CDF of logistic distribution, then the model turns out to be a logistic regression model.

Identification Conditions

Identification Conditions

Proposition 8.1 (Identification of a Single Index Model) -

For the semiparametric single index model $Y=g(x^T\beta_0)+u$, identification of β_0 and $g(\cdot)$ requires that

- (i) x should not contain a constant/intercept, and must contain at least one continuous variable. Moreover, $\|\beta_0\|=1$.
- (ii) $g(\cdot)$ is differentiable and is not a constant function on the support of $x^T\beta_0$.
- (iii) For the discrete components of x, varying the values of the discrete variables will not divide the support of $x^T\beta_0$ into disjoint subsets.

Identification Condition (i)

- Note that the location and the scale of β_0 are not identified.
- The vector x cannot include an intercept because the function $g(\cdot)$ (which is to be estimated in nonparametric manners) includes any location and level shift.
 - That is, β_0 cannot contain a location parameter.

Identification Condition (i)

- Some normalization criterion (scale restrictions) for β_0 are needed.
 - One approach is to set $\|\beta_0\|$.
 - The second approach is to set one component of β_0 to equal one. This approach requires that the variable corresponding to the component set to equal one is continuously distributed and has a non-zero coefficient.
 - Then, x must be dimension 2 or larger. If x is one-dimensional, then $\beta_0 \in \mathbb{R}^1$ is simply normalized to 1, and the model is the one-dimensional nonparametric regression $E(Y \mid x) = g(x)$ with no semiparametric component.

Identification Conditions (ii) and (iii)

- The function $g(\cdot)$ cannot be a constant function and must be differentiable on the support of $x^T \beta_0$.
- x must contain at least one continuously distributed variable and this continuous variable must have non-zero coefficient.
 - If not, $x^T\beta_0$ only takes a discrete set of values and it would be impossible to identify a continuous function $g(\cdot)$ on this discrete support.

Estimation: Ichimura's Method

Ichimura's Method¹

- Suppose that the functional form of $g(\cdot)$ were known.
- Then we could estimate β_0 by minimizing the least-squares criterion:

$$\sum_{i=1} \left[Y_i - g(X_i^T \beta) \right]^2$$

with respect to β .

- We could think about replacing $g(\cdot)$ with a nonparametric estimator $\hat{g}(\cdot)$.
- However, since g(z) is the conditional mean of Y_i given $X_i^T\beta_0=z$, $g(\cdot)$ depends on unknown β_0 , so we cannot estimate $g(\cdot)$ here.

¹Ichimura (1993).

• Nevertheless, for a fixed value of β , we can estimate

$$G(X_i^T\beta) := \mathbb{E}(Y_i \mid X_i^T\beta) = \mathbb{E}(g(X_i^T\beta) \mid X_i^T\beta).$$

- In general $G(X_i^T \beta) \neq g(X_i^T \beta)$.
- When $\beta=\beta_0$, it holds that $G(X_i^T\beta_0)=g(X_i^T\beta_0).$

 \bullet First, we estimate $G(X_i^T\beta)$ with the leave-one-out NW estimator:

$$\hat{G}_{-i}(X_i^T \beta) := \hat{\mathbb{E}}_{-i}(Y_i \mid X_i^T \beta)$$

$$= \frac{\sum_{j \neq i} Y_j K\left(\frac{X_j^T \beta - X_i^T \beta}{h}\right)}{\sum_{j \neq i} K\left(\frac{X_j^T \beta - X_i^T \beta}{h}\right)}.$$

• Second, using the leave-one-out NW estimator $\hat{G}_{-i}(X_i^T\beta)$, we estimate β with

$$\hat{\beta} := \arg\min_{\beta} \sum_{i=1}^{n} \left[Y_i - \hat{G}_{-i}(X_i^T \beta) \right]^2 w(X_i) \mathbf{1}(X_i \in A_n)$$

$$:= \arg\min_{\beta} S_n(\beta),$$

which is called Ichimura's estimator (the WSLS estimator).

- $w(X_i)$ is a nonnegative weight function.
- $\mathbf{1}(X_i \in A_n)$ is a trimming function to trim out small values of $\hat{p}(X_i^T\beta) = \frac{1}{nh} \sum_{j \neq i} K\left(\frac{X_j^T\beta X_i^T\beta}{h}\right)$, so that we do not suffer the random denominator problem.
 - $A_{\delta} = \{x : p(x^T \beta) \ge \delta, \text{ for } \forall \beta \in \mathcal{B}\}.$
 - $A_n = \{x : ||x x^*|| \le 2h, \text{ for } \exists x^* \in A_\delta\}$, which shrinks to A_δ as $n \to \infty$ and $h \to 0$.

- Hardle, Hall and Ichimura (1993) suggest picking β and the bandwidth h jointly by minimization of $S_n(\beta)$.
- Further discussions on bandwidth selection follow in Section 8.4.

- Let $\hat{\beta}$ denote the semiparametric estimator of β_0 obtained from minimizing $S_n(\beta)$.
- To derive the asymptotic distribution of $\hat{\beta}$, the following conditions are needed:

Assumpttion 8.1

The set A_{δ} is compact, and the weight function $w(\cdot)$ is bounded and posotive on A_{δ} . Define the set

$$D_z = \{z : z = x^T \beta, \beta \in \mathcal{B}, x \in A_\delta\}.$$

Letting $p(\cdot)$ denote the PDF of $z \in D_z$, $p(\cdot)$ is bounded below by a positive constant for $\forall z \in D_z$

Assumpttion 8.2

 $g(\cdot)$ and $p(\cdot)$ are 3 times differentiable w.r.t. $z=x^{\beta}$. The third derivatives are Lipschitz continuous uniformly over \mathcal{B} for $\forall z \in D_z$.

Assumpution 8.3 -

The kernel function is a bounded second order kernel, which has bounded support; is twice differentiable; and its second derivative is Lipschitz continuous.

Assumpution 8.4 -

$$\begin{split} \mathbb{E}(|Y^m|) < \infty \text{ for } ^\exists m \geq 3. \text{ var}(Y \mid x) \text{ is bounded and bounded} \\ \text{away from zero for } ^\forall x \in A_\delta. \ \frac{q \ln(h)}{nh^{3+\frac{3}{m-1}}} \to 0 \text{ and } nh^8 \to 0 \text{ as } \\ n \to \infty. \end{split}$$

Theorem 8.1. Under assumptions 8.1 through 8.4,

$$\sqrt{n}(\hat{\beta} - \beta_0) \xrightarrow{d} \text{Normal}(0, \Omega_I),$$

with

$$\Omega_{I} = V^{-1} \Sigma V^{-1},
V = \mathbb{E}\{w(X_{i})(g_{i}^{(1)})^{2}
\times (X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))(X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))^{T}\},
\Sigma = \mathbb{E}\{w(X_{i})\sigma^{2}(X_{i})(g_{i}^{(1)})^{2}
\times (X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))(X_{i} - E_{A}(X_{i} \mid X_{i}^{T} \beta_{0}))^{T}\},$$

where

- $(g_i^{(1)}) = \frac{\partial g(v)}{\partial v} \mid_{v=X_i^T \beta_0}$,
- $\mathbb{E}_A(X_i \mid v) = \mathbb{E}(X_i \mid x_A^T \beta_0 = v),$
- x_A has the distribution of X_i conditional on $X_i \in A_{\delta}$.

- See Ichimura (1993); and Hardle, Hall and Ichimura (1993) for the proof of **Theorem 8.1**.
 - Horowitz (1998) provides an excellent heuristic outline for proving Theorem 8.1, using only the familiar Taylor series methods, the standard LLN, and the Lindeberg-Levy CLT.
- We can consistently estimate Avar $\left(\sqrt{n}(\hat{\beta}-\beta)\right)=\Omega_I$ with its sample analogue.

Optimal Weight under the Homoscedasticity Assumption

- Here we introduce the following homoscedasticity assumption: $\mathbb{E}(u_i^2 \mid X_i) = \sigma^2$.
- Under this assumptaion, the optimal choice of $w(\cdot)$ is $w(X_i)=1.$
- In this case,

$$\hat{\beta} = \arg\min_{\beta} \sum_{i=1}^{n} (Y_i - \hat{G}_{-i}(X_i^T \beta)^2) \mathbf{1}(X_i \in A_n)$$

is semiparametrically efficient in the sense that Ω_I is the semiparametric variance lower bound (conditional on $X \in A_{\delta}$).

Optomal Weight under Heteroscedasticity

- In general, $\mathbb{E}(u_i^2 \mid X_i) = \sigma^2(X_i)$.
 - \bullet The semiparametrically efficient estimator $\hat{\beta}_{opt}$ has a complicated structure.
- An infeasible case: If one assues that $\mathbb{E}(u_i^2 \mid X_i) = \sigma^2(X_i^T \beta_0)$, that is, the conditional variance depends only on the single index $X_i^T \beta_0$, the choice of $w(X_i) = \frac{1}{\sigma_{X_i^T \beta_0}^2}$ can lead to a semiparametrically efficient estimation.

Direct Semiparametric Estimators for β

Bandwidth Selection

Klein and Spady (1993)

Lewbel (2000)

Manski's (1975) Maximum Score

Estimator

Horowitz's (1992) Smoothed

Maximum Score Estimator

Han's (1987) Maximum Rank

Estimator

Multinomial Discrete Choice Models

Ai's (1997) Semiparametric

Maximum Likelihood Approach

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- Ichimura, H. (1993) "Semiparametric Least Squares (SLS) and Weighted SLS Estimation of Single-Index Models," Journal of Econometrics, 3, 205-228.
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References (2)

Useful references also include some lecture notes of the following topic courses:

- ECON 718 NonParametric Econometrics (Bruce Hansen, Spring 2009, University of Wisconsin-Madison),
- セミノンパラメトリック計量分析(末石直也, 2014 年度後期, 京都大学).