Nonparametric Estimation of Conditional PDF

Yasuyuki Matsumura

Graduate School of Economics, Kyoto University

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Introduction

• We consider the estimation of the conditional PDF g(Y|X) when both Y and X are general multivariate vectors.

Settings

- $Z = (X, Y) = (Z^c, Z^d)$
- ullet Z^d consists of r discrete variables.
 - $X^d \in \mathbb{R}^{r_x}, Y^d \in \mathbb{R}^{r_y}$.
- ullet Z^c consists of q continuous variables.
 - $\bullet \ X^c \in \mathbb{R}^{q_x}, Y^c \in \mathbb{R}^{q_y}.$
- $r = r_x + r_y, q = q_x + q_y.$

Kernel Methods

- Let Z_{is}^d denote the s-th component of Z_i^d .
- Define a univariate kernel function

$$l(Z_{is}^d, Z_{js}^d, \lambda_s) = \left\{ \begin{array}{ll} 1 - \lambda_s & \text{if } Z_{is}^d = Z_{js}^d, \\ \frac{\lambda_s}{c_s - 1} & \text{if } Z_{is}^d \neq Z_{js}^d. \end{array} \right.$$

The product kernel is given by

$$L_{\lambda, Z_i^d, Z_j^d} = \prod_{s=1}^r l(Z_{is}^d, Z_{js}^d, \lambda_s).$$

Kernel Methods

- Let Z_{is}^c denote the s-th component of Z_i^c .
- Define a univariate kernel function $w(\cdot)$ in the same way as Section 5.1.
- Then, the product kernel is given by

$$W_{h,Z_{i}^{c},Z_{j}^{c}} = \prod_{s=1}^{q} \frac{1}{h_{s}} w \left(\frac{Z_{is}^{c} - Z_{js}^{c}}{h_{s}} \right).$$

- $\bullet \ \ \mathsf{Define} \ K_{\gamma,Z_i,z} = L_{\lambda,Z_i^d,z} \times W_{h,Z_i^c,z^c}.$
- Apply the same notation $L(\cdot)$ and $W(\cdot)$ to Y and X.



Kernel Methods

We estimate

$$g(y|x) = \frac{f(x,y)}{\mu(x)}$$

by the following nonparametric estimator:

$$\hat{g}(y|x) = \frac{\hat{f}(x,y)}{\hat{\mu}(x)},$$

where

$$\hat{f}(x,y) = \hat{f}(z) = \frac{1}{n} \sum_{i=1}^{n} K_{\gamma,Z_i,z},$$

$$\hat{\mu}(x) = \frac{1}{n} \sum_{i=1}^{n} K_{\gamma,X_i,x}.$$

- Consider the case where the independent variables are all relevent.
 - Irrelevant independent variables will be asymptotically smoothed out.
- As in Section 5.2, we choose the tuning parameters h and λ that minimize a sample analogue of $I_{1n}-2I_{2n}$:

$$CV(h,\lambda) = \frac{1}{n} \sum_{i=1}^{n} \frac{\hat{G}_{-i}(X_i)}{\hat{\mu}_{-i}(X_i)^2} - \frac{2}{n} \sum_{i=1}^{n} \frac{\hat{f}_{-i}(X_i)}{\hat{\mu}_{-i}(X_i)}.$$

- Take \hat{h} and $\hat{\lambda}$ as the CV choices.
- Let ${h_s}^0$ and ${\lambda_s}^0$ denote the minimizers of the leading term of $CV(h,\lambda)$.

Racine et al. [2004]

Where ${h_s}^0=c_{1s}n^{rac{-1}{q+4}}$ and ${\lambda_s}^0=c_{2s}n^{rac{-2}{q+4}}$, it holds that

$$\frac{\hat{h}_s}{h_s^0} \stackrel{p}{\to} 1, \quad \frac{\hat{\lambda}_s}{\lambda_s^0} \stackrel{p}{\to} 1.$$

Theorem 5.4

Under several assumptions given in Racine et al. (2004),

$$\begin{split} \frac{\hat{h}_s - {h_s}^0}{{h_s}^0} &= O_p\left(n^{\frac{-\alpha}{q+4}}\right), \quad \alpha = \min\left\{2, \frac{q}{2}\right\}, \\ \frac{\hat{\lambda}_s - {\lambda_s}^0}{{\lambda_s}^0} &= O_p\left(n^{-\beta}\right), \quad \beta = \min\left\{\frac{1}{2}, \frac{4}{q+4}\right\}. \end{split}$$

Theorem 5.5 (Asymptotic Normality)

$$\sqrt{nh_1 \cdots h_q} \left(\hat{g}(y|x) - g(y|x) - \sum_{s=1}^q \hat{h}_s^2 B_{1s}(z) - \sum_{s=1}^r \hat{\lambda}_s B_{2s}(z) \right)$$

$$\xrightarrow{d} N(0, \Omega(z)),$$

where $B_{1s}(z), B_{2s}(z), \Omega(z)$ are defined by

$$B_{1s}(z) = \begin{cases} \frac{1}{2} \kappa_2 \frac{f_{ss}(x,y)}{\mu(x)} (s = 1, \dots, q_y), \\ \frac{1}{2} \kappa_2 \frac{f_{ss}(x,y) - \mu_{ss}(x)g(y|x)}{\mu(x)} (s = q_y + 1, \dots, q), \end{cases}$$

$$B_{2s}(z) = \begin{cases} \frac{1}{c_s - 1} \sum_{v^d \in \mathcal{D}} \mathbf{1}_s(v^d, z^d) f(z^c, v^d) (s = 1, \dots, r_y), \\ \frac{1}{c_s - 1} \sum_{u^d \in \mathcal{D}} \mathbf{1}_s(u^d, x^d) \frac{f(z^c, y^d, u^d) - g(y|x)\mu(x^c, u^d)}{\mu(x)} (s = r_y + 1, \dots, q) \end{cases}$$

$$\Omega(z) = \frac{\kappa^q g(y|x)}{\mu(x)}.$$

Stochastic Equicontinuity

- Take an empirical process $v_n(t)$.
- We say $v_n(t)$ is stochastic equicontinuous $t=t_0$ if

$$\begin{split} \operatorname{For}^{\,\forall} & \epsilon > 0,^{\forall} \, \eta > 0,^{\exists} \, \delta > 0; \\ & \limsup_{n \to \infty} \mathbb{P} \left(\sup_{t \in T, \, \rho(t,t_0) < \delta} |v_n(t) - v_n(t_0)| > \eta \right) < \epsilon. \end{split}$$

Proof of Theorem 5.5

- The smoothing parameters $\hat{h}_s, \hat{\lambda}_s$ which we take as the minimizers of $CV(h,\lambda)$ are stochastic.
- On the other hand, the parameters h_s, λ_s that are defined as $h_s = c_{1s} \times n^{\frac{-1}{q+4}}, \lambda_s = c_{2s} \times n^{\frac{-2}{q+4}}$ (which satisfy $\frac{\hat{h}_s}{h_s} \stackrel{p}{\rightarrow} 1, \frac{\hat{\lambda}_s}{\lambda_s} \stackrel{p}{\rightarrow} 1$) are nonstochastic.
- By using stochastic equicontinuity arguments, we know that the asymptotic distribution of $\hat{g}(y|x)$ is the same WHETHER we use stochastic $\hat{h}_s, \hat{\lambda}_s$ OR nonstochastic h_s, λ_s .
- Therefore, we consider only the nonstochastic smoothing parameter case.

Proof of Theorem 5.5

• To derive the asymptotic normality of $\hat{g}(y|x)$, we write

$$\hat{g}(y|x) - g(y|x) = \frac{(\hat{g}(y|x) - g(y|x))\hat{\mu}(x)}{\hat{\mu}(x)} \equiv \frac{\hat{m}(y,x)}{\hat{\mu}(x)},$$

where
$$\hat{m}(y,x)=(\hat{g}(y|x)-g(y|x))\hat{\mu}(x)=\hat{f}(y,x)-g(y|x)\hat{\mu}(x).$$

Proof of Theorem 5.5

- We consider the computation of
 - $\mathbb{E}(\hat{m}(y,x))$,
 - $var(\hat{m}(y,x))$,

so that we will obtain the asymptotic normality of $\hat{m}(y,x)$:

$$\sqrt{nh_1\cdots h_q}\{\hat{m}(y,x)-(\text{bias terms})\}\stackrel{d}{\to} N(0,\kappa^qf(y,x)).$$

Note that we have already established

$$\hat{\mu}(x) - \mu(x) = Op\left(\sum_{s=q_y+1}^{q} h_s^2 + \frac{1}{\sqrt{nh_{q_y+1}\cdots h_q}}\right).$$

• Then, we derive the asymptotic normality of $\hat{g}(y|x)$:

$$\sqrt{nh_1\cdots h_q}(\hat{g}(y|x)-g(y|x)-(\text{bias temrs}))\overset{d}{
ightarrow}N(0,\Omega(z)).$$

References

• Li, Q. and J. S. Racine, (2007). *Nonparametric Econometrics: Theory and Practice*, Princeton University Press.