

Selectivity Models and Censored Models

Li and Racine (2007, Chapters 10 and 11)

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Sample Selection Issues

Sample Selection

- Sample selection issues frequently arise in empirical studies.
- We concern that the treatment effect for those “selected as treated” will differ from that for persons randomly selected from the general population.
- Pioneering parametric approaches to deal with sample selection can be found in Heckman (1976, 1979).

Semiparametric Type-2 Tobit Models

Type-2 Tobit Models

- The Type-2 Tobit model is the four equation system:

$$Y_{1i}^* = X_{1i}^T \beta_1 + u_{1i},$$

$$Y_{2i}^* = X_{2i}^T \beta_2 + u_{2i},$$

$$Y_{1i} = 1(Y_{1i}^* > 0),$$

$$Y_{2i} = Y_{2i}^* \times 1(Y_{1i} = 1).$$

- The variables (Y_{1i}^*, Y_{2i}^*) are latent (unobserved).
- The observed variables are $(Y_{1i}, Y_{2i}, X_{1i}, X_{2i})$.
- Effectively, Y_{2i}^* is only when $Y_{1i} = 1$, equivalently when $Y_{1i}^* > 0$.
- Typically, the second equation is of interest, e.g. the coefficient β_2 .

Type-2 Tobit Models: Estimation

- The Type-2 Tobit model is a classical selection model introduced by Heckman (1976).
- It is conventional to assume that the error terms (u_{1i}, u_{2i}) are independent of $X_i = (X_{1i}, X_{2i})$.
- For details of Heckman's estimation procedure, see the attached pdf file.
- Heckman's estimation is one of the parametric approaches, as he imposes the following parametric distributional assumptions on the joint distribution of the errors:

$$\begin{bmatrix} u_{1i} \\ u_{2i} \end{bmatrix} \sim \text{Normal} \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \sigma_{12} \\ \sigma_{21} & \sigma_2^2 \end{bmatrix} \right)$$

Semiparametric Type-2 Tobit Models

- Here we do not impose parametric distributional assumptions on the joint distribution of the errors.
- Assume that (u_{1i}, u_{2i}) are independent of $X_i = (X_{1i}, X_{2i})$.
- Then, we obtain

$$\begin{aligned}\mathbb{E}(Y_{2i} \mid X_i, Y_{1i} = 1) &= X_{2i}^T \beta_2 + \mathbb{E}(u_{2i} \mid X_i, Y_{1i} = 1) \\ &\equiv X_{2i}^T \beta_2 + g(X_{1i}^T \beta_1),\end{aligned}$$

where

$$g(z) = \mathbb{E}(u_{2i} \mid u_{1i} > -z) = 1 - F_{u_2|u_1}(-z),$$

and $F_{u_2|u_1}(\cdot)$ is the conditional CDF of u_{2i} given u_{1i} .

- The functional form of $g(\cdot)$ is unknown.

- The simple regression of Y_{2i} on X_{2i} using the available data yields

$$Y_{2i} = X_{2i}^T \beta_2 + g(X_{1i}^T \beta_1) + \epsilon_{2i},$$
$$\mathbb{E}(\epsilon_{2i} \mid X_i, Y_{1i} = 1) = 0,$$

which is a partially linear single index model.

- Here we review the following estimation methods:
 - Powell (1987),
 - Ichimura and Lee (1991),
 - Gallant and Nychka (1987),
 - Heckman (1990)¹.

¹He proposes an estimation of intercept.

- Powell (1987) proposes a two-step estimation procedure.
- **Infeasible Estimation:** Define $Z_i = X_{1i}^T \beta_1$. If Z_i were observed, the regression is

$$Y_{2i} = X_{2i}^T \beta_2 + g(Z_i) + \epsilon_{2i},$$

which is a partially linear model.

- This can be estimated using Robinson's approach.
- Note that the intercept is absorbed by $g(\cdot)$, and that it must be excluded from X_{2i} ².

²Recall the identification conditions in semiparametric partially linear models.

Powell (1987): Feasible Two-Step Estimation

- In practice, Z_i is not observed.
- We implement the following two-step approach.
- **1st Step:** Estimate β_1 by a semiparametric binary choice estimator, or by Powell's (1984) CLAD estimator ³.
- **2nd Step:** Let $\hat{\beta}_1$ denote the estimator of β_1 .
- Replace Z_i with $\hat{Z}_i = X_{1i}^T \hat{\beta}_1$: $Y_{2i} = X_{2i}^T \beta_2 + g(\hat{Z}_i) + \epsilon_{2i}$.
- Estimate β_2 and $g(\cdot)$ by Robinson's estimator.
- Note that $\hat{Z}_i = X_{1i}^T \hat{\beta}_1$ is a generated regressor, and that the asymptotic distribution will differ from the result presented in Chapter 7.

³CLAD 推定量を使うのは、後ほど触れる Type-3 Tobit の 2 段階推定の方が適切なのでは？

Ichimura and Lee (1991)

- Ichimura and Lee (1991) propose a joint estimator for $\theta = (\beta_1^T, \beta_2^T)^T$ based on the nonlinear regression:

$$Y_{2i} = X_{2i} + g(X_{1i}\beta_1) + \epsilon_{2i}$$

for observations i such that Y_{2i} is observed.

- Their objective function is given by

$$Q_n(\theta) = \frac{1}{n} \sum_{i=1}^n 1(X_i \in \mathcal{X}) [Y_i - X_{2i}^T \beta_2 - \hat{g}(X_{1i}^T \beta_1)]^2,$$

where

$$\hat{g}(X_{1i}^T \beta_1) = \frac{\sum_{j \neq i} (Y_{2j} - X_{2j}^T \beta_2) K_h \left(\frac{(X_{1i} - X_{1j})^T \beta_1}{h} \right)}{\sum_{j \neq i} K_h \left(\frac{(X_{1i} - X_{1j})^T \beta_1}{h} \right)}$$

is a leave-one-out NW estimator of $\mathbb{E}(Y_{2i} - X_{2i}^T \beta_2 \mid X_{1i}^T \beta_1)$ ⁴.

⁴教科書は leave-one-out になっていない。

- Their estimator is an extension of a NLLS Heckit estimator, which is based on the equation

$$Y_{2i} = X_{2i}^T \beta_2 + \sigma_{12} \lambda(X_{1i}^T \beta_1) + \epsilon_{2i}.$$

- Such estimators ignore the first equation in the system.
- This is convenient as it simplifies the estimation.
- However, ignoring relevant information reduces efficiency.
- Ichimura and Lee derive the asymptotic normality:

$$\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{d} \text{Normal}(0, A^{-1} \Sigma A^{-1}).$$

- They also derive consistent estimators \hat{A} and $\hat{\Sigma}$.

Gallant and Nychka (1987): Semi-Nonparametric MLE

- Gallant and Nychka suggest approximating the joint density of the error terms $f(u_{1i}, u_{2i})$ by a series expansion:

$$\tilde{f}(u_{1i}, u_{2i}) = \exp \left[-\frac{u_{1i}^2}{2\sigma_1^2} - \frac{u_{2i}^2}{2\sigma_2^2} \right] \left[\sum_{j=0}^K \sum_{k=0}^K \gamma_{jk} u_{1i}^j u_{2i}^k \right].$$

- $\tilde{f}(u_{1i}, u_{2i})$ is a baseline distribution of a joint normal expression.
- This is accompanied by a power series expansion allowing for a general form of the CDF.
- Using the above joint density formula, we can compute $\tilde{f}(u_{1i}, u_{2i})$ and then construct a log-likelihood function.
- Maximizing the log-likelihood function, we obtain estimators of β_1 and other parameters.
- The estimator has consistency under $K \rightarrow \infty$, and $\frac{K}{n} \rightarrow 0$ as $n \rightarrow \infty$.

- Coppejans and Gallant (2002) show that one can use data-driven methods to select the power series expansion terms when estimating $f(u_{1i}, u_{2i})$.
- Newey (1999) proposes a two-step series-based estimation method.
 - First, estimate β_1 efficiently.
 - Second, select β_2 solving an efficient score equation.
- For details of nonparametric series methods, see Li and Racine (2007, Chapter 15).
- 教科書にタイポが多いのと、元論文にアクセスできないのとで、不正確な内容が含まれているかもしれないため、何かおかしい点があれば指摘していただきたいです。

Heckman (1990): Intercept Estimation

- In the semiparametric Type-2 Tobit model, we cannot identify an intercept term, which cannot be separated from $g(\cdot)$.
- One might be interested in the intercept, for example, when determining “wage gaps” between unionized and non-unionized workers, or when decomposing wage differentials between different socioeconomic groups, etc \dots .

- Letting μ denote the intercept, we write

$$Y_{2i}^* = \mu + \tilde{X}_{2i}^T \delta + u_{2i},$$

where $X_{2i} = (1, \tilde{X}_{2i}^T)^T$, and $\beta_2 = (\mu, \delta^T)^T$.

- Then, we obtain

$$\mathbb{E}(Y_{2i} \mid X_i, Y_{1i} = 1) = \mu + \tilde{X}_{2i}^T \delta + g(X_{1i}^T \beta_1).$$

- Recall the definition of $g(\cdot)$:

$$g(z) = \mathbb{E}(u_{2i} \mid u_{1i} > -z),$$

which leads to

$$\lim_{z \rightarrow \infty} g(z) = \mathbb{E}(u_{2i}) = 0, \text{ or}$$

$$\lim_{z \rightarrow \infty} \mathbb{E}(Y_{2i} - \tilde{X}_{2i}^T \delta \mid Y_{1i} = 1, X_{1i}^T \beta_1 > z) = \mu.$$

- Heckman (1990) suggests to use the observations such that $\mathbb{E}(u_{2i} \mid Y_{1i} = 1) = g(X_{1i}^T \beta_1)$, i.e., the observations such that $g(\cdot)$ satisfies $g(-\infty) = 0$.
- Thus, μ can be rewritten as

$$\mu = \mathbb{E}(Y_{2i} - \tilde{X}_{2i}^T \delta \mid Y_{1i} = 1, X_{1i}^T \beta_1 > \gamma_n),$$

where $\gamma \rightarrow \infty$ is a bandwidth.

- This can be estimated by

$$\tilde{\mu} = \frac{\sum_{i=1}^n (Y_{2i} - \tilde{X}_{2i}^T \hat{\delta}) Y_{1i} 1(X_{1i}^T \hat{\beta}_1 > \gamma_n)}{\sum_{i=1}^n Y_{1i} 1(X_{1i}^T \hat{\beta}_1 > \gamma_n)}.$$

Extension: Andrews and Schafgans (1998)

- Since the indicator function $1(\cdot)$ is not differentiable, it is difficult to examine the asymptotic distribution of $\tilde{\mu}$.
- Andrews and Schafgans (1998) suggest to replace the indicator function with a smoothed non-decreasing CDF $s(\cdot)$, which satisfies

$$s(z) = 0 \text{ for } z \leq 0,$$

$$s(z) = 1 \text{ for } z \geq b \text{ for some } 0 < b < \infty, \text{ and}$$

$$s(\cdot) \text{ has third bounded derivatives.}$$

- They estimate μ by

$$\hat{\mu} = \frac{\sum_{i=1}^n (Y_{2i} - \tilde{X}_{2i}\hat{\delta})Y_{1i}s(X_{1i}^T\hat{\beta}_1 > \gamma_n)}{\sum_{i=1}^n Y_{1i}s(X_{1i}^T\hat{\beta}_1 > \gamma_n)}.$$

- They find that the asymptotic distribution has a non-standard rate, depending on the distribution of $X_{1i}^T\beta_1$.

Semiparametric Type-3 Tobit Models

Type-3 Tobit Models

- The Type-3 Tobit model is the four equation system:

$$Y_{1i}^* = X_{1i}^T \beta_1 + u_{1i},$$

$$Y_{2i}^* = X_{2i}^T \beta_2 + u_{2i},$$

$$Y_{1i} = \max\{Y_{1i}^*, 0\},$$

$$Y_{2i} = Y_{2i}^* \times 1(Y_{1i} > 0).$$

- The difference from the Type-2 is that Y_{1i} is censored than binary.
- We observe Y_{2i}^* only when there is no censoring on Y_{1i}^* .
- Typically, the second equation is of interest, e.g. the coefficient β_2 .

Type-3 Tobit Models: Parametric Approaches

- Parametric approaches to estimate the Type-3 Tobit models impose parametric distributional assumptions on the joint distribution of the errors.
- Vella (1992, 1998)
- Wooldridge (1994)
- See the attached file for details.

Semiparametric Type-3 Tobit Models

- Here we do not assume that the joint distribution of (u_{1i}, u_{2i}) is known.
- Instead, we have $\mathbb{E}(u_{2i} \mid u_{1i}) = g(u_{1i})$, where $g(\cdot)$ is an unknown function.
- In this case, it is easy to see that $\mathbb{E}(Y_{2i} \mid X_i, u_{1i}) = X_{2i}^T \beta_2 + g(u_{1i})$.
- Thus, we obtain

$$Y_{2i} = X_{2i}^T \beta_2 + g(u_{1i}) + v_{2i},$$

$$\mathbb{E}(v_{2i} \mid u_{1i}, Y_{1i} > 0) = 0.$$

Semiparametric Type-3 Tobit Models: Estimation

- If u_{1i} were known, this would be a partially linear model.
- In practice, u_{1i} is unknown.
- We can estimate u_{1i} by Tobit, CLAD, etc \dots .
- Here we review the following estimation methods:
 - Li and Wooldridge (2002),
 - Chen (1997),
 - Honore, Kyriazidou and Udry (1997),
 - Lee (1994),
 - the semiparametric Type-2 Tobit estimator based on Ichimura (1993); and Ichimura and Lee (1991).

- Li and Wooldridge suggest a multistep method to estimate β_2 .
- **1st Step:** Estimate β_1 , for example, by Powell's (1984) CLAD estimator⁵. We assume that for the 1st step there is a \sqrt{n} -consistent, and asymptotically normally distributed, estimator for β_1 .
- **2nd Step:** Replacing u_{1i} with \hat{u}_{1i} , we implement Robinson's approach to estimate β_2 .
- They establish the \sqrt{n} -normality of their estimator $\hat{\beta}_2$:

$$\sqrt{n}(\hat{\beta}_2 - \beta_2) \xrightarrow{d} \text{Normal}(0, \Sigma).$$

- $\text{Avar}(\hat{\beta}_2)$ can be consistently estimated.

⁵Powell's CLAD (censored least absolute deviation) estimator will be reviewed below in Chapter 11.

- Li and Wooldridge's (2002) estimator does not achieve the semiparametric efficiency bound. Efficient estimation can usually be achieved by a one-step procedure, where β_1 and β_2 are estimated simultaneously as in Ai (1997).
- Powell's CLAD estimator is a parametric approach, i.e., the generated regressor is estimated from a parametric model. Ahn and Powell (1993) suggest to estimate β_1 in the 1st stage using a nonparametric regression model.

- Assume that (U_{1i}, u_{2i}) is independent of (X_{1i}, X_{2i}) .
- Under the above assumption, it holds that

$$\begin{aligned}\mathbb{E}(Y_{2i} \mid X_{1i}, X_{2i}, u_{1i} > 0, X_{1i}^T \beta_1 > 0, Y_{1i} > 0) \\ &= \mathbb{E}(Y_{2i} \mid u_{1i} > 0, X_i) \\ &= X_{2i}^T \beta_2 + \alpha_0,\end{aligned}$$

where α_0 is a constant. Note that α_0 is not the intercept of the original model.

- **1st Step:** Estimate β_1 consistently by Honore and Powell (1984), or by Powell's CLAD. Let $\hat{\beta}_1$ denote the consistent estimator of β_1 .
- **2nd Step:** Run the following least squares:

$$\min_{\beta_2, \alpha} \frac{1}{n} \sum_{i=1}^n 1\{Y_{1i} - X_{1i}^T \hat{\beta}_1 > 0, X_{1i}^T \hat{\beta}_1 > 0\} (Y_{2i} - X_{2i}^T \beta_2 - \alpha)^2.$$

- A problem arising with Chen's (1997) estimator is that it may trim out too many observations, which leads to inefficient estimation.
- Chen (1997) suggests an alternative estimator that trims far fewer data points in finite-sample applications.

Honore, Kyriazidou and Udry (1997)

- Honore, Kyriazidou and Udry (1997) suggest to relax the normality assumption as it can be seen in Heckman (1979).
- Instead, they assume that the distribution of the error terms (u_{1i}, u_{2i}) given regressors X_i is symmetric, with arbitrary heteroscedasticity permitted.
- In this case, conditional on the sample selection, the conditional distribution is no longer symmetric.
- Their basic idea is that u_{2i} is symmetrically distributed around 0 if one estimate β_2 using observations for which $-X_{1i}^T\beta_1 < u_{1i} < X_{1i}^T\beta_1$ (i.e., $0 < Y_{1i} < 2X_{1i}^T\beta_1$).

- Honore, Kyriazidou and Udry (1997) suggest the following estimation method.
- **1st Step:** Estimate β_1 consistently, for example, by Powell's CLAD. Let $\hat{\beta}_1$ denote the consistent estimator of β_1 .
- **2nd Step:** Run the following least absolute deviations:

$$\min_{\beta_2} \frac{1}{n} \sum_{i=1}^n 1\{0 < Y_{1i} < 2X_{1i}^T \hat{\beta}_1\} | Y_{2i} - X_{2i}^T \beta_2 | .$$

- They establish the \sqrt{n} -normality of their estimator.



Estimation Based on Ichimura (1993); Ichimura and Lee (1991)

Christofides, Li, Liu and Min (2003): Comparison of the Estimators

Tests for Selection Bias

Tests for Selection Bias

Nonparametric Sample Selection Model

References

- Textbooks and Lecture Notes:
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