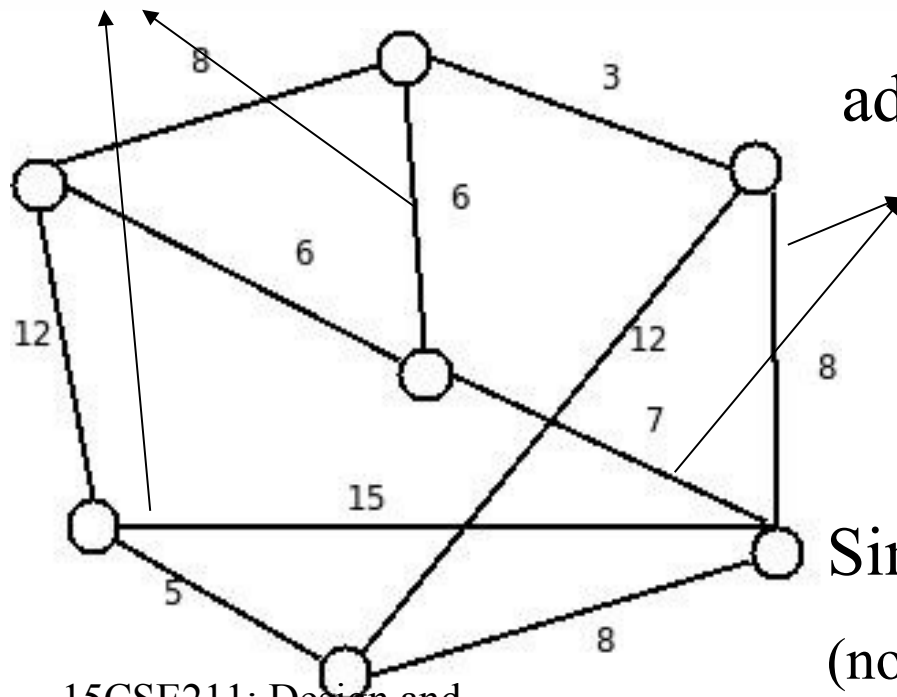


# Graph Algorithms

# Graph Definitions

- A graph  $G = (V, E)$  is a set of vertices  $V$ , and a collection of edges  $E$  which is a subset of  $V \times V$ 
  - Directed, undirected or mixed

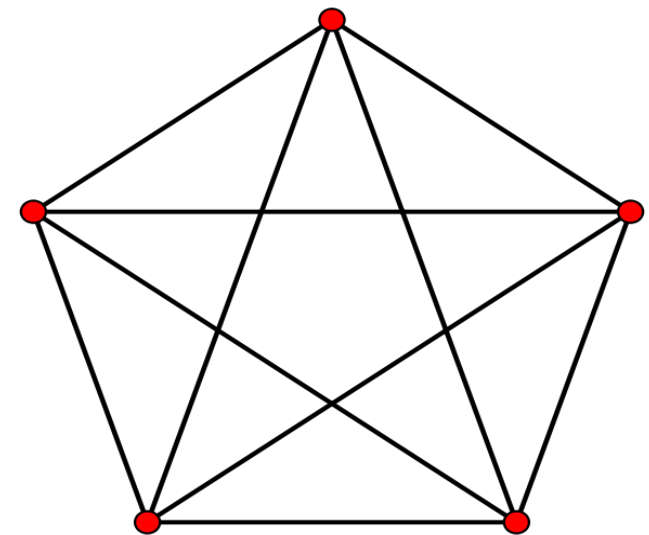
independent



Simple Graph

(no loops, parallel edges)

Complete Graph



# Degree

- Number of edges incident at  $v$  ( $d(v)$ )
  - In-degree – number of incoming edges to vertex  $v$
  - Out-degree – number of outgoing edges
- An *isolated* vertex has degree 0
- Min degree of  $G \rightarrow \delta(G) = \min \{d(v) \mid v \in V\}$
- Total degree of  $G$  is  $2m$  (number of edges)
- To remember
  - Number of vertices of odd degree is always even in a graph

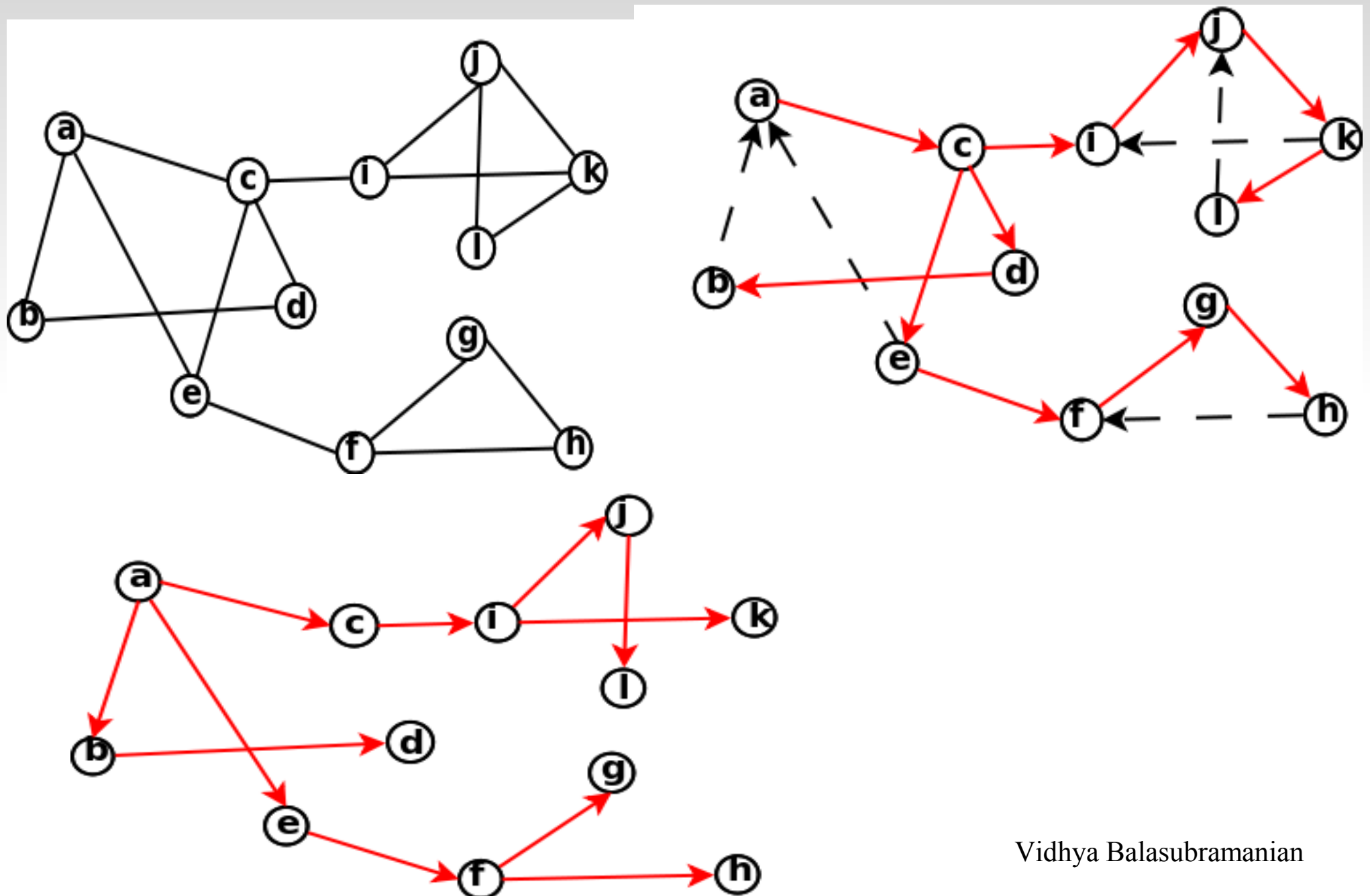
# Graph Representations

- Adjacency list
  - Each vertex has incidence container
    - List of vertices incident on  $v$
  - Edge list
  - Useful in path algorithms or if graph is sparse
- Adjacency matrix
  - Edge list
  - Matrix  $A$  where  $A[i,j]$  represents edge
  - Edge retrieval quick
- Path – list of vertices connective  $u$  and  $v$

# Graph Traversal

- Depth first search
  - Recursive –  $O(m+n)$  algorithm
  - Start with some node  $v$ 
    - Of all neighbors of  $v$ , goto next  $w$  which is unexplored do DFS( $w$ )
    - If  $w$  explored, then mark edge as back edge
- Breadth first search
  - Discovery in levels, marks new nodes in levels
  - $O(m+n)$
- Applications
  - Checking connectivity, cycle detection, finding biconnected components

# Example



# Minimum Spanning Tree

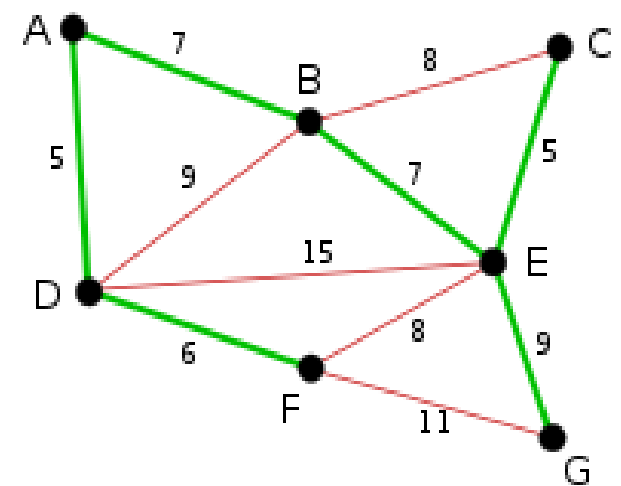
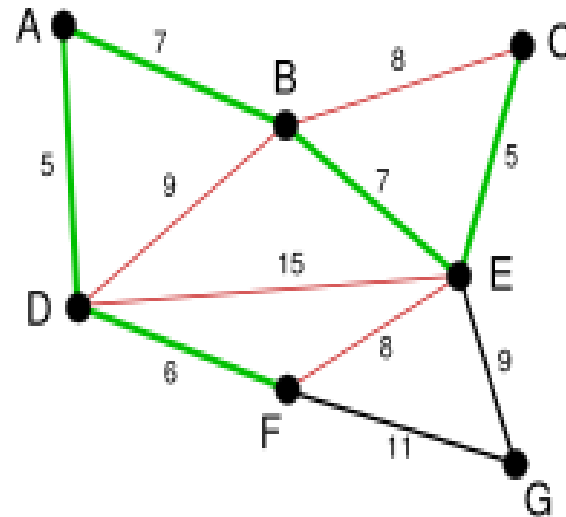
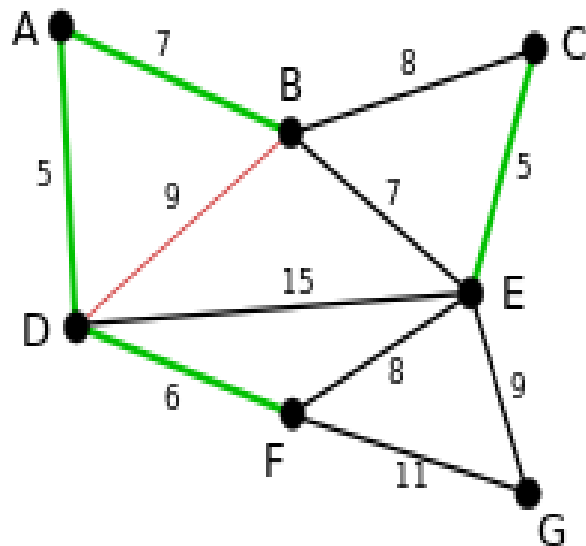
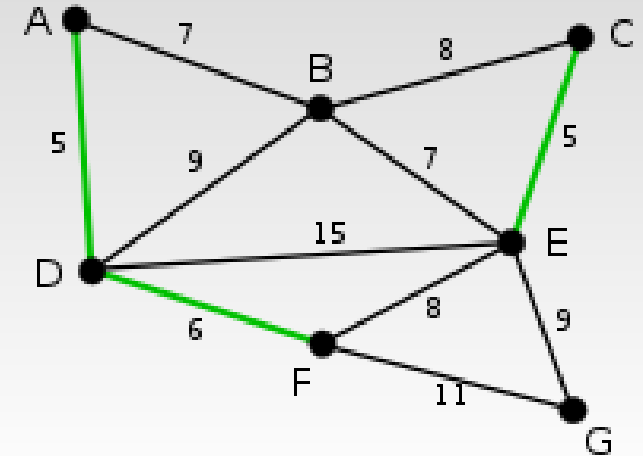
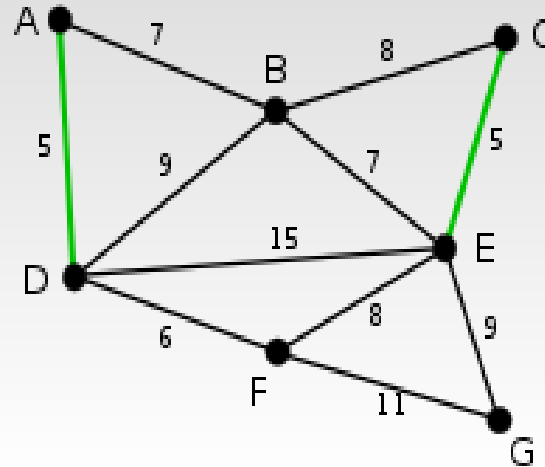
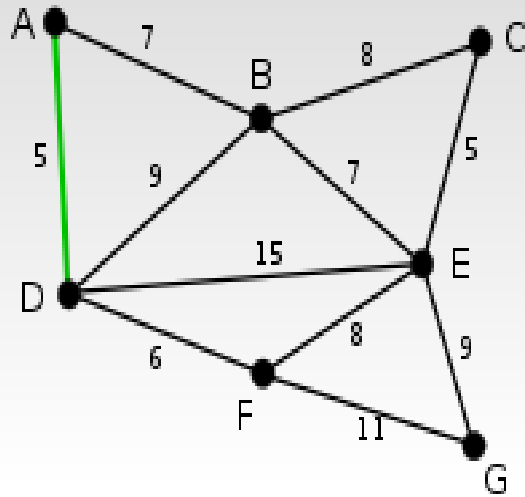
- Given a weighted undirected graph  $G$ , goal is to find a  $T$  such that
  - $T$  contains all vertices in  $G$
  - Sum of weights of edges in  $T$  is minimum
- Different algorithms
  - Prim's
  - Kruskal
  - Boruvka's
- All use some greedy strategy

# Kruskal's Algorithm

- Let every node in  $G$  be a cluster  $C(v)$
- Initialize a priority queue  $Q$  with all edges in  $G$  using weights as keys
- Take the minimum weight edge in  $Q$  and if  $C(u) \neq C(v)$ 
  - add the edge to MST  $T$
  - Merge the clusters  $C(u)$  and  $C(v)$
- Repeat till there are no more clusters to merge



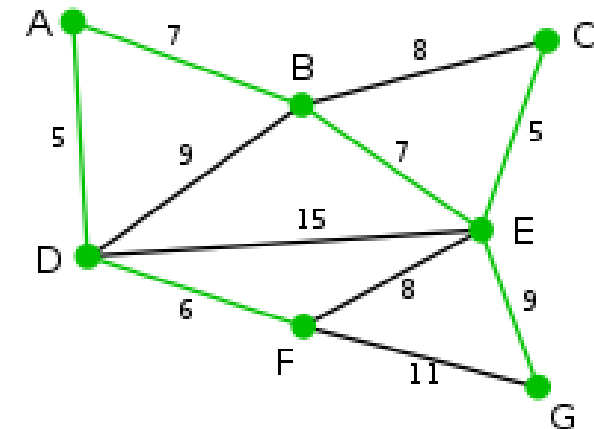
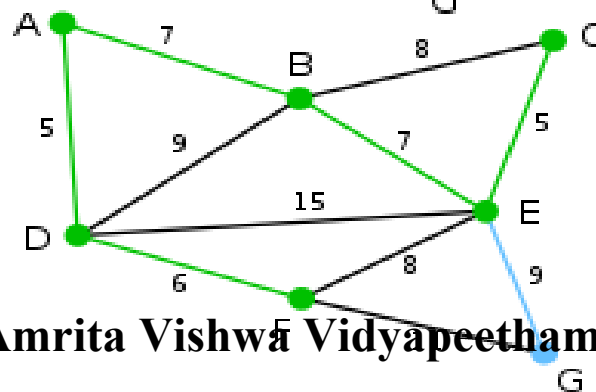
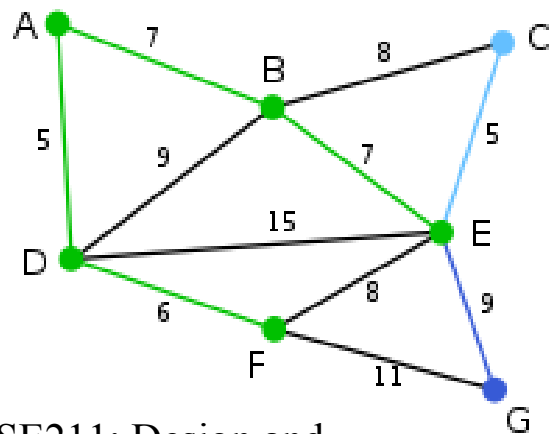
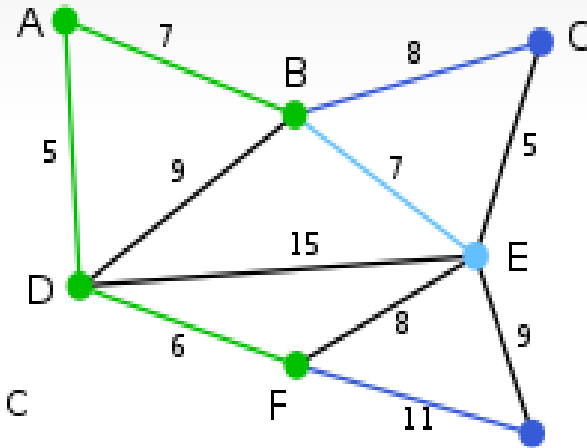
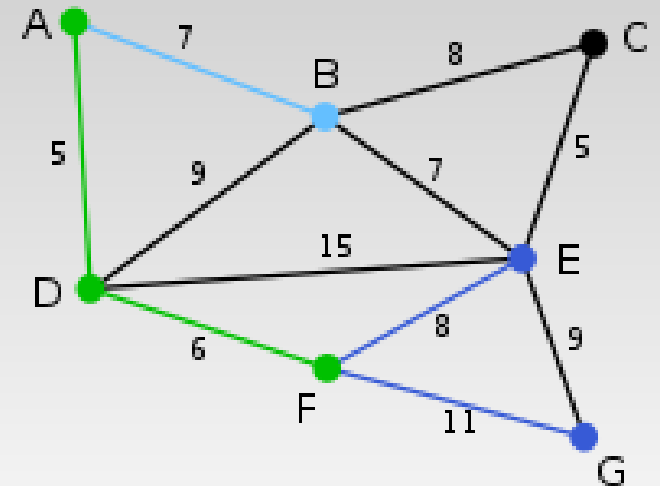
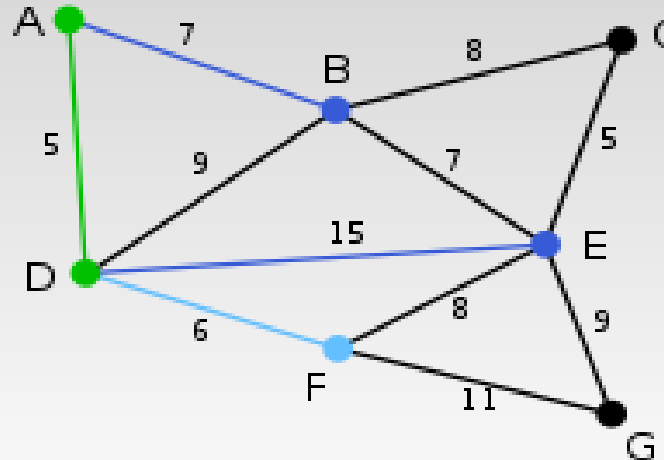
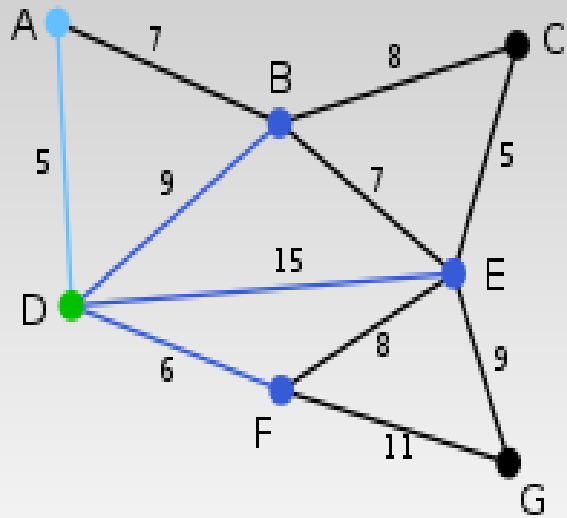
# Kruskal's Algorithm: Example



# Prim's Algorithm

- Similar to Dijkstra
- Pick any vertex  $v$  of  $G$
- Initialize for all  $u$  not  $v$ ,  $d[u]$  to infinity and  $d[v]=0$
- Remove from  $Q$   $u$  with minimum  $d[u]$ 
  - Add  $u$  and edge  $(u,v)$  to  $T$
  - For all neighbors  $z$  of  $u$ , do relaxation by finding  $d[z] = w(u,z)$ , and update  $Q$

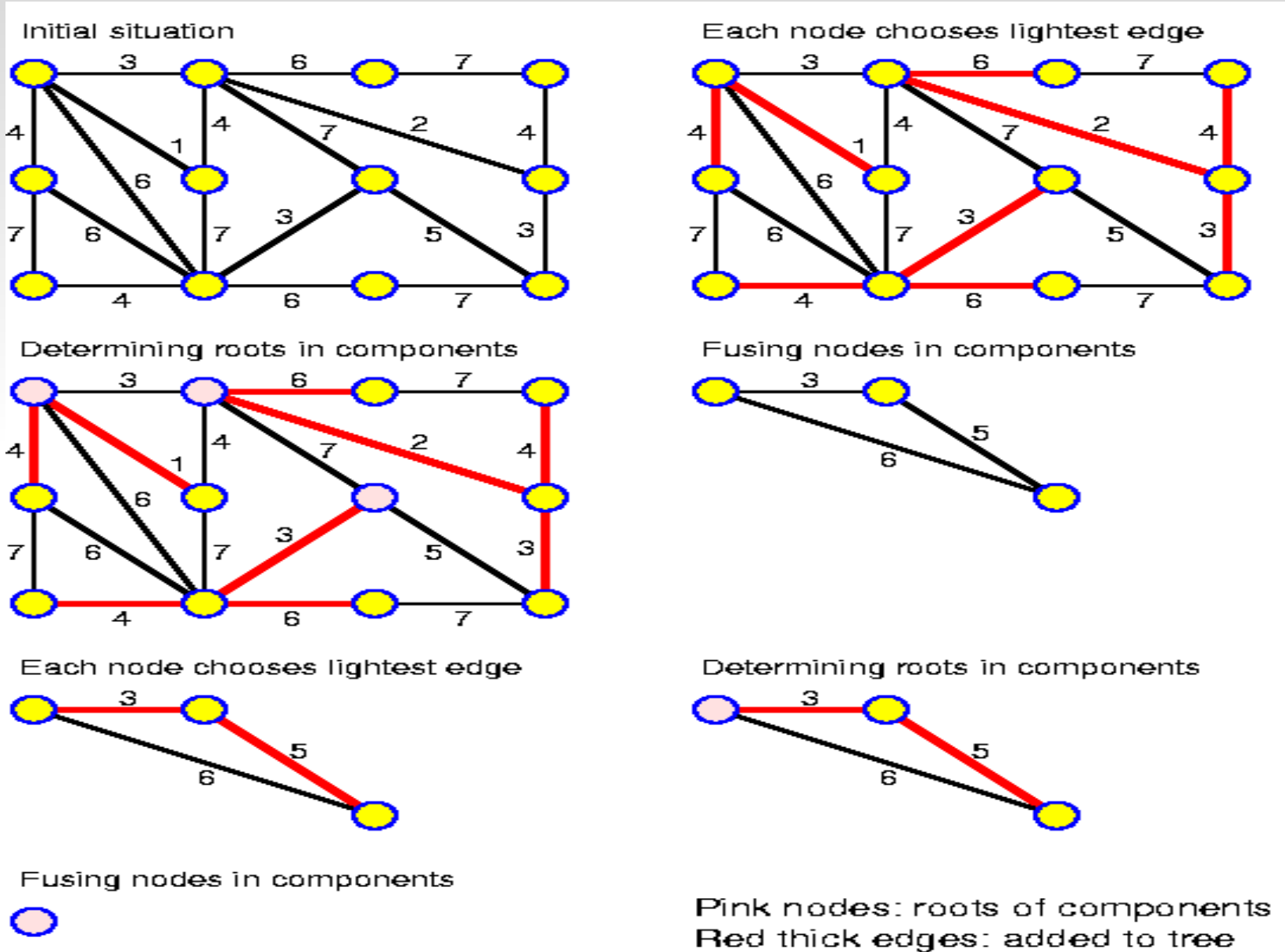
# Example



# Baruvka's Algorithm

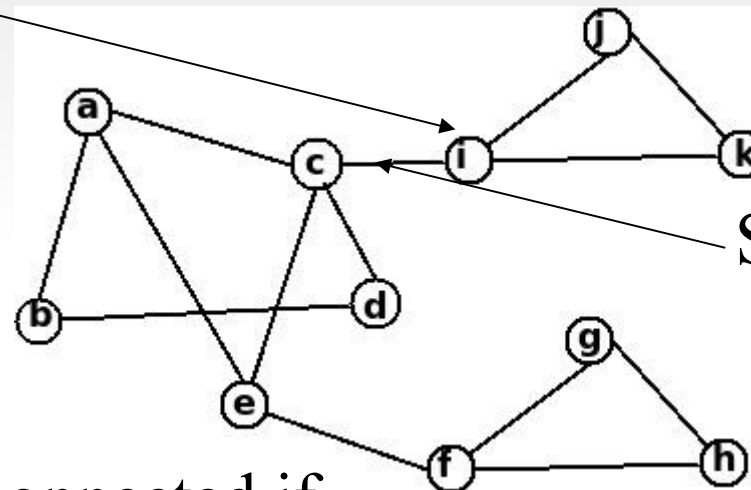
- Here greedy strategy explicitly optimizes certain priorities of vertices
- Initially every vertex is a component  $C_i$
- Find the smallest weight edge  $(v,u)$  in  $E$  and add to  $C_i$  such that
  - $v$  is in  $C_i$ ,  $u$  is not in  $C_i$
  - Add  $e$  to  $T$

# Example



# Biconnected Components

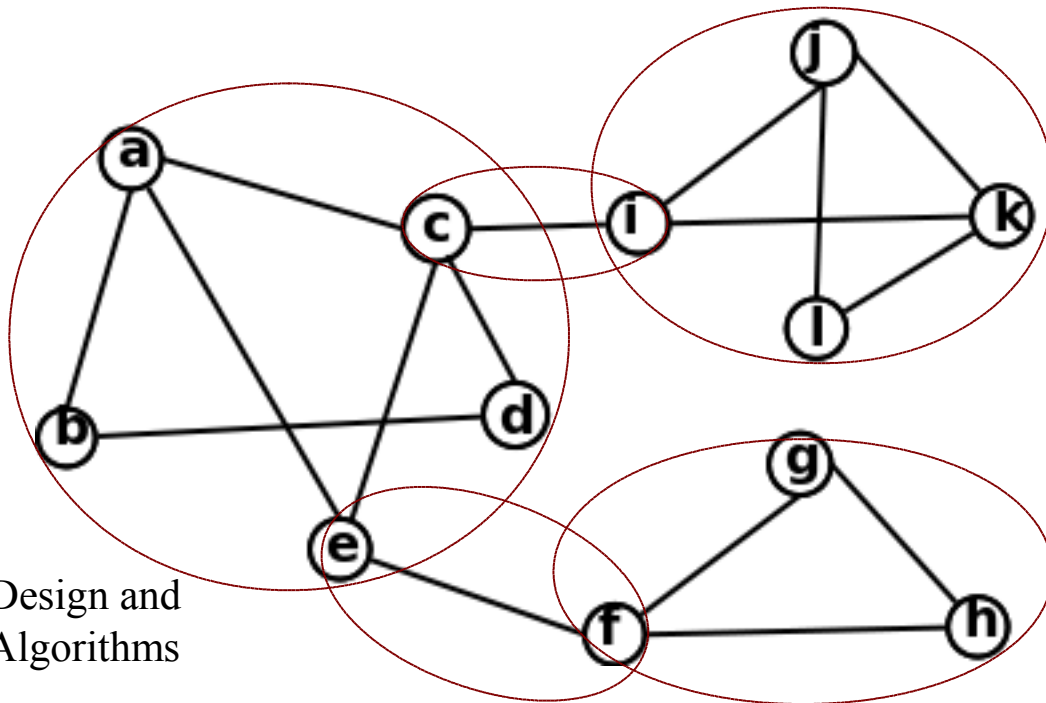
- Separation or cut edge - Edge whose removal disconnects a graph
- Separation vertex – vertex removal disconnects graph



- Graph/component biconnected if
  - There are no separation edge or vertices
  - For any two vertices  $u, v$ , there are 2 disjoint paths between them

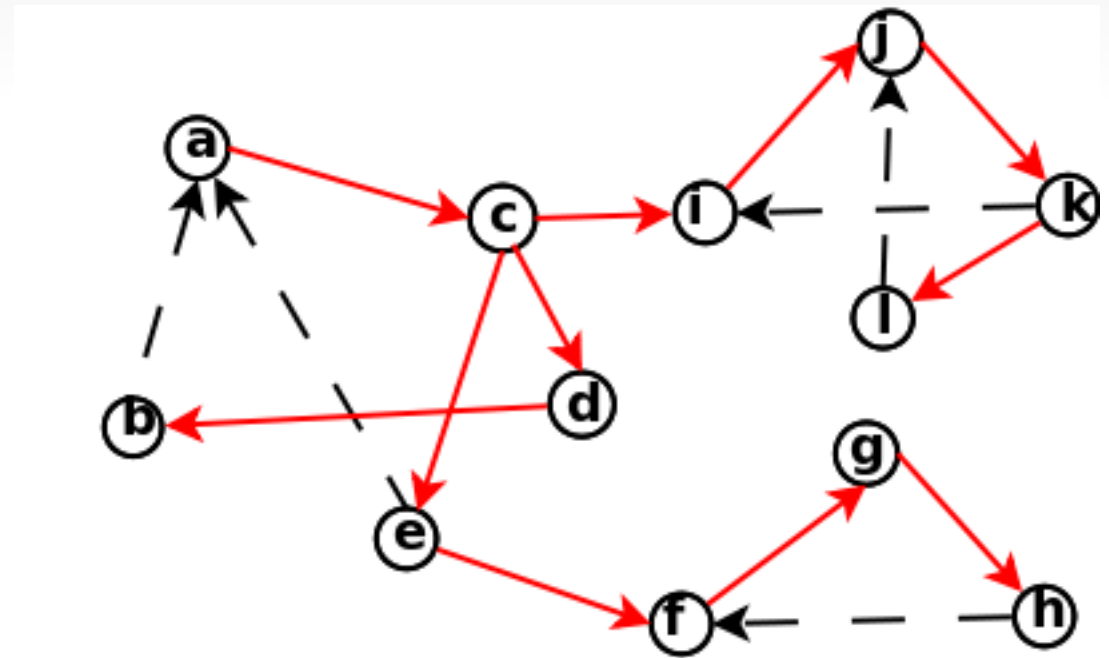
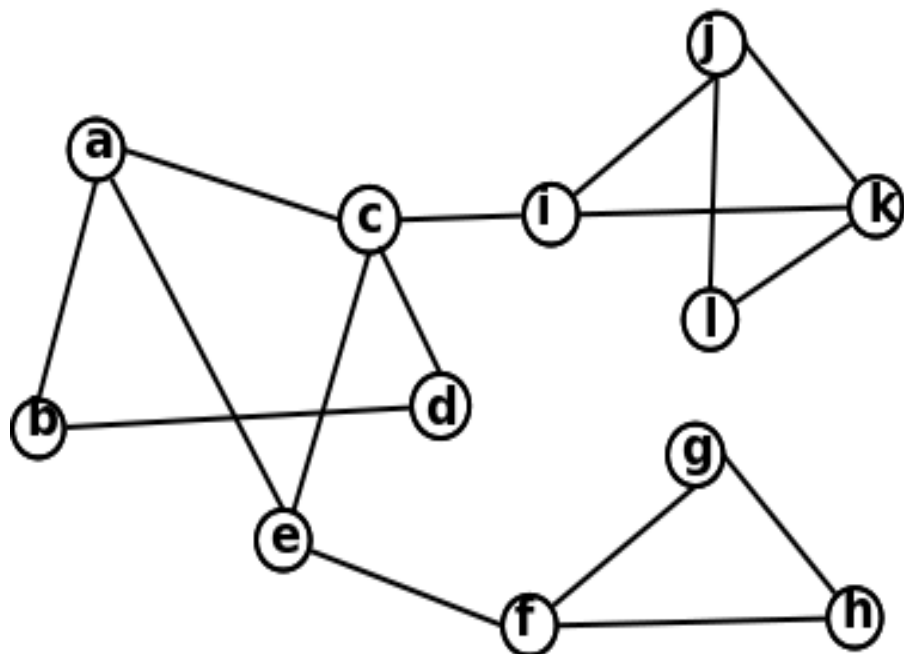
# Biconnected components

- Lemma : Let  $G$  be a biconnected graph. The following are equivalent
  - $G$  is biconnected
  - For any two vertices of  $G$ , there is a simple cycle containing them
  - $G$  does not have any separation vertices or separation edges



# Compute Biconnected Components via DFS

- To construct biconnected components of  $G$  we need to compute the equivalence classes of the link relation among  $G$ 's edges
- Steps
  1. Do a DFS traversal of  $G$





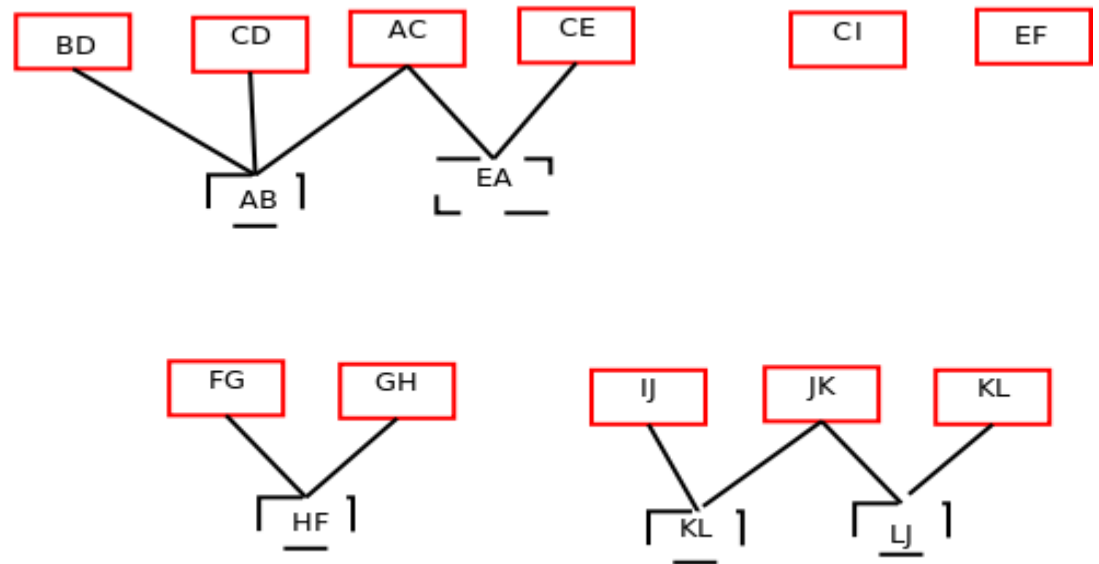
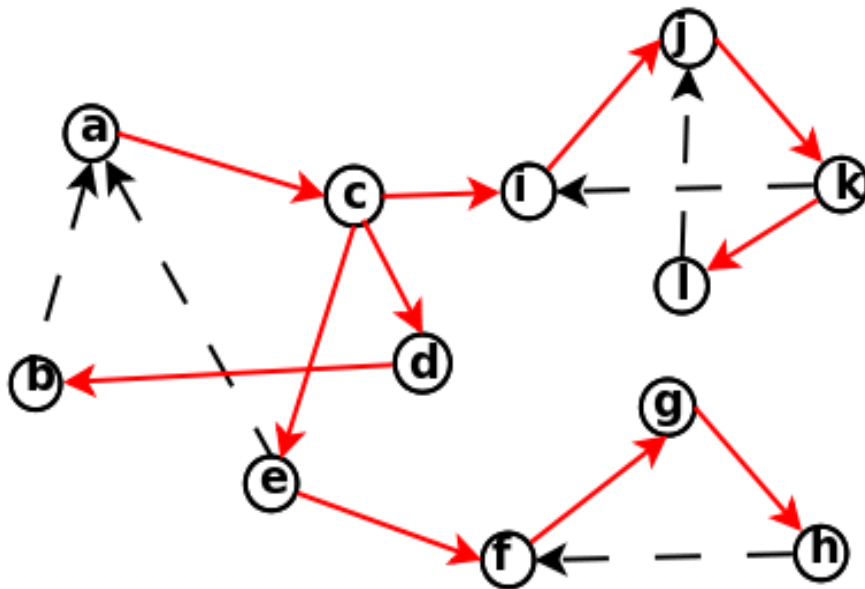
# Auxiliary Graph

- Construct an auxiliary graph  $B$  as follows

The vertices of  $B$  are edges of  $G$

For every back edge  $e$  of  $G$ , let  $f_1, \dots, f_k$  be the discovery edges of  $G$  that form a cycle with  $e$

Graph B contains edges  $(e, f_1), (e, f_2), \dots, (e, f_k)$

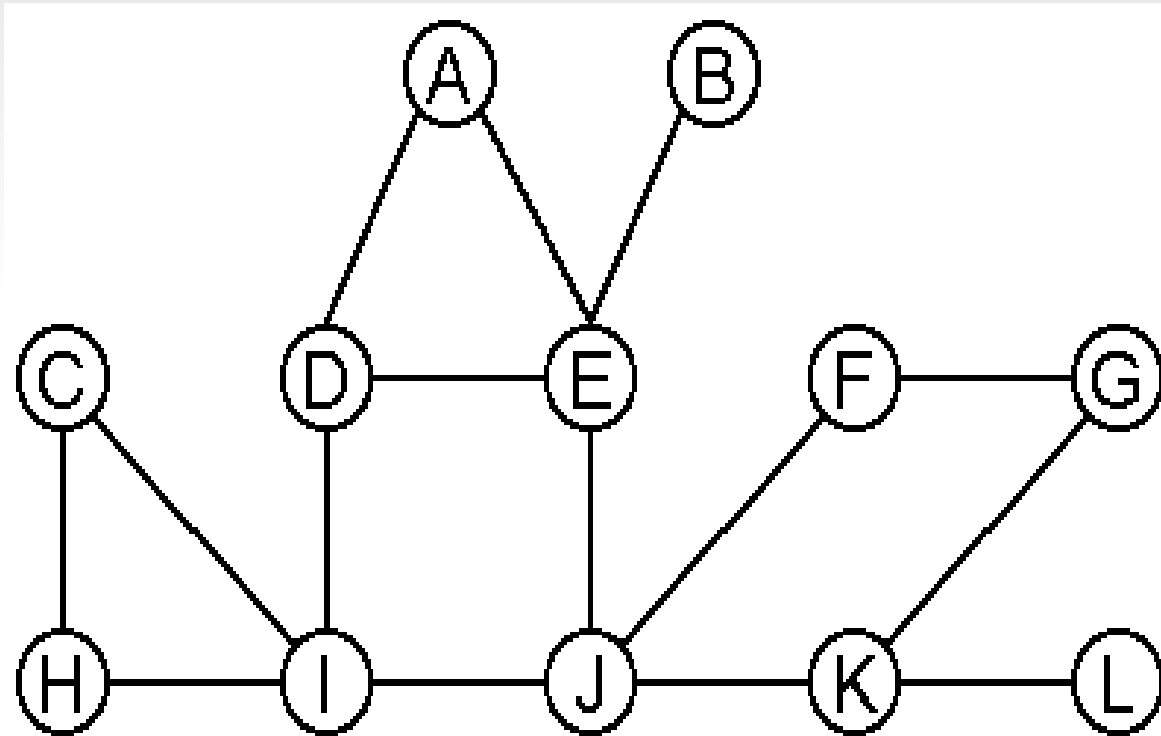


# Finding the components

- The connected components of the auxiliary graph  $B$  correspond to link components of the graph  $G$  that induced  $B$ 
  - Compute the connected components of  $B$  for example by performing a DFS traversal of the auxiliary graph  $B$
  - For each connected component of  $B$ , output the vertices of  $B$  as a link component of  $G$ 
    - Vertices of  $B$  are edges of  $G$
- Complexity
  - Finding separation edges and vertices –  $O(m+n)$
  - Finding auxiliary graph  $O(mn)$ 
    - Reduce this by finding a spanning forest of  $B$

# Exercise

- Find all the biconnected components of this graph using DFS method



# Strongly Connected Components

Two nodes  $a$  and  $b$  in a directed graph are connected if there are paths between  $a$  to  $b$  and vice versa

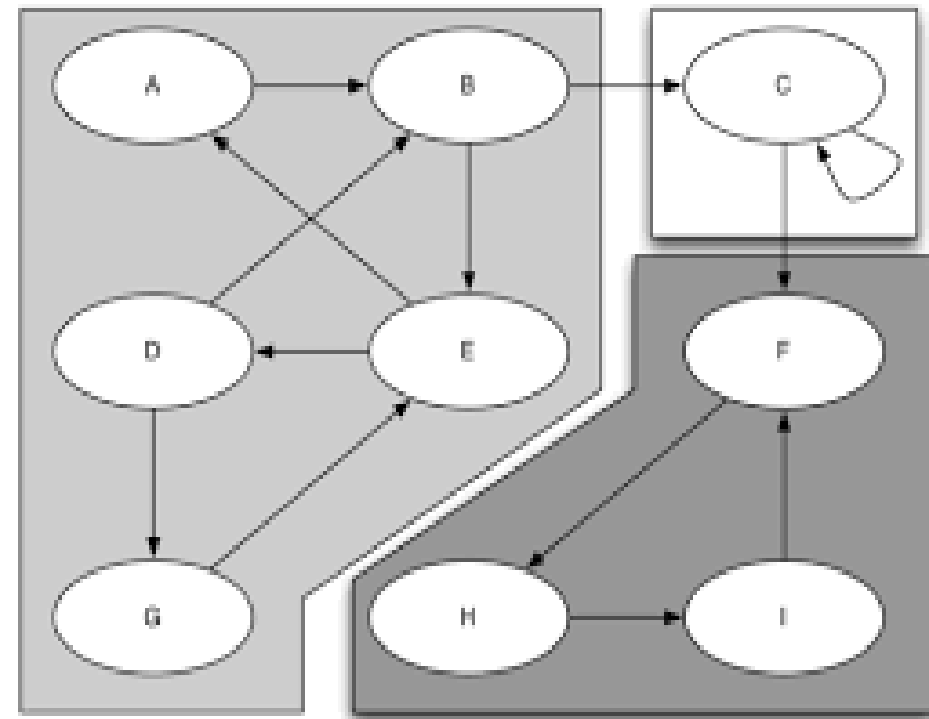
- A directed graph is strongly connected if there are directed paths between every pair of nodes
- Directed graph is DAG of its strongly connected components

Use DFS to find the components

Apply DFS on graph and then on transpose graph  $G'$

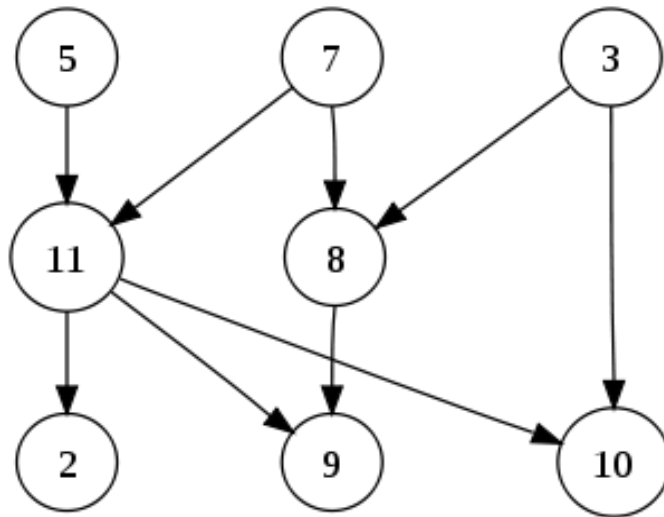
$G'$  has same set of vertices with all of the edges reversed compared to the orientation of the corresponding edges in  $G$

15CSE211: Design and  
Analysis of Algorithms



# Digraphs

- A directed graph or digraph is a pair  $G=(V,E)$  of
  - a set  $V$ , whose elements are called vertices or nodes
  - a set  $A$  of ordered pairs of vertices, called arcs, directed edges, or arrows
- A directed acyclic graph (DAG) is a directed graph with no directed cycles



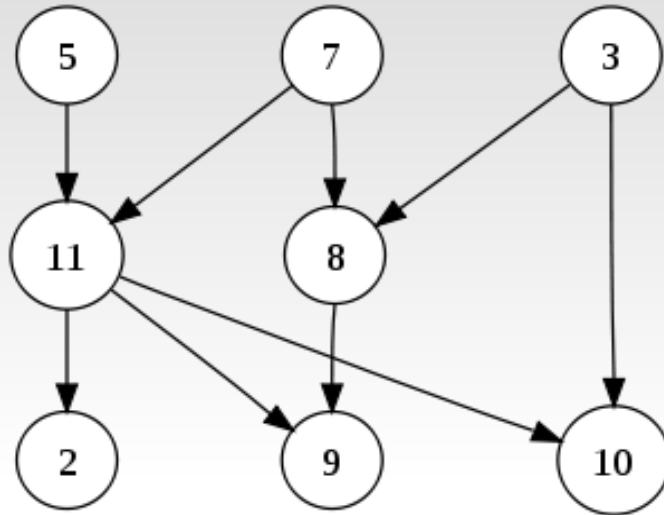
# Digraph Application

- Used to model several kinds of structures in maths or science
- Scheduling
  - Edge (a, b) indicates task a must be completed before b
- Topological Ordering
- Data Processing Networks
  - data enters a processing element through its incoming edges and leaves the element through its outgoing edges
  - Bayesian Networks
  - Compilers
  - Circuit Design

# Topological Ordering

- A DAG is a digraph that has no directed cycles and a topological ordering of a digraph is a numbering  $v_1, \dots, v_n$  of the vertices such that
  - for every edge  $(v_i, v_j)$ , we have  $i < j$
- Example
  - In task scheduling, a topological ordering is a task sequence that satisfies the precedence constraints
- Theorem
  - A digraph admits a topological ordering if and only if it is a DAG

# Example



- For the above graph these are some valid topological ordering
  - 5, 7, 3, 11, 8, 2, 9, 10
  - 3, 5, 7, 8, 11, 10, 9, 2



# Topological Sorting Algorithm

- Let  $S$  be an empty stack
- For each vertex  $u$  of  $G$ , set  $\text{incounter}(u)$  as the  $\text{indegree}(u)$ 
  - If  $\text{incounter}(u) = 0$ , push it in the stack
- Set  $i$  as 1
- If  $S$  is empty it has a directed cycle
- Pop the  $i$ th vertex  $u_i$  from the stack and increment  $i$ 
  - For each neighbor  $v$  of  $u_i$ , decrement  $\text{incounter}(v)$  by 1
  - If  $\text{incounter}(v) = 0$ , push it in stack
  - Do this this while stack has elements in it

# Analysis

- Runs in  $O(n+m)$  time –  $n$  vertices and  $m$  edges
  - Initial computation of indegree  $O(n+m)$
- Uses  $O(n)$  auxiliary space (stack)
- If some vertices are not numbered then there is a cycle
  - Any vertex on a directed cycle will not be visited
  - A vertex visited only when incounter is 0
    - Implies all its previous predecessors were previously visited