

MATH 55: Discrete Mathematics

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Chapter 1

Combinatorics

1.1 Introduction

We begin our discussion of combinatorics by giving two basic rules that will govern how we count things.

Theorem 1.1: Rule of sum

If A_1, A_2, \dots, A_n are disjoint sets, then

$$\bigcup_{i=1}^n A_i = \sum_{i=1}^n |A_i|.$$

Theorem 1.2: Rule of product

If an action is composed of k steps such that there are x_i choices for step i , then the action can be performed in $x_1 x_2 \cdots x_k$ different ways.

We'll apply these rules (especially the rule of product) to two different types of problems. First, we can count the number of ways we can arrange a set of objects.

Theorem 1.3: Counting arrangements

The number of arrangements (or permutations) of n objects is given by $n!$.

Note: We define $0! = 1$ since there is, technically, one way to arrange an empty set of objects.

Proof. Constructing a permutation of n objects is an action that requires n different steps.

1. Step 1 is picking the first element in the permutation; there are n ways to do this.
2. Step 2 is picking the second element in the permutation; since we've already picked an element to be first, there are $n - 1$ ways to pick this element.
3. Step 3 is picking the third element; there are $n - 2$ ways to do this.
- \vdots
- n . Step n is picking the final element; all but one element has already been chosen, so there is only one way to pick this element.

By the rule of product, there are $n \cdot (n - 1) \cdot (n - 2) \cdots 1 = n!$ ways to permute the elements in S . \square

We can also count the number of subsets we can create using a set of objects, regardless of arrangement

order. This type of problem is so fundamental to combinatorics that it gets a special name and symbol, given below.

Definition: Combination

Consider a set S that has size n . The number of size- k subsets of S is called “ n choose k ” and is denoted by $\binom{n}{k}$. For $k < 0$ or $k > n$, we define $\binom{n}{k} = 0$.

Theorem 1.4: Counting subsets

For $0 \leq k \leq n$,

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}.$$

Proof. Let S be a set with size n . We will count, in two different ways, the number of size- k permutations of the elements in S .

(i) We first use the rule of product to directly compute the number of permutations:

$$n \cdot (n-1) \cdot (n-2) \cdots (n-k+1) = \frac{n!}{(n-k)!}.$$

(ii) There are $\binom{n}{k}$ ways to choose the k letters we’re permuting. For each of these choices, there are $k!$ ways to arrange them. So, there are

$$k! \cdot \binom{n}{k}$$

size- k permutations of the elements in S .

Both of the expressions we’ve found count the same thing, so they must be equal. That is,

$$k! \cdot \binom{n}{k} = \frac{n!}{(n-k)!} \implies \binom{n}{k} = \frac{n!}{k!(n-k)!},$$

as desired. \square

This is an example of a combinatorial proof—we can prove an equivalence between two expressions by showing that they count the same thing. This will be a useful (and enlightening!) technique when proving other statements.

1.2 Pascal’s Triangle

1.3 things to save for later

Chapter 2

Number Theory

2.1 Introduction

In this chapter we'll extend our discussion to the set of integers \mathbb{Z} . We don't know anything about primes, GCDs, or modular arithmetic yet—only the basic properties of integer arithmetic.

We begin by formalizing the idea of division and remainders, as we learned back in fourth grade. Remember that, when we divide two integers a and b , we're left with a unique quotient q and remainder r .

Theorem 2.1: Division Algorithm

For any integers a and $b > 0$, there exist unique integers q and r such that

$$a = bq + r, \quad 0 \leq r < b.$$

Oftentimes, we're only interested in the remainder that comes from this division. In this case, we write $r = a \bmod b$.

The division algorithm is a powerful tool in number theory! We can use it to define and prove a variety of important things, the first of these being the notion of divisibility.

Definition: Divisibility

We say that b divides a (or b is a divisor of a) if there exists an integer q such that $a = bq$. When b divides a , we write $b \mid a$.

One intuitive consequence of this theorem is that the “divisibility relation” is transitive.

Theorem 2.2: Transitive divisibility

If $c \mid b$ and $b \mid a$ then $c \mid a$.

We may use this to prove a much more general and useful theorem about integer combinations. (These are like linear combinations, but with strictly integer coefficients.)

Theorem 2.3: Integer combination theorem

If $d \mid a$ and $d \mid b$ then $d \mid ax + by$ for all $x, y \in \mathbb{Z}$.

With this groundwork laid, we can begin talking about GCDs and related topics.

2.2 Greatest Common Divisors

The greatest common divisor between two numbers a and b is the largest divisor that the numbers have in common. This GCD is represented by $\gcd(a, b)$ or, more compactly, (a, b) . (We define $(a, 0) = a$, and $(0, 0)$ is undefined.) If $(a, b) = 1$, then we say that a and b are relatively prime.

In this section are two significant theorems regarding the GCD. In preparation, we have another intuitive fact, which we state as a lemma.

Lemma 2.4

For positive integers d and a , if $d \mid a$, then $d \leq a$.

Proof. Suppose $d \mid a$. Then $a = dq$ for some integer $q \geq 1$, meaning

$$\begin{aligned} a - d &= dq - d \\ &= d(q - 1) \end{aligned}$$

Since $q - 1 \geq 0$, $a - d \geq 0$ and $d \leq a$. \square

From this, we get our first wildly unintuitive theorem.

Theorem 2.5: Bezout's theorem

For integers a, b , $\gcd(a, b)$ is an integer combination of a and b . That is, there exist integers x and y such that $ax + by = \gcd(a, b)$.

Note: This integer combination is not unique.

Proof. Let $g = \gcd(a, b)$ and let $l = ax_0 + by_0$ be the smallest integer of the form $ax + by$. We will prove that $g = l$ by showing that (i) $g \leq l$ and (ii) $l \leq g$.

(i) By definition, $g \mid a$ and $g \mid b$. So by the integer combination theorem, $g \mid ax + by$ for all x, y , meaning $g \mid l$. Therefore, $g \leq l$.

(ii) We will show that l is a common divisor of a and b . Suppose, to the contrary, that $l \nmid a$; by the division algorithm,

$$a = lq + r, \quad 0 < r < l.$$

We may rewrite this equation as

$$\begin{aligned} r &= a - lq \\ &= a - (ax_0 + by_0)q \\ &= a(1 - x_0q) + b(-y_0q) \end{aligned}$$

So r is an integer combination of a and b . But, since $0 < r < l$, this contradicts the definition of l as the smallest positive integer combination of a and b . Therefore l is a common divisor of a and b , and since g is the greatest of these common divisors, $l \leq g$. \square

This result is important in its own right, but it also has a very useful corollary.

Corollary 2.6

a and b are relatively prime if and only if there exist $x, y \in \mathbb{Z}$ such that $ax + by = 1$.

Proof. (\Rightarrow) Suppose a and b are relatively prime. It immediately follows from Bezout's theorem that there exist $x, y \in \mathbb{Z}$ such that $ax + by = 1$.

(\Leftarrow) Conversely, suppose there exist $x, y \in \mathbb{Z}$ such that $ax + by = 1$. Let d be a common divisor of a and b ; by the integer combination theorem, $d \mid ax + by$, meaning $d \mid 1$. So the only common divisors of a and b are ± 1 , meaning $\gcd(a, b) = 1$ and a and b are relatively prime. \square

Bezout's theorem is one of the two “pillars” of this section on GCDs. The other is Euclid's theorem, stated below.

Theorem 2.7: Euclid's theorem

For $a, b, x \in \mathbb{Z}$, $\gcd(a, b) = \gcd(b, a - bx)$.

Arguably the most useful special case of this theorem applies the division algorithm to quickly compute GCDs.

Corollary 2.8: Euclidean algorithm

$\gcd(a, b)$ can be found by repeatedly computing $\gcd(b, a \bmod b)$.

Euclid's algorithm is very fast. Its worst-case runtime is when it acts on two consecutive Fibonacci numbers (in which case the “quotient” is always zero), and even then it will (by Lamé's theorem) only take at most $5k$ steps, where k is the number of digits in $b \leq a$.

Not only does Euclid's algorithm find (a, b) , but it can also help us determine the coefficients of the integer combination that gives (a, b) . There are two methods of doing this, both of which are demonstrated below.

Example: Bottom-up method

Suppose we want to find integers x and y that satisfy $(847, 203) = 847x + 203y$. First, we compute the GCD using Euclid's algorithm:

$$(847, 203) = (203, 35) = (35, 28) = (28, 7) = (7, 0) = 7$$

Now, we'll back-trace the above computation to write each $a \bmod b$ in the form $a - bq$:

$$\begin{aligned} 7 &= 35 - 28 \\ &= 35 - (203 - 5 \cdot 35) \\ &= 6 \cdot 35 - 1 \cdot 203 \\ &= 6 \cdot (847 - 4 \cdot 203) - 1 \cdot 203 \\ &= 6 \cdot 847 - 35 \cdot 203 \end{aligned}$$

So the desired integers are $x = 6$ and $y = -35$.

Example: Top-down method

Suppose we want to find integers x and y that satisfy $(847, 203) = 847x + 203y$. First, we compute the GCD using Euclid's algorithm, as we did above. Now, we'll trace the above computation and write each new number as a linear combination of the algorithm's “roots”.

$$\begin{array}{lll} (1) & a & = 847 \\ (2) & b & = 203 \\ (1) - 4(2) & = (3) & a - 4b = 35 \\ (2) - 5(3) & = (4) & -5a + 21b = 28 \\ (3) - (4) & = (5) & 6a - 25b = 7 \end{array}$$

So the desired integers are $x = 6$ and $y = -35$.

We'll finish this section with another important theorem which, as we will see, establishes an connection

between GCDs and prime numbers.

Theorem 2.9: The important theorem

If $d \mid ab$ and $(d, a) = 1$ then $d \mid b$.

Proof. Suppose $d \mid ab$ and $(d, a) = 1$. Then $ab = dq$ for some integer q , and by Bezout's theorem

$$\begin{aligned} (d, a) = 1 &\implies dx + ay = 1 \\ &\implies dxb + aby = b \\ &\implies dxb + dqy = b \\ &\implies d(xb + qy) = b \end{aligned}$$

Therefore, $d \mid b$. \square

2.3 Primes

Moving on from the basic notion of the GCD, we define another basic idea: primality.

Definition: Prime number

An integer $p > 1$ is prime if its only positive divisors are 1 and p .

Definition: Composite number

If $n > 1$ is not prime, then n is called composite.

Note: This implies that 0 and 1 are neither prime nor composite.

Although they get decreasingly common at higher orders of magnitude, the primes are infinite. Euclid gave a very simple proof of this, a variation on which is given below.

Theorem 2.10: Euclid's theorem

There are infinitely many primes.

Proof. Suppose, to the contrary, that p is the largest prime number. Notice that no number $2, \dots, p$ divides $p! + 1$, meaning $p! + 1$ is either prime or has a prime factor that is greater than p . Either way, this contradicts our assumption that p is the largest prime. \square

Despite this, it can also be shown that, for any number n , there exists a list of n consecutive prime numbers. Namely, $(n+1)! + 2, (n+1)! + 3, \dots, (n+1)! + (n+1)$.

It can be shown, by strong induction, that every number can be expressed as the product of primes. Our aim is to show that this product is unique. As a step toward this, we give a variation on the important theorem.

Theorem 2.11: Theorem of prime importance

If p is prime and $p \mid ab$, then $p \mid a$ or $p \mid b$.

Proof. Suppose p is prime and $p \mid ab$. If $p \mid a$, then we're done; otherwise, $p \nmid a$, and therefore $(p, a) = 1$. So by the important theorem, $p \mid b$. Either way, $p \mid a$ or $p \mid b$. \square

Corollary 2.12

If p is prime and $p \mid a_1 a_2 \cdots a_n$, then $p \mid a_1$ or $p \mid a_2$ or \cdots or $p \mid a_n$.

Now, the centerpiece of the section.

Theorem 2.13: Fundamental theorem of arithmetic

Every integer $n \geq 2$ can be uniquely factored into primes.

Proof. Suppose, to the contrary, that m is the smallest number with at least two prime factorizations, say

$$p_1 p_2 \cdots p_r = m = q_1 q_2 \cdots q_s.$$

Since $p_1 \mid m$, $p_1 \mid q_1 q_2 \cdots q_s$ and, by the previous corollary, $p \mid q_i$ for some i ; without loss of generality, say $p_1 \mid q_1$. But since q_1 is prime, this means $p_1 = q_1$, so

$$p_2 \cdots p_r = \frac{m}{p_1} = q_2 \cdots q_s.$$

So $\frac{m}{p_1}$ has two different prime factorizations, contradicting our assumption for m . \square

We can use this fundamental theorem to solve a pretty neat counting problem.

Theorem 2.14: Number of positive divisors from prime factorization

Let $a = \prod_{i=1}^r p_i^{\alpha_i}$, where p_1, \dots, p_r are distinct primes and $\alpha_i \geq 0$.

a has $(1 + \alpha_1)(1 + \alpha_2) \cdots (1 + \alpha_r)$ positive divisors.

Similarly, the exponents of this prime factorization can be used to quickly determine the greatest common divisor and least common multiple between two numbers.

Theorem 2.15: GCD and LCD from prime factorization

Let

$$a = \prod_{i=1}^r p_i^{\alpha_i} \text{ and } b = \prod_{i=1}^r p_i^{\beta_i},$$

where p_1, \dots, p_r are distinct primes and $\alpha_i, \beta_i \geq 0$.

$$\gcd(a, b) = \prod_{i=1}^r p_i^{\min\{\alpha_i, \beta_i\}} \text{ and } \text{lcm}(a, b) = \prod_{i=1}^r p_i^{\max\{\alpha_i, \beta_i\}}.$$

Note that the least common multiple is commonly denoted $[a, b]$. We give one last significant consequence of unique prime factorizations.

Theorem 2.16: gcd · lcm

For any $a, b \geq 1$, $(a, b)[a, b] = ab$.

2.4 Modular Arithmetic

Modular arithmetic will be essential to the rest of our discussion of number theory. Informally, this is the arithmetic in which two numbers are called “congruent” if, when divided by some number, they have the same

remainder. A more formal definition is below.

Definition: Modular congruence

For $m > 0$, we say that a is congruent to b modulo m if $m \mid a - b$. Symbolically, $a \equiv_m b$. (Here, m is called the modulus.)

A more common notation for modular congruence is $a \equiv b \pmod{m}$, but we won't use this here.

The relation \equiv_m has a lot in common with the relation $=$. In fact, \equiv_m can be called an equivalence relation since it has the following three properties.

Theorem 2.17: Modular congruence as an equivalence relation

For any integers a, b, c :

- (a) Reflexivity. $a \equiv_m a$.
- (b) Symmetry. If $a \equiv_m b$ then $b \equiv_m a$.
- (c) Transitivity. If $a \equiv_m b$ and $b \equiv_m c$ then $a \equiv_m c$.

Now we'll explore some of the things we're "allowed" to do with this relation.

Theorem 2.18: Operations on \equiv_m

If $a \equiv_m b$ and $c \equiv_m d$, then

- (a) $a + c \equiv_m b + d$
- (b) $ac \equiv_m bd$

Corollary 2.19: Power rule

If $a \equiv_m b$ then $a^n \equiv_m b^n$ for all $n \geq 0$.

Putting all this together, we get what may be a superficially surprising fact.

Corollary 2.20: Polynomial rule

Let $P(x)$ be a polynomial with integer coefficients. If $a \equiv_m b$, then $P(a) \equiv_m P(b)$.

With this polynomial theorem, here's a little aside. Out of a variety of modular relationships that have to do with the digits of a number, we give a simple one.

Theorem 2.21

Define $S(x)$ to be the sum of the digits of x . $x \equiv_9 S(x)$.

Proof. Let x have digits $a_n a_{n-1} \cdots a_1 a_0$. Then

$$x = \sum_{k=0}^n a_k 10^k \equiv_9 \sum_{k=0}^n a_k 1^k = S(x).$$

Therefore, $x \equiv_9 S(x)$. \square

Now we'll continue with our discussion of arithmetic. We've seen that we can add (and thus subtract) and multiply on both sides of a congruence. We can only divide, however, under certain conditions.

Theorem 2.22: Cancellation theorem

If $ax \equiv_m ay$ and $\gcd(a, m) = 1$, then $x \equiv_m y$.

Proof. Suppose $ax \equiv_m ay$ and $(a, m) = 1$. By definition,

$$\begin{aligned} m &| ax - ay \\ m &| a(x - y) \end{aligned}$$

By the important theorem, $m | x - y$ and $x \equiv_m y$. \square

We can generalize this theorem slightly, if we allow ourselves to change the modulus.

Theorem 2.23

If $ax \equiv_m ay$ and $\gcd(a, m) = d$, then $x \equiv_{m/d} y$.

The cancellation theorem gives one idea of what it means to “undo” multiplication in a modular sense. Alternatively, we can define the multiplicative inverse of a number mod m .

Definition: Multiplicative inverse

An integer a has a multiplicative inverse if there exists an integer x such that $ax \equiv_m 1$.

Unfortunately, not every number has an inverse; fortunately, it is easy to check if a number has one!

Theorem 2.24: Existence and uniqueness of an inverse

a has an inverse mod m if and only if $(a, m) = 1$. The inverse is unique up to congruence mod m .

Proof. (\Rightarrow) Suppose a has an inverse mod m . By definition, there exists an integer x such that $ax \equiv_m 1$, so $m | ax - 1$. So there exists another integer y such that

$$\begin{aligned} my &= ax - 1 \\ ax - my &= 1 \end{aligned}$$

By Bezout's theorem, $(a, m) = 1$.

(\Leftarrow) All of the steps above are reversible, so if $(a, m) = 1$ then a has an inverse mod m . \square

If the modulus is prime, then we can make an even stronger statement.

Corollary 2.25

If p is prime, then the numbers $1, 2, \dots, p - 1$ have unique inverses mod p .

2.5 Applications

Here we state four theorems that utilize everything we've discussed so far, largely modular arithmetic.

Theorem 2.26: Wilson's theorem

If p is prime then $(p - 1)! \equiv_m -1$.

Proof. Let p be prime, so the numbers $1, 2, \dots, p-1$ have inverses mod p . The only ones of these that are their own inverses are 1 and $p-1$.

To see this, consider a number a that is its own inverse, so $a^2 \equiv_p 1$ and $p \mid a^2 - 1$. By the theorem of prime importance, $p \mid a-1$ or $p \mid a+1$. The only integers (among $1, 2, \dots, p-1$) satisfying this condition are 1 and $p-1$.

Therefore, all of the other numbers $2, \dots, p-2$ are inverses of each other, so when we compute $(p-1)!$ we get

$$(p-1)! \equiv_p (p-1) \cdot 1.$$

Finally, since $p-1 \equiv_p -1$, we get $(p-1)! \equiv_p -1$. \square

It isn't important for us, but Wilson's theorem is actually an iff theorem, since it can be shown that if n is composite then $(n-1)! \not\equiv_n -1$. So in theory, we could use Wilson's theorem to determine if n is prime; in practice, $(n-1)!$ is big. Like, really big. So we must resort to other means.

Theorem 2.27: Fermat's little theorem

If p is prime, then $a^p \equiv_p a$ for any $a \in \mathbb{Z}$. (Alternatively, $a^{p-1} \equiv_p 1$.)

Proof. We have two cases.

(i) If $p \mid a$, then $a \equiv_p 0$ and $a^p \equiv_p 0^p$. Since $a^p = 0$, by transitivity, $a^p \equiv_p a$. (And, by the cancellation theorem, $a^{p-1} \equiv_p 1$.)

(ii) Notice that the numbers $0, 1, 2, \dots, p-1$ are all distinct mod p . By the cancellation theorem contrapositive, since $(a, p) = 1$, the numbers $0, a, 2a, \dots, (p-1)a$ are also distinct mod p . Now, since each of these lists covers all possible remainders mod p ,

$$\begin{aligned} \{0, a, 2a, \dots, (p-1)a\} &\equiv_p \{0, 1, 2, \dots, (p-1)\} \\ \{a, 2a, \dots, (p-1)a\} &\equiv_p \{1, 2, \dots, (p-1)\} \end{aligned}$$

We can multiply all of the elements in each of these sets to get

$$\begin{aligned} a \cdot 2a \cdots (p-1)a &\equiv_p 1 \cdot 2 \cdots (p-1) \\ (p-1)! a^{p-1} &\equiv_p (p-1)! \\ a^{p-1} &\equiv_p 1 \end{aligned}$$

Finally, multiplying by a gives $a^p \equiv_p a$. \square

Our next theorem will generalize Fermat's theorem. First, however, we'll need some scaffolding in the form of a new definition.

Definition: Totient function

For $n \geq 1$, define the totient function $\phi(n)$ as the number of elements in the set $\{1, 2, \dots, n\}$ that are relatively prime to n .

This totient function has a couple of convenient properties that are useful in certain computations.

Theorem 2.28: Computing $\phi(n)$

If n has distinct prime factors p_1, p_2, \dots, p_r , then

$$\phi(n) = n \left(1 - \frac{1}{p_1}\right) \left(1 - \frac{1}{p_2}\right) \cdots \left(1 - \frac{1}{p_r}\right).$$

Proof. We use the principle of inclusion and exclusion to prove the $r = 3$ case. We count in four phases:

1. Place no restrictions on the numbers we count.
2. Subtract the numbers that are multiples of at least one prime.
3. Add back the numbers that are multiples of at least two primes.
4. Subtract the numbers that are multiples of all three primes.

This gives

$$\begin{aligned}\phi(n) &= n - \frac{n}{p_1} - \frac{n}{p_2} - \frac{n}{p_3} + \frac{n}{p_1 p_2} + \frac{n}{p_1 p_3} + \frac{n}{p_2 p_3} - \frac{n}{p_1 p_2 p_3} \\ &= n \left(1 - \frac{1}{p_1} - \frac{1}{p_2} - \frac{1}{p_3} + \frac{1}{p_1 p_2} + \frac{1}{p_1 p_3} + \frac{1}{p_2 p_3} - \frac{1}{p_1 p_2 p_3} \right) \\ &= n \left(1 - \frac{1}{p_1} \right) \left(1 - \frac{1}{p_2} \right) \left(1 - \frac{1}{p_3} \right)\end{aligned}$$

The method here can be easily extended to other values of r , be it much more cumbersome. \square

There's some other, less rigorous intuition to be gained from this formula. Each factor represents a proportion of numbers that do not have p_i as a factor (each of these proportions is independent), and multiplying all of these together gives the total proportion of numbers that do not have any p_i as a factor.

This leads to one other nice property of totients, given below.

Corollary 2.29

If $(x, y) = 1$, then $\phi(xy) = \phi(x)\phi(y)$.

Finally, we have one more “pure” result, also related to totients. It is a generalization of Fermat's theorem.

Theorem 2.30: Euler's theorem

If $(a, m) = 1$, then $a^{\phi(m)} \equiv_m 1$.

As an interlude, consider again Fermat's theorem, specifically its contrapositive: if $a^n \not\equiv_n a$ then n is not prime. This gives us a “probable prime test”; it isn't perfect since Fermat's theorem isn't an iff statement, but it does filter out the vast majority of composite numbers.

A number n that passes the Fermat test for all possible bases a is called an industrial-grade prime. Some of these IGP's, of course, are composite; such numbers are called Carmichael numbers. (There are tests to weed these out, but they won't be covered here.)

We will, however, give a couple of practical methods for computing $a^n \bmod m$ for large n . First, if $(a, m) = 1$ and $\phi(m)$ are known, we may be able to exploit Euler's theorem in some way (often using the division algorithm). This method is simple, but it has limited use; the next one is much more widely applicable.

Example: Seed planting

Suppose we want to compute $6^{83} \bmod 79$. First, we decompose the exponent into powers of two:

$$83 = 64 + 16 + 2 + 1.$$

Now we'll go through all the powers of two from 64 to 1 and, starting with 6^0 (the seed), successively

square numbers, multiplying by an extra 6 whenever we encounter a power of two that is listed above.

$$\begin{aligned}
 \boxed{64} &\rightarrow 6^0 \cdot 6 = 6 \\
 32 &\rightarrow 6^2 = 36 \\
 \boxed{16} &\rightarrow 36^2 \cdot 6 = 7776 \equiv_{79} 34 \\
 8 &\rightarrow 34^2 = 1156 \equiv_{79} 50 \\
 4 &\rightarrow 50^2 = 2500 \equiv_{79} 51 \\
 \boxed{2} &\rightarrow 51^2 \cdot 6 = 15606 \equiv_{79} 43 \\
 \boxed{1} &\rightarrow 43^2 \cdot 6 = 11094 \equiv_{79} 34
 \end{aligned}$$

So, $6^{83} \bmod 79 = 34$.

Using this, we can make a statement that is much more immediately practical in cryptography.

Consider a public key $\{n, e\}$ and a private key d known only to the recipient. The idea is to construct a function that is easy to compute using the public key, but very difficult to invert without knowing the private key. Specifically,

- to encipher a message m the sender computes $c = m^e \bmod n$, and
- to decipher the resulting ciphertext the recipient computes $m = c^d \bmod n$. (Note that, in order to unambiguously recover a message, we must have $m < n$.)

Now the problem becomes actually choosing values of n , e , and d to make this work. The process is simple:

1. n is the product of two (private) primes p and q .
2. d is a random number that is relatively prime to $\phi(n) = (p-1)(q-1)$.
3. $e \geq 0$ is an integer that satisfies $de - \phi(n)f = 1$ for some $f \geq 0$. (Note that this means $de \equiv_{\phi(n)} 1$.)

The proof that this works is similarly straightforward.

Theorem 2.31: RSA encryption

Let n, d, e be chosen as described above. If $c = m^e \bmod n$, then $c^d \bmod n = m$.

Proof. Suppose $c = m^e \bmod n$ and n, d, e are chosen as described above. Since we require $0 \leq m < n$, we need only show that $c^d \bmod n \equiv_n m$.

By definition

$$c = m^e \bmod n \equiv_n m.$$

So

$$c^d \bmod n \equiv_n c^d \equiv_n (m^e)^d = m^{ed}.$$

Since $ed - \phi(n)f = 1$,

$$m^{ed} = m^{1+\phi(n)f} = m \cdot (m^{\phi(n)})^f.$$

By Euler's theorem,

$$m \cdot (m^{\phi(n)})^f \equiv_n m \cdot 1^f = m.$$

Therefore, $c^d \bmod n \equiv_n m$ and $c^d \bmod n = m$. \square

Chapter 3

Graph Theory

3.1 Introduction

Just as the central objects of previous chapters were combinations and integers, the central object of this chapter is the graph.

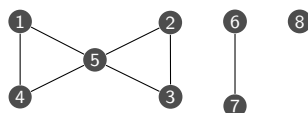
Definition: Graph

A graph $G = (V, E)$ consists of a finite vertex set V and an edge set E where E contains size-2 subsets of V .

This definition is precise, but it isn't very nice to work with. In practice, we usually think of a graph using its picture. For example, we associate the graph

$$V = \{1, 2, 3, 4, 5, 6, 7, 8\}$$
$$E = \left\{ \{1, 4\}, \{1, 5\}, \{2, 3\}, \{2, 5\}, \{3, 5\}, \{4, 5\}, \{6, 7\} \right\}$$

with the picture below.



Note that, since graphs are defined in terms of sets, they cannot contain loops or “multi-edges”. (If we were to allow multi-edges, we would have a multi-graph.)

We say that two vertices are adjacent if there is an edge between them. The degree $d(v)$ of a vertex v is the number of vertices that are adjacent to v .

Now we can get into some basic properties of graphs.

Lemma 3.1: Handshake lemma

For any graph, the sum of the degrees of the vertices is twice the number of edges. That is, if $G = (V, E)$, then

$$\sum_{v \in V} d(v) = 2|E|.$$

Proof. If we count the edges leaving each vertex, then every edge is counted exactly twice. \square

This result's namesake is its application to gatherings of people. If partygoers go around and shake hands with each other, each handshake increases the partygoers' “degree sum” by two. Therefore, this degree sum must always be even.

Corollary 3.2: Oddballs

In any graph, the number of vertices with odd degree must be even.

Proof. If the number of vertices with odd degree is odd, then the sum of the degrees is

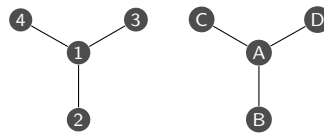
$$\text{even} + \cdots + \text{even} + \text{odd} + \cdots + \text{odd} = \text{even} + \text{odd} = \text{odd},$$

which can't happen (by the handshake lemma). \square

Graphs are considered to be equal if they have the same vertex and edge sets. We can push the vertices around as much as we want and, so long as no edges are created or severed, we will still have the same graph.

Two graphs that have the same fundamental structure (though not necessarily the same vertex labels) are called isomorphic. Specifically, two graphs G, H are isomorphic if $x \sim y \iff f(x) \sim f(y)$ for some function (isomorphism) f , where $x, y \in V_G$ and \sim is an “adjacency” relation.

The following graphs are not equal, but they are isomorphic.



There are certain types of graphs that are particularly interesting. One class of these is defined below.

Definition: Complete graph

A complete graph K_n consists of n vertices, where every vertex is adjacent to every other vertex.

One well-known problem in graph theory has to do with coloring the edges of a complete graph (say, red and blue) and seeing what monochromatic subgraphs emerge, if any. A useful analogy for these is in the context of friends and strangers: if an edge between two vertices is colored red, we say the vertices are “friends”, whereas if the edge is blue the vertices are strangers. We'll start simple with K_6 .

Theorem 3.3: Ramsey's theorem, (3, 3)

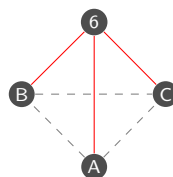
In any collection of six people, there must exist three mutual friends or three mutual strangers.

Equivalently, if the edges of K_6 are colored red and blue, then it must contain a red K_3 or a blue K_3 .

Proof. After coloring the edges of K_6 , vertex 6 must have

- (a) at least three red edges or
- (b) at least three blue edges.

We'll begin with case (a). Consider the subgraph of K_6 which includes vertex 6 along with three of its red-adjacent nodes.



If any of the edges among A, B, C are red, then we have a red triangle. Otherwise, all of the edges are blue, meaning we have a blue triangle!

Case (b) can be proved in the same way. \square

A follow-up question that we could ask in response to this is whether we can state a similar theorem for, say, K_5 . It turns out that we can't; finding a counterexample is relatively straightforward. Thus, 6 is known as the third Ramsey number—it describes the smallest complete graph that contains either a red K_3 or a blue K_3 after edge coloring.

We'll now discover a similar number for a red K_3 or blue K_4 .

Corollary 3.4: Ramsey's theorem, (3, 4)

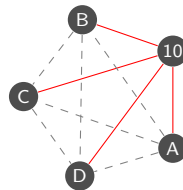
Any group of ten people must contain three mutual friends or four mutual strangers.

Equivalently, if the edges of K_{10} are colored red and blue, then it must contain a red K_3 or a blue K_4 .

Proof. After coloring the edges of K_{10} , vertex 10 must have

- (a) at least four red edges or
- (b) at least six blue edges.

We'll begin with case (a). Consider the subgraph of K_{10} which includes vertex 10 along with four of its red-adjacent vertices.



If any of the edges among A, B, C, D are red, then we have a red K_3 . Otherwise, all of the edges are blue, meaning we have a blue K_4 .

As for case (b), consider the graph of K_{10} which includes vertex 10 along with six of its blue-adjacent vertices (similar to the above subgraph). If we remove vertex 10 and consider only vertices $A-F$, we get a K_6 ; by the previous theorem, this must contain a red K_3 or a blue K_3 . If it contains a red K_3 , then we're done; if it contains a blue K_3 , then since each vertex is also connected to vertex 10 via a blue edge, this blue K_3 is part of a larger blue K_4 . \square

We can go a bit lower with K_9 .

Corollary 3.5: Ramsey's theorem, (3, 4)

The above holds for nine people or, equivalently, K_9 .

Proof. Suppose we color the edges of K_9 . By the previous corollary, if any vertex has

- (a) at least four red edges or
- (b) at least six blue edges,

then we're done. Otherwise, since each vertex has eight edges, every vertex has exactly three red edges and five blue edges. But this is impossible by the oddball corollary since the red subgraph has nine vertices, each with degree 3. \square

This is as far as we can go with (3, 4); there is a counterexample for K_8 . The corresponding Ramsey number, then, is $R(3, 4) = 9$.

3.2 Walking on Graphs

Now we'll introduce some more vocabulary so that we can more effectively describe other classes of graphs.

Definition: Walk

A walk on a graph is a sequence of adjacent vertices, with repetition. The length of such a walk is the number of vertices in the sequence, minus one.

Definition: Path

A path is a walk with no repeated vertices.

We can state a seemingly trivial relationship between these two objects, but it reveals a new technique of proof that we will take advantage of throughout this chapter.

Theorem 3.6

For vertices x and y , a path from x to y exists if and only if a walk from x to y exists.

Proof. (\Rightarrow) Let P be a path from x to y . By definition, P is also a walk from x to y .

(\Leftarrow) We give an extremal argument. If there is a walk from x to y , then there is a walk W of minimum length. We claim that W is a path.

If there are repeated vertices in W , then there is a shorter walk that can be created by removing the vertices between the repetitions, so W is not a minimal walk. Therefore, if W is a minimal walk, then there are not repeated vertices in W . \square

We have a couple more definitions along the same lines as the previous ones.

Definition: Trail

A trail is a walk with no repeated edges. A trail is closed if it begins and ends at the same vertex.

Definition: Cycle

A cycle is a closed trail such that removing the last vertex also yields a path.

We can use this vocabulary to formalize an characteristic of graphs that is immediately obvious when looking at one.

Definition: Connected graph

A graph is connected if, for all vertices x and y , a path exists from x to y .

Another immediate application of all this vocabulary comes in defining a couple other important classes of graphs.

Definition: Eulerian graph

An Eulerian trail is one that visits all edges of a graph at least once.

A connected graph is Eulerian if it can be drawn as a closed trail; such a trail is called an Eulerian circuit.

The degrees of the vertices of a graph with Eulerian characteristics have nice relationships! These are given below; the proof of the second theorem is very similar to that of the first, so we omit it for clarity.

Theorem 3.7

If G is a connected graph that can be drawn as an Eulerian trail from x to y , where $x \neq y$, then

- (a) vertices x and y each have odd degree and
- (b) all other vertices have even degree.

Proof. Consider any Eulerian trail from x to y . For any vertex v other than x and y , every time we enter v we must also immediately leave v , so $d(v)$ is even. The same is true for x after the initial exit and for y after the final entry, so $d(x)$ and $d(y)$ are both odd. \square

Theorem 3.8

If a connected graph G is Eulerian, then all vertices have even degree.

It turns out that both of these are actually if and only if theorems—their converses are also true!

Theorem 3.9: Eulerian graph theorem

If G is a connected graph and every vertex has even degree, then G is Eulerian.

Proof. We do strong induction on the number of edges in G . The base case, $e = 0$, is obviously true.

Now let G be a connected graph with $e > 0$ edges. Suppose as our inductive hypothesis that the theorem holds for all connected graphs with fewer than e edges. Since every vertex has even degree, every vertex has a degree of at least 2. So G must contain a cycle C .

If $G = C$, then we're done. Otherwise, remove the edges of C from G , creating the graph $G - C$, which has fewer edges than G ; moreover, each vertex of $G - C$ still has even degree. From here, we have two cases.

- (a) If $G - C$ is connected, then by the inductive hypothesis, $G - C$ is Eulerian. Thus $G - C$ can be drawn as an Eulerian circuit, beginning and ending at a vertex v on C ; from here we can draw C . Thus all of G can be drawn as an Eulerian circuit, meaning G is Eulerian.
- (b) If $G - C$ is not connected, then $G - C$ has connected components, each of which is Eulerian (by the inductive hypothesis). We can draw G using the same idea as before. We trace out C , traversing each new component of G when we first visit it; we are guaranteed to visit each component at least once.

Either way, we conclude that G is Eulerian. \square

Corollary 3.10

If G is connected and all vertices have even degree, except for vertices x and y , then G has an Eulerian trail from x to y .

Proof. Insert a new vertex z that is adjacent to only x and y . This new graph $G + z$ is still connected, and all vertices have even degree, so by the previous theorem it is Eulerian. So $G + z$ has an Eulerian circuit beginning and ending at z , thus removing z gives an Eulerian trail from x to y . \square

When we generalize these Eulerian notions slightly, we get a new class of graphs, defined below.

Definition: Hamiltonian graph

Given a graph G :

- a Hamiltonian path is one that visits every vertex of G .
- a Hamiltonian cycle is one that visits every vertex of G .
- G is Hamiltonian if it contains a Hamiltonian cycle.

Unfortunately, unlike Eulerian graphs, it is unknown if there is an efficient way to determine if a large graph has a Hamiltonian cycle. But there are sometimes efficient tests! (For example, if G has n vertices and each vertex has a degree of at least $n/2$, then G is Hamiltonian.)

3.3 Trees and Planar Graphs

Now we'll describe a couple of other types of graphs.

Definition: Tree

A tree is a connected graph with no cycles. A disconnected graph whose components are trees is called a forest.

A quick aside: Cayley's theorem states that, for $n \geq 1$, the number of distinct (unlabeled) trees with n vertices is n^{n-2} . The proof of this statement is beyond the scope of this course.

Definition: Leaf

In a tree, a vertex with degree 1 is called a leaf.

We'll show, now, that all trees have leaves!

Theorem 3.11

Any tree with at least two vertices has at least two leaves.

Proof. We give an external argument. Consider the longest path in T , which has v_1 as its first vertex. We claim that v_1 must be a leaf.

Suppose, to the contrary, that v_1 is adjacent to a vertex $v \neq v_2$. If v is on T , then T contains a cycle; if v is not on T , then v_1 is adjacent to both v and v_2 , giving a path that is longer than T . Either way, we get a contradiction.

By the same logic, the final vertex in T is also a leaf. Therefore, T contains two leaves, meaning its graph also contains two leaves. \square

Notice, now, that when we remove a leaf from a tree, we are still left with a tree. This leads to nice induction proofs, like the one below!

Theorem 3.12

Every tree with n vertices has $n - 1$ edges.

Proof. We'll do induction on n , the number of vertices on the graph. The base cases $n = 1$ and $n = 2$ are obviously true.

Now suppose as our inductive hypothesis that the statement holds for any tree with n vertices. If we take a tree T with $n + 1$ vertices and remove one of its leaves, we are left with a tree that has n vertices; by the inductive hypothesis, the "reduced" tree has $n - 1$ edges, so T has n edges, as desired. \square

Finally, we have a theorem which is useful for "communicating" uniquely between vertices.

Theorem 3.13

Any two vertices on a tree are connected by a unique path.

Proof. Since the tree T is connected, we know that a path P exists from x to y . Suppose there was also a different path Q that connected these vertices.

Let P and Q be identical up until vertex a , and let b be the next point on P that is also on Q . (We may have $a = x$ and $b = y$.) Then, starting at a , we can reach b via the path P , and we can get back to a by backtracking Q . This describes a cycle in T , which is not allowed by the definition of a tree. \square

Trees are a special type of another class of graphs, defined below.

Definition: Planar graph

A planar graph is a graph that can be drawn in such a way that no edges cross.

Notice that planar graphs divide the plane into regions, called faces. (The region outside of the graph is also a face.) This brings us to one last theorem from Euler.

Theorem 3.14

If G is a connected plane graph with n vertices, \mathcal{E} edges, and f faces, then

$$n - \mathcal{E} + f = 2.$$

Proof. We do induction on \mathcal{E} , the number of edges. The base cases $\mathcal{E} = 0$ and $\mathcal{E} = 1$ are trivial.

Suppose, as our inductive hypothesis, that the statement holds when $\mathcal{E} = K$. Now let G be a connected plane graph with $\mathcal{E} = k + 1$. We have two cases.

- (a) If G is a tree with n vertices, then $\mathcal{E} = n - 1$ and $f = 1$, which satisfies $n - \mathcal{E} + f = 2$. (No induction necessary here.)
- (b) If G is not a tree, then it must contain a cycle. After removing an edge from the cycle, the new graph remains connected, but has one fewer face; that is, it has n vertices, k edges, and $f - 1$ faces. By the inductive hypothesis:

$$\begin{aligned} n - k + (f - 1) &= 2 \\ n - (k + 1) + f &= 2 \\ n - \mathcal{E} + f &= 2, \end{aligned}$$

as desired.

Either way, we get $n - \mathcal{E} + f = 2$. \square

This actually explains why we can't construct Venn diagrams with more than three circles! One with four circles would have $n = 12$, $f = 16$, and $\mathcal{E} = 24$, which violates the above theorem.

Usually, graphs are made nonplanar when they have "too many edges". The next theorem gives an edge-related condition that a graph must satisfy to even possibly be planar.

Theorem 3.15

If G is planar with $n \geq 3$ vertices and \mathcal{E} edges, then $\mathcal{E} \leq 3n - 6$.

Proof. Suppose G has n vertices, \mathcal{E} edges, and f faces. We have two cases.

- (a) G is connected. Construct the “edge-face” matrix M with \mathcal{E} rows and f columns; the (i, j) entry is 1 if edge i borders face j , and the entry is otherwise 0.

Let x be number of 1s in M . Since every edge borders at most two faces, $x \leq 2\mathcal{E}$; also, since each face has at least three edges, $x \geq 3f$. Thus $3f \leq 2\mathcal{E}$. By Euler’s theorem, $f = 2 - n + \mathcal{E}$, so

$$\begin{aligned} 3(2 - n + \mathcal{E}) &\leq 2\mathcal{E} \\ \mathcal{E} &\leq 3n - 6, \end{aligned}$$

as desired.

- (b) G is disconnected. Insert $k - 1$ edges at arbitrary locations such that they create the connected graph G^+ . (Note that this graph is still planar.) Applying Case (a) to G^+ gives

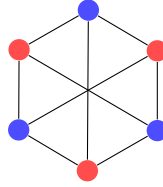
$$\mathcal{E} < \mathcal{E} + (k - 1) \leq 3n - 6,$$

as desired.

either way, we get $\mathcal{E} \leq 3n - 6$. \square

We can use this to quickly show that the complete graph K_5 is nonplanar.

Another important graph that turns out to be nonplanar is $K_{3,3}$, which is drawn below.



A proof of this graph’s nonplanarity is below.

Theorem 3.16

$K_{3,3}$ is nonplanar.

Proof. Suppose, to the contrary, that $K_{3,3}$ is planar. Then by Euler’s theorem, $f = 5$, so its edge-face matrix has 9 rows and 5 columns. Let x be the number of 1s in this matrix, so $x \leq 18$. But for $K_{3,3}$ every face must have at least four edges (notice that it has no triangles), meaning $x \geq 4f = 20$, a contradiction. \square

As it turns out, by Kuratowski’s theorem, every nonplanar graph contains K_5 or $K_{3,3}$, or a subdivision of K_5 or $K_{3,3}$. (To subdivide a graph is to add degree-2 nodes along the existing edges of the graph, so as to not drastically change its overall structure.)

3.4 Graph Coloring

One well-known class of problems in graph theory has to do with coloring graphs—assigning each vertex a color, with certain restrictions. For our purposes, we’ll restrict ourselves to the following.

Definition: Properly colored graph

A graph is properly colored by giving each vertex a color in such a way that no adjacent vertices have the same color.

We introduce some related vocabulary that more specifically describes graphs that are properly colorable.

Definition: k -colorable

A graph is k -colorable if it can be properly colored with k colors or less. (A graph that is 2-colorable is also called bipartite.)

Definition: Chromatic number

The chromatic number of a graph, denoted $\chi(G)$, is the smallest k for which G is k -colorable.

A graph is 1-colorable only when G has no edges. Creating a condition for 2-colorability is slightly more interesting!

Theorem 3.17: 2-colorable graphs

G is 2-colorable if and only if it has no odd cycles (cycles with an odd number of vertices).

Proof. (\Rightarrow) We prove the contrapositive. Suppose G has an odd cycle consisting of vertices v_1, \dots, v_{2k+1} . If we color this graph using two colors, then all of the odd vertices must be one color, and all the even vertices another. But v_1 and v_{2k+1} are both odd, so they must have the same color, meaning the graph is not 2-colorable.

(\Leftarrow) Suppose G has no odd cycles. It suffices to prove this for connected G because, if each component is 2-colorable, then so is G .

We have two cases.

- (a) Suppose G is a tree. We'll prove this case by induction on the number n of vertices. The statement is clearly true for the base case $n = 1$.

Suppose as our inductive hypothesis that any tree with n vertices is 2-colorable. (The no-odd-cycles condition is built into the tree by definition.) Consider a tree with $n + 1$ vertices and remove a leaf; we now have a tree with n vertices, which we assume to be colorable. Now add back the leaf, assign it the color opposite that of the vertex it's adjacent to, and we're done.

- (b) Suppose G is not a tree. Temporarily remove edges from G until we do have a tree (called a spanning tree); from case (a), this tree is 2-colorable. Now put all the edges back—we claim that no edge connects vertices of the same color.

When we add an edge from, say, x to y , we get an even cycle C . This means the number of steps from x to y is odd, so x and y have opposite colors. Thus, when we insert all of the deleted edges, we still have a 2-coloring.

Either way, if G has no odd cycles, then it is 2-colorable. \square

We'll now consider colorings of planar graphs in particular. This has an important application in mapmaking! Every map (in the colloquial sense) can be represented equivalently using its dual graph. This is the graph whose vertices are regions on the map, and whose edges represent boundaries between regions.

The four-color theorem states that any map can be "properly colored" using only four colors. That is, using four colors, one can color a map such that no adjacent regions have the same color.

We will not prove the four-color theorem here, but we will prove its analogs for 6-colorings and 5-colorings.

Theorem 3.18: Six-color theorem

Every planar graph is 6-colorable.

Proof. We do induction on the number of vertices n . The base cases $n \leq 6$ are obvious.

Suppose, as our inductive hypothesis, that any planar graph with n vertices is 6-colorable.

Consider a graph with $n + 1$ vertices. This graph has at least one vertex v of degree 5 or less; if we remove v , we are left with a graph that has n vertices, which (by the IHOP) is 6-colorable. Now if we add v back into the graph, it is adjacent to at most five vertices, so there is a color we can assign to v that has not been used by any adjacent vertex. \square

Theorem 3.19: Five-color theorem

Every planar graph is 5-colorable.

Proof. We do induction on the number of vertices n . The base cases $n \leq 5$ are obvious.

Suppose, as our inductive hypothesis, that any planar graph with n vertices is 5-colorable.

Consider a graph with $n + 1$ vertices. This graph has at least one vertex v of degree 5 or less; if we remove v , we are left with a graph that has n vertices, which (by the IHOP) is 5-colorable. Now if we add v back into the graph and it has less than five adjacent colors, then we're done; otherwise, v has five adjacent colors. We claim that, in this case, one vertex can be re-colored, which would free up a color for v .

Label the vertices adjacent to v as v_1, \dots, v_5 in clockwise-ascending order. (This order is not necessarily unique.) Suppose these vertices are respectively colored red, yellow, green, blue, and some fifth color.

Change the color of v_1 from red to green. Then take all green vertices adjacent to v_1 and color them red. Then color all red vertices adjacent to those green. If we continue this, we get one of two cases.

- (a) The process eventually terminates and we can immediately color v red.
- (b) We come back to v_3 and color it red, putting us back at square one. But now we can do the same process with v_2 and v_4 : change v_4 from blue to yellow, and continue the chain until it terminates. (Here, the chain will never reach v_2 since it's being guarded by an entirely red-green chain!) We can now safely color v blue.

Either way, we can re-color the graph in such a way that allows us to safely color v , as desired. \square

FORGOT THE LEMMA THAT ALL PLANAR GRAPHS HAVE A VERTEX WITH DEGREE FIVE OR LESS!

3.5 Tournaments (Lec. 23)

TOURNAMENTS (Directed graphs)

- DEF. A tournament is a complete directed graph.
- THM. Every graph has a directed Hamiltonian path. (Pf. Induction on vertices.)
- DEF. For a tournament, player x is a king (or king chicken) if, for every other player y , either $x \rightarrow y$ or there exists a player z such that $x \rightarrow z \rightarrow y$.
- THM. Every tournament has a king. (Pf. The person who won the most games is a king.)

MINIMUM SPANNING TREES (Weighted graphs)

- come back later...