EndSem 2

August 3, 2021

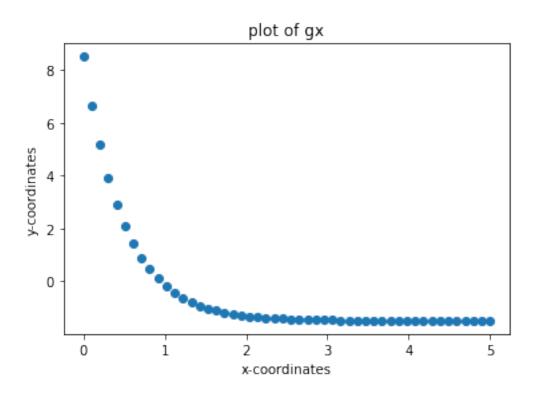
0.1 First we are making a scatter plot of the function

```
g(x) = A_1 + A_2 \cdot e^{-A_3 \cdot x}
```

```
[]: import math
  import numpy as np
A1 = -1.5
A2 = 10
A3 = 2
x = np.linspace(0,5,50)
def myf(b):
  return A1 + (A2*math.exp(-A3*b))
gx = list(map(myf, x))
```

```
[]: import matplotlib.pyplot as plt
plt.title("plot of gx")
plt.xlabel("x-coordinates")
plt.ylabel("y-coordinates")
plt.scatter(x,gx)
```

[]: <matplotlib.collections.PathCollection at 0x7f5d48b175d0>

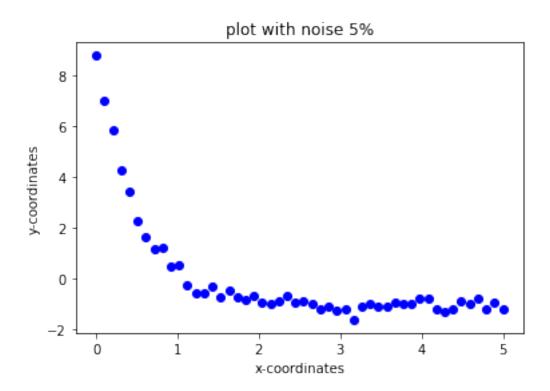


```
mu = 1
sd = 0.5
noiselist = np.random.normal(mu,sd,50)
def noisef(x, k):
    Amp = 0.01*k*max(gx)
    np.random.seed(0)
    noise = Amp*noiselist
    return gx + noise
g1x = noisef(x, 5)
g2x = noisef(x, 7)
g3x = noisef(x, 10)
```

Plotting the Noise data obtained with 5%, 7%, 10% Noise Amplitudes

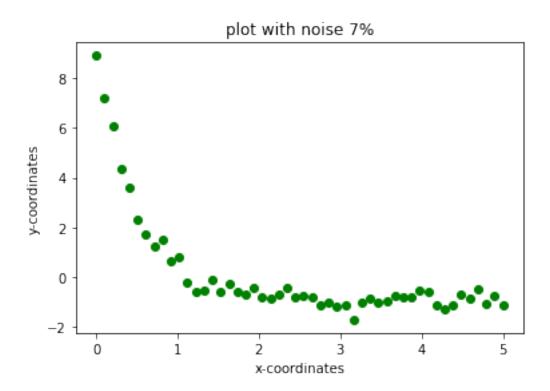
```
[]: plt.title("plot with noise 5%")
  plt.xlabel("x-coordinates")
  plt.ylabel("y-coordinates")
  plt.scatter(x, g1x, color='blue',label='noise = 5%')
```

[]: <matplotlib.collections.PathCollection at 0x7f5d48b174d0>



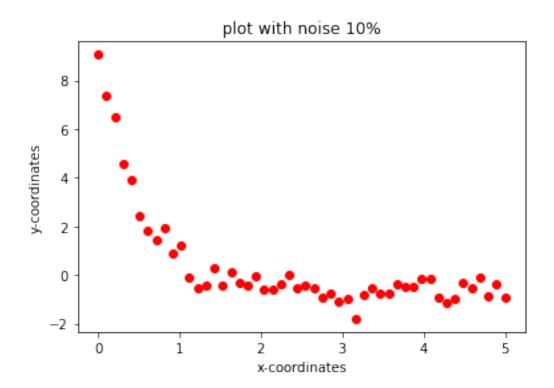
```
[]: plt.title("plot with noise 7%")
  plt.xlabel("x-coordinates")
  plt.ylabel("y-coordinates")
  plt.scatter(x, g2x, color='green')
```

[]: <matplotlib.collections.PathCollection at 0x7f5d46b8a110>



```
[]: plt.title("plot with noise 10%")
  plt.xlabel("x-coordinates")
  plt.ylabel("y-coordinates")
  plt.scatter(x, g3x, color='red')
```

[]: <matplotlib.collections.PathCollection at 0x7f5d46b14290>



0.2 Curve-Fitting

[]: from scipy import optimize

0.2.1 Now we will fit the curve using scipy

```
def myfunc(x, B1, B2, B3):
    return B1 + B2*np.exp(-B3*x)

[]: print("The difference in values of A1,B1 and A2,B2 and A3,B3 with 5%,7% and 10%
    →noise")
    params1, params1_covariance = optimize.curve_fit(myfunc, x, g1x, p0=[2,2,2])
    print(A1-params1[0], A2-params1[1], A3-params1[2])
    params2, params2_covariance = optimize.curve_fit(myfunc, x, g2x, p0=[2,2,2])
```

print(A1-params2[0], A2-params2[1], A3-params2[2])
params3, params3_covariance = optimize.curve_fit(myfunc, x, g3x, p0=[2,2,2])
print(A1-params3[0], A2-params3[1], A3-params3[2])

The difference in values of A1,B1 and A2,B2 and A3,B3 with 5%,7% and 10% noise -0.4156088233480699 0.033053407800498036 -0.012388395815381426

- -0.5818315991438257 0.0462858239317665 -0.017364239590608843
- -0.8311433037759148 0.0661479777195293 -0.02484894439703922

It can be here-by observed that as the noise is increasing the magnitude of the

difference is increasing

