

### Prim's Algorithm:

```
#include <stdio.h>

#include <limits.h>

#include <stdbool.h>

#define V 5 // Number of vertices in the graph

// Function to find the vertex with the minimum key value from the set of vertices not yet
included in MST

int minKey(int key[], bool mstSet[]) {
    int min = INT_MAX, min_index;
    for (int v = 0; v < V; v++)
        if (mstSet[v] == false && key[v] < min)
            min = key[v], min_index = v;
    return min_index;
}

// Function to print the constructed MST stored in parent[]

void printMST(int parent[], int graph[V][V]) {
    printf("Edge \tWeight\n");
    for (int i = 1; i < V; i++)
        printf("%d - %d \t%d \n", parent[i], i, graph[i][parent[i]]);
}

// Function that implements Prim's Algorithm

void primMST(int graph[V][V]) {
    int parent[V]; // Array to store the constructed MST
    int key[V];    // Key values to pick the minimum weight edge
    bool mstSet[V]; // To represent set of vertices included in MST

    // Initialize all keys as INFINITE
    for (int i = 0; i < V; i++)
        key[i] = INT_MAX, mstSet[i] = false;
```

```

// Include first vertex in MST
key[0] = 0; // Make key 0 so that this vertex is picked as the first vertex
parent[0] = -1; // First node is always the root of MST

// The MST will have V vertices
for (int count = 0; count < V - 1; count++) {
    // Pick the minimum key vertex from the set of vertices not yet included in MST
    int u = minKey(key, mstSet);

    // Add the picked vertex to the MST Set
    mstSet[u] = true;

    // Update key value and parent index of the adjacent vertices of the picked vertex
    for (int v = 0; v < V; v++)
        // graph[u][v] is non zero only for adjacent vertices of u
        // mstSet[v] is false for vertices not yet included in MST
        // Update the key only if graph[u][v] is smaller than key[v]
        if (graph[u][v] && mstSet[v] == false && graph[u][v] < key[v])
            parent[v] = u, key[v] = graph[u][v];
    }

    // Print the constructed MST
    printMST(parent, graph);
}

int main() {
    // Example graph represented as an adjacency matrix
    int graph[V][V] = {
        {0, 2, 0, 6, 0},
        {2, 0, 3, 8, 5},

```

```
{0, 3, 0, 0, 7},  
{6, 8, 0, 0, 9},  
{0, 5, 7, 9, 0}  
};
```

```
// Function call to Prim's algorithm
```

```
primMST(graph);
```

```
return 0;
```

```
}
```

### **Kruskal's Algorithm:**

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#define V 4 // Number of vertices in the graph
```

```
// Structure to represent an edge
```

```
struct Edge {
```

```
    int src, dest, weight;
```

```
};
```

```
// Structure to represent a graph
```

```
struct Graph {
```

```
    int V, E; // V = vertices, E = edges
```

```
    struct Edge* edges; // Array of edges
```

```
};
```

```
// Structure to represent a subset for Union-Find
```

```
struct subset {
```

```
    int parent;
```

```

    int rank;
};

// Function to create a graph with V vertices and E edges
struct Graph* createGraph(int V, int E) {
    struct Graph* graph = (struct Graph*) malloc(sizeof(struct Graph));
    graph->V = V;
    graph->E = E;
    graph->edges = (struct Edge*) malloc(graph->E * sizeof(struct Edge));
    return graph;
}

// A utility function to find the subset of an element i (uses path compression)
int find(struct subset subsets[], int i) {
    if (subsets[i].parent != i)
        subsets[i].parent = find(subsets, subsets[i].parent);
    return subsets[i].parent;
}

// A function that does union of two sets of x and y (uses union by rank)
void Union(struct subset subsets[], int x, int y) {
    int xroot = find(subsets, x);
    int yroot = find(subsets, y);

    // Attach smaller rank tree under root of the higher rank tree
    if (subsets[xroot].rank < subsets[yroot].rank)
        subsets[xroot].parent = yroot;
    else if (subsets[xroot].rank > subsets[yroot].rank)
        subsets[yroot].parent = xroot;
    else {

```

```

        subsets[yroot].parent = xroot;
        subsets[xroot].rank++;
    }
}

// Compare two edges according to their weights (for qsort)
int compare(const void* a, const void* b) {
    struct Edge* a1 = (struct Edge*) a;
    struct Edge* b1 = (struct Edge*) b;
    return a1->weight > b1->weight;
}

// Function to print the MST
void printMST(struct Edge result[], int e) {
    printf("Edges in the Minimum Spanning Tree:\n");
    for (int i = 0; i < e; ++i)
        printf("%d -- %d == %d\n", result[i].src, result[i].dest, result[i].weight);
}

// Function to implement Kruskal's algorithm
void KruskalMST(struct Graph* graph) {
    int V = graph->V;
    struct Edge result[V]; // Array to store the resulting MST
    int e = 0; // Index for result[]
    int i = 0; // Index for sorted edges

    // Step 1: Sort all the edges in non-decreasing order of their weight
    qsort(graph->edges, graph->E, sizeof(graph->edges[0]), compare);

    // Allocate memory for creating V subsets

```

```

struct subset* subsets = (struct subset*) malloc(V * sizeof(struct subset));

// Create V subsets with single elements
for (int v = 0; v < V; ++v) {
    subsets[v].parent = v;
    subsets[v].rank = 0;
}

// Number of edges to be taken is equal to V-1
while (e < V - 1 && i < graph->E) {
    // Step 2: Pick the smallest edge. Check if it forms a cycle with the MST formed so far.
    struct Edge next_edge = graph->edges[i++];

    int x = find(subsets, next_edge.src);
    int y = find(subsets, next_edge.dest);

    // If including this edge does not cause a cycle, include it in the result
    if (x != y) {
        result[e++] = next_edge;
        Union(subsets, x, y);
    }
}

// Print the resulting MST
printMST(result, e);

// Free memory
free(subsets);
}

```

```
int main() {  
    // Number of vertices and edges in the graph  
    int V = 4; // Vertices  
    int E = 5; // Edges  
    struct Graph* graph = createGraph(V, E);  
  
    // Adding the edges  
    graph->edges[0].src = 0;  
    graph->edges[0].dest = 1;  
    graph->edges[0].weight = 10;  
  
    graph->edges[1].src = 0;  
    graph->edges[1].dest = 2;  
    graph->edges[1].weight = 6;  
  
    graph->edges[2].src = 0;  
    graph->edges[2].dest = 3;  
    graph->edges[2].weight = 5;  
  
    graph->edges[3].src = 1;  
    graph->edges[3].dest = 3;  
    graph->edges[3].weight = 15;  
  
    graph->edges[4].src = 2;  
    graph->edges[4].dest = 3;  
    graph->edges[4].weight = 4;  
  
    // Call Kruskal's algorithm to find MST  
    KruskalMST(graph);  
}
```

```
// Free memory
free(graph->edges);
free(graph);

return 0;
}
```